

Figure 1.—Map showing localities of multichannel seismic-reflection profiles offshore and on land in the mesozoselal area and vicinity of the 1886 Charleston earthquake. The tracklines of the high-resolution profiles (G1-G24) and two of the deep-penetration profiles (G28 and G29) collected by the RV Gyré are shown. Tracklines of deep-penetration profiles from an earlier (1979) survey are labeled CH; the trackline labeled 1974 is from a 1974 survey and is not discussed here. Some unlabeled seismic lines, from other surveys, are shown. Interpreted Cenozoic (compressional and extensional) and Triassic(?) extensional faults are indicated. Cenozoic normal faults Y and Z are interpreted from tracklines CH1 and CH2 respectively. The modified-Mercall intensity-X isoseismal line for the 1886 earthquake (labeled MM X) is shown from Bollinger (1977). The Helena Banks fault zone overlies the narrow Kiawah Triassic(?) basin, shown by the screen pattern. The faults indicated near the crossing of tracklines G28 and G29 are not discussed in the text but this feature, observed in older data shown by Dillon and others (1979), was discussed by Behrendt and others (1983). Inset shows enlargement of transition area between two main branches of the Helena Banks fault: note normal fault Y perpendicular to the main Helena Banks fault trend from CH1. Paired arrows indicate strike-slip movement.

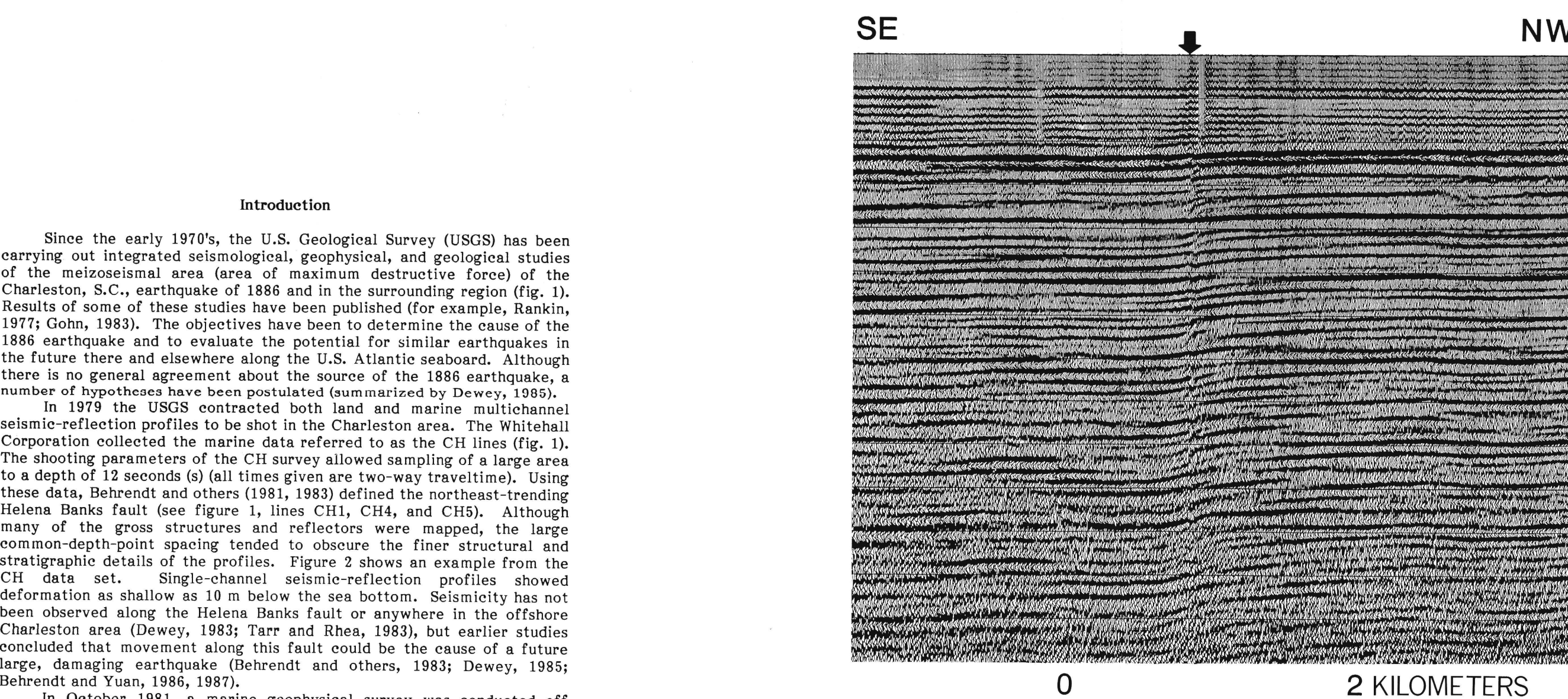


Figure 4.—Seismic section crossing the Helena Banks fault from line G9, plotted at 3:1 vertical exaggeration to show deformation details. Arrow indicates fault. Vertical axis is two-way traveltime, in seconds.

