



NOTES ON BASE
This quadrangle is part of a series of topographic maps made from stereoscopic Viking Orbiter images.

ADOPTED FIGURE
The figure of Mars used for computation of the map projection is an oblate spheroid (flattening of 1/192) with an equatorial radius of 3,393.4 km and a polar radius of 3,375.7 km.

PROJECTION
Mercator, Lambert Conformal Conic, and Polar Stereographic projections are used for this map series. The scale of the series is 1:2,000,000 at lat ±27.476° (Mercator), lat ±35.85° and ±59.17° (Lambert), and lat ±75.008° (Polar Stereographic). The projections have common scales of 1:1,952,947 at lat ±30° and 1:1,939,394 at lat ±65°.

CONTOURS
Contours were compiled on analytical stereoplotters that use stereoscopic Viking Orbiter pictures. The parameters for stereoplotters were computed analytically, based on the adjusted positions and orientations of the spacecraft cameras (Wu and others, 1982). Horizontal and vertical controls were established by analytical photogrammetric aerotriangulation (Wu and Schaler, 1984), using the General Integral Analytical Triangulation (GIANT) program of the U.S. Geological Survey. Primary controls used in the control network include the Viking Orbiter Secondary Experiment Data Record, radio occultation measurements from Mariner 9 and Viking Missions (Klore and others, 1973; Lindal and others, 1979), Earth-based radar observations (Downs and others, 1975), and the Mars primary control network of the Rand Corporation (Davies and others, 1978). Elevation values (expressed in meters) are given with respect to the adopted Mars topographic datum. This datum is defined by a gravity field described in terms of fourth-order and fourth-degree spherical harmonics combined with a 6.1 millibar atmospheric pressure surface derived from Mariner 9 radio occultation data (Lorell and others, 1972; Klore and others, 1973; Wu, 1978, 1981).

Local mismatches between contour lines shown here and images on controlled photostacks are the result of improvements in control nets during the course of compilation. Estimated elevation accuracy is approximately 1 km (one contour interval).

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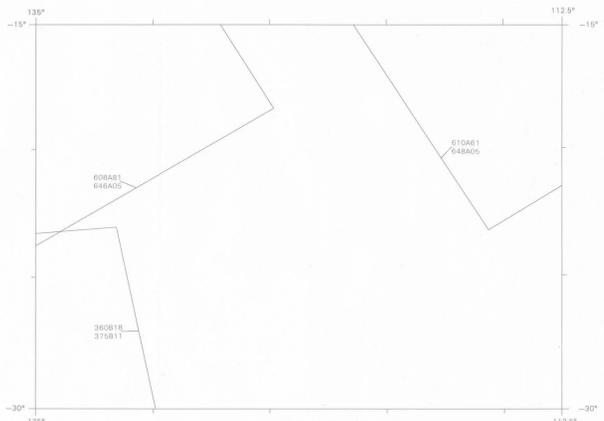
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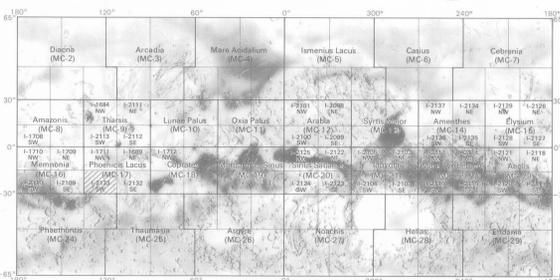
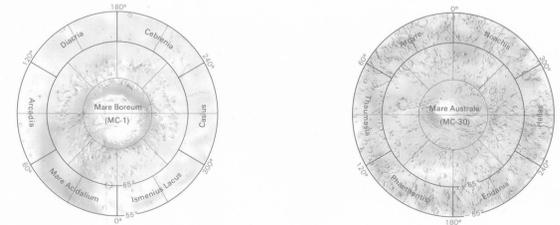
Wu, S.S.C., and Schaler, F.J., 1984, Mars control network, in Technical papers of the 50th annual meeting of the American Society of Photogrammetry, v. 2, Washington, D.C., March 11-16, 1984, p. 456-463.

INDEX OF STEREMODEL COVERAGE
This topographic map was made from the pairs of Viking pictures outlined above. Copies of various enhancements of these pictures are available from National Space Science Data Center, Code 601, Goddard Space Flight Center, Greenbelt, MD 20771.



SCALE 1:2,000,000 (1 mm = 2 km) AT -27.476° LATITUDE
(SCALE 1:2,251,800 (1 mm = 2.25 km) AT 0° LATITUDE)
MERCATOR PROJECTION
CONTOUR INTERVAL 1000 METERS

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INDEX OF PUBLISHED TOPOGRAPHIC MAPS
Quadrangle availability is indicated by an "P" series number

TOPOGRAPHIC MAP OF THE PHOENICIS LACUS SOUTHWEST QUADRANGLE (MC-17 SW) OF MARS

NOTE TO USERS
Users noting errors or omissions are urged to indicate them on the map and to forward it to U.S. Geological Survey, Building 4, Room 412, 2255 North Gemini Drive, Flagstaff, AZ 86001. A replacement copy will be returned.

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