

DOCUMENTATION OF FINITE-DIFFERENCE MODEL
FOR
SIMULATION OF THREE-DIMENSIONAL GROUND-WATER FLOW

By

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The efficiency of the program has been improved significantly by Steven P. Larson who added the option of storing input arrays on disk and modified the solution routine to use only single-subscript arrays.

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INTRODUCTION

This report documents a finite-difference model for simulation of ground-water flow in three dimensions. Although the techniques for constructing numerical models of ground-water flow in three dimensions have been available in the petroleum literature for some time, the large computer-memory requirements for simulation of realistic ground-water problems have discouraged development of such models. To minimize the core requirements for these simulations, Bredehoeft and Pinder (1970) described a quasi three-dimensional model which is a sequence of two-dimensional ground-water flow models coupled by terms representing flow through intervening confining beds. In practice there has been some difficulty getting convergence with this approach. The fully three-dimensional model described in this report can be reduced to a quasi three-dimensional model in terms of the equations being solved and computer-memory requirements, yet converges to a solution much faster because all equations are solved simultaneously.

The iterative numerical technique used to solve the set of simultaneous finite-difference equations is the strongly implicit procedure (SIP) originally described by Stone (1968) for problems in two dimensions and extended to three dimensions by Weinstein, Stone and Kwan (1969). Weinstein and others (1969) claim that SIP converges faster than the iterative alternating-direction implicit procedure (ADI) (used for solution in two dimensions by Bredehoeft and Pinder, 1970) and that SIP is less subject to roundoff errors than ADI.

THEORETICAL DEVELOPMENT

Ground-water flow equation

The flow of ground water in a porous medium in three dimensions may be expressed as (Jacob, 1950, Cooper, 1966)

$$\nabla^2 h = \frac{S_s}{K} \frac{\partial h}{\partial t} \quad (1)$$

in which h is hydraulic head (L);

S_s is specific storage (L^{-1});

K is hydraulic conductivity ($L T^{-1}$).

Permitting hydraulic conductivity to be heterogeneous and anisotropic and adding a source term, equation 1 becomes

$$\nabla \cdot (K_{ij} \frac{\partial h}{\partial x_j}) = S_s \frac{\partial h}{\partial t} + W(x,y,z,t) \quad (2)$$

in which $W(x,y,z,t)$ is a volumetric flux per unit volume (T^{-1}).

Assuming that the coordinate axes x, y and z are aligned with the principal directions of the hydraulic conductivity tensor, the cross-product terms drop out of equation 2 and it becomes in expanded form

$$\frac{\partial}{\partial x} (K_{xx} \frac{\partial h}{\partial x}) + \frac{\partial}{\partial y} (K_{yy} \frac{\partial h}{\partial y}) + \frac{\partial}{\partial z} (K_{zz} \frac{\partial h}{\partial z}) = S_s \frac{\partial h}{\partial t} + W(x,y,z,t) \quad (3)$$

in which

K_{xx}, K_{yy}, K_{zz} are the principal components of the hydraulic conductivity tensor ($L T^{-1}$).

In the finite-difference simulator, it is often convenient to represent a hydraulic unit by one layer of nodes. For this approach, equation 3 is multiplied by b, the thickness of the hydraulic unit giving

$$\frac{\partial}{\partial x} (T_{xx} \frac{\partial h}{\partial x}) + \frac{\partial}{\partial y} (T_{yy} \frac{\partial h}{\partial y}) + \frac{\partial}{\partial z} (bK_{zz} \frac{\partial h}{\partial z}) = S' \frac{\partial h}{\partial t} + bW(x,y,z,t) \quad (4)$$

in which T_{xx} , T_{yy} are the principal components of the transmissivity tensor ($L^2 T^{-1}$);

S' is the storage coefficient (dimensionless).

Although the model is designed to solve equation 4, it will solve equation 3 by substituting hydraulic conductivity, specific storage, and $W(x,y,z,t)$ for transmissivity, storage coefficient, and $bW(x,y,z,t)$, respectively.

Finite-difference approximation

In order to solve equation 3 or 4 for a heterogeneous, anisotropic porous medium with irregular boundaries, one approach is to subdivide the region into blocks in which the medium properties are assumed to be uniform. The continuous derivatives in equation 3 or 4 are replaced by finite-difference approximations for the derivatives at a point (the node at the center of the block). The result is N equations in N unknowns (head values at the nodes) where N is the number of blocks representing the porous medium.

Utilizing a block-centered, finite-difference grid in which variable grid spacing is permitted (figure 1), equation 4 may be approximated as

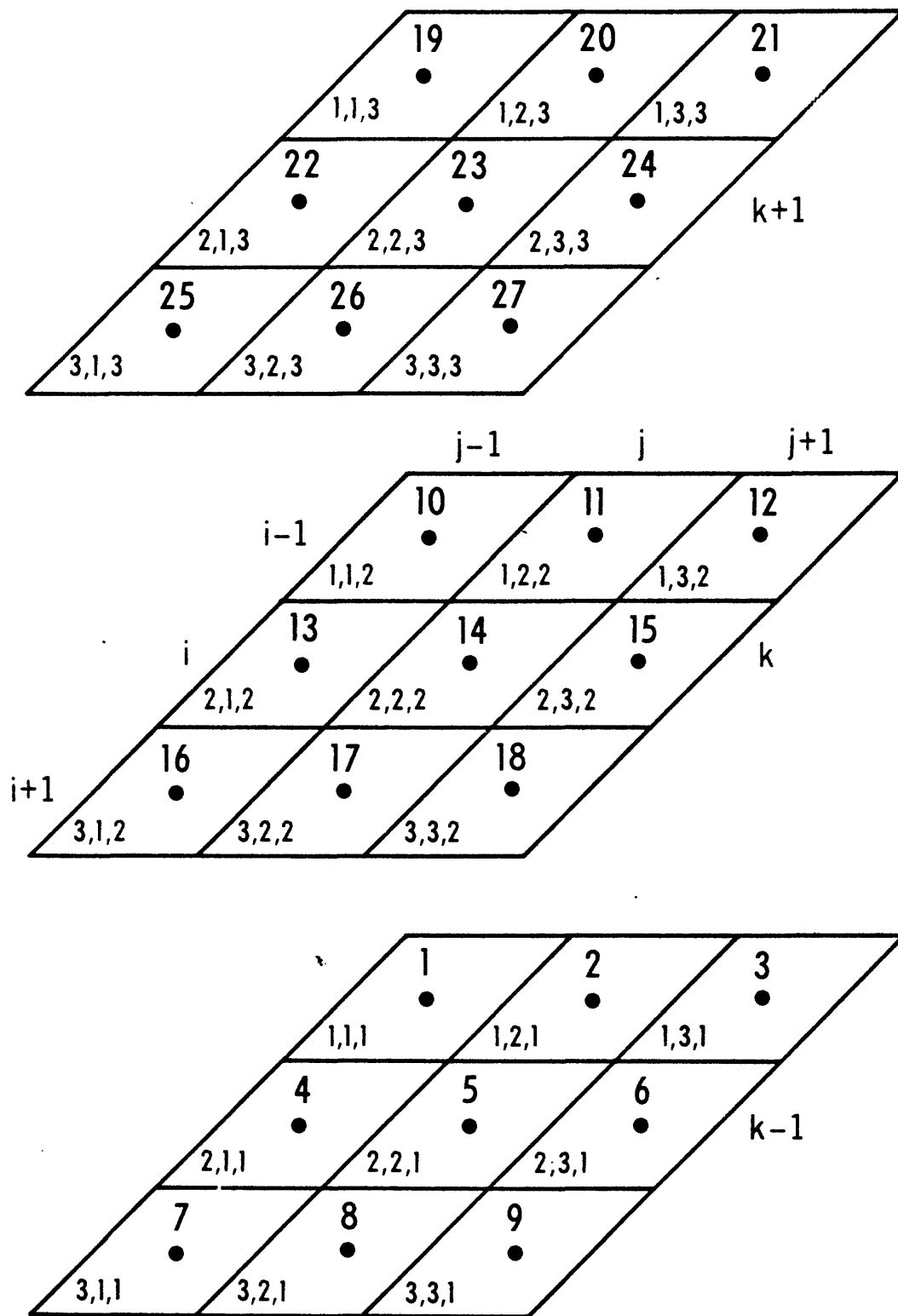


Figure 1.--Index scheme for finite-difference grid and the normal ordering of nodes for 3 X 3 X 3 problem. The numerical values of the indices (i,j,k) for this problem are given in the lower left-hand corner of each block.

$$\frac{1}{\Delta x_j} \left[(T_{xx} \frac{\partial h}{\partial x})_{i,j+\frac{1}{2},k} - (T_{xx} \frac{\partial h}{\partial x})_{i,j-\frac{1}{2},k} \right] +$$

$$\frac{1}{\Delta y_i} \left[(T_{yy} \frac{\partial h}{\partial y})_{i+\frac{1}{2},j,k} - (T_{yy} \frac{\partial h}{\partial y})_{i-\frac{1}{2},j,k} \right] +$$

$$\frac{1}{\Delta z_k} \left[(bK_{zz} \frac{\partial h}{\partial z})_{i,j,k+\frac{1}{2}} - (bK_{zz} \frac{\partial h}{\partial z})_{i,j,k-\frac{1}{2}} \right] =$$

$$\frac{S'_{i,j,k}}{\Delta t} (h_{i,j,k} - \hat{h}_{i,j,k}) + bW_{i,j,k} \quad (5)$$

in which Δx_j is the space increment in the x direction for column j (L);

Δy_i is the space increment in the y direction for row i (L);

Δz_k is the space increment in the z direction for layer k (L);

Δt is the time increment (T);

i is the index in the y dimension;

j is the index in the x dimension;

k is the index in the z dimension;

$\hat{h}_{i,j,k}$ is the hydraulic head at the previous time step (L).

The final approximation for equation 4 is

$$\begin{aligned}
& \frac{1}{\Delta x_j} \left\{ [T_{xx}(i, j+\frac{1}{2}, k) \frac{(h_{i,j+1,k} - h_{i,j,k})}{\Delta x_{j+\frac{1}{2}}}] - [T_{xx}(i, j-\frac{1}{2}, k) \frac{(h_{i,j,k} - h_{i,j-1,k})}{\Delta x_{j-\frac{1}{2}}}] \right\} + \\
& \frac{1}{\Delta y_i} \left\{ [T_{yy}(i+\frac{1}{2}, j, k) \frac{(h_{i+1,j,k} - h_{i,j,k})}{\Delta y_{i+\frac{1}{2}}}] - [T_{yy}(i-\frac{1}{2}, j, k) \frac{(h_{i,j,k} - h_{i-1,j,k})}{\Delta y_{i-\frac{1}{2}}}] \right\} + \\
& \frac{1}{\Delta z_k} \left\{ [(bK_{zz})_{i,j,k+\frac{1}{2}} \frac{(h_{i,j,k+1} - h_{i,j,k})}{\Delta z_{k+\frac{1}{2}}}] - [(bK_{zz})_{i,j,k-\frac{1}{2}} \frac{(h_{i,j,k} - h_{i,j,k-1})}{\Delta z_{k-\frac{1}{2}}}] \right\} \\
& = \frac{S'_{i,j,k}}{\Delta t} (h_{i,j,k} - \hat{h}_{i,j,k}) + bW_{i,j,k} \quad . \quad (6)
\end{aligned}$$

Following a convention similar to that introduced by Stone (1968), the notation in equation 6 may be simplified by writing

$$\begin{aligned}
& F_{i,j,k} (h_{i,j+1,k} - h_{i,j,k}) - D_{i,j,k} (h_{i,j,k} - h_{i,j-1,k}) + \\
& H_{i,j,k} (h_{i+1,j,k} - h_{i,j,k}) - B_{i,j,k} (h_{i,j,k} - h_{i-1,j,k}) + \\
& S_{i,j,k} (h_{i,j,k+1} - h_{i,j,k}) - Z_{i,j,k} (h_{i,j,k} - h_{i,j,k-1}) \\
& = \frac{S'_{i,j,k}}{\Delta t} (h_{i,j,k} - \hat{h}_{i,j,k}) + bW_{i,j,k} \quad , \quad (7)
\end{aligned}$$

in which

$$B_{i,j,k} = \left[\frac{2T_{yy}[i,j,k] T_{yy}[i-1,j,k]}{T_{yy}[i,j,k] \Delta y_{i-1} + T_{yy}[i-1,j,k] \Delta y_i} \right] / \Delta y_i \quad (8a)$$

and the terms in brackets is the harmonic mean of

$$\frac{T_{yy}[i,j,k]}{\Delta y_i}, \quad \frac{T_{yy}[i-1,j,k]}{\Delta y_{i-1}}.$$

Similarly,

$$D_{i,j,k} = \left[\frac{2T_{xx}[i,j,k] T_{xx}[i,j-1,k]}{T_{xx}[i,j,k] \Delta x_{j-1} + T_{xx}[i,j-1,k] \Delta x_j} \right] / \Delta x_j; \quad (8b)$$

$$F_{i,j,k} = \left[\frac{2T_{xx}[i,j,k] T_{xx}[i,j+1,k]}{T_{xx}[i,j,k] \Delta x_{j+1} + T_{xx}[i,j+1,k] \Delta x_j} \right] / \Delta x_j; \quad (8c)$$

$$H_{i,j,k} = \left[\frac{2T_{yy}[i+1,j,k] T_{yy}[i,j,k]}{T_{yy}[i,j,k] \Delta y_{i+1} + T_{yy}[i+1,j,k] \Delta y_i} \right] / \Delta y_i; \quad (8d)$$

$$S_{i,j,k} = \left[\frac{2(bK_{zz})_{i,j,k+1} (bK_{zz})_{i,j,k}}{(bK_{zz})_{i,j,k} \Delta z_{k+1} + (bK_{zz})_{i,j,k+1} \Delta z_k} \right] / \Delta z_k; \quad (8e)$$

$$Z_{i,j,k} = \left[\frac{2(bK_{zz})_{i,j,k-1} (bK_{zz})_{i,j,k}}{(bK_{zz})_{i,j,k} \Delta z_{k-1} + (bK_{zz})_{i,j,k-1} \Delta z_k} \right] / \Delta z_k. \quad (8f)$$

Use of the harmonic mean 1) insures continuity across block boundaries at steady state for an irregular grid and 2) makes the appropriate coefficients zero at no-flow boundaries.

If the upper hydrologic unit is under water-table conditions, the specific yield is inserted for the storage coefficient and the transmissivities in equations 8 are defined as a function of the head for the previous iteration. As an example

$$T_{xx}^n(i,j,k) = K_{xx}(i,j,k) b_{i,j,k}^{n-1}$$

in which $b_{i,j,k}^{n-1}$ is the saturated thickness of the upper hydrologic unit at iteration n-1;
n is the iteration index.

The notation in equation 7 can be simplified by eliminating all subscripts not including a '+1' or '-1'. After rearranging equation 7 by placing all of the unknowns on the left-hand side, it becomes

$$Bh_{i-1} + Dh_{j-1} + Eh + Fh_{j+1} + Hh_{i+1} + Sh_{k+1} + Zh_{k-1} = Q \quad (9)$$

in which

$$E = - (B + D + F + H + S + Z + \frac{S'}{\Delta t});$$

$$Q = - \frac{S'}{\Delta t} \hat{h} + bW.$$

Source Term

The source term $W(x,y,z,t)$ can include well discharge and recharge from precipitation. In the model the source term is computed as

$$(bW)_{i,j,k} = \frac{Q_{w[i,j,k]}}{\Delta x_j \Delta y_i} - q_{re[i,j,k]}$$

in which

$Q_{w[i,j,k]}$ is the well discharge (L^3T^{-1});

$q_{re[i,j,k]}$ is the volumetric flux per unit area of the uppermost hydraulic unit (LT^{-1}). (Adding this term to other layers will require modifications to the code.)

To solve equation 3 instead of 4, divide $Q_{w[i,j,k]}$ and $q_{re[i,j,k]}$ by Δz_k for data input.

Numerical Solution by the Strongly Implicit Procedure

The following development follows that given in Weinstein, Stone and Kwan (1969). The nodes (i,j,k) may be ordered as in figure 1 so that j is swept through first ($j = 1,2,\dots,J$), i is swept through second ($i = 1,2,\dots,I$) and k last ($k = 1,2,\dots,K'$). Ordering the set of equations 9 in the same manner, they may be represented by the matrix equation

$$\bar{A} \bar{h} = \bar{Q} \quad (10)$$

in which

$$\bar{h} = \begin{bmatrix} h_{1,1,1} \\ h_{1,2,1} \\ : \\ h_{1,J,1} \\ h_{2,1,1} \\ h_{2,2,1} \\ : \\ h_{2,J,1} \\ : \\ : \\ h_{I,J,K'} \end{bmatrix}$$

and I is the number of rows;

J is the number of columns;

K' is the number of layers.

\bar{Q} has the same form as \bar{h} , and the matrix \bar{A} is shown in figure 2. Equation 10 may be solved directly by factoring \bar{A} into lower \bar{L} and upper \bar{U} triangular matrices. However, \bar{L} has non-zero elements in all the diagonals from Z to E and \bar{U} has non-zero elements in all of the diagonals from E to S. Consequently, solution by Gaussian elimination for problems of practical size requires excessive computation time and computer storage.

