

**MAGNETOTELLURIC DATA ACROSS THE
BATTLE MOUNTAIN-EUREKA AND
CARLIN TRENDS, NORTH OF EUREKA, NEVADA**

by

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INTRODUCTION

Genesis of gold deposits along the Battle Mountain-Eureka and Carlin trends in northern Nevada is not fully understood and subject to conflicting models (e.g. Arehart and others, 1993; Ilchik and Barton, 1997; Radtke, 1985; Shawe, 1991; Sillitoe and Bonham, 1990; Tosdal, 1998). A general consensus among these models is that regional structures somehow controlled the spatial distribution of the deposits. To investigate crustal structures that may be related to the genesis of gold deposits along these trends, a regional southwest-northeast profile of magnetotelluric (MT) soundings was acquired in 1999 and 2000 (line MT1-MT1', Figure 1). Resistivity modeling of the MT data can be used to infer the deep resistivity structure of the crust to help investigate possible tectonic controls on the emplacement of mineral deposits along these linear trends. The purpose of this report is to release the MT sounding data.

MAGNETOTELLURIC METHOD

The magnetotelluric (MT) method is a passive surface geophysical technique, which uses the earth's natural electromagnetic fields to investigate the electrical resistivity structure of the subsurface. The resistivity of geologic units is largely dependent upon their fluid content, porosity, degree of fracturing, temperature, and conductive mineral content (Keller, 1989). Saline fluids within the pore spaces and fracture openings can reduce resistivities in a resistive rock matrix. Also, resistivity can be lowered by the presence of conductive clay minerals, carbon, and metallic mineralization. It is common for altered volcanic rocks to contain authigenic minerals that have resistivities ten times lower than those of the surrounding rocks (Nelson and Anderson, 1992). Increased temperatures cause higher ionic mobility and mineral activation energy, reducing rock resistivities significantly. Unaltered, unfractured igneous rocks are normally very resistive (typically 1,000 ohm-m or greater), whereas fault zones will show low resistivity (less than 100 ohm-m) when they are comprised of rocks fractured enough to have hosted fluid transport and consequent mineralogical alteration (Eberhart-Phillips and others, 1995). Carbonate rocks are moderately to highly resistive (hundreds to thousands of ohm-m) dependent upon their fluid content, porosity, fracturing, and impurities. Marine shales, mudstones, and clay-rich alluvium are normally very conductive (a few ohm-m to tens of ohm-m). Unaltered, metamorphic rocks (non-graphitic) are moderately to highly resistive (hundreds to thousands of ohm-m). Tables of electrical

resistivity for a variety of rocks, minerals and geological environments may be found in Keller (1987) and Palacky (1987).

The MT method can be used to probe the crust from depths of tens of meters to depths of tens of kilometers (Vozoff, 1991). Natural variations of the Earth's magnetic and electric field are measured and recorded at each MT station. The main frequency bands used by the MT method are 10,000 Hz to 1 Hz from worldwide lightning activity and 1 Hz to 0.0001 Hz from geomagnetic micro-pulsations. The natural electric and magnetic fields propagate vertically in the earth because the very large resistivity contrast between the air and the earth causes a vertical refraction of both fields transmitted into the earth (Vozoff, 1972).

The natural electric and magnetic fields are recorded in two orthogonal, horizontal directions. The vertical magnetic field ("tipper") is also recorded. The resulting time-series signals are used to derive earth tensor apparent resistivities and phases by first converting them to complex cross-spectra using FFT (fast-Fourier-transform) techniques. Least-squares, cross-spectral analysis (Bendat and Piersol, 1971) is used to solve for a tensor-transfer function that relates the observed electric fields to the magnetic fields under the assumption that the Earth consists of a two-input, two-output, linear system with the magnetic fields as input and the electric fields as output (Rodriguez and others, 1996). Prior to conversion to apparent resistivity and phase, the tensor is normally rotated into principal directions that correspond to the direction of maximum and minimum apparent resistivity. For a two-dimensional (2-D) Earth, the MT fields can be de-coupled into transverse electric (TE) and transverse magnetic (TM) modes; 2-D modeling is generally done to fit both modes. When the geology satisfies the 2-D assumption, the MT data for the TE mode is assumed to represent the situation when the electric field is along the geologic strike, and the data for the TM mode is assumed to represent the situation when the electric field is across strike. The MT method is well suited for studying complicated geological environments because the electric and magnetic relations are sensitive to vertical and horizontal variations in resistivity. The method is capable of establishing whether the electromagnetic fields are responding to subsurface terranes of effectively 1-, 2-, or 3-dimensions. An introduction to the MT method and references for a more advanced understanding are contained in Dobrin and Savit (1988) and Vozoff (1991).