Introduction

Since the early 1970's, the U.S. Geological Survey (USGS) has carried out integrated seismological, geophysical, and geological studies of the mesozoselal area (area of maximum destructive force) of the Charleston, S.C., earthquake of 1886 and in the surrounding region (fig. 1). Results of some of these studies have been published (for example, Rankin, 1977; Gohn, 1983). The objectives have been to determine the cause of the 1886 earthquake and to evaluate the potential for similar earthquakes in the future there and elsewhere along the U.S. Atlantic seaboard. Although there is no general agreement about the source of the 1886 earthquake, a number of hypotheses have been postulated (summarized by Dewey, 1983).

In 1979 the USGS contracted both land and marine multichannel seismic-reflection profiles to be shot in the Charleston area. The Whitehall Corporation collected the marine data referred to as the CH lines (fig. 1). The shooting parameters of the CH survey allowed sampling of a large area to a depth of 15 seconds (6 all times given two-way traveltime). Using these data, Behrendt and others (1981, 1983) defined the northeast-trending Helena Banks fault (see figure 1, lines CH1, CH4, and CH5). Although many of the gross structures and reflectors were mapped, the large common-depth-point spacing tended to obscure the finer structural and stratigraphic details of the profiles. Figure 2 shows an example from the CH data set. Single-channel seismic-reflection profiles showed deformation as shallow as 10 m below the sea bottom. Seismicity has not been observed along the Helena Banks fault or anywhere in the offshore Charleston area (Dewey, 1983; Tarr and Rhea, 1983), but earlier studies concluded that movement along this fault could be the cause of a future large, damaging earthquake (Behrendt and others, 1983; Dewey, 1983; Behrendt and Yuan, 1986, 1987).

In October 1981, a marine geophysical survey was conducted off Charleston by the research vessel (RV) Gyré. The objective of the survey was to better define the configuration and history of the Helena Banks fault zone. Three distinct data sets were collected during the Gyré cruise: a high-resolution seismic-reflection survey, a deep-penetration (F+ record length) seismic-reflection survey, and a simultaneous gravity survey. Gyré lines 1 through 24 (G1-G24, fig. 1) represent the first high-resolution seismic survey in the offshore Charleston area and are the primary focus of this report. The deep-penetration lines, Gyré lines 25 through 29 (only G28 and G29 are shown in figure 1), were located to investigate deep (5 to 5 s) diffractions that were identified on some of the seismic profiles as possible intrusives suggested by previous aeromagnetic studies (Kilgord and Behrendt, 1977, 1979; Behrendt and Kilgord, 1979).

Along the Gyré lines, although results from lines 27 through 29 are unusable due to an equipment malfunction, only the high-resolution data are presented here. Behrendt and Yuan (1986, 1987) discussed these results and their tectonic implications but presented only a few small-scale examples of the actual seismic-reflection record sections.

RV Gyré data set

During the seven-day RV Gyré cruise, 680 km of high-resolution multichannel seismic-reflection data were collected with a 10-m shotpoint interval and 20-m group intervals an additional 18 km of single-channel mini-seismic data were obtained over Gyré line 12 (G12, fig. 1). The high-resolution Gyré lines 1 through 24 combined with the previous CH data provide a dense grid of multichannel seismic-reflection data close to the 1886 mesozoselal area (fig. 1), the densest set of publicly available multichannel seismic-reflection data on the U.S. Atlantic continental margin.

This map shows sections of all the high-resolution seismic-reflection profiles that cross the Helena Banks fault zone (fig. 3). All the sections but one are displayed at a 6:1 vertical exaggeration to enhance the resolution of small-displacement, steeply dipping faults and to match the display of the CH lines. The exception, a section shown in figure 4, has a 3:1 vertical exaggeration. Vertical exaggeration was calculated assuming an average seismic velocity of 2.0 km/s (Behrendt and others, 1983) for the upper second of section, one second corresponding to one kilometer of depth.