To include as many zero diagonals in \bar{L} and \bar{U} as possible, a modifying matrix \bar{B} can be added to \bar{A} such that $(\bar{A}+\bar{B})$ factors into \bar{L} and \bar{U} as shown in figures 3 and 4. With this modification, equation 10 becomes

$$(\bar{A} + \bar{B}) \bar{h} = \bar{Q} + \bar{B}\bar{h} \quad (11)$$

Equation 11 can be solved readily if the right-hand side is known. This leads to an iterative scheme defined by the following equation:

$$(\bar{A} + \bar{B}) \bar{h}^n = \bar{Q} + \bar{B}\bar{h}^{n-1} \quad (12)$$

in which n is an iteration index. To reduce roundoff errors, equation 12 is put in residual form by adding and subtracting $\bar{A}\bar{h}^{n-1}$ to the right hand side:

$$(\bar{A} + \bar{B}) \bar{\xi}^n = \bar{R}^{n-1} \quad (13)$$

in which $\bar{\xi}^n = \bar{h}^n - \bar{h}^{n-1}$;

$$\bar{R}^{n-1} = \bar{Q} - \bar{A}\bar{h}^{n-1}.$$

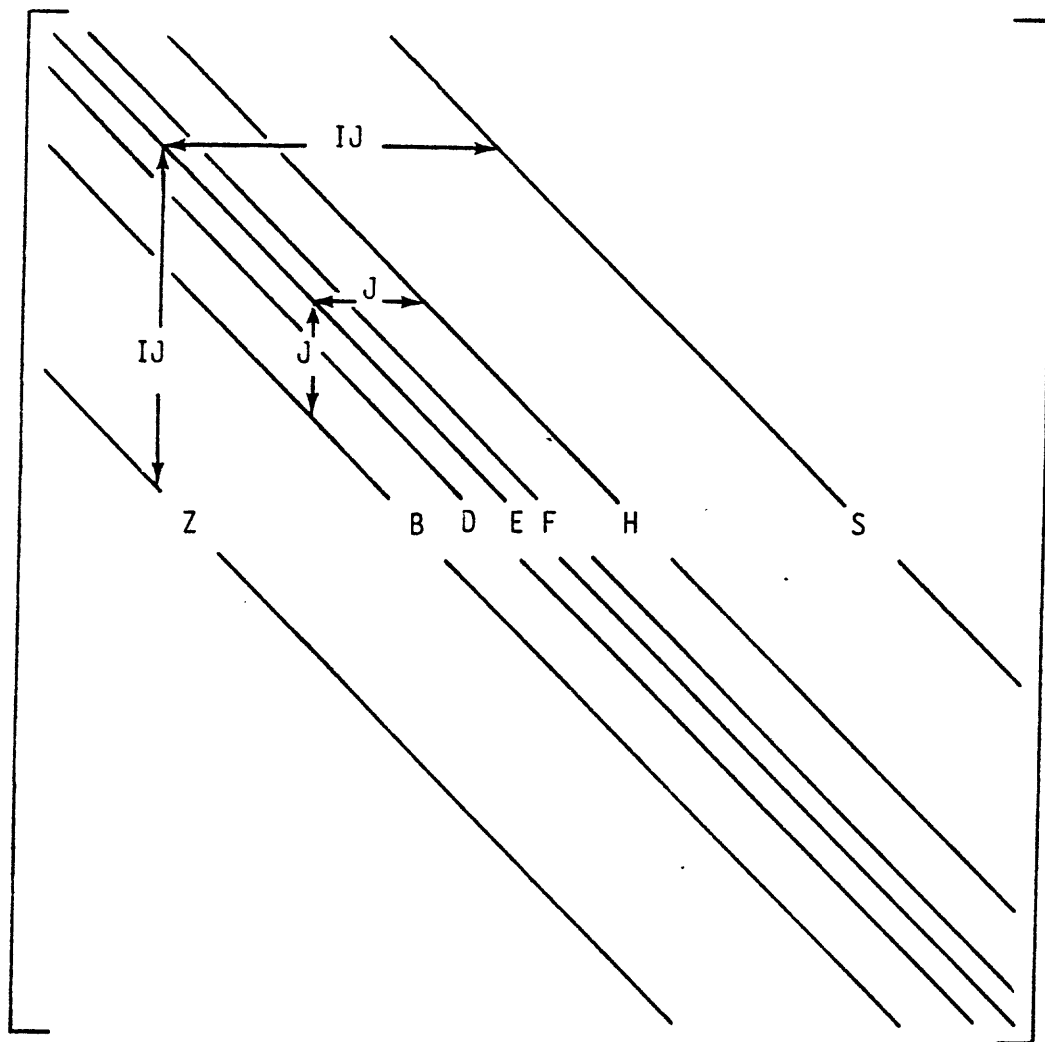


Figure 2.--Matrix A.

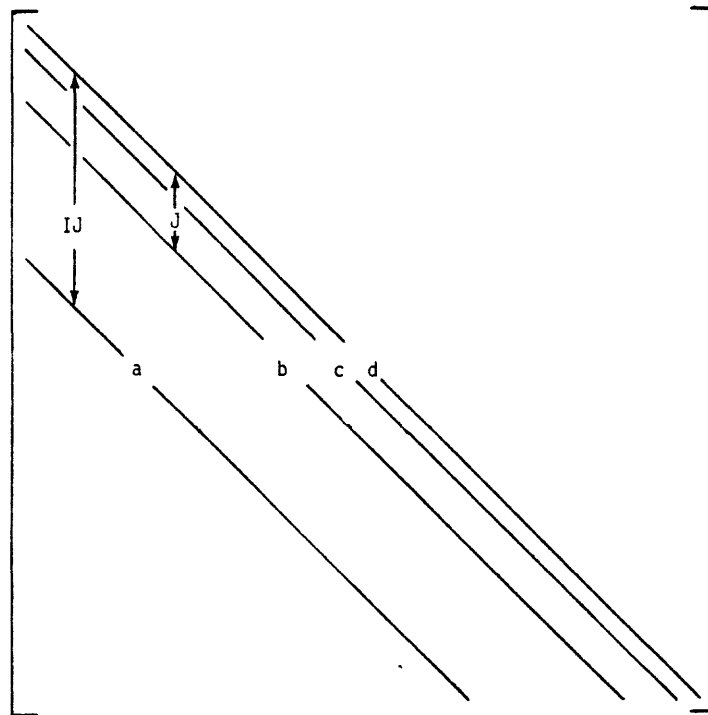


Figure 3.--Lower triangular factor \bar{L} of $(\bar{A}+\bar{B})$.

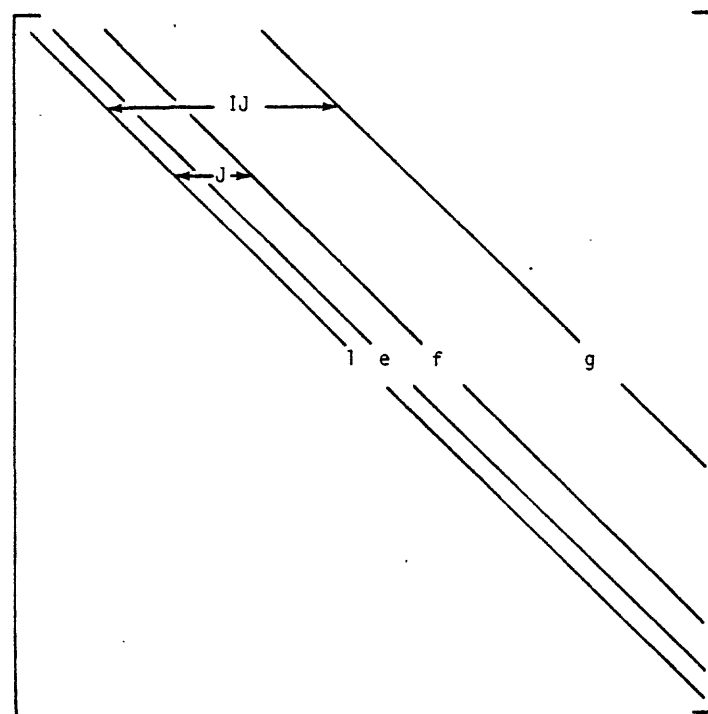


Figure 4.--Upper triangular factor \bar{U} of $(\bar{A}+\bar{B})$.

\bar{R}^{n-1} is known from the previous iteration. The (i,j,k) element of \bar{R}^{n-1} is given by

$$R^{n-1} = Q - (Bh_{i-1}^{n-1} + Dh_{j-1}^{n-1} + Eh^{n-1} + Fh_{j+1}^{n-1} + Hh_{i+1}^{n-1} + Sh_{k+1}^{n-1} + Zh_{k-1}^{n-1}).$$

When $\xi_{\max}^n < \varepsilon$, an arbitrary error criterion, a solution to equation 13 is obtained.

Derivation of the SIP algorithm requires 1) the relationships defining

$$(\overline{A+B}) = \overline{LU}; \quad (14)$$

2) an appropriate definition of \bar{B} ; and 3) relationships among the elements of \bar{A} and $(\overline{A+B})$. The matrix $(\overline{A+B})$ is shown in figure 5 and the elements of $(\overline{A+B})$ or \overline{LU} are defined by

$$\begin{aligned} Z' &= a \\ A &= ae_{k-1} \\ T &= af_{k-1} \\ B' &= b \\ C &= e_{i-1}b \\ D' &= c \\ E' &= ag_{k-1} + bf_{i-1} + e_{j-1}c + d \\ F' &= de \\ G &= f_{j-1}c \\ H' &= fd \\ U &= bg_{i-1} \\ W &= g_{j-1}c \\ S' &= gd \end{aligned} \quad (15)$$

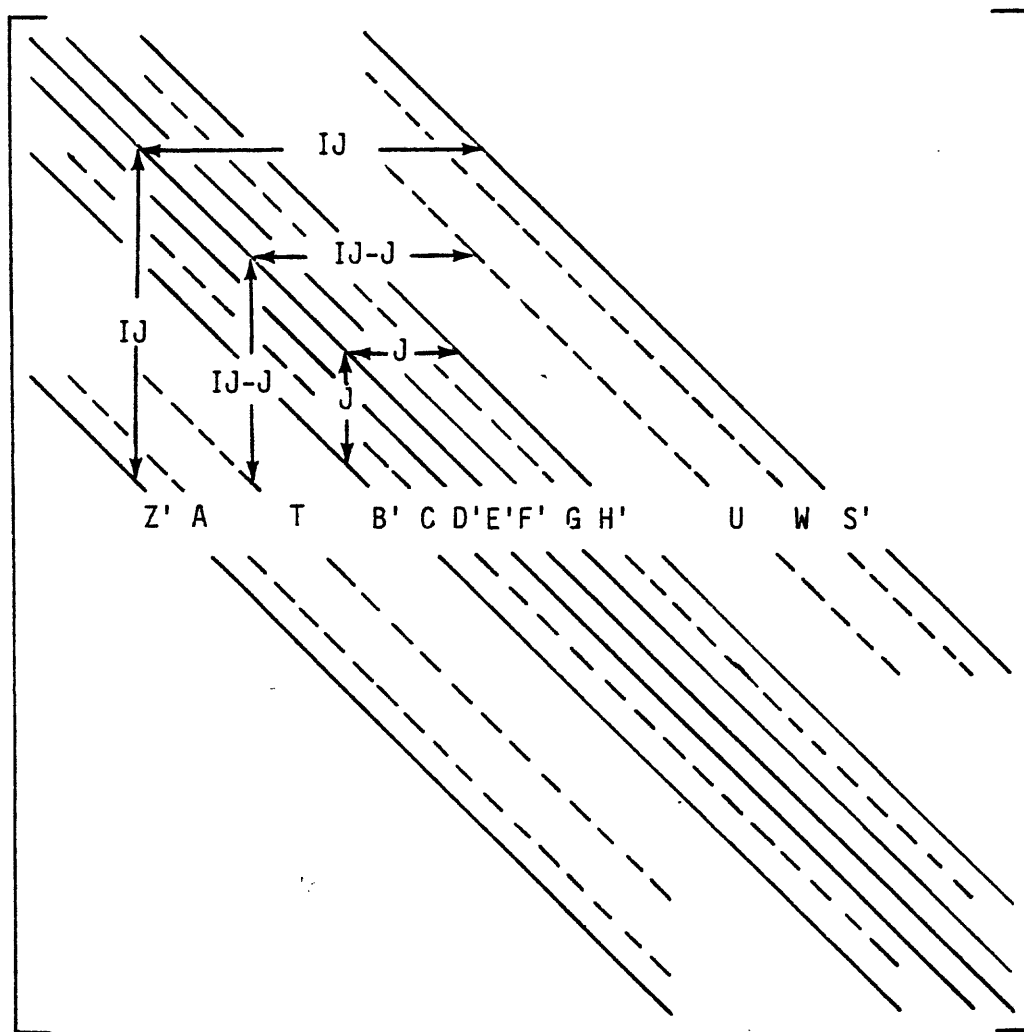


Figure 5.--Matrix $\overline{(A+B)}$.

The nodal values associated with the elements of $\overline{\overline{A+B}}$ not in the original difference equation 9 (namely, those associated with the coefficients C,G,A,W,T,U) are shown in figure 6. Stone (1968) and Weinstein, Stone and Kwan (1969) have found it effective to define $\overline{\overline{B}}$ (there are many ways of defining $\overline{\overline{B}}$ that will satisfy equation 14) so that the contribution of these additional terms is partially cancelled. Their definition of $\overline{\overline{B}}$ can be seen by writing $\overline{\overline{B}}\xi$ for node (i,j,k) as

$$\begin{aligned}
& C [\xi_{i-1,j+1} - \omega (-\xi + \xi_{i-1} + \xi_{j+1})] + \\
& G [\xi_{i+1,j-1} - \omega (-\xi + \xi_{j-1} + \xi_{i+1})] + \\
& A [\xi_{j+1,k-1} - \omega (-\xi + \xi_{j+1} + \xi_{k-1})] + \\
& W [\xi_{j-1,k+1} - \omega (-\xi + \xi_{j-1} + \xi_{k+1})] + \\
& T [\xi_{i+1,k-1} - \omega (-\xi + \xi_{i+1} + \xi_{k-1})] + \\
& U [\xi_{i-1,k+1} - \omega (-\xi + \xi_{i-1} + \xi_{k+1})]
\end{aligned} \tag{16}$$

in which ω is an iteration parameter. Weinstein, Stone and Kwan (1969) define different parameters for each of the three planes in space, but in practice use only one parameter each iteration. The term $(-\xi + \xi_{i-1} + \xi_{j+1})$ is the second order correct approximation for $\xi_{i-1,j+1}$. The remaining elements of $\overline{\overline{B}}\xi$ for node (i,j,k) in 16 have similar relationships. (See Remson and others, 1971, p. 226 for derivation of this type of approximation.)

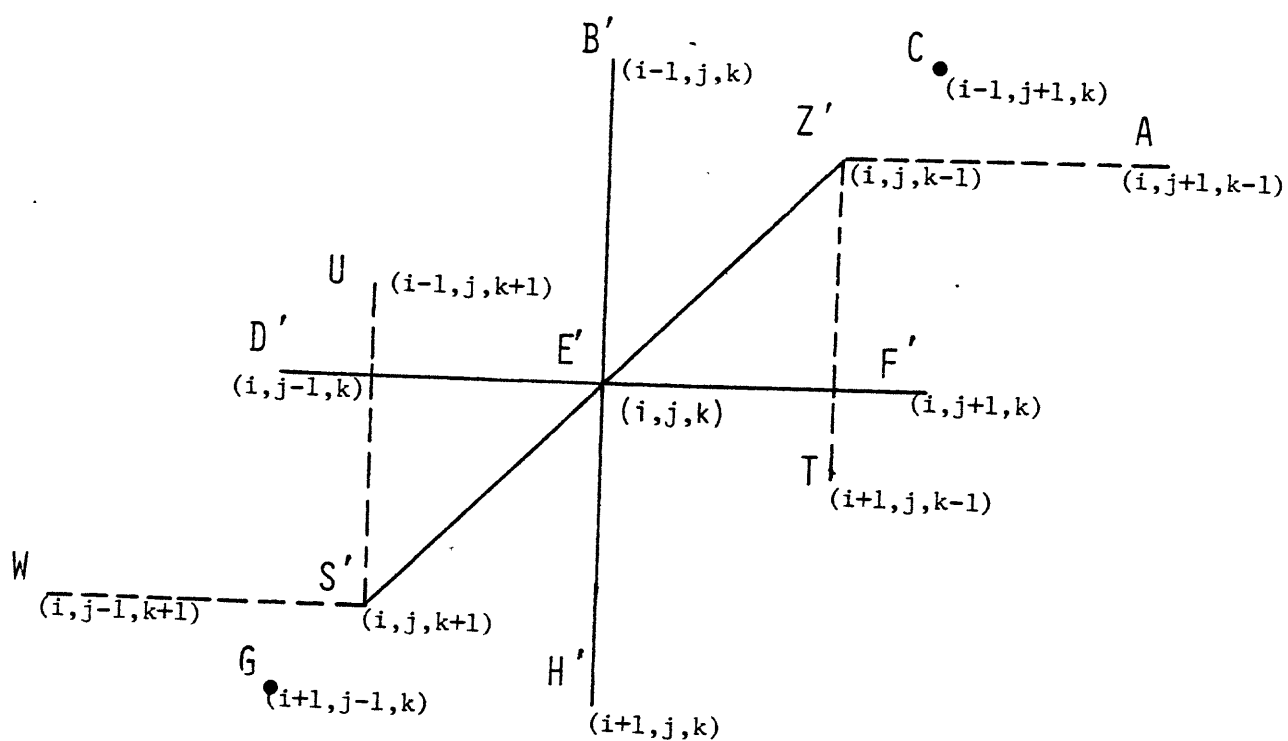
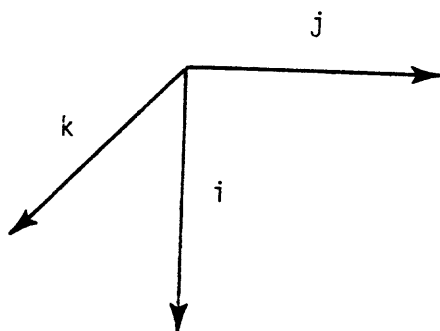


Figure 6.--Coefficients for normal ordering scheme.

With these definitions, equation 13 written for node (i,j,k) is

$$\begin{aligned}
& B\xi_{i-1}^n + D\xi_{j-1}^n + E\xi_{j+1}^n + F\xi_{j+1}^n + H\xi_{i+1}^n + S\xi_{k+1}^n + Z\xi_{k-1}^n + \\
& C[\xi_{i-1,j+1}^n - \omega (-\xi_{i-1}^n + \xi_{i-1}^n + \xi_{j+1}^n)] + \\
& G[\xi_{i+1,j-1}^n - \omega (-\xi_{i+1}^n + \xi_{j-1}^n + \xi_{i+1}^n)] + \\
& A[\xi_{j+1,k-1}^n - \omega (-\xi_{j+1}^n + \xi_{j+1}^n + \xi_{k-1}^n)] + \\
& W[\xi_{j-1,k+1}^n - \omega (-\xi_{j-1}^n + \xi_{j-1}^n + \xi_{k+1}^n)] + \\
& T[\xi_{i+k,k-1}^n - \omega (-\xi_{i+1}^n + \xi_{i+1}^n + \xi_{k-1}^n)] + \\
& U[\xi_{i-1,k+1}^n - \omega (-\xi_{i-1}^n + \xi_{i-1}^n + \xi_{k+1}^n)] = R^{n-1}. \quad (17)
\end{aligned}$$

By collecting coefficients associated with nodal positions in the original difference equation and using equations 15, the SIP algorithm can be derived as

$$\begin{aligned}
a &= Z/(1+\omega (e_{k-1} + f_{k-1})) \\
b &= B/(1+\omega (e_{i-1} + g_{i-1})) \\
c &= D/(1+\omega (f_{j-1} + g_{j-1})) \\
A &= ae_{k-1} \\
C &= be_{i-1} \\
G &= cf_{j-1} \\
W &= cg_{j-1} \\
T &= af_{k-1} \\
U &= bg_{i-1}
\end{aligned}$$

$$\begin{aligned}
d &= E + \omega (A + C + G + W + T + U) - ce_{j-1} - bf_{i-1} - ag_{k-1} \\
e &= (F - \omega (A + C))/d \\
f &= (H - \omega (G + T))/d \\
g &= (S - \omega (W + U))/d.
\end{aligned} \tag{18}$$

Equation 14 may be combined with equation 13 to give

$$\bar{\bar{L}}\bar{\bar{U}}\bar{\xi}^n = \bar{R}^{n-1}. \tag{19}$$

Define the vector \bar{V}^n by

$$\bar{\bar{U}}\bar{\xi}^n = \bar{V}^n. \tag{20}$$

Then equation 19 becomes

$$\bar{\bar{L}}\bar{V}^n = \bar{R}^{n-1}. \tag{21}$$

After solving equations 18, the intermediate vector \bar{V}^n can be computed; for node (i,j,k) equation 21 is (refer to figure 3 for the elements of $\bar{\bar{L}}$)

$$aV_{k-1}^n + bV_{i-1}^n + cV_{j-1}^n + dV^n = R^{n-1}$$

or

$$V^n = (R^{n-1} - aV_{k-1}^n - bV_{i-1}^n - cV_{j-1}^n)/d.$$

The vector $\bar{\xi}^n$ may then be computed by backward substitution.