MAGNETOTELLURIC SURVEY

Fourteen MT soundings were located along or near profile MT1-MT1' (Figure 1) with spacing that varied from 1.3 to 16.9 kilometers. The profile orientation is roughly perpendicular to the Battle Mountain-Eureka and Carlin trends. All stations were collected with our portable EMI MT-1 system (EMI, 1996). The horizontal electric fields were sensed using an L-shaped, three-electrode array with dipole lengths of 30 m. The orthogonal, horizontal magnetic fields in the direction of the electric-field measurement array were sensed using permalloy-cored induction coils (Stanley and Tinkler, 1983). Frequencies sampled ranged from 100 to 0.01 Hz using single station recordings of both orthogonal horizontal components of the electric and magnetic fields, along with the vertical magnetic field at all stations except station 78. Sampling this frequency range in previous areas of widely varying geology has allowed us to probe the crust from depths of hundreds of meters to depths of tens of kilometers.

The recorded time-series data were transformed to the frequency domain and Fourier analyzed to determine a two-dimensional apparent resistivity and phase tensor at each site. The data were rotated to maximum and minimum apparent resistivity directions so that propagation modes for the signals were decoupled into TE and TM modes. Reference sensors to help reduce bias in the impedance determinations due to instrument or environmental noise (Gamble and others, 1979a; Clarke and others, 1983) were not used. Although remote reference techniques were not used in our survey, we did sort cross-power files to select optimal signal-to-noise data sets (Appendix).

The effects of near-surface resistivity anomalies cause "static shifts" (Sternberg and others, 1988) in the data. Static shifts of this data set ranged from 0.0 to 1.3 of a log decade. Only station 80 had a static shift of 1.3 of a log decade. The remainder of the stations had an average of 0.2 of a log decade static shift.

MAGNETOTELLURIC DATA

The following table shows fourteen magnetotelluric (MT) station locations (from southwest to northeast). Coordinates are referenced to the 1866 Clarke spheroid and North American 1927 Western United States datum. Longitude and latitude format below is decimal degrees. Elevation is in meters.

<u>Station</u>	<u>Longitude</u>	<u>Latitude</u>	<u>Elev (m)</u>
88	-116.47773	39.52744	1890
87	-116.27814	39.55249	1850
86	-116.15948	39.60576	1870
85	-116.04913	39.62802	1820
89	-115.97073	39.75141	1780
109	-115.87795	39.70953	1870
83	-115.80588	39.73506	2050
82	-115.71711	39.79929	1780
81	-115.63851	39.79379	1810
80	-115.54086	39.77805	2170
108	-115.53142	39.76552	2120
79	-115.47101	39.80462	2020
77	-115.39775	39.81638	1870
78	-115.32175	39.83858	1910

The figures in the Appendix represent the field-processed MT data for each station after the time series data were converted to the frequency domain and the tensor-transfer function was rotated into principal directions as described above in the "Magnetotelluric Method" section.

For each station, nine separate graph plots are given:

1. Apparent Resistivity for the rotated maximum (x symbol) and minimum (o symbol) modes
2. Impedance Phase for the rotated maximum (x symbol) and minimum (o symbol) modes
3. Rotation Angle for the impedance tensor (corresponds to the direction of maximum apparent resistivity)
4. Impedance Skew for the impedance tensor
5. Multiple Coherency for the rotated maximum (x symbol) and minimum (o symbol) modes of the electric field
6. Impedance Polar Plots (at 12 selected frequencies)
7. Tipper Magnitude for the vertical magnetic field
8. Tipper Strike for the vertical magnetic field, and
9. HzHx (x symbol) and HzHy (o symbol) Coherency

Error bars that appear on the Apparent Resistivity, Impedance Phase, Skew, Tipper Magnitude, and Tipper Strike plots represent probable errors within one standard deviation of the sample variance (Gamble and others, 1979b).

Apparent resistivity is a measure of the magnitude of the electric field strength over the magnetic field strength for a given frequency. The impedance phase is proportional to the slope of the apparent resistivity curve on a log-log scale, but from a baseline at -45 degrees (Vozoff, 1991). A measure of the dimensionality for MT data is provided by the impedance skew of the impedance tensor (Vozoff, 1972). If the effective measured

resistivity response to the geology beneath a MT station is truly 1-D or 2-D, then the skew will be zero. Both instrument and environmental sources of noise contribute to non-zero skew values, but are typically small (about 0.1) for relatively low noise level recordings. Higher skews (above 0.2) are an indication of either 3-D resistivity responses to the geology or higher levels of noise. Man-made electrical noise, such as power lines, power generators, moving vehicles and trains can have a negative effect on MT data quality. All these local disturbances produce an incoherent noise mainly affecting frequencies above 1 Hz. Other man-made electrical noise, such as direct current electric trains and active cathodic protection of pipelines produce coherent electromagnetic signals mainly affecting frequencies below 1 Hz.