Field operations and data processing

The sound source for the high-resolution survey was a tuned array of two 1.5-liter (60-cubic-inch) water guns firing on distance every 10 m. The twelve-channel, 220-m-long streamer had a near offset of 103 m. Using a Tektronix DTS V recording system, three seconds of digital data were obtained at a 1-m sampling rate. However, the higher frequencies were attenuated and this high sample rate was unnecessary. The RV Gyré was equipped with an integrated navigation system which combined hyperbolic loran-C with periodic corrections of absolute positions from navigation satellites. The absolute accuracy is estimated to be ± 50 m. The relative error for shotpoints is approximately ± 0.5 m based on position checks made every hundred shotpoints. Such high relative accuracy is important in multichannel processing because in order for multiple traces from different shots to "see" the same depth point, a constant shotpoint interval must be maintained. Common-depth-point data are then sorted and stacked, enhancing signal and attenuating noise.

The data were processed by means of the USGS seismic-processing system in Denver, Colo. A total of 210 field tapes were demultiplexed and corrected for spherical divergence. Near-trace plots provided a preliminary check on the data. The data were then sorted by common point depth according to the observers' reports, and some editing of bad records was done. Although three seconds of data were recorded in the field, only the first two seconds were processed because of noise at depths below 1.4 s.

Eight common depth points were selected every 1 to 4 km, depending on the uniformity of the strata, for velocity analyses. These methods and velocity analysis were applied; computer-determined signal coherence versus stacking velocity, constant-velocity analysis applied to stacks, and constant-velocity analysis applied to common-depth-point gathers. Time-velocity pairs that were similar, though differently derived from the three methods, were plotted by common depth point to check for realistic velocity structures. The optimal time-velocity pairs were ultimately stored and used for normal moveout correction. The normal moveout correction accounts for different reflection arrival times due to variations in the offset distance between source and geophone.

The velocity studies from the Gyré data show high coherence when gradually increasing stacking velocities (in the 1.7 to 2.0 km/s range) are applied down to the arrival of the J reflection, a significant marker that occurs between 0.8 and 1.2 s throughout the Gyré survey area (Behrendt and others, 1983; Behrendt and Yuan, 1986, 1987). The J reflection, which has been identified previously on land (Yantis and others, 1983; Schill and others, 1983; Hamilton and others, 1983) and offshore (Dillon and others, 1979; Behrendt and others, 1983) and attributed to the high acoustic-impedance contrast between a series of Jurassic (Langphere, 1983) basalt flows and overlying Upper Cretaceous sediments, provided an easily recognized target for processing tests. The lithology and geochemistry of the basalt are discussed by Gohn and others (1977, 1979), Gottfried and others (1977, 1983), and Schneider and others (1979).

Stacking velocities above the J reflection increase with depth gradually, but at the J reflection show a sharp step-like increase of 0.1 to 0.5 km/s stacking velocities are 2.0-2.5 km/s at depths consistent with the arrival of the J reflection as extrapolated from the CH survey (for example, figure 2). This increase in velocity results in a dramatic increase in interval velocities from approximately 1.8-2.0 km/s above the J reflection to 3.0-3.5 km/s at and below the J reflection. The interval velocity range for the J reflection is low when compared to that of the seismic-reflection velocities on land of 4.4 to 5.7 km/s (Ackerkern, 1983) and at sea of 5.8 to 6.3 km/s (Dillon and others, 1979). However, these calculated interval velocities are used only to give an indication that stacking velocities used during processing are realistic and consistent with existing information. Velocity analysis below the J reflection is of little or no use because of the poor signal-to-noise ratio and little normal moveout with the short streamer, so a standard stacking velocity of 3.5 km/s at 2.0 s was applied.

Signal analysis included autocorrelation and frequency spectral analysis. We performed standard tests of different deconvolution and bandpass filters, and automatic-gain control gates. Inspection of data from each line determined the severity of the mute (partial seismic-trace editing) and the need for further (whole-trace) editing.

The processing scheme that produced the best results on test sections was applied to the entire seismic profile. For most of the profiles this optimal processing scheme varied little. Typically, the steps used to produce the final stacks were: demultiplex and spherical divergence correction, zero-amplitude shot edit, geometry definition, CDP sort, zero-amplitude channel edit, mute, automatic-gain control (1.0-s gate), predictive (15-ms gap) deconvolution, velocity analysis, time-velocity pairs storage, normal moveout correction, mute, 12-fold stack, bandpass filter (usually 20 to 85 Hz), automatic-gain control (1.0-s gate), and final display. The final stacks in figure 3 were plotted with a horizontal scale of 30 traces per inch and a vertical scale of 1.5 in/s prior to reducing the impact in multichannel processing because in order for multiple traces from different shots to "see" the same depth point, a constant shotpoint interval must be maintained. Common-depth-point data are then sorted and stacked, enhancing signal and attenuating noise.