Equation 20 for node (i,j,k) is (refer to figure 4 for the elements of $\bar{\bar{U}}$)

$$\xi^n + e\xi_{j+1}^n + f\xi_{i+1}^n + g\xi_{a+1}^n = V^n$$

or

$$\xi^n = V^n - (e\xi_{j+1}^n + f\xi_{i+1}^n + g\xi_{k+1}^n).$$

Stone (1968) and Weinstein and others (1969) recommend that a second ordering scheme be used every other iteration. In the second ordering scheme, j is swept through first in increasing order ($j = 1, 2, \dots, J$), i is second in decreasing order ($i = I, I-1, \dots, 1$), and k last in decreasing order ($k = K, K'-1, \dots, 1$). (See figure 7.) This tends to give an overall symmetry to $\overline{(A+B)}$ for the two iterations (compare figures 6 and 8) and speeds convergence.

The algorithm for the second (or 'reverse') ordering scheme is derived in a manner analogous to that for the 'normal' ordering scheme given above. The SIP reverse algorithm is outlined below:

$$\begin{aligned}
 a &= S / (1 + \omega(e_{k+1} + f_{k+1})) \\
 b &= H / (1 + \omega(e_{i+1} + g_{i+1})) \\
 c &= D / (1 + \omega(f_{j-1} + g_{j-1})) \\
 A &= ae_{k+1} \\
 C &= be_{i+1} \\
 G &= cf_{j-1} \\
 W &= cg_{j-1} \\
 T &= af_{k+1} \\
 U &= bg_{i+1} \\
 d &= E + \omega(C + G + A + W + T + U) - ag_{k+1} - bf_{i+1} - ce_{j-1} \\
 e &= (F - \omega(C + A)) / d \\
 f &= (B - \omega(G + T)) / d \\
 g &= (Z - \omega(W + U)) / d.
 \end{aligned} \tag{22}$$

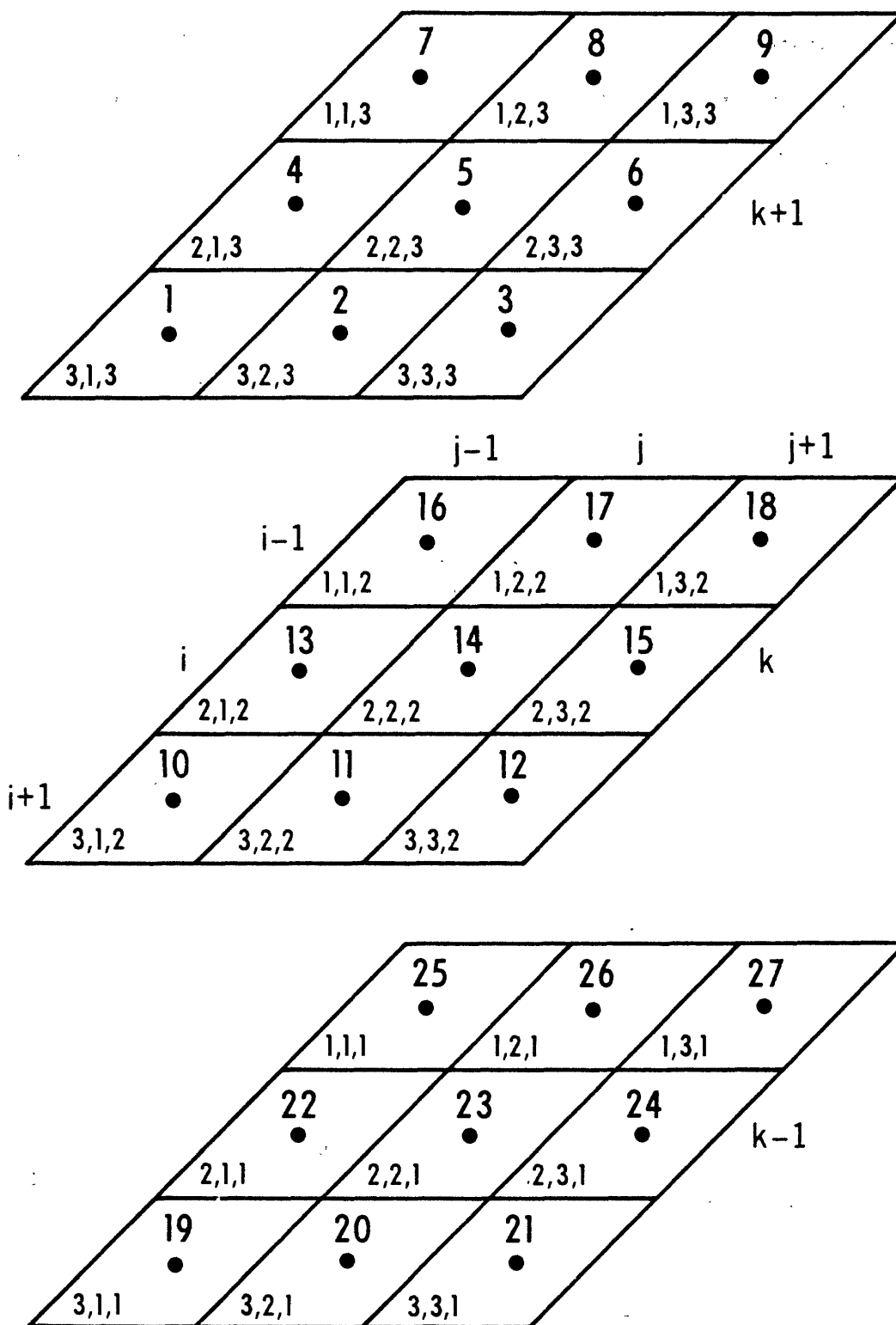


Figure 7.--Reverse ordering of nodes for a 3 X 3 X 3 problem. The numerical values of the indices (i,j,k) for this problem are given in the lower left-hand corner of each block.

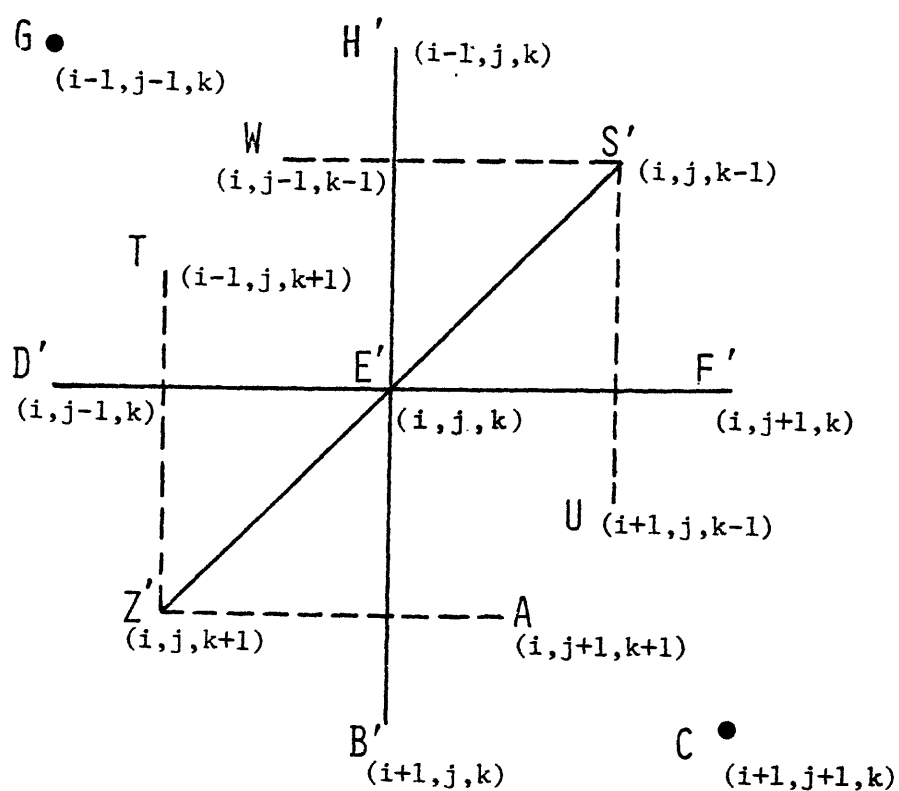
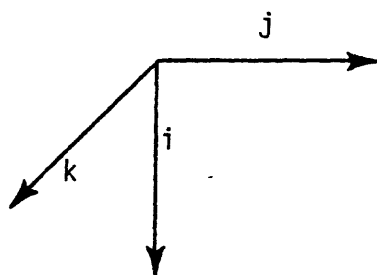


Figure 8.--Coefficients of reverse ordering scheme.

For node (i,j,k) equation 21 is

$$aV_{k+1}^n + bV_{i+1}^n + cV_{j-1}^n + dV^n = R^{n-1}$$

or

$$V^n = (R^{n-1} - aV_{k+1}^n - bV_{i+1}^n - cV_{j-1}^n) / d.$$

The vector $\bar{\xi}^n$ is computed with equation 20 which, for node (i,j,k), is

$$\xi^n + e\xi_{j+1}^n + f\xi_{i-1}^n + g\xi_{k-1}^n = V^n$$

or

$$\xi^n = V^n - e\xi_{j+1}^n - f\xi_{i-1}^n - g\xi_{k-1}^n.$$

Iteration parameters

A sequence of iteration parameters ranging from 0 to 1 is cycled until convergence is achieved. The minimum parameter is not critical and 0 is arbitrarily chosen. The maximum parameter is given by

$$1 - \omega_{\max} = (\text{Min over grid}) \left[\frac{\pi^2}{2J^2(1+\rho_1)}, \frac{\pi^2}{2I^2(1+\rho_2)}, \frac{\pi^2}{2K^2(1+\rho_3)} \right] \quad (23a)$$

in which

$$\rho_1 = \frac{K_{yy}[i,j,k](\Delta x_j)^2}{K_{xx}[i,j,k](\Delta y_i)^2} + \frac{K_{zz}[i,j,k](\Delta x_j)^2}{K_{xx}[i,j,k](\Delta z_k)^2} \quad (23b)$$

$$\rho_2 = \frac{K_{xx}[i,j,k](\Delta y_i)^2}{K_{yy}[i,j,k](\Delta x_j)^2} + \frac{K_{zz}[i,j,k](\Delta y_i)^2}{K_{yy}[i,j,k](\Delta z_k)^2} \quad (23c)$$

$$\rho_3 = \frac{K_{xx}[i,j,k](\Delta z_k)^2}{K_{zz}[i,j,k](\Delta x_j)^2} + \frac{K_{yy}[i,j,k](\Delta z_k)^2}{K_{zz}[i,j,k](\Delta y_i)^2} \quad (23d)$$

Equations 23 are the same ones used to calculate the minimum parameter for the iterative alternating-direction implicit procedure (ADI) and are based on a von Neumann error analysis of the normalized ADI equations. (See Weinstein and others, 1969, for references.) Commonly 4 to 10 parameters are used in one cycle and are arranged geometrically between minimum and maximum with the equation

$$\omega_{\ell+1} = 1 + (1 - \omega_{\max})^{\ell/L-1}, \ell = 0, 1, \dots, L-1 \quad (24)$$

in which ℓ is the iteration parameter index;

L is the number of parameters in a cycle.

In the model, equation 23b, 23c, and 23d are modified to use B,D,F,H,S and Z defined by equations 8. For example, equation 23b is computed as

$$\rho_1 = \frac{\text{Max } [B,H]}{\text{Min } [D,F]} + \frac{\text{Max } [S,Z]}{\text{Min } [D,F]}$$

The sequence of parameters computed with equations 23 and 24 gives rapid convergence for most anisotropic problems ($K_{xx} \approx K_{yy} \gg K_{zz}$). For problems with isotropic layers, however, the parameters, computed with these equations may give slower convergence. Based on an analysis of the contribution of terms in equations 23, the second terms of equations 23 were dropped and the resulting sequence of parameters generally give good convergence rates for both isotropic and anisotropic simulations. However, if the sequence of parameters computed by the equations in the program are all (except the first parameter) close to 1.0 and if this results in slow convergence or even divergence, bypass the computations in the model and insert $W_{\max} \approx 0.99863$. The resulting sequence of parameters (such as 0.0, 0.80772, 0.96303, 0.99289, 0.99863) may give a satisfactory rate of convergence.

Boundaries in the numerical scheme

Within the limits of the finite-difference grid the irregular geometry of the porous medium is simulated by assigning zero transmissivity to blocks outside the system. These blocks, however, must be included in the SIP algorithm in order to preserve the required seven-diagonal coefficient matrix \bar{A} . Constant-head boundaries are treated without using special conditional statements by skipping constant-head nodes in the algorithm.

PRACTICAL CONSIDERATIONS FOR APPLICATION

Initial Conditions

In many simulations, the important results are not the computed head, but the changes in head caused by a stress, such as pumping of wells. For this objective, if the flow equations for every layer are linear (that is, all hydraulic units are confined), the computed drawdown can be superimposed on the natural flow system. Consequently, the initial head for the simulation may be horizontal and there is no need to impose a natural flow system as the initial condition. However, if the user wishes to start a simulation using the head distribution in the natural flow system as the initial surface, a steady state simulation can be made with the model to compute the initial surface. This type of simulation is also useful to check the transmissivity and leakance distribution in the model.

If initial conditions are specified so that transient flow is occurring in the system at the start of the simulation, it should be recognized that the water levels will change during the simulation, not only in response to the pumping stress, but also due to the initial conditions. Initial conditions of this type are appropriate if the simulation is started part way through the history of development of the aquifer system.

Treatment of boundary conditions

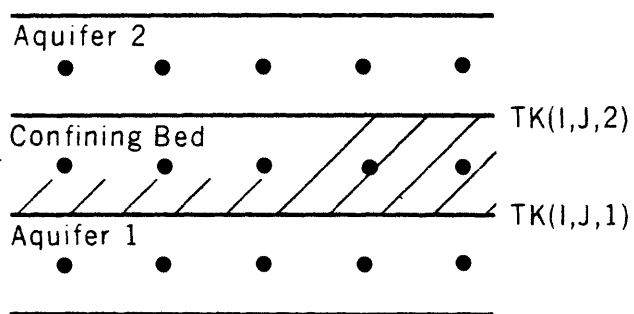
Boundaries that can be treated by the model are of two types: constant head and constant flux. Constant-head boundaries are specified by assigning a negative storage coefficient to the nodes that define the constant-head boundary. A constant flux may be zero (impermeable boundaries) or have a finite value. A zero-flux boundary is treated by assigning a zero transmissivity to nodes outside the boundary. The harmonic mean of the transmissivity at the cell boundary is zero, and consequently, the flux across

the boundary is zero. A no-flow boundary is inserted around the border of each layer of the model as a computational expediency, and constant head or finite-flux boundaries are placed inside this border. A finite-flux boundary is treated by assigning recharge wells to the appropriate nodes.

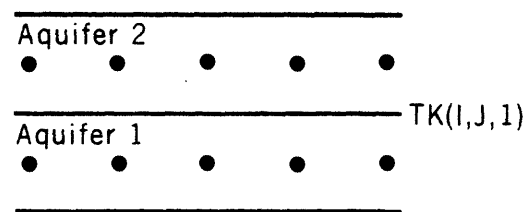
Treatment of Confining Layers

A confining bed in which storage is insignificant may be simulated in either of two ways: 1) It may be represented by one or more layers of nodes as illustrated in figure 9a with $TK(I,J,K)$ computed in the program by equation 26c (see Appendix II). This approach is necessary if horizontal components of flow in the confining bed are significant 2) If horizontal components of flow in the confining bed can be ignored, the system can be simulated in the same manner as the quasi three-dimensional model described by Bredehoeft and Pinder (1970) with a savings in computer time and storage. For this approach the confining beds are not represented by layers of nodes (figure 9b). Instead, the effects of vertical flow through the confining bed are incorporated in the vertical components of hydraulic conductivity of the adjacent aquifers. In practice, this is accomplished by reading the TK values, which are normally computed by equation 26c, with the rest of the data input. ($K'-1$ sets of TK values must be read). The TK values are equal to the ratio K_{zz}/b for each confining bed and $\Delta z = 1.0$ for all layers. This approach is designed to be used in solving equation 4. However, for certain simple problems in which the confining bed is horizontal, TK values can be read and nodes representing the confining bed eliminated when the model is used to solve equation 3 if the appropriate Δz values are retained in the data input.

If storage in the confining bed is significant, a number of layers of nodes will be required to give a good approximation to the gradients near the boundaries of the confining layer. To reduce computation time and storage



a.



b.

Figure 9.--Simulating two aquifers separated by a confining bed with three layers of nodes (a) or two layers of nodes (b).

requirements, an analytic approximation analogous to that used in the simulator for flow in two dimensions (Bredehoeft and Pinder, 1970, P.C. Trescott, G.F. Pinder and S.P. Larson, written communication, 1975) may be more suitable.

Designing the finite-difference grid

In designing a finite-difference grid, the following considerations should be kept in mind:

1. Nodes representing pumping and observation wells should be close to their relative positions to facilitate calibration. If several pumping wells are close together, their discharge may be lumped, and assigned to one node since discharge is distributed over the volume of the block.

2. Boundaries within the project area should be located accurately. Distant boundaries can be located approximately and with fewer nodes by expanding the grid. In expanding a finite-difference grid in the positive J direction, experience has shown that restricting the ratio $\Delta x_j / \Delta x_{j-1} \leq 1.5$ will avoid large truncation errors and possible convergence problems. This rule applies in all three dimensions. If the quasi three-dimensional approach is used and TK values are used with the data input, set $\Delta z = 1.0$ for all layers.

3. Place nodes closer together in areas of rapidly changing transmissivity in each layer.

4. The grid should be oriented so that a minimum of nodes are outside the porous medium. Orienting the grid with respect to latitude and longitude or some other geographic grid system is a secondary consideration. However, if the aquifer is anisotropic, orient the grid with its axes parallel to the

principal directions of the transmissivity tensor. Otherwise, the flow equation would include cross-product terms which are not considered in the SIP algorithm.

5. Number the rows in the short dimension for plotting maps on the line printer or for plotting data with an X-Y drum plotter. On these plots, the X direction is vertical and, for practical purposes, this dimension is unlimited. The Y direction is across the page which limits this dimension to the maximum width of the page.(See figure 10).