In the survey area, noise from a number of small power lines and small moving vehicles was negligible at distances of 0.4 km and greater from the noise source. Power line levels were measured at each site and were typically less than 20% of the maximum recordable signals. Noise from larger power lines, power generators, pipelines, railroads, and steam-driven trains, mostly near mining operations, was negligible at least 5 km from them. Recordings were not made when noise from moving vehicles affected the magnetic signals. Local lightning, wind, and rainstorms can also degrade data quality, but these were avoided by not recording during active thunderstorm periods. Wind noise was minimized by burying the magnetic induction coils.

Predicted values of the electric field can be computed from the measured values of the magnetic field (Vozoff, 1991). The coherence of the predicted electric field with the measured electric field is a measure of the signal-to-noise ratio provided in the multiple coherency plot. Values are normalized between 0 and 1, where values at 0.5 signify signal levels equal to noise levels. For this data set, coherencies were generally at an acceptable level, except at times in the "dead band" (0.1 to 1 Hz) and at times in the lower frequencies (0.01 to 0.1). The lower frequency ionospheric signals are related to sunspot activity whose levels typically follow an 11-year cycle. The sunspot activity was near the highest level of the cycle during the 1999 and 2000 surveys.

The figures in the Appendix represent the raw field MT data at each station, which includes some data scatter and poor signal-to-noise ratios. Our only effort at removing noisy data points was to visually inspect and select the best signal-to-noise field data to combine into the final data plots.

The impedance polar plots provide a measure of the MT data dimensionality (Reddy and others, 1977). For 1-D resistivity

structures, the principal impedance polar diagram (dashed line) is a circle. For 2-D or 3-D resistivity structures, the principal impedance polar diagram (dashed line) elongates either parallel or perpendicular to strike direction. Over resistors, the principal impedance polar diagram elongates perpendicular to strike direction and over conductors, the principal impedance polar diagram elongates parallel to strike direction. Also, for 2-D resistivity structures, the additional impedance polar diagram (solid line) attains the shape of a symmetric clover leaf. For 3-D resistivity structures, the additional impedance polar diagram (solid line) elongates in one direction and its amplitude is comparable to that of the principal impedance polar diagram (dashed line). Sites whose polar plots indicated 3-D character in the lower frequencies were MT stations 77, 80, 82, 83, 86, 88, and 89 (Figure 1).

The tipper can be solved for when the vertical component of the magnetic field is measured. The tipper magnitude is a measure of the tipping of the magnetic field out of the horizontal plane (Vozoff, 1991). The magnitude is zero for the 1-D case and typically increases between 0.1 to 0.5, and rarely as great as 1, as it responds to vertical and sub-vertical structures. The tipper strike is typically used to help resolve the 90-degree ambiguity in the impedance rotation angle. The vertical component of the magnetic field was measured at all MT stations except station 78. The tipper magnitude of these stations was typically 0.1 to 0.4 over the lower frequencies indicating vertical structure at depth. The HzHx and HzHy coherency is a measure of the signal-to-noise ratio of the vertical magnetic field with respect to each of the orthogonal horizontal magnetic field directions. Values are normalized between 0 and 1, where values at 0.5 signify signal levels equal to noise levels. These three-component magnetic field coherencies provide a check on the signal-to-noise ratio of the measured values in the tipper magnitude and tipper strike plots.

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APPENDIX

MAGNETOTELLURIC DATA PLOTS

For stations 77, 79-89, 108, and 109, there are nine separate graph plots:

1. Apparent Resistivity for the rotated maximum (x symbol) and minimum (o symbol) modes
2. Impedance Phase for the rotated maximum (x symbol) and minimum (o symbol) modes
3. Rotation Angle for the impedance tensor (corresponds to the direction of maximum apparent resistivity)
4. Impedance Skew for the impedance tensor
5. Multiple Coherency for the rotated maximum (x symbol) and minimum (o symbol) modes of the electric field
6. Impedance Polar Plots (at 12 selected frequencies)
7. Tipper Magnitude for the vertical magnetic field
8. Tipper Strike for the vertical magnetic field, and
9. HzHx (x symbol) and HzHy (o symbol) Coherency

Station 78 has only the first six graph plots above, since the vertical magnetic field data (Tipper, Hz) was not acquired. Refer to the "Magnetotelluric Data" section in this report for an explanation of these plots.

Figure 1. Index map. Magnetotelluric transect (MT1-MT1') acquired in 1999 and 2000 in northeastern Nevada. Shaded zones are two northwest-trending mineralized belts in northeastern Nevada, the well-known Carlin trend and the Battle Mountain-Eureka trend. Base map adapted from Struhsacker and others (1996).