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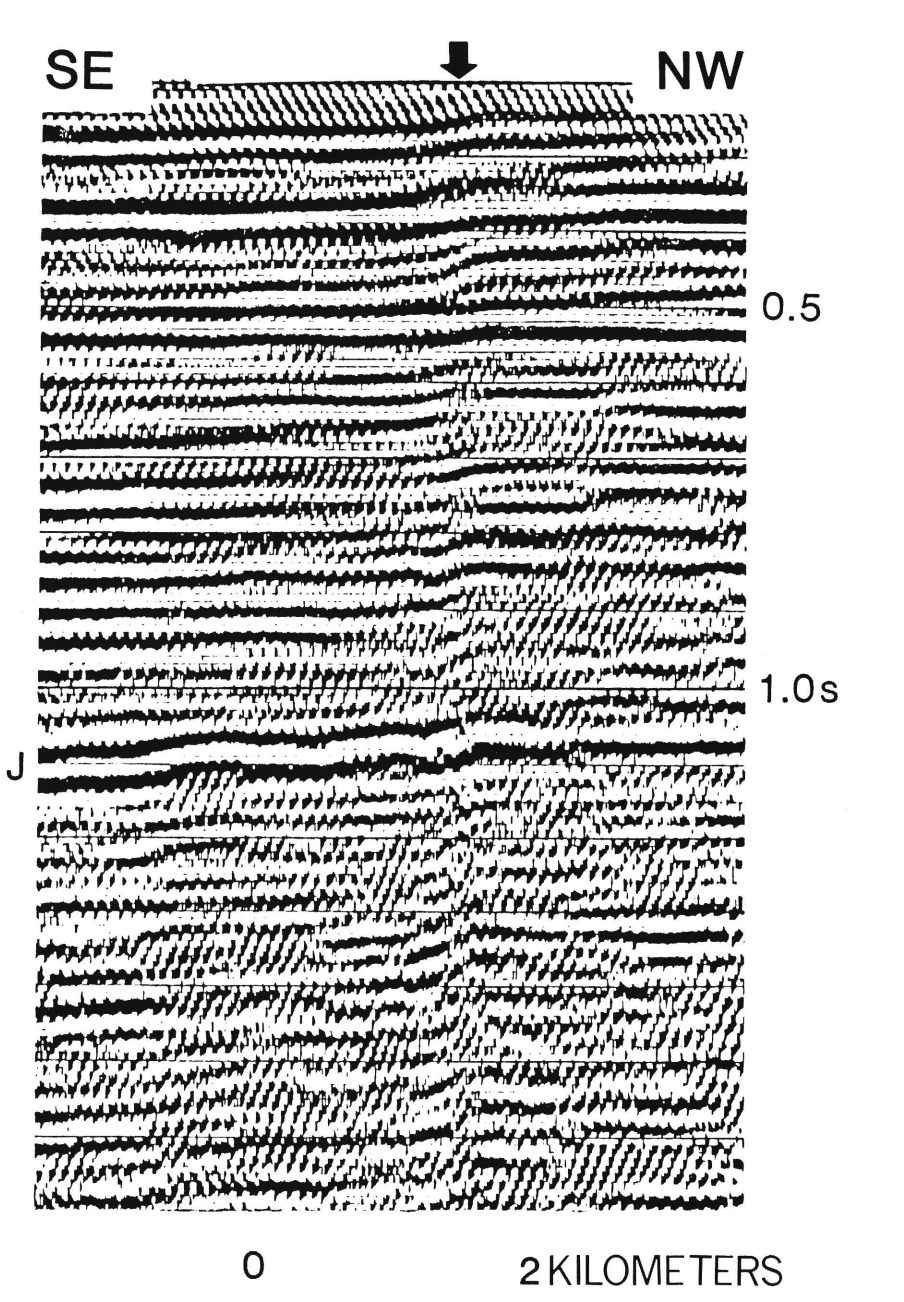


Figure 2.—Section of seismic profile from CH4 crossing the Helena Banks fault (indicated by arrow). J reflection is labelled. Vertical axis is two-way traveltime, in seconds. Vertical exaggeration x6.