6. The core requirements and computation time are proportional to the number of nodes representing the porous medium.

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APPENDIX I

NOTATION

a, b, c, d	elements of lower triangular factor $\bar{\bar{L}}$;
$A, B, C, D, E, F, G,$ H, S, T, U, W, Z	coefficients of $(\bar{\bar{A+B}})$;
$\bar{\bar{A}}$	coefficient matrix;
b	saturated thickness of a hydraulic unit (L);
B, D, E, F, H, S, Z	coefficients in difference equation;
$\bar{\bar{B}}$	modifying matrix;
e, f, g	elements of upper triangular factor, $\bar{\bar{U}}$;
h	hydraulic head (L);
\hat{h}	hydraulic head at the previous time step (L);
i	index in the y dimension;
I	number of rows;
j	index in the x dimension;
J	number of columns;
k	index in the z dimension;
K'	number of layers;
K	hydraulic conductivity (LT^{-1});
K_{xx}, K_{yy}, K_{zz}	principal components of the hydraulic conductivity tensor (LT^{-1});
ℓ	iteration parameter index;
L	number of parameters in a cycle;
$\bar{\bar{L}}$	lower triangular factor of $(\bar{\bar{A+B}})$;
n	iteration index;
N_a	number of arrays required for the options;

q_{re}	volumetric flux per unit area of the uppermost hydraulic unit (LT^{-1});
Q	known term in difference equation;
Q_w	well discharge (L^3T^{-1});
R^{n-1}	residual for previous iteration;
S'	storage coefficient (dimensionless);
S_s	specific storage (L^{-1});
T_{xx}, T_{yy}	principal components of the transmissivity tensor (L^2T^{-1});
\bar{U}	upper triangular factor of $\overline{(A+B)}$;
\bar{V}	intermediate vector in SIP algorithm;
W	volumetric flux per unit volume (T^{-1});
Δt	time increment (T);
Δx	space increment in the x direction (L);
Δy	space increment in the y direction (L);
Δz	space increment in the z direction (L);
ϵ	closure criterion;
$\bar{\xi}$	vector of change in head for an iteration;
ρ_1, ρ_2, ρ_3	hydraulic conductivity ratios;
ω	iteration parameter.

APPENDIX II

COMPUTER PROGRAM

Main Program

The main program first assigns storage space to arrays required in the simulation. Storage space is reserved in a vector Y and is allocated to the arrays based on the dimensions of the problem specified on card 3 of the data deck. (See Appendix III). The minimum dimension of Y is approximately

$$YDIM \approx 15 IJK' + N_a IJ. \quad (25)$$

in which N_a is the sum of arrays required for options (see table 1).

Table 1.--Additional arrays required for options

Option	Number of arrays
Water-table conditions in upper unit	2
Recharge from precipitation	1

Equation 25 is approximate, but normally will give a value that is sufficient for the simulation. The exact dimension required is printed on the first page of the output as "WORDS OF VECTOR Y USED = XXXX". For new simulations, the program does not need to be recompiled as long as the dimension of Y is large enough and FORTRAN statements do not need to be modified.

After allocation of storage space to the arrays, the addresses of the first element of each array are passed to the subroutines. (See table 2 for details). In table 2 the variables giving the dimensions of the arrays are defined in Appendix V; the first array is the only double precision array.

The remainder of the main program controls the sequence of computations.

Subroutine DATAI

Instructions for the preparation of the data deck are given in Appendix III. Data may be input to the model in any consistent set of units in which second is the time unit. It is organized into four groups: Data in groups I and II

Table 2.--Arrays passed to the subroutines and their relative location in the vector Y.

Array	Sequence number in vector Y	Subroutine						Dimensions
		DATAI	STEP	SOLVEI	COEF	CHECKI	PRNTAI	
PHI	1	X	X	X	X	X	X	(IO, JO, KO)*8
STRT	2	X	X	X	X	X	X	IO, JO, KO
OLD	3	X	X	X	X	X		
T	4	X	X	X	X	X	X	
S	5	X	X	X	X	X	X	
TR	6	X	X	X	X	X		
TC	7	X	X	X	X	X		
TK	8	X	X	X	X	X		IK, JK, K5
WELL	9	X	X	X	X	X	X	IO, JO, KO
EL	10			X				
FL	11			X				
GL	12			X				
V	13			X				
XI	14			X				
DELX	15	X	X	X	X	X	X	JO
DELY	16	X	X	X	X	X	X	IO
DELZ	17	X	X	X	X	X		KO
DDN	18		X					IMAX
FACT	19	X	X	X	X	X		KO, 3
TEST3	20		X	X				ITMX1
JFLO	21					X		NCH, 3
FLOW	22					X		NCH
PERM	23	X			X			IP, JP
BOTTOM	24	X			X			
QRE	25	X			X	X		IQ, JQ

are the simulation options and scalar parameters; group III cards are used to initialize the arrays. These three groups are required for each new simulation. Group IV contains data that varies with each new pumping period. The program permits changing well discharge and the time parameters each pumping period, but the program can be modified to read other data with this set of cards.

If the simulation is a continuation of a previous run, the initial head for the continuation (not the starting head for the run) is read either from cards or from disk depending on how the results of the previous run were saved. (See the section on technical information for details of the data set on disk.) A three-dimensional simulation may require a large number of data cards. To reduce the number of cards that must be read with each run, the program includes options to place the arrays on disk and, on subsequent runs, read the data from disk rather than from cards. The data requirements for this option are included in Appendix III and definition of the direct access file on disk is explained in the section on technical information.

Time Parameters. The time parameters include the initial time step, DELT; a multiplication factor for increasing the size of the time step, CDLT; the number of time steps; NUMT; and the simulation period, TMAX. Since the rate of water-level change decreases during a pumping period, the time step is increased by the factor CDLT each step (commonly 1.5). For any time step (k) the time increment is given by

$$DELT_k = CDLT * DELT_{k-1}.$$

DELT₀ is the time step recorded on the data card.

The program has two options for selecting the time parameters:

1. To simulate a given period of time, select CDLT and an appropriate DELT₀, and set NUMT greater than the expected number of time steps. The program computes the required initial DELT₀ (which will not exceed the value of DELT₀ coded on card 1 of group IV) and NUMT to arrive exactly at TMAX on the final step.

2. To simulate a given number of time steps, set TMAX greater than the expected simulation period and the program will use ΔT_0 , CDLT and NUMT as specified on the time parameter card.

To minimize the error due to approximation of the time derivative, several time steps should be simulated before the first step at which results are displayed. This suggestion should be followed unless the system is nearly at steady state before the results are needed. In this case a one-step simulation may be satisfactory but this approach should be checked by making one run as a multi-step simulation so that the results can be compared.

For steady-state simulations, set the storage coefficient of each layer to zero. Compute for one time step of any length (for example, set TMAX = 1, NUMT = 1, CDLT = 1, $\Delta T = 24$) and the program should iterate to a solution. The maximum permitted number of iterations (ITMAX) should be larger for steady-state than for transient simulations.

Initialization. In addition to reading data and computing the time parameters this routine initializes other arrays and scalar parameters. In particular, note that the division of well discharge by the area of the block needs to be done only once for each pumping period.

Subroutine STEP

Subroutine STEP initializes variables for a new time step and controls the printing and punching of results for designated time steps. In this routine, the computed head values, cumulative time and cumulative values for the mass balance parameters are punched on cards if PUN2 is specified in the options in group I of data input or are written on a previously defined data set on disk if DK2 is specified in the options. (See the section on technical information for details about the data set on disk).

Subroutine SOLVE

This subroutine computes the SIP iteration parameters and has the SIP normal and reverse algorithms which are outlined in the section on numerical solution. The algorithm is shortened for computation on the lowermost and uppermost layers.

In this routine the usual (I,J,K) notation has been replaced in favor of single-subscript notation. Less time is involved in finding the value of a variable with a single subscript than in finding the value of one with three subscripts and as a consequence computational efficiency is improved. The subscripts used in this notation are defined in the code.

Computational efficiency is also improved by including the computation of the term $S'/\Delta t$ and the coefficients B,D,F,H,S, and Z in this routine rather than in COEF.

If the permitted number of iterations for the time step is exceeded, the message "EXCEEDED PERMITTED NUMBER OF ITERATIONS" is printed. Following the message, the mass balance, head matrix and other data specified in the options are printed. This information is useful in determining the cause of non convergence. The mass-balance parameter values and head values for the last iteration are punched if PUNC is specified in the option or written on disk if DK2 is specified. These results can be used to extend the simulation if it appears that a solution can be obtained.

Subroutine COEF

If the upper hydraulic unit is under water-table conditions, its transmissivity as a function of saturated thickness is recomputed every iteration. For those nodes where the computed head drops below the bottom elevation of the unit, a message 'NODE I, J IN LAYER K GOES DRY' is printed. A similar message is printed if a well node goes dry. The hydraulic conductivity at these nodes is set to zero and computation continues. No provision is made to permit these blocks to resaturate because the additional code for this special situation is not warranted in a general program.

The T coefficients TR, TC and TK may be computed once and saved for artesian units; for water-table units, TR and TC are recomputed every iteration and TK stays constant until block K+1 desaturates, then $TK(I,J,K) = 0.0$. They are defined as

$$TR(I,J,K) = \frac{2T_{xx[j+1]} T_{xx}}{T_{xx} \Delta x_{j+1} + T_{xx[j+1]} \Delta x} ; \quad (26a)$$

$$TC(I,J,K) = \frac{2T_{yy[i+1]} T_{yy}}{T_{yy} \Delta y_{i+1} + T_{yy[i+1]} \Delta y} ; \quad (26b)$$

$$TK(I,J,K) = \frac{2(bK_{zz})_{k+1} (bK_{zz})}{(bK_{zz}) \Delta z_{k+1} + (bK_{zz})_{k+1} \Delta z} . \quad (26c)$$

Subroutine CHECK

A mass balance is computed in this routine. The results are expressed in two ways: 1) as a cumulative volume of water from each source and each type of discharge, and 2) as rates for the current time step. Note that 'leakage' and 'evapotranspiration' appear in the mass balance but are set to zero because these options are not included in the current version of the model.

In the cumulative mass balance, storage is treated as a source of water. Flow to and from constant-head boundaries is computed with Darcy's law using the gradients from constant-head nodes to adjacent nodes inside the porous medium. Other computations in the algorithm are self-explanatory. The difference between the sum of recharge sources and sum of discharges from the system is usually less than one percent.

To the right of the cumulative mass balance are printed the flow rates for the current time step. Below the cumulative mass balance are printed the flow rates to individual constant head nodes (if included in the simulation). This is followed by the net flow rate to the top layer from below and the net flow rate to the bottom layer from above.

The last item is the listing of the absolute value of the maximum head change for each iteration. This information is useful if convergence is slow with SIP because it may indicate that a slightly larger error criterion will give a satisfactory solution with considerably fewer iterations.

Subroutine PRNTAI

This routine prints maps of drawdown and(or) hydraulic head for selected layers. Up to three characters are plotted for each block with the right-most character as close to the location of the node as the printer will allow. The user specifies XSCALE and YSCALE, the multiplication factors required to change from units used in the model to units used in the map (in general they

should be the same); DINCH, the number of map units per inch; FACT1 and FACT2, the multiplication factors for adjusting the values of drawdown and head to be plotted, respectively; MESUR, the name of the unit used on the map, and vectors LEVEL1 and LEVEL2 which contain the layers for which maps are to be printed. As an example, assume that the length unit used in the model is feet, the map is to be scaled at 3 miles per inch and drawdown values to the nearest foot and head values to the nearest 10 feet are to be plotted for layers 1 and 3. Then XSCALE = YSCALE = 5280, DINCH = 3, FACT1 = 1; FACT2 = 0.1; MESUR = MILES; LEVEL1 (1) = LEVEL2 (1) = 1; and LEVEL1(2) = LEVEL2(2) = 3.

To print a map of maximum possible size, number the rows in the short dimension to take advantage of the orientation of the map on the computer page where the X direction is vertical and the Y direction horizontal. (See figure 10). The origin is the upper left-hand corner of the block for row 2, column 2. Orienting the map with the origin in the upper left hand corner, the right and bottom sides of the map include the node locations for the second to last column and row, respectively. The border is located to the nearest inch outside these node locations and may or may not fall on the block boundaries depending on the scaling. The map is automatically centered on the page and is limited to a maximum of 12 inches (30 cm) in the Y direction. If the parameters for a map are specified such that the Y dimension is more than 12 inches (30 cm) adjustments are automatically made to fit the map within this limit. A common mistake is to specify a value for Y scale that is less than 1.0. This generates the message 'NOTE: GENERALLY SCALE SHOULD BE > OR = 1.0' and a suitable adjustment is made to DINCH. In the X direction the map is limited only by the dimension of the NX vector (for example, when the dimension of NX is 100, the map is limited in the X direction to $100 - 1 = 99$ inches [250 cm]). Several parameters (PRNT, BLANK, N1, N2, N3, and XN1) are initialized in the BLOCK DATA routine to values that assume the line printer

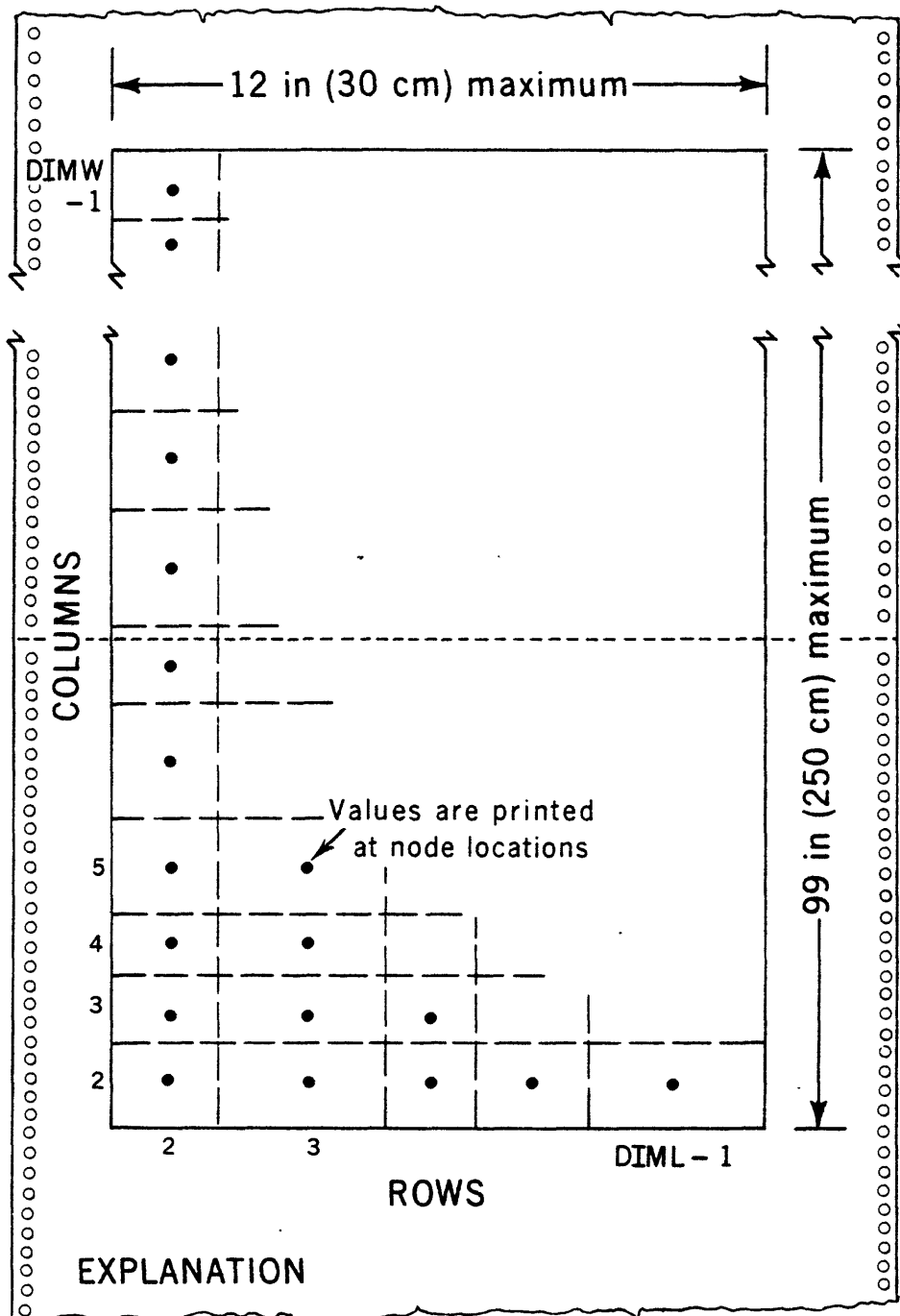


Figure 10.--Orientation of maps on computer page.

prints 6 lines per inch, 10 characters per inch, and 132 characters per line. These parameter values may need to be changed for a line printer with other specifications.

The PRNTAI subroutine can be modified to cycle a set of alphameric symbols for drawdown. If this type of map is desired, remove the C from column 1 of statements PRN1060 and PRN1230. This will cycle the symbols 1,2,3,4,5,6,7,8,9,0 for drawdown. To plot a different set of symbols will require modification of the initialization of SYM in BLOCK DATA. To cycle more than 10 symbols will require more extensive changes to the initialization of SYM and modifications to the code in ENTRY PRNTA.

BLOCK DATA

The BLOCK DATA routine initializes scalar parameters and arrays used in PRNTAI and other subroutines.

Technical Information

Use of disk facilities for storage of array data and interim results.

Options are included in the program to enable storage and retrieval of array data (STRT, S, T, etc.) and the saving of interim head values without punching them on cards. Use of these options can be particularly beneficial at remote terminals with low speed data transmission or without punch output capability. Also, the type of read statements used afford more efficient data transmission from disk than from cards.

Storage of array data is accomplished via a direct access data set that is defined by a DEFINE FILE statement in the main program (card MAN 0310) and by a DD statement in the JCL string used to execute the program. To establish the data set, the DEFINE FILE statement and the DD statement must indicate the amount of space that is required. The DEFINE FILE statement takes the following form:

DEFINE FILE 2{XX,???,U,KKK}

MAN0310

where ??? is the number of nodes per layer for the problem being solved (IO * JO) and XX is the number of records to be reserved for data set storage. The value of XX is 3 times KO, plus KO-1 if TK values are assigned, plus 2 for the water table option, plus 1 for the recharge option. Parameters U and KKK are indicators and do not vary.

The DD statement contains information, such as account number, that will be different for each user. Also, the first reference to the data set is somewhat different from subsequent references. To utilize one of the disk packs for semi-permanent storage of user data, the first reference to the data set will take the following general form if the FORTGCG procedure is used to compile and execute the program.

```
//G0.FT02FOOL DD DSN=Data Set Name,  
// UNIT=ONLINE,DISP={NEW,KEEP},  
// SPACE={????,{XX}},DCB={RECFM=F}
```

where ???? is the number of bytes per record that are to be reserved and should be set equal to IO * JO [*4].

When this initial allocation is processed the system will indicate in the HASP system log, JCL string output, the volume on which the data set was established (for example, SYS011 or SYS015). Subsequent use of the data set must indicate this information by modifying the underlined parameters in the initial reference to the data set. Thus the DD statement will read:

```
//G0.FT02FOOL DD DSN=Data Set Name,  
// UNIT=ONLINE,DISP=SHR,VOL=SER=YYYYYY
```


where the DSN parameter is the same as the initial run and YYYYYY indicates the volume (for example, SYS015) on which the data set was established by the initial run. The individual data arrays that are to be stored and later retrieved from this data set are specified on the parameter card for each array. These specifications are discussed completely in Appendix III.

Interim results. The initial head, cumulative simulation time, and mass balance parameters may be read from a data set on disk if DK1 is specified in the options. These data are the results of a previous simulation run and were written on disk because DK2 was specified in the previous run. They permit intermediate results to be examined before extending the simulation period. The same procedure also applies in simulations where the permitted number of iterations is exceeded.

The unit number for the data set is 4; an example of the JCL required to generate space for the data set on a disk is given below:

```
//STEP1 EXEC PGM=IEFBR14
//SYSUT1 DD DSN=Data Name Set, VOL=SER=Disk Name, UNIT=3330, DISP={NEW,KEEP},
// SPACE={TRK,{5,1}}, DCB={RECFM=VBS, BLKSIZE=13030}
```

Note that with the data set defined this way an extra 28K bytes of storage are required for the two buffers. If the block size is reduced, the storage required for the buffers is reduced correspondingly. If a procedure such as FORTGCG is used, insert a card analogous to

```
//G0.FT04F001 DD UNIT=3330, VOL=Disk Name, DISP=SHR, DSN=Data Set Name
before the //G0.SYSIN DD * card to define unit 4.
```

JCL to execute a compiled program which includes unit 4 follows:

// Job card

```
//A EXEC PGM= Program Name, REGION=410K, TIME=3
//STEPLIB DD DSN='Data Set Name',VOL=SER=Disk Name,UNIT=3330,DISP=SHR
//FT04FOO1 DD UNIT=3330,VOL=SER=Disk Name, DISP=SHR,DSN=Data Set Name
//FT06FOO1 DD SYSOUT=A
//FT07FOO1 DD SYSOUT=B
//FT05FOO1 DD *
```

DATA

/*

Unless the program is modified, writing on unit 4 destroys data previously written on this unit.

Storage Requirements. The amount of core that is needed can be found in table 3.

Table 3--Core requirements for compiling and executing program

Item	K bytes required
For compilation	
FORTRAN G, LEVEL 21	120
FORTRAN H, OPT=2	250
For execution	
FORTRAN G, LEVEL 21	88
FORTRAN H, OPT=2	72
BUFFERS	
Unit 4	28
Unit 2	$((IO*JO*4+Z^+)/1000)*2$
Vector Y	$X^{++}/256$

[†] Round $IO*JO*4$ up to the nearest 2000 bytes (for example, if $IO*JO*4=6400$, let $Z=1600$ and the buffer space for Unit 2 will be 16K).

⁺⁺ X is the dimension of Y in the main program.

Computation time. Computation time is a function of many variables but as an approximation, about 0.001 second of CPU time on the IBM 370/155 is required for each interior node each iteration using the FORTRAN H, OPT = 2 compiler. For example, a steady-state problem designed by Weeks and others (1974) with 2116 interior nodes requiring 25 iterations to satisfy the error criterion took 51 seconds of CPU time.

Using a source code generated with the FORTRAN G, LEVEL 21 compiler, the computation time is increased by about one half.

FORTRAN IV. The program includes several FORTRAN IV features that are not in ANS FORTRAN (for example, ENTRY, END parameter in read statement, mixed-mode expressions, G format code, literal enclosed in apostrophes). If the program is used at a computer center where the FORTRAN compiler does not include these extensions, programmers at the selected installations may be available to modify the computer code as necessary.

Program Limitations

The model documented in this report was motivated primarily by a need to find a substitute for Bredehoeft and Pinder's (1970) quasi three-dimensional model. Consequently, the model should be reasonably free of errors for this type of simulation. The model has not been tested on all types of simulations in which equation 3 is being solved. Consequently, undiscovered errors in the logic may appear as the model is applied to new problems. I would appreciate hearing about 'bugs' in the logic so that corrections can be made and other users informed.

The finite-difference model for simulation of ground-water flow in two dimensions (P.C. Trescott, G.F. Pinder and S.P. Larson, written communication, 1975) includes evapotranspiration and an approximation to transient effects

of confining beds in the source term, and permits an aquifer to change from artesian to water-table conditions. Some of these features (particularly evapotranspiration) can be added to the three-dimensional model with only moderate changes to the code.

APPENDIX III

DATA DECK INSTRUCTIONS

Group I: Title, Simulation Options and Problem Dimensions

This group of cards, which are read by the main program, contains data required to dimension the model. To specify an option on card 4 punch the characters underlined in the definition. For an option not used, that section of the card 4 can be left blank.

Note: Default typing of variables applies for all data input.

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
1	1-80	20A4	HEADING	Any title the user wishes to print on one line at the start of output.
2	1-52	I3A4	"	
4	1-10	I10	IO	Number of rows
	11-20	I10	JO	Number of columns
	21-30	I10	KO	Number of layers
	31-40	I10	ITMAX	Maximum number of iterations per time step
	41-50	I10	NCH	Number of constant head nodes
	1-4	A4	IDRAW	<u>DRAW</u> to print drawdown
	6-9	A4	IHEAD	<u>HEAD</u> to print hydraulic head
	11-14	A4	IFLOW	<u>MASS</u> to compute a mass balance
	16-18	A3	IDK1	<u>DK1</u> to read initial head, elapsed time, and mass balance parameters from unit 4 on disk
	21-23	A3	IDK2	<u>DK2</u> to write computed head, elapsed time, and mass balance parameters on unit 4 (disk)
	26-29	A4	IWATER	<u>WATE</u> if the upper hydrologic unit is unconfined
	31-34	A4	IQRE	<u>RECH</u> for a constant recharge that may be a function of space

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
4	36-39	A4	IPU1	<u>PUN1</u> to read initial head, elapsed time, and mass balance parameters from cards
	41-44	A4	IPU2	<u>PUN2</u> to punch computed head, elapsed time, and mass balance parameters on cards
	46-49	A4	ITK	<u>ITKR</u> to read the value of TK(I,J,K) for simulations in which confining layers are not represented by layers of nodes. $TK(I,J,K) = K_{zz}/b.$

Group II: Scalar parameters

The parameters required in every problem are underlined. The other parameters are required as noted; when not required, their location on the card can be left blank. The G format is used to read E, F and I format data. Minimize mistakes by always right-justifying data in the field. If F format data do not contain significant figures to the right of the decimal point, the decimal point can be omitted.

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
1	1-10	G10.0	<u>NPER</u>	Number of pumping periods for the simulation
	11-20	G10.0	<u>KTH</u>	Number of time steps between printouts
	<u>Note:</u> To print only the results for the final time step in a pumping period, make KTH greater than the expected number of time steps. The program always prints the results for the final time step.			
	21-30	G10.0	<u>ERR</u>	Error criteria for closure (L)
2	<u>Note:</u> When the head change at all nodes on subsequent iterations is less than this value (for example, 0.01 foot), the program has converged to a solution for the time step.			
	31-40	G10.0	<u>LENGTH</u>	Number of iteration parameters
	1-10	G10.0	XSCALE	Factor to convert model length unit to unit used in X direction on maps (e.g. to convert from feet to miles, XSCALE = 5280). <u>For no maps, card 2 is blank</u>
	11-20	G10.0	YSCALE	Factor to convert model length unit to unit used in Y direction on maps.
	21-30	G10.0	DINCH	Number of map units per inch
	31-40	G10.0	FACT1	Factor to adjust value of drawdown printed*
	41-49	9I1	LEVEL1(I)	Layers for which drawdown maps are to be printed. List the layers starting in column 41; the first zero entry terminates the printing of drawdown maps.

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
2	51-60	G10.0	FACT2	Factor to adjust value of head printed*
	61-69	9I1	LEVEL2(I)	Layers for which head maps are to be printed. List layers starting in column 61; the first zero entry terminates the printing of head maps.
	71-78	A8	MESUR	Name of map length unit.
3	1-20	G20.10	SUM	Parameters in which elapsed time and cumulative volumes for mass balance are stored. For the start of a simulation insert three blank cards. <u>For continuation</u> of a previous run using cards as input, replace the three blank cards with the first three cards of punched output from the previous run. Using data from disk for input, leave the three blank cards in the data deck.
	21-40	G20.10	SUMP	
	41-60	G20.10	PUMPT	
	61-80	G20.10	CFLUXT	
4	1-20	G20.10	QRET	
	21-40	G20.10	CHST	
	41-60	G20.10	CHDT	
	61-80	G20.10	FLUXT	
5	1-20	G20.10	STORT	
	21-40	G20.10	ETFLXT	
	41-60	G20.10	FLXNT	

<u>*Value of drawdown or head</u>	<u>FACT 1 or FACT 2</u>	<u>Printed value</u>
	0.01	1
	0.1	5
52.57	1.0	53
	10.0	526
	100.0	***

Group III: Array Data

Each of the following data sets (except data set 1) consists of a parameter card and, if the data set contains variable data, a set of data cards. If the data set requires data for each layer, a parameter card and data cards (for layers with variable data) are required for each layer. Each parameter card contains at least five variables:

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
Every Parameter Card	1-10	G10.0	FAC	If IVAR = 0, FAC is the value assigned to every element of the matrix for this layer.
	11-20	G10.0	IVAR	If IVAR = 1, FAC is the multiplication factor for the following set of data cards for this layer. = 0 if no data cards are to be read for this layer. = 1 if data cards for this layer follow.
	21-30	G10.0	IPRN	= 0 if input data for this layer are to be printed; = 1 if input data for the layer are <u>not</u> to be printed.
Trans- missivity Parameter Cards also have these Variables	31-40	G10.0	FACT(K,1)	multiplication factor for transmissivity in x direction
	41-50	G10.0	FACT(K,2)	multiplication factor for transmissivity in the y direction
	51-60	G10.0	FACT(K,3)	multiplication factor for hydraulic conductivity in the z direction. (Not used when confining bed nodes are eliminated and TK values are read)
Every Parameter Card	61-70	G10.0	IRECS	= 0 if the matrix is being read from cards or if each element is being set equal to FAC . = 1 if the matrix is to be read from disk (unit 2)
	71-80	G10.0	IRECD	= 0 if the matrix is <u>not</u> to be stored on disk. = 1 if the matrix being read from cards or set equal to FAC <u>is</u> to be stored on disk (unit 2) for later retrieval.

When data cards are included, start each row on a new card. To prepare a set of data cards for an array that is a function of space, the general procedure is to overlay the finite-difference grid on a contoured map of the parameter and record the average value of the parameter for each finite-difference block on coding forms according to the appropriate format. In general, record only significant digits and no decimal points (except for data set 2); use the multiplication factor to convert the data to their appropriate values. For example, if DELX ranges from 1000 to 15000 feet, coded values should range from 1-15; the multiplication factor (FAC) would be 1000.

<u>DATA SET</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
1	1-80	8F 10.4	PHI(I,J,K)	Head values for continuation of a previous run (L)
2	1-80	8F 10.4	STRT(I,J,K)	Starting head matrix (L)
3	1-80	20F 4.0	S (I,J,K)	Storage coefficient (dimensionless)

Note: This matrix is also used to locate constant head boundaries by coding a negative number at constant head nodes. At these nodes T must be greater than zero. If equation 3 is to be solved, read specific storage instead of storage coefficient.

4	1-80	20F 4.0	T(I,J,K)	Transmissivity (L^2/t)
---	------	---------	----------	----------------------------

Note 1) Zero values are required around the perimeter of the T matrix for each layer for reasons inherent in the computational scheme. This is done automatically by the program.

2) See the previous page for the additional requirements on the parameter cards for this data set.

3) If the upper active layer is unconfined and PERM and BOTTOM are to be read for this layer, insert a parameter card for this layer with only the values for FACT on it. If equation 3 is to be solved read hydraulic conductivity instead of transmissivity.

5	1-80	20F 4.0	TK(I,J,K)	K_{zz}/b
---	------	---------	-----------	------------

Note: This data set is read only if specified in the options. The number of layers of TK values = K' - 1. See the discussion of the treatment of confining layers.

6	1-80	20F 4.0	PERM(I,J)	Hydraulic conductivity (L/T) (see note 1 for data set 4)
7	1-80	20F 4.0	BOTTOM(I,J)	Elevation of bottom of water-table unit (L)

<u>DATA SET</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	DEFINITION
-----------------	----------------	---------------	-----------------	------------

Note: Data sets 6 and 7 are required only for simulating unconfined conditions in the upper hydrologic unit.

8	1-80	20F 4.0	QRE(I,J)	Recharge rate (L/T)
---	------	---------	----------	---------------------

Note: Omit if not used

9	1-80	8G10.0	DELX(J)	Grid spacing in x direction (L)
10	1-80	8G10.0	DELY(I)	Grid spacing in y direction (L)
11	1-80	8G10.0	DELZ(K)	Grid spacing in z direction (L)

Group IV: Parameters that change with the pumping period

The program has two options for the simulation period:

1. To simulate a given number of time steps, set TMAX to a value larger than the expected simulation period. The program will use NUMT, CDLT, and DELT as coded. If NUMT is greater than 50 change the dimension of ITTØ in subroutine STEP to the appropriate size.
2. To simulate a given pumping period, set NUMT larger than the number required for the simulation period (for example, 50). The program will compute the exact DELT (which will be \leq DELT coded) and NUMT to arrive exactly at TMAX on the last time step.

<u>CARD</u>	<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>
1	1-10	G10.0	<u>KP</u>	Number of the pumping period
	11-20	G10.0	<u>KPM1</u>	Number of the previous pumping period
	Note: KPM1 is currently not used			
	21-30	G10.0	<u>NWEL</u>	Number of wells for this pumping period
	31-40	G10.0	<u>TMAX</u>	Number of days in this pumping period
	41-50	G10.0	<u>NUMT</u>	Number of time steps
	51-60	G10.0	<u>CDLT</u>	Multiplying factor for DELT
	Note: 1.5 is commonly used			
	61-70	G10.0	<u>DELT</u>	Initial time step in hours

If NWEL: 0 the following set of cards is omitted

<u>DATA SET 1</u>		(NWEL cards)		
<u>COLUMNS</u>	<u>FORMAT</u>	<u>VARIABLE</u>	<u>DEFINITION</u>	
1-10	G10.0	K	Layer in which well is located	
11-20	G10.0	I	Row location of well	
21-30	G10.0	J	Column location of well	
31-40	G10.0	WELL(I,J,K)	Pumping rate (L^3/t), negative for a pumping well.	

For each additional pumping period, another set of group IV cards is required (that is, NPER sets of group IV cards are required).

APPENDIX IV

EXAMPLE SIMULATION

The following pages illustrate the data input and results of the steady-state simulation of a hypothetical problem including two aquifers separated by a confining layer (figure 11). Boundaries are no-flow except for a constant-head boundary along the left side of the upper aquifer. The aquifers are identical except that the upper aquifer is unconfined. The confining bed is not represented by a layer of nodes because only vertical flow is simulated and this is incorporated in the equations for the two aquifers. The finite-difference grid, therefore, consists of two layers of nodes with uniform grid spacing. There are two discharging wells, one in each of the two aquifers.

Table 4 lists the data input required for this simulation. The format for data are given in Appendix III. The location of numbers on the data cards should not be difficult to determine because they are either in fields of 4 or 10 spaces. In general, zero values have not been coded.

The printout of this simulation follows Table 4 and is either self-explanatory or has been discussed in Appendix II.

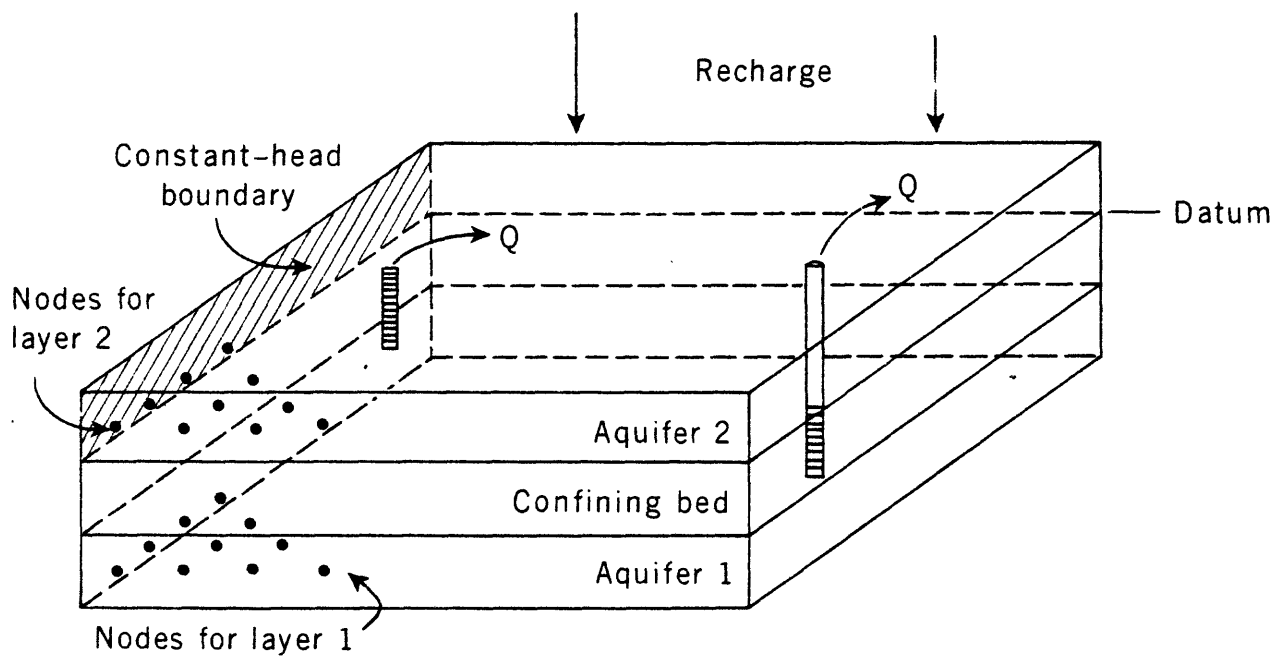


Figure 11.--Schematic illustration of example problem.

TABLE 4.--DATA INPUT FOR EXAMPLE PROBLEM.

GROUP I	IFER HAS A FREE SURFACE-----PUMPING FROM 2 AQUIFERS, UPPER AQU							
	ORAW				ITKR			
	20	MASS	20	WATE RECH	50	18	ITKR	
GROUP II	1	1000	1	.001	5	1012		1000FEET
	1000	1000	1	2				
GROUP III	100							
	100							
GROUP IV	1		1					
	-1							
GROUP V	-1							
	-1							
GROUP VI	-1							
	-1							
GROUP VII	-1							
	-1							
GROUP VIII	-1							
	-1							
GROUP IX	-1							
	-1							
GROUP X	-1							
	-1							
GROUP XI	-1							
	-1							
GROUP XII	-1							
	-1							
GROUP XIII	-1							
	-1							
GROUP XIV	-1							
	-1							
GROUP XV	-1							
	-1							
GROUP XVI	-1							
	-1							
GROUP XVII	-1							
	-1							
GROUP XVIII	-1							
	-1							
GROUP XIX	-1							
	-1							
GROUP XX	-1							
	-1							
GROUP XXI	-1							
	-1							
GROUP XXII	-1							
	-1							
GROUP XXIII	-1							
	-1							
GROUP XXIV	-1							
	-1							
GROUP XXV	-1							
	-1							
GROUP XXVI	-1							
	-1							
GROUP XXVII	-1							
	-1							
GROUP XXVIII	-1							
	-1							
GROUP XXIX	-1							
	-1							
GROUP XXX	-1							
	-1							
GROUP XXXI	-1							
	-1							
GROUP XXXII	-1							
	-1							
GROUP XXXIII	-1							
	-1							
GROUP XXXIV	-1							
	-1							
GROUP XXXV	-1							
	-1							
GROUP XXXVI	-1							
	-1							
GROUP XXXVII	-1							
	-1							
GROUP XXXVIII	-1							
	-1							
GROUP XXXIX	-1							
	-1							
GROUP XL	-1							
	-1							
GROUP XLI	-1							
	-1							
GROUP XLII	-1							
	-1							
GROUP XLIII	-1							
	-1							
GROUP XLIV	-1							
	-1							
GROUP XLV	-1							
	-1							
GROUP XLVI	-1							
	-1							
GROUP XLVII	-1							
	-1							
GROUP XLVIII	-1							
	-1							
GROUP XLIX	-1							
	-1							
GROUP L	-1							
	-1							
GROUP LI	-1							
	-1							
GROUP LII	-1							
	-1							
GROUP LIII	-1							
	-1							
GROUP LIV	-1							
	-1							
GROUP LV	-1							
	-1							
GROUP LVI	-1							
	-1							
GROUP LVII	-1							
	-1							
GROUP LVIII	-1							
	-1							
GROUP LVIX	-1							
	-1							
GROUP LX	-1							
	-1							
GROUP LXI	-1							
	-1							
GROUP LXII	-1							
	-1							
GROUP LXIII	-1							
	-1							
GROUP LXIV	-1							
	-1							
GROUP LXV	-1							
	-1							
GROUP LXVI	-1							
	-1							
GROUP LXVII	-1							
	-1							
GROUP LXVIII	-1							
	-1							
GROUP LXIX	-1							
	-1							
GROUP LXX	-1							
	-1							
GROUP LXXI	-1							
	-1							
GROUP LXXII	-1							
	-1							
GROUP LXXIII	-1							
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GROUP LXXIV	-1							
	-1							
GROUP LXXV	-1							
	-1							
GROUP LXXVI	-1							
	-1							
GROUP LXXVII	-1							
	-1							
GROUP LXXVIII	-1							
	-1							
GROUP LXXIX	-1							
	-1							
GROUP LXXX	-1							
	-1							
GROUP LXXXI	-1							
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GROUP LXXXII	-1							
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GROUP LXXXIII	-1							
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GROUP LXXXIV	-1							
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GROUP LXXXV	-1							
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GROUP LXXXVI	-1							
	-1							
GROUP LXXXVII	-1							
	-1							
GROUP LXXXVIII	-1							
	-1							
GROUP LXXXIX	-1							
	-1							
GROUP LXXXX	-1							
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GROUP LXXXXI	-1							
	-1							
GROUP LXXXXII	-1							
	-1							
GROUP LXXXXIII	-1							
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GROUP LXXXXIV	-1							
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GROUP LXXXXV	-1							
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GROUP LXXXXVI	-1							
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GROUP LXXXXVII	-1							
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GROUP LXXXXVIII	-1							
	-1							
GROUP LXXXXIX	-1							
	-1							
GROUP LXXXXX	-1							
	-1							
GROUP LXXXXXI	-1							
	-1							
GROUP LXXXXXII	-1							
	-1							
GROUP LXXXXXIII	-1							
	-1							
GROUP LXXXXXIV	-1							
	-1							
GROUP LXXXXXV	-1							
	-1							
GROUP LXXXXXVI	-1							
	-1							
GROUP LXXXXXVII	-1							
	-1							
GROUP LXXXXXVIII	-1							
	-1							
GROUP LXXXXXIX	-1							
	-1							
GROUP LXXXXXX	-1							
	-1							
GROUP LXXXXXXI	-1							
	-1							
GROUP LXXXXXXII	-1							
	-1							
GROUP LXXXXXXIII	-1							
	-1							
GROUP LXXXXXXIV	-1							
	-1							
GROUP LXXXXXXV	-1							
	-1							
GROUP LXXXXXXVI	-1							
	-1							
GROUP LXXXXXXVII	-1							
	-1							
GROUP LXXXXXXVIII	-1							
	-1							
GROUP LXXXXXXIX	-1							
	-1							
GROUP LXXXXXXX	-1							
	-1							
GROUP LXXXXXXXI	-1							
	-1							
GROUP LXXXXXXXII	-1							
	-1							
GROUP LXXXXXXXIII	-1							
	-1							
GROUP LXXXXXXXIV	-1							
	-1							
GROUP LXXXXXXXV	-1							
	-1							
GROUP LXXXXXXXVI	-1							
	-1							
GROUP LXXXXXXXVII	-1							
	-1							
GROUP LXXXXXXXVIII	-1							
	-1							
GROUP LXXXXXXXIX	-1							
	-1							
GROUP LXXXXXXXX	-1							
	-1							
GROUP LXXXXXXXXI	-1							
	-1							
GROUP LXXXXXXXXII	-1							
	-1							
GROUP LXXXXXXXXIII	-1							
	-1							
GROUP LXXXXXXXXIV	-1							
	-1							
GROUP LXXXXXXXXV	-1							
	-1							

-----PUMPING FROM 2 AQUIFERS. UPPER AQUIFER HAS A FREE SURFACE-----

NUMBER OF ROWS = 20
 NUMBER OF COLUMNS = 20
 NUMBER OF LAYERS = 2

 MAXIMUM PERMITTED NUMBER OF ITERATIONS = 50
 NUMBER OF CONSTANT HEAD NODES = 18

SIMULATION OPTIONS:	DRAW	MASS	WATE	RECH	ITKR
				WORDS OF VECTOR Y USED = 12992	
				NUMBER OF PUMPING PERIODS = 1	
				TIME STEPS BETWEEN PRINTOUTS = 1	
				ERROR CRITERIA FOR CLOSURE = 0.9999999E-03	

ON ALPHAMERIC MAP1

MULTIPLICATION FACTOR FOR X DIMENSION = 1000.000
 MULTIPLICATION FACTOR FOR Y DIMENSION = 1000.000
 MAP SCALE IN UNITS OF 1000FEET
 NUMBER OF 1000FEET PER INCH = 2.000000
 MULTIPLICATION FACTOR FOR DRAWDOWN = 10.00000
 MULTIPLICATION FACTOR FOR HEAD = 0.0

PRINTED FOR LAYERS 1 2 0 0 0 0 0 0
 PRINTED FOR LAYERS 0 0 0 0 0 0 0 0

 FOR LAYER 1
 FOR LAYER 2
 FOR LAYER 1

0.0 0.0 0.0 0.0 0.0 0.0

TRANSMISSIVITY = 0.9999996E-01 FOR LAYER 1

DIRECTIONAL TRANSMISSIVITY MULTIPLICATION FACTORS FOR LAYER 1

X = 1.000000

Y = 1.000000

Z = 0.0

TRANSMISSIVITY = 0.9999996E-01 FOR LAYER 2

DIRECTIONAL TRANSMISSIVITY MULTIPLICATION FACTORS FOR LAYER 2

X = 1.000000

Y = 1.000000

Z = 0.0

TK = 0.9999997E-08 FOR LAYER 1

HYDRAULIC CONDUCTIVITY = 0.9999999E-03 FOR LAYER 2

BOTTOM ELEVATION = 0.0 FOR LAYER 2

RECHARGE RATE = 0.9999999E-09 FOR LAYER 2

DELX = 1000.000

DELY = 1000.000

DELZ = 1.000000

SOLUTION BY THE STRONGLY IMPLICIT PROCEDURE

5 ITERATION PARAMETERS: 0.0 0.70459100 0.0 0.91273350 0.0 0.97422070 0.0 0.99238460 0.0

PUMPING PERIOD NO. 11 1.00 DAYS

NUMBER OF TIME STEPS = 1

DELT IN HOURS = 24.000

MULTIPLIER FOR DELT = 1.000

2 WELLS

K	I	J	PUMPING RATE
1	10	5	-1.00
2	10	15	-1.00

 I TIME STEP NUMBER = 1 I

SIZE OF TIME STEP IN SECONDS= 86400.00
 TOTAL SIMULATION TIME IN SECONDS= 86400.00
 MINUTES= 1440.00
 HOURS= 24.00
 DAYS= 1.00
 YEARS= 0.00

DURATION OF CURRENT PUMPING PERIOD IN DAYS= 1.00
 YEARS= 0.00

CUMULATIVE MASS BALANCE:

SOURCES:

 STORAGE = 0.0
 RECHARGE = 26438.11
 CONSTANT FLUX = 0.0
 CONSTANT HEAD = 145961.88
 LEAKAGE = 0.0
 TOTAL SOURCES = 172399.94
 DISCHARGES:

 EVAPOTRANSPIRATION = 0.0
 CONSTANT HEAD = 0.0
 QUANTITY PUMPED = 172799.81
 LEAKAGE = 0.0
 TOTAL DISCHARGE = 172799.81
 DISCHARGE-SOURCES = 399.88
 PER CENT DIFFERENCE = 0.23

RATES FOR THIS TIME STEP:

 STORAGE = 0.0
 RECHARGE = 0.3060
 CONSTANT FLUX = 0.0
 PUMPING = -2.0000
 EVAPOTRANSPIRATION = 0.0
 CONSTANT HEAD = 1.6894
 IN = 0.0
 OUT = 0.0
 LEAKAGE = 0.0
 FROM PREVIOUS PUMPING PERIOD = 0.0
 TOTAL = 0.0
 SUM OF RATES = -0.0046

L**3/T

IV-7

FLOW RATES TO CONSTANT HEAD NODES:

K	I	J	RATE (L**3/T)	K	I	J	RATE (L**3/T)	K	I	J	RATE (L**3/T)
2	2	2	0.8160883E-01	2	3	2	0.8287251E-01	2	4	2	0.8543676E-01
2	5	2	0.8936179E-01	2	6	2	0.9468210E-01	2	7	2	0.1012863
2	8	2	0.10866478	2	9	2	0.1153280	2	10	2	0.1184522
2	11	2	0.1147698	2	12	2	0.1075212	2	13	2	0.9957021E-01
2	14	2	0.9234345E-01	2	15	2	0.8635312E-01	2	16	2	0.8169365E-01
2	17	2	0.7830906E-01	2	18	2	0.7611233E-01	2	19	2	0.7503170E-01

FLOW TO TOP LAYER = -0.9975219 FLOW TO BOTTOM LAYER = -0.9975219 POSITIVE UPWARD
 MAXIMUM HEAD CHANGE FOR EACH ITERATION:

3.4372	0.7898	0.5177	0.6253	1.3647	0.0958	0.2184	0.3409	0.7132
0.0415	0.0415	0.0936	0.1805	0.4106	0.0268	0.0605	0.1020	0.2055
0.0122	0.0122	0.0275	0.0532	0.1209	0.0079	0.0178	0.0301	0.0605
0.0036	0.0036	0.0081	0.0157	0.0356	0.0023	0.0052	0.0088	0.0178
0.0011	0.0011	0.0024	0.0046	0.0104	0.0007			

TIME STEP : 1

ITERATIONS: 45

PLOT OF DRAWDOWN LAYER 1

45	45	46	47	47	48	49	50	49	48	47	46	45	44	43	43	18.00
45	45	46	46	47	48	49	50	50	49	47	46	45	44	43	43	16.00
44	45	45	46	47	48	49	50	50	48	47	46	45	44	43	42	14.00
44	44	45	45	46	47	49	50	50	48	47	45	44	43	42	41	12.00
43	43	44	44	45	47	48	49	50	49	47	46	44	43	42	41	10.00
41	42	42	43	44	45	46	48	48	47	46	44	43	42	41	40	8.00
40	40	41	41	42	43	44	45	46	45	44	43	41	40	39	38	6.00
38	38	39	40	41	42	43	43	43	43	42	41	40	38	38	37	4.00
36	37	37	38	39	39	40	41	41	40	40	39	38	37	36	35	2.00
34	34	35	36	37	37	38	39	39	38	37	36	35	34	33	32	0.00
32	32	33	34	35	36	37	38	38	37	36	35	34	33	31	30	1000FEET
30	30	30	31	33	34	36	37	38	37	35	34	32	30	29	28	8.00
27	27	28	29	31	33	35	38	40	38	35	32	30	28	27	26	6.00
25	25	26	27	29	31	35	41	47	41	35	31	28	26	25	24	4.00
22	22	23	24	26	30	35	45	68	44	34	29	26	24	22	21	2.00
20	20	21	22	24	27	31	36	42	36	30	26	23	21	20	19	0.00
18	18	19	20	21	24	27	30	32	29	26	23	21	19	18	17	1000FEET
16	17	17	18	20	22	24	26	27	26	24	21	19	18	17	16	8.00
0.0	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00	24.00	26.00	28.00	30.00	1000FEET

DISTANCE FROM ORIGIN IN Y DIRECTION, IN 1000FEET

EXPLANATION

R = CONSTANT HEAD BOUNDARY
** = VALUE EXCEEDED 3 FIGURES
MULTIPLICATION FACTOR = 10.000

PLOT OF DRAWDOWN LAYER 2

45	46	47	48	50	51	53	53	52	51	46	47	46	45	44	41	41	18.00
45	45	46	47	48	50	52	54	53	52	49	47	46	44	43	43	42	16.00
44	45	46	47	48	51	53	56	58	56	53	50	47	45	44	43	42	14.00
44	44	45	46	48	51	55	61	67	61	55	50	47	45	43	42	41	12.00
43	43	44	45	47	50	56	66	92	66	55	50	46	44	42	41	40	10.00
41	42	42	44	46	48	52	58	65	54	52	48	45	42	41	40	39	8.00
40	40	41	42	43	45	48	51	53	51	48	45	42	41	39	38	37	6.00
38	38	39	40	41	42	44	46	46	45	44	42	40	38	37	36	35	4.00
36	36	36	37	38	39	40	41	42	41	40	39	37	36	35	34	33	2.00
33	33	34	35	35	36	37	38	38	38	37	36	35	34	33	32	31	0.0
31	31	31	32	33	34	34	35	35	35	34	33	32	31	30	29	29	18.00
28	28	28	29	30	31	31	32	32	32	31	30	29	28	27	27	26	16.00
24	25	25	26	27	28	29	29	30	29	28	27	26	25	24	23	23	14.00
21	21	21	22	23	24	25	26	27	26	25	24	22	21	21	20	19	12.00
17	17	17	18	19	20	21	22	23	22	21	19	18	17	17	16	16	10.00
12	12	13	13	14	14	15	16	17	16	15	14	13	13	12	12	11	8.00
7	7	7	7	8	8	9	9	9	9	8	8	7	7	7	6	6	6.00
R	R	R	R	R	R	R	R	R	R	R	R	R	R	R	R	R	4.00
0.0	2.00	4.00	6.00	8.00	10.00	12.00	14.00	16.00	18.00	20.00	22.00	24.00	26.00	28.00	30.00	32.00	34.00

DISTANCE FROM ORIGIN IN Y DIRECTION, IN 1000FEET

EXPLANATION

R = CONSTANT HEAD BOUNDARY
*** = VALUE EXCEEDED 3 FIGURES
MULTIPLICATION FACTOR = 10.000

[illegible]

DRAWDOWN, LAYER 2 -----

1	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0
2	0.0 4.52	0.0 0.0	0.66 0.66	1.20 1.22	1.67 1.69	2.08 2.11	2.44 2.47	2.77 2.79	3.06 3.08	3.32 3.34	3.56 3.59	3.78 3.81	3.97 4.00	4.13 4.17	4.27 4.31	4.37 4.41	4.45 4.48	4.49 4.53
3	0.0 4.55	0.0 0.0	0.66 0.68	1.22 1.25	1.69 1.73	2.11 2.15	2.47 2.51	2.79 2.83	3.08 3.13	3.34 3.39	3.59 3.64	3.81 3.87	4.00 4.07	4.17 4.25	4.31 4.39	4.41 4.49	4.48 4.56	4.53 4.60
4	0.0 4.62	0.0 0.0	0.68 0.71	1.25 1.30	1.73 1.80	2.15 2.21	2.51 2.58	2.83 2.90	3.13 3.19	3.39 3.46	3.64 3.72	3.87 3.96	4.07 4.18	4.25 4.38	4.39 4.52	4.49 4.62	4.56 4.68	4.60 4.71
5	0.0 4.72	0.0 0.0	0.71 0.75	1.30 1.37	1.80 1.88	2.21 2.30	2.58 2.66	2.90 2.98	3.19 3.27	3.46 3.55	3.72 3.82	3.96 4.09	4.18 4.34	4.38 4.56	4.52 4.73	4.62 4.82	4.68 4.85	4.71 4.85
6	0.0 4.85	0.0 0.0	0.75 0.80	1.37 1.45	1.88 1.98	2.30 2.40	2.66 2.75	2.98 3.06	3.27 3.35	3.55 3.64	3.82 3.93	4.09 4.24	4.34 4.55	4.56 4.84	4.73 5.05	4.82 5.10	4.85 5.07	4.85 5.02
7	0.0 4.99	0.0 0.0	0.80 0.85	1.45 1.54	1.98 2.09	2.40 2.51	2.75 2.85	3.06 3.15	3.35 3.43	3.64 3.73	3.93 4.05	4.24 4.40	4.55 4.81	4.84 5.24	5.05 5.58	5.10 5.51	5.07 5.34	5.02 5.21
8	0.0 5.14	0.0 0.0	0.85 0.90	1.54 1.63	2.09 2.22	2.51 2.62	2.85 2.93	3.15 3.21	3.43 3.49	3.73 3.79	4.05 4.13	4.40 4.56	4.81 5.10	5.24 5.82	5.58 6.61	5.51 6.09	5.34 5.64	5.21 5.37
9	0.0 5.25	0.0 0.0	0.90 0.92	1.63 1.68	2.22 2.31	2.62 2.67	2.93 2.96	3.21 3.22	3.49 3.50	3.79 3.80	4.13 4.16	4.56 4.62	5.10 5.29	5.82 6.47	6.61 9.20	6.09 6.74	5.64 5.83	5.37 5.45
10	0.0 5.29	0.0 0.0	0.92 0.89	1.68 1.62	2.31 2.20	2.67 2.60	2.96 2.91	3.22 3.19	3.50 3.47	3.80 3.77	4.16 4.11	4.62 4.53	5.29 5.08	6.47 6.59	9.20 5.52	6.74 5.45	5.83 5.29	5.45 5.15
11	0.0 5.23	0.0 0.0	0.89 0.84	1.62 1.52	2.20 2.07	2.60 2.49	2.91 2.82	3.19 3.11	3.47 3.39	3.77 3.68	4.11 4.00	4.53 4.36	5.08 4.76	6.59 5.19	6.59 5.52	6.06 5.45	5.61 5.29	5.35 5.15
12	0.0 5.09	0.0 0.0	0.84 0.78	1.52 1.42	2.07 1.94	2.49 2.36	2.82 2.71	3.11 3.01	3.39 3.29	3.68 3.58	4.00 3.86	4.36 4.17	4.76 4.47	5.19 4.76	5.52 4.97	5.45 5.02	5.29 4.99	5.15 4.94
13	0.0 4.91	0.0 0.0	0.78 0.73	1.42 1.33	1.94 1.83	2.36 2.24	2.71 2.59	3.01 2.90	3.29 3.19	3.58 3.46	3.86 3.73	4.17 3.99	4.47 4.24	4.76 4.46	4.97 4.63	5.02 4.71	4.99 4.74	4.94 4.74
14	0.0 4.74	0.0 0.0	0.73 0.69	1.33 1.26	1.83 1.74	2.24 2.14	2.59 2.49	2.90 2.80	3.19 3.09	3.46 3.35	3.73 3.60	3.99 3.84	4.24 4.06	4.46 4.25	4.63 4.39	4.71 4.49	4.74 4.54	4.74 4.57
15	0.0 4.58	0.0 0.0	0.69 0.65	1.26 1.20	1.74 1.66	2.14 2.06	2.49 2.41	2.80 2.72	3.09 3.00	3.35 3.26	3.60 3.50	3.84 3.72	4.06 3.92	4.25 4.09	4.39 4.23	4.49 4.33	4.54 4.40	4.57 4.44
16	0.0 4.45	0.0 0.0	0.65 0.63	1.20 1.16	1.66 1.61	2.06 2.00	2.41 2.34	2.72 2.65	3.00 2.93	3.26 3.19	3.50 3.42	3.72 3.63	3.92 3.82	4.09 3.98	4.23 4.12	4.33 4.22	4.40 4.29	4.44 4.33
17	0.0 4.36	0.0 0.0	0.63 0.61	1.16 1.13	1.61 1.57	2.00 1.96	2.34 2.30	2.65 2.61	2.93 2.89	3.19 3.14	3.42 3.37	3.63 3.58	3.82 3.76	3.98 3.92	4.12 4.05	4.22 4.15	4.29 4.22	4.33 4.27
18	0.0 4.29	0.0 0.0	0.61 0.60	1.13 1.11	1.57 1.55	1.96 1.94	2.30 2.28	2.61 2.59	2.89 2.86	3.14 3.12	3.37 3.34	3.58 3.55	3.76 3.73	3.92 3.88	4.05 4.01	4.15 4.11	4.22 4.19	4.27 4.24
19	0.0 4.26	0.0 0.0	0.60 0.60	1.11 0.0	1.55 0.0	1.94 0.0	2.28 0.0	2.59 0.0	2.86 0.0	3.12 0.0	3.34 0.0	3.55 0.0	3.73 0.0	3.88 0.0	4.01 0.0	4.11 0.0	4.19 0.0	4.24 0.0
20	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0

APPENDIX V

DEFINITION OF PROGRAM VARIABLES

A	DUMMY ARRAY NAME USED TO INPUT MATRIX DATA;
B	$TC(I-1,J,K)/DELY(I)$;
BOTTOM	ELEVATION OF THE BOTTOM OF THE UPPER UNIT;
COLT	MULTIPLYING FACTOR FOR THE TIME STEP;
D	$TR(I,J-1,K)/DELX(J)$;
DDN	VECTOR THAT CONTAINS DRAWDOWN VALUES (L);
DELT	TIME INCREMENT (T);
DELX	GRID SPACING IN THE X DIRECTION (L);
DELY	GRID SPACING IN THE Y DIRECTION (L);
DELZ	GRID SPACING IN THE Z DIRECTION (L);
DLM	DUMMY ARRAY USED TO COMPLETE THE ARGUMENT LIST FOR ENTRY ARRAY WHEN THE LAST 3 ELEMENTS ARE NOT REQUIRED;
FL	ELEMENT OF UPPER TRIANGULAR FACTOR U;
ERR	CLOSURE CRITERIA (L);
F	$TR(I,J,K)/DELX(J)$;
FAC	SEE EXPLANATION IN GROUP III; ARRAY DATA;
FL	ELEMENT OF UPPER TRIANGULAR FACTOR U;
FLOW	FLOW RATE TO A CONSTANT-HEAD NODE (L^3/T);
GL	ELEMENT OF UPPER TRIANGULAR FACTOR U;
H	$TC(I,J,K)/DELY(I)$;
HEADNG	TITLE FOR SIMULATION;
IO	NUMBER OF ROWS;
ICLK	VECTOR CONTAINING PROBLEM OPTIONS;
ICK1	OPTION TO READ HEAD DATA FROM DISK;
ICK2	OPTION TO WRITE RESULTS ON DISK;
IDRAW	OPTION TO PRINT DRAWDOWN;
IERR	= 2; PROGRAM HAS EXCEEDED PERMITTED ITERATIONS;
IFINAL	= 0 ALL TIME STEPS EXCEPT THE LAST; = 1 LAST TIME STEP IN PUMPING PERIOD;
IFLO	OPTION TO COMPUTE A VOLUMETRIC BALANCE;
IHEAD	OPTION TO PRINT HEAD MATRIX;
IK,JK,K5	DIMENSIONS OF TK ARRAY;
IMAX	MAXIMUM OF IO,JO;
IN	DUMMY ARRAY USED TO PRINT MATRIX NAMES IN DATA;
INFT	AN ARRAY OF FORMATS USED TO READ MATRIX DATA;
IOFT	AN ARRAY OF FORMATS USED TO PRINT MATRIX DATA;
IP,JP	DIMENSIONS OF PERM AND BOTTOM ARRAYS;
IPRN	SEE EXPLANATION IN GROUP III; ARRAY DATA;
IPU1	OPTION TO READ HEAD AND MASS BALANCE VALUES FROM CARDS;
IPU2	OPTION TO PUNCH RESULTS ON CARDS;
IQ,JQ	DIMENSIONS OF QRE ARRAY;
IGRE	OPTION FOR RECHARGE;
ISUM	THE CUMULATIVE WORDS OF STORAGE USED IN THE VECTOR Y;
IRECD	SEE EXPLANATION IN GROUP III; ARRAY DATA;
IRECS	SEE EXPLANATION IN GROUP III; ARRAY DATA;
IRN	COUNTER TO INDICATE THE CURRENT RECORD NUMBER IN THE DIRECT ACCESS DATA SET;
IT	ITERATION COUNTER;
ITMAX	MAXIMUM NUMBER OF ITERATIONS PER TIME STEP;
ITMX1	ITMAX+1;
ITTO	VECTOR CONTAINING TOTAL NUMBER OF ITERATIONS PER TIME STEP;

IVAR	SEE EXPLANATION IN GROUP III: ARRAY DATA;
IWATER	OPTION FOR WATER-TABLE CONDITIONS IN UPPER LAYER;
J0	NUMBER OF COLUMNS;
JFLO	ARRAY CONTAINING LOCATION OF CONSTANT-HEAD NODES;
K0	NUMBER OF LAYERS;
KP	NUMBER OF THE PUMPING PERIOD;
KPM1	NOT CURRENTLY USED;
KT	TIME STEP COUNTER;
KTH	NUMBER OF TIME STEPS BETWEEN PRINTOUTS;
L	VECTOR CONTAINING INITIAL ADDRESS OF ARRAYS;
LENGTH	NUMBER OF ITERATION PARAMETERS;
LEVEL1	VECTOR CONTAINING LAYERS FOR WHICH DRAWDOWN MAPS ARE TO BE PRINTED;
LEVEL2	VECTOR CONTAINING LAYERS FOR WHICH HEAD MAPS ARE TO BE PRINTED;
NAME	AN ARRAY OF MATRIX NAMES;
NCH	NUMBER OF CONSTANT-HEAD NODES;
NPER	NUMBER OF PUMPING PERIODS;
NLMT	NUMBER OF TIME STEPS;
NWEL	NUMBER OF WELLS FOR A PUMPING PERIOD;
OLD	HEAD AT THE END OF THE PREVIOUS TIME STEP;
PERM	HYDRAULIC CONDUCTIVITY OF THE UPPER UNIT;
PHI	HYDRAULIC HEAD (L);
QR	RECHARGE RATE (L/T);
QRE	RECHARGE RATE (L/T);
RHO	S/DELTA (1/T);
RHOP	VECTOR CONTAINING ITERATION PARAMETERS;
S	STORAGE COEFFICIENT;
STRT	HYDRAULIC HEAD AT THE START OF THE SIMULATION;
SU	$TK(I,J,K)/DELZ(K)$;
SUM	TOTAL ELAPSED TIME IN THE SIMULATION (T);
SUMP	TOTAL ELAPSED TIME IN THE PUMPING PERIOD (T);
T	TRANSMISSIVITY (L^2/T);
TC	HARMONIC AVERAGE OF $T/DELY \otimes I+1/2,J,K$ (L/T);
TEST	= 0 CLOSURE CRITERIA SATISFIED; = 1 CLOSURE CRITERIA NOT SATISFIED;
TEST3	MAXIMUM CHANGE IN HEAD FOR THE TIME STEP;
TF	AN ARRAY USED TO READ AND TRANSFER DIRECTIONAL TRANSMISSIVITY FACTORS;
TK	HARMONIC AVERAGE OF $BK/DELZ \otimes I,J,K+1/2$ (L/T);
TMAX	NUMBER OF DAYS IN THE PUMPING PERIOD (T);
TR	HARMONIC AVERAGE OF $T/DELX \otimes I,J+1/2,K$ (L/T);
V	INTERMEDIATE VECTOR;
WELL	WELL DISCHARGE (L^3/T);
XI	ARRAY CONTAINING INCREMENTAL HEAD VALUES IN SIP SOLUTION (L);
Y	VECTOR CONTAINING ARRAY STORAGE;
Z	$TK(I,J,K-1)/DELZ(K)$.

DEFINITION OF VARIABLES IN CHECKI SUBROUTINE

CFLUX	INFLOW FROM RECHARGE WELLS (L^3/T);
CFLXT	CUMULATIVE VOLUME OF WATER FROM RECHARGE WELLS (L^3);
CHD1	RATE OF OUTFLOW TO CONSTANT HEAD BOUNDARY (L^3/T);
CHD2	RATE OF INFLOW FROM CONSTANT HEAD BOUNDARY (L^3/T);
CHDT	CUMULATIVE DISCHARGE TO CONSTANT HEAD BOUNDARY (L^3);

CHST	CUMULATIVE VOLUME OF WATER INFLOW FROM CONSTANT HEAD BOUNDARY (L**3);
DIFF	ERROR IN MASS BALANCE (L**3);
ETFLUX	EVAPOTRANSPIRATION RATE (L**3/T);
ETFLXT	CUMULATIVE DISCHARGE BY ET (L**3);
FLUX	RATE OF LEAKAGE DUE TO GRADIENTS AT THE START OF THE PUMPING PERIOD (L**3/T);
FLUXS	NET LEAKAGE RATE (L**3/T);
FLXN	RATE OF DISCHARGE BY LEAKAGE (L**3/T);
FLXNT	CUMULATIVE VOLUME OF WATER DISCHARGED BY LEAKAGE (L**3);
FLXPT	CUMULATIVE VOLUME OF WATER INFLOW FROM LEAKAGE (L**3);
PERCNT	PERCENT ERROR IN CUMULATIVE MASS BALANCE;
PUMP	DISCHARGE FROM WELLS (L**3/T);
PUMPT	CUMULATIVE VOLUME OF WATER DISCHARGED BY PUMPING WELLS (L**3);
QREFLX	RECHARGE RATE (L**3/T);
QRET	CUMULATIVE VOLUME OF WATER DERIVED FROM RECHARGE (L**3);
STOR	RATE OF CHANGE IN STORAGE FOR THE TIME STEP (L**3/T);
STORT	CUMULATIVE VOLUME OF WATER DERIVED FROM STORAGE (L**3);
SLMR	SUM OF RECHARGE AND DISCHARGE RATES FOR THE TIME STEP (L**3/T);
TCTL1	CUMULATIVE VOLUME OF WATER FROM ALL SOURCES (L**3);
TCTL2	CUMULATIVE VOLUME OF WATER DISCHARGED FROM THE SYSTEM (L**3);
X	NET FLOW TO BOTTOM LAYER (L**3/T);
Y	NET FLOW TO TOP LAYER (L**3/T);

DEFINITION OF VARIABLES IN THE PRINTAI SUBROUTINE

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BLANK      CONTAINS BLANK SYMBOLS;
DINCH     NUMBER OF MAP UNITS PER INCH;
DIST      LOCATION OF NEXT COLUMN OF NODAL VALUES TO BE PRINTED;
FACT1     FACTOR FOR ADJUSTING VALUE OF DRAWDOWN PRINTED;
FACT2     FACTOR FOR ADJUSTING VALUE OF HEAD PRINTED;
K         ADJUSTED VALUE OF DRAWDOWN OR HEAD;
LA        LAYER FOR WHICH A MAP IS BEING PRINTED;
MESUR     NAME OF MAP LENGTH UNIT;
N         INDEX FOR SYMBOLS;
NA        INDICES FOR LOCATING X LABEL;
NC        NUMBER OF BLANKS BEFORE GRAPH;
NG        = 1, FOR DRAWDOWN MAP;
          = 2, FOR HEAD MAP;
N1        NUMBER OF LINES PER INCH;
N2        NUMBER OF CHARACTERS PER INCH;
N3        NUMBER OF CHARACTERS PER LINE;
N4        NUMBER OF LINES IN THE PLOT;
N8        MAXIMUM NUMBER OF CHARACTERS IN Y DIRECTION;
NXD       NUMBER OF INCHES IN THE X DIMENSION OF PLOT;
NYD       NUMBER OF INCHES IN THE Y DIMENSION OF PLOT;
PRNT      CONTAINS THE ARRANGEMENT OF SYMBOLS FOR EACH LINE;
SPACNG    CONTOUR INTERVAL (L);
SYM       VECTOR CONTAINING SYMBOLS USED IN THE PLOT;
TITLE     TITLE FOR PLOT;
VF1,VF2,VF3 VARIABLE FORMATS FOR CENTERING PLOT;
WIDTH     WIDTH OF MODEL (L);
XLABEL    LABEL FOR X AXIS;
XN        NUMBERS FOR X AXIS;

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XX1	1 INCH/(N1*2);
XSCALE	MULTIPLICATION FACTOR TO CONVERT MODEL LENGTH UNIT TO UNIT USED IN X DIRECTION ON MAPS;
XSF	X SCALE FACTOR;
YDIM	LENGTH OF AQUIFER IN Y DIRECTION (L).
YLABEL	LABEL FOR Y AXIS;
YLEN	LOCATION OF NEXT VALUE IN THE COLUMN TO BE PRINTED;
YN	NUMBERS FOR Y AXIS;
YSCALE	MULTIPLICATION FACTOR TO CONVERT MODEL LENGTH UNIT TO UNIT USED IN Y DIRECTION ON MAPS;
YSF	Y SCALE FACTOR;
Z	LOCATION OF NEXT LINE TO BE PRINTED.

APPENDIX VI
Program Listing

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C -----MAN0010
C FINITE-DIFFERENCE MODEL FOR SIMULATION OF GROUND-WATER FLOW IN MAN0020
C THREE DIMENSIONS, SEPTEMBER, 1975 BY P.C. TRESCOTT, U. S. G. S. MAN0030
C WITH CONTRIBUTIONS TO MAIN, DATAI AND SOLVE BY S.P. LARSON MAN0040
C -----MAN0050
C SPECIFICATIONS: MAN0060
C REAL *8YSTR MAN0070
C MAN0080
C MAN0090
C DIMENSION Y(102000), L(25), HEADNG(33), NAME(42), INFT(2,2), IOFT(MAN0100
19,4), DUM(3) MAN0110
C MAN0120
C EQUIVALENCE (YSTR,Y(1)) MAN0130
C MAN0140
C COMMON /INTEGR/ IO,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NMAN0150
1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCMAN0160
2H,IDK1,IDK2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK MAN0170
COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR MAN0180
COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9) MAN0190
C MAN0200
C DATA NAME/2*4H ,4H S,4HTART,4HING ,4HHEAD,4H ,4H STO,4HRAGMAN0210
1E,4H COE,4HFFIC,4HIENT,2*4H ,4H TR,4HANSM,4HISSI,4HVITY,5*4H MAN0220
2 ,4H TK,4H HY,4HDRAU,4HLIC ,4HCOND,4HUCTI,4HVITY,2*4H ,4HBOYMAN0230
3T,4HOM E,4HLEVA,4HTION,2*4H ,4H R,4HECHA,4HRGE ,4HRAE/ MAN0240
DATA INFT/4H(20F,4H4.0),4H(8F1,4H0.4)/ MAN0250
DATA IOFT/4H(1H0,4H,I2,,4H2X,2,4H0F6,,4H1/(5,4HX,20,4HF6.1,4H)) ,MAN0260
14H ,4H(1H0,4H,I5,,4H14F9,4H.5/((,4H1H ,4H5X,1,4H4F9,,4H5)) ,4HMAN0270
2 ,4H(1H0,4H,I5,,4H10EU,4H2.5/,4H(1H ,4H,5X,,4H10E1,4H2.5),4H) MAN0280
3,4H(1H0,4H,I5,,4H10E1,4H1.3/,4H(1H ,4H,5X,,4H10E1,4H1.3),4H) / MAN0290
C MAN0300
C DEFINE FILE 2(8,1520,U,KKK) MAN0310
C .....MAN0320
C MAN0330
C ---READ TITLE, PROGRAM SIZE AND OPTIONS--- MAN0340
C READ (5,200) HEADNG MAN0350
C WRITE (6,190) HEADNG MAN0360
C READ (5,160) IO,J0,K0,ITMAX,NCH MAN0370
C WRITE (6,180) IO,J0,K0,ITMAX,NCH MAN0380
C READ (5,210) IDRAW,IHEAD,IFLO,IDK1,IDK2,IWATER,IQRE,IPU1,IPU2,ITK MAN0390
C WRITE (6,220) IDRAW,IHEAD,IFLO,IDK1,IDK2,IWATER,IQRE,IPU1,IPU2,ITKMAN0400
C IERR=0 MAN0410
C MAN0420
C ---COMPUTE DIMENSIONS FOR ARRAYS--- MAN0430
C J1=J0-1 MAN0440
C I1=I0-1 MAN0450
C K1=K0-1 MAN0460
C I2=I0-2 MAN0470
C J2=J0-2 MAN0480
C K2=K0-2 MAN0490
C IMAX=MAX0(IO,J0) MAN0500
C NCD=MAX0(1,NCH) MAN0510
C ITMX1=ITMAX+1 MAN0520
C ISIZ=IO*J0*K0 MAN0530
C IK1=IO*J0 MAN0540
C IK2=MAX0(IK1*K1,1) MAN0550
C ISUM=2*ISIZ+1 MAN0560

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L(1)=1
DC 30 I=2,14
IF (I.NE.8) GO TO 20
L(8)=ISUM
ISUM=ISUM+IK2
IF (IK2.EQ.1) GO TO 10
IK=I0
JK=J0
K5=K1
GO TO 30
10 IK=1
JK=1
K5=1
GO TO 30
20 L(I)=ISUM
ISUM=ISUM+ISIZ
30 CONTINUE
L(15)=ISUM
ISUM=ISUM+J0
L(16)=ISUM
ISUM=ISUM+I0
L(17)=ISUM
ISUM=ISUM+K0
L(18)=ISUM
ISUM=ISUM+IMAX
L(19)=ISUM
ISUM=ISUM+K0*3
L(20)=ISUM
ISUM=ISUM+ITMX1
L(21)=ISUM
ISUM=ISUM+3*NCD
L(22)=ISUM
ISUM=ISUM+NCD
L(23)=ISUM
IF (IWATER.NE.ICHK(6)) GO TO 40
ISUM=ISUM+IK1
L(24)=ISUM
ISUM=ISUM+IK1
IP=I0
JP=J0
GO TO 50
40 ISUM=ISUM+1
L(24)=ISUM
ISUM=ISUM+1
IP=1
JP=1
50 L(25)=ISUM
IF (IQRE.NE.ICHK(7)) GO TO 60
ISUM=ISUM+IK1
IQ=I0
JQ=J0
GO TO 70
60 ISUM=ISUM+1
IQ=1
JQ=1
70 WRITE (6,170) ISUM

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MAN0570
MAN0580
MAN0590
MAN0600
MAN0610
MAN0620
MAN0630
MAN0640
MAN0650
MAN0660
MAN0670
MAN0680
MAN0690
MAN0700
MAN0710
MAN0720
MAN0730
MAN0740
MAN0750
MAN0760
MAN0770
MAN0780
MAN0790
MAN0800
MAN0810
MAN0820
MAN0830
MAN0840
MAN0850
MAN0860
MAN0870
MAN0880
MAN0890
MAN0900
MAN0910
MAN0920
MAN0930
MAN0940
MAN0950
MAN0960
MAN0970
MAN0980
MAN0990
MAN1000
MAN1010
MAN1020
MAN1030
MAN1040
MAN1050
MAN1060
MAN1070
MAN1080
MAN1090
MAN1100
MAN1110
MAN1120

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C		MAN1130
C	---PASS INITIAL ADDRESSES OF ARRAYS TO SUBROUTINES---	MAN1140
	CALL DATAI(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7)),	MAN1150
	1,Y(L(8)),Y(L(9)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(19)),Y(L(23)),Y(L(MAN1160
	224)),Y(L(25)))	MAN1170
	CALL STEP(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7)),	MAN1180
	1Y(L(8)),Y(L(9)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(19)),Y(L(18)),Y(L(2	MAN1190
	20)))	MAN1200
	CALL SOLVE(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7)),	MAN1210
	1,Y(L(8)),Y(L(9)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(19)),Y(L(10)),Y(L(MAN1220
	211)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(20)),Y(L(25)))	MAN1230
	CALL COEF(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7)),	MAN1240
	1Y(L(8)),Y(L(9)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(19)),Y(L(23)),Y(L(2	MAN1250
	24)),Y(L(25)))	MAN1260
	CALL CHECKI(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7))	MAN1270
	1),Y(L(8)),Y(L(9)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(19)),Y(L(21)),Y(L(MAN1280
	2(22)),Y(L(25)))	MAN1290
	CALL PRNTAI(Y(L(1)),Y(L(2)),Y(L(4)),Y(L(5)),Y(L(9)),Y(L(15)),Y(L(1	MAN1300
	16)))	MAN1310
C		MAN1320
C	---START COMPUTATIONS---	MAN1330
C	*****	MAN1340
C	---READ AND WRITE DATA FOR GROUPS II AND III---	MAN1350
	CALL DATAIN	MAN1360
	IRN=1	MAN1370
	NIJ=IO*JO	MAN1380
	DO 80 K=1,KO	MAN1390
	LOC=L(2)+(K-1)*NIJ	MAN1400
80	CALL ARRAY(Y(LOC),INFT(1,2),IOFT(1,1),NAME(1),IRN,DUM)	MAN1410
	DO 90 K=1,KO	MAN1420
	LOC=L(5)+(K-1)*NIJ	MAN1430
90	CALL ARRAY(Y(LOC),INFT(1,1),IOFT(1,2),NAME(7),IRN,DUM)	MAN1440
	DO 100 K=1,KO	MAN1450
	LOC=L(4)+(K-1)*NIJ	MAN1460
	L1=L(19)+K-1	MAN1470
	L2=L(19)+KO+K-1	MAN1480
	L3=L(19)+2*KO+K-1	MAN1490
	CALL ARRAY(Y(LOC),INFT(1,1),IOFT(1,2),NAME(13),IRN,DUM)	MAN1500
	Y(L1)=DUM(1)	MAN1510
	Y(L2)=DUM(2)	MAN1520
	Y(L3)=DUM(3)	MAN1530
100	WRITE (6,230) K,Y(L1),Y(L2),Y(L3)	MAN1540
	IF (ITK.NE.ICHK(10)) GO TO 120	MAN1550
	DO 110 K=1,K1	MAN1560
	LOC=L(8)+(K-1)*NIJ	MAN1570
110	CALL ARRAY(Y(LOC),INFT(1,1),IOFT(1,3),NAME(19),IRN,DUM)	MAN1580
120	IF (IWATER.NE.ICHK(6)) GO TO 130	MAN1590
	K = KO	MAN1595
	CALL ARRAY(Y(L(23)),INFT(1,1),IOFT(1,4),NAME(25),IRN,DUM)	MAN1600
	CALL ARRAY(Y(L(24)),INFT(1,1),IOFT(1,1),NAME(31),IRN,DUM)	MAN1610
130	IF (IQRE.EQ.ICHK(7)) CALL ARRAY(Y(L(25)),INFT(1,1),IOFT(1,4),NAME(MAN1620
	137),IRN,DUM)	MAN1630
	CALL MOAT	MAN1640
C		MAN1650
C	---COMPUTE TRANSMISSIVITY FOR UNCONFINED LAYER---	MAN1660
	IF (IWATER.EQ.ICHK(6)) CALL TRANS(1)	MAN1670
C		MAN1680

C	---COMPUTE T COEFFICIENTS---	MAN1690
	CALL TCOF	MAN1700
C		MAN1710
C	---COMPUTE ITERATION PARAMETERS---	MAN1720
	CALL ITER	MAN1730
C		MAN1740
C	---READ TIME PARAMETERS AND PUMPING DATA FOR A NEW PUMPING PERIOD---	MAN1750
140	CALL NEWPER	MAN1760
C		MAN1770
	KT=0	MAN1780
	IFINAL=0	MAN1790
C		MAN1800
C	---START NEW TIME STEP COMPUTATIONS---	MAN1810
150	CALL NEWSTP	MAN1820
C		MAN1830
C	---START NEW ITERATION IF MAXIMUM NO. ITERATIONS NOT EXCEEDED---	MAN1840
	CALL NEWITA	MAN1850
C		MAN1860
C	---PRINT OUTPUT AT DESIGNATED TIME STEPS---	MAN1870
	CALL OUTPUT	MAN1880
C		MAN1890
C	---LAST TIME STEP IN PUMPING PERIOD ?---	MAN1900
	IF (IFINAL.NE.1) GO TO 150	MAN1910
C		MAN1920
C	---CHECK FOR NEW PUMPING PERIOD---	MAN1930
	IF (KP.LT.NPER) GO TO 140	MAN1940
C		MAN1950
	STOP	MAN1960
C		MAN1970
C	---FORMATS---	MAN1980
C		MAN1990
C		MAN2000
C		MAN2010
160	FORMAT (8I10)	MAN2020
170	FORMAT ('0',54X,'WORDS OF VECTOR Y USED =',I7)	MAN2030
180	FORMAT ('0',62X,'NUMBER OF ROWS =',I5/60X,'NUMBER OF COLUMNS =',I5/61X,'NUMBER OF LAYERS =',I5//39X,'MAXIMUM PERMITTED NUMBER OF ITERATIONS =',I5//48X,'NUMBER OF CONSTANT HEAD NODES =',I5)	MAN2040
190	FORMAT ('1',33A4)	MAN2050
200	FORMAT (20A4)	MAN2060
210	FORMAT (16(A4,1X))	MAN2070
220	FORMAT ('-SIMULATION OPTIONS: ',11(A4,4X))	MAN2080
230	FORMAT (1H0,44X,'DIRECTIONAL TRANSMISSIVITY MULTIPLICATION FACTORS	MAN2090
	1 FOR LAYER',I3,/,76X,'X =',G15.7/76X,'Y =',G15.7/76X,'Z =',G15.7)	MAN2100
	END	MAN2110
		MAN2120
		MAN2130-

	SUBROUTINE DATAI(PHI,STRT,OLD,T,S,TR,TC,TK,WELL,DELX,DELY,DELZ,FACDAT0010	
	IT,PERM,BOTTOM,QRE)	DAT0020
C	-----	DAT0030
C	READ AND WRITE DATA	DAT0040
C	-----	DAT0050
C	SPECIFICATIONS:	DAT0060
C	REAL *8PHI	DAT0070
	REAL *8XLABEL,YLABEL,TITLE,XN1,MESUR	DAT0080
C		DAT0090
	DIMENSION PHI(I0,J0,K0), STRT(I0,J0,K0), OLD(I0,J0,K0), T(I0,J0,K0), S(I0,J0,K0), TR(I0,J0,K0), TC(I0,J0,K0), TK(IK,JK,K5), WELL(I0,J0,K0), DELX(J0), DELY(I0), DELZ(K0), FACT(K0,3), PERM(IP,JP), BOTDAT0130	DAT0100
	3TOM(IP,JP), QRE(IQ,JQ), TF(3), A(I0,J0), IN(6), IOFT(9), INFT(2)	DAT0110
C		DAT0120
	COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NDAT0160	DAT0130
	1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCDAT0170	DAT0140
	2H,IDX1,IDX2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK	DAT0150
	COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR	DAT0160
	COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9)	DAT0170
	COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT	DAT0180
	COMMON /PR/ XLABEL(3),YLABEL(6),TITLE(6),XN1,MESUR,PRNT(122),BLANKDAT0220	DAT0190
	1(60),DIGIT(122),VF1(6),VF2(6),VF3(7),XSCALE,DINCH,SYM(17),XN(100),	DAT0200
	2YN(13),NA(4),N1,N2,N3,YSCALE,FACT1,FACT2	DAT0210
	RETURN	DAT0220
C	DAT0230
C	*****	DAT0240
	ENTRY DATAIN	DAT0250
C	*****	DAT0260
C		DAT0270
C	---READ AND WRITE SCALAR PARAMETERS---	DAT0280
C	READ (5,330) NPER,KTH,ERR,LENGTH	DAT0290
	WRITE (6,340) NPER,KTH,ERR	DAT0300
	READ (5,460) XSCALE,YSCALE,DINCH,FACT1,(LEVEL1(I),I=1,9),FACT2,(LEVEL2(I),I=1,9),MESUR	DAT0310
	IF (XSCALE.NE.0.) WRITE (6,470) XSCALE,YSCALE,MESUR,MESUR,DINCH,FACT1,LEVEL1,FACT2,LEVEL2	DAT0320
C		DAT0330
C	---READ CUMULATIVE MASS BALANCE PARAMETERS---	DAT0340
	READ (5,450) SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETFLXT,FLXNT	DAT0350
	IF (IDX1.EQ.ICHK(4)) GO TO 20	DAT0360
	IF (IPU1.NE.ICHK(8)) GO TO 50	DAT0370
C		DAT0380
C	---READ INITIAL HEAD VALUES FROM CARDS---	DAT0390
	DO 10 K=1,K0	DAT0400
	DO 10 I=1,I0	DAT0410
10	READ (5,360) (PHI(I,J,K),J=1,J0)	DAT0420
	GO TO 30	DAT0430
C		DAT0440
C	---READ INITIAL HEAD AND MASS BALANCE PARAMETERS FROM DISK---	DAT0450
	20 READ (4) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETFLXT,FLXNT	DAT0460
	REWIND 4	DAT0470
30	WRITE (6,430) SUM	DAT0480
	DO 40 K=1,K0	DAT0490
		DAT0500
		DAT0510
		DAT0520
		DAT0530
		DAT0540
		DAT0550
		DAT0560

WRITE (6,440) K	DAT0570
DO 40 I=1,I0	DAT0580
40 WRITE (6,350) I,(PHI(I,J,K),J=1,J0)	DAT0590
C	DAT0600
50 DO 60 K=1,K0	DAT0610
DO 60 I=1,I0	DAT0620
DO 60 J=1,J0	DAT0630
WELL(I,J,K)=0.	DAT0640
TR(I,J,K)=0.	DAT0650
TC(I,J,K)=0.	DAT0660
IF (K.NE.K0) TK(I,J,K)=0.	DAT0670
60 CONTINUE	DAT0680
RETURN	DAT0690
C *****	DAT0700
ENTRY ARRAY(A,INFT,IOFT,IN,IRN,TF)	DAT0710
C *****	DAT0720
READ (5,330) FAC,IVAR,IPRN,TF,IRECS,IRECD	DAT0730
IC=4*IRECS+2*IVAR+IPRN+1	DAT0740
GO TO (70,70,90,90,120,120), IC	DAT0750
70 DO 80 I=1,I0	DAT0760
DO 80 J=1,J0	DAT0770
80 A(I,J)=FAC	DAT0780
WRITE (6,280) IN,FAC,K	DAT0790
GO TO 140	DAT0800
90 IF (IC.EQ.3) WRITE (6,290) IN,K	DAT0810
DO 110 I=1,I0	DAT0820
READ (5,INFT) (A(I,J),J=1,J0)	DAT0830
DO 100 J=1,J0	DAT0840
100 A(I,J)=A(I,J)*FAC	DAT0850
110 IF (IC.EQ.3) WRITE (6,IOFT) I,(A(I,J),J=1,J0)	DAT0860
GO TO 140	DAT0870
120 READ (2,IRN) A	DAT0880
IF (IC.EQ.6) GO TO 140	DAT0890
WRITE (6,290) IN,K	DAT0900
DO 130 I=1,I0	DAT0910
130 WRITE (6,IOFT) I,(A(I,J),J=1,J0)	DAT0920
140 IF (IRECD.EQ.1) WRITE (2,IRN) A	DAT0930
IRN=IRN+1	DAT0940
RETURN	DAT0950
C *****	DAT0960
ENTRY MDAT	DAT0970
C *****	DAT0980
DO 150 K=1,K0	DAT0990
DO 150 I=1,I0	DAT1000
DO 150 J=1,J0	DAT1010
IF (I.EQ.1.OR.I.EQ.I0.OR.J.EQ.1.OR.J.EQ.J0) T(I,J,K)=0.	DAT1020
IF (IDK4.NE.ICHK(4).AND.IPU1.NE.ICHK(8)) PHI(I,J,K)=STRT(I,J,K)	DAT1030
IF (K.NE.K0.OR.IWATER.NE.ICHK(6)) GO TO 150	DAT1040
IF (I.EQ.1.OR.I.EQ.I0.OR.J.EQ.1.OR.J.EQ.J0) PERM(I,J)=0.	DAT1050
150 CONTINUE	DAT1060
C DELX	DAT1070
READ (5,330) FAC,IVAR,IPRN	DAT1080
IF (IVAR.EQ.1) READ (5,330) (DELX(J),J=1,J0)	DAT1090
DO 170 J=1,J0	DAT1100
IF (IVAR.NE.1) GO TO 160	DAT1110
DELX(J)=DELX(J)*FAC	DAT1120

	GO TO 170	DAT1130
160	DELX(J)=FAC	DAT1140
170	CCONTINUE	DAT1150
	IF (IVAR.EQ.1.AND.IPRN.NE.1) WRITE (6,370) (DELX(J),J=1,J0)	DAT1160
	IF (IVAR.EQ.0) WRITE (6,300) FAC	DAT1170
C DELY	DAT1180
	READ (5,330) FAC,IVAR,IPRN	DAT1190
	IF (IVAR.EQ.1) READ (5,330) (DELY(I),I=1,I0)	DAT1200
	DO 190 I=1,I0	DAT1210
	IF (IVAR.NE.1) GO TO 180	DAT1220
	DELY(I)=DELY(I)*FAC	DAT1230
	GO TO 190	DAT1240
180	DELY(I)=FAC	DAT1250
190	CONTINUE	DAT1260
	IF (IVAR.EQ.1.AND.IPRN.NE.1) WRITE (6,380) (DELY(I),I=1,I0)	DAT1270
	IF (IVAR.EQ.0) WRITE (6,310) FAC	DAT1280
C DELZ	DAT1290
	READ (5,330) FAC,IVAR,IPRN	DAT1300
	IF (IVAR.EQ.1) READ (5,330) (DELZ(K),K=1,K0)	DAT1310
	DO 210 K=1,K0	DAT1320
	IF (IVAR.NE.1) GO TO 200	DAT1330
	DELZ(K)=DELZ(K)*FAC	DAT1340
	GO TO 210	DAT1350
200	DELZ(K)=FAC	DAT1360
210	CONTINUE	DAT1370
	IF (IVAR.EQ.1.AND.IPRN.NE.1) WRITE (6,390) (DELZ(K),K=1,K0)	DAT1380
	IF (IVAR.EQ.0) WRITE (6,320) FAC	DAT1390
C		DAT1400
C	---INITIALIZE VARIABLES---	DAT1410
	B=0.	DAT1420
	D=0.	DAT1430
	F=0.	DAT1440
	H=0.	DAT1450
	SU=0.	DAT1460
	Z=0.	DAT1470
	IF (XSCALE.NE.0.) CALL MAP	DAT1480
	RETURN	DAT1490
C	DAT1500
C	---READ TIME PARAMETERS AND PUMPING DATA FOR A NEW PUMPING PERIOD---	DAT1510
C	*****	DAT1520
C	ENTRY NEWPER	DAT1530
C	*****	DAT1540
C		DAT1550
	READ (5,330) KP,KPM1,NWEL,TMAX,NUMT,CDLT,DELT	DAT1560
C		DAT1570
C	---COMPUTE ACTUAL DELT AND NUMT---	DAT1580
	DT=DELT/24.	DAT1590
	TM=0.0	DAT1600
	DO 220 I=1,NUMT	DAT1610
	DT=CDLT*DT	DAT1620
	TM=TM+DT	DAT1630
	IF (TM.GE.TMAX) GO TO 230	DAT1640
220	CONTINUE	DAT1650
	GO TO 240	DAT1660
230	DELT=TMAX/TM*DELT	DAT1670
	NUMT=I	DAT1680

240	WRITE (6,400) KP,TMAX,NUMT,DELT,CDLT	DAT1690
	DELT=DELT*3600.	DAT1700
	TMAX=TMAX*86400.	DAT1710
	SLMP=0.0	DAT1720
C		DAT1730
C	---READ AND WRITE WELL PUMPING RATES---	DAT1740
	WRITE (6,410) NWEL	DAT1750
	IF (NWEL.EQ.0) GO TO 260	DAT1760
	DC 245 K = 1,K0	DAT1761
	DC 245 I = 1,I0	DAT1762
	DC 245 J = 1,J0	DAT1763
245	WELL(I,J,K) = 0.0	DAT1764
	DO 250 II=1,NWEL	DAT1770
	READ (5,330) K,I,J,WELL(I,J,K)	DAT1780
	WRITE (6,420) K,I,J,WELL(I,J,K)	DAT1790
250	WELL(I,J,K)=WELL(I,J,K)/(DELT(J)*DELY(I))	DAT1800
260	RETURN	DAT1810
C		DAT1820
C	---FORMATS---	DAT1830
C		DAT1840
C		DAT1850
C		DAT1860
280	FORMAT (1H0,52X,6A4,' =',G15.7,' FOR LAYER',I3)	DAT1870
290	FORMAT (1H1,45X,6A4,' MATRIX, LAYER',I3/46X,41(' '))	DAT1880
300	FORMAT ('0',72X,'DELT =',G15.7)	DAT1890
310	FORMAT ('0',72X,'DELY =',G15.7)	DAT1900
320	FORMAT ('0',72X,'DELZ =',G15.7)	DAT1910
330	FORMAT (8G10.0)	DAT1920
340	FORMAT ('0',51X,'NUMBER OF PUMPING PERIODS =',I5/49X,'TIME STEPS BETWEEN PRINTOUTS =',I5//51X,'ERROR CRITERIA FOR CLOSURE =',G15.7/)	DAT1930
350	FORMAT ('0',I2,2X,20F6.1/(5X,20F6.1))	DAT1940
360	FORMAT (8F10.4)	DAT1950
370	FORMAT (1H1,46X,40HGRID SPACING IN PROTOTYPE IN X DIRECTION/47X,40	DAT1960
	1(' ')/(10',12F10.0))	DAT