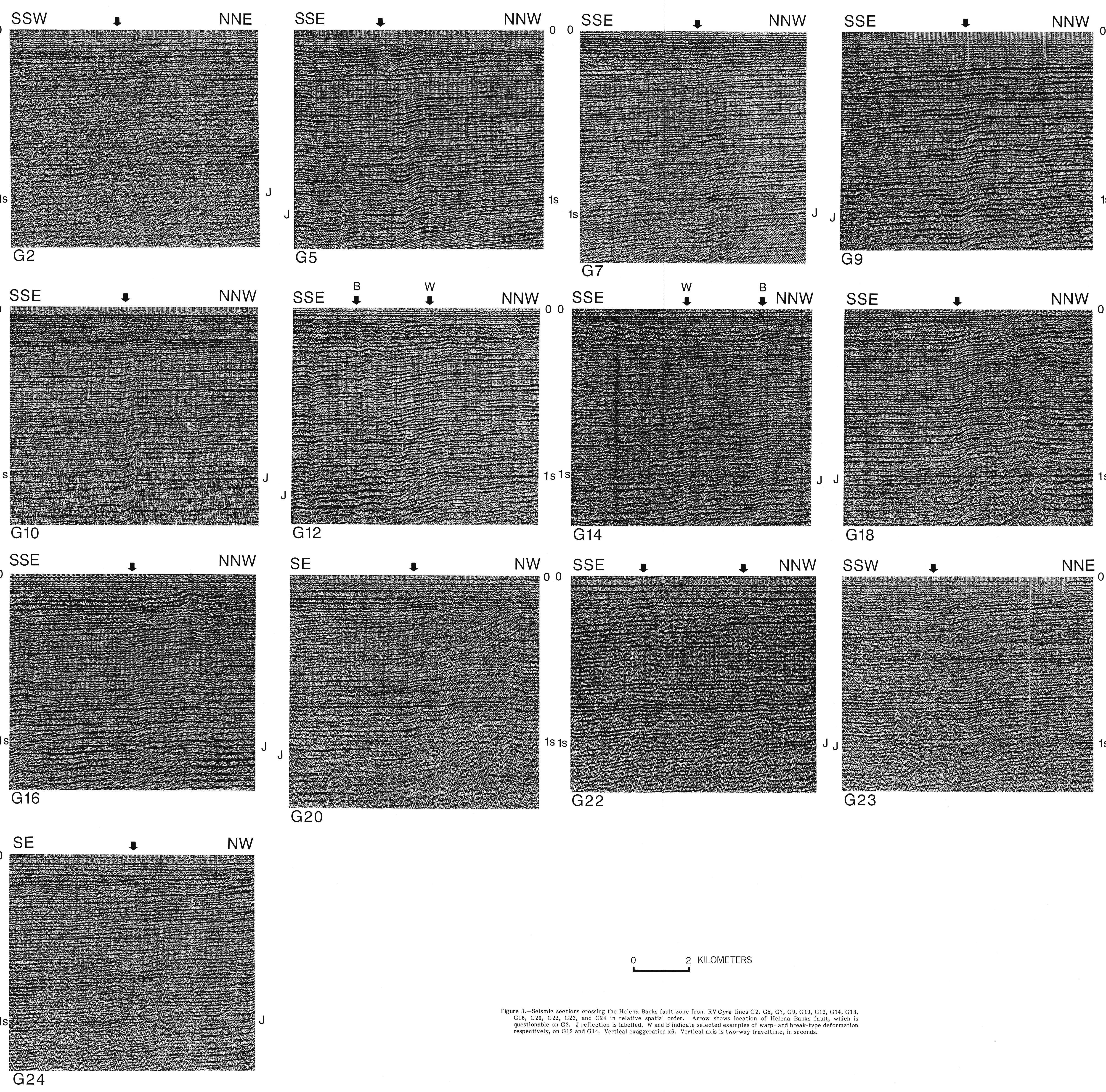


Figure 3.—Seismic sections crossing the Helena Banks fault zone from RV Gyré lines G2, G5, G7, G9, G10, G12, G14, G16, G20, G22, G23, and G24 in relative spatial order. Arrow shows location of Helena Banks fault, which is questionable on G2. J reflection is labelled. W and B indicate selected examples of warp- and break-type deformation respectively, on G12 and G14. Vertical exaggeration x6. Vertical axis is two-way traveltime, in seconds.

## HIGH-RESOLUTION MULTICHANNEL SEISMIC-REFLECTION PROFILES ACROSS THE HELENA BANKS STRIKE-SLIP FAULT ZONE OFFSHORE OF THE CHARLESTON, SOUTH CAROLINA, EARTHQUAKE AREA

By  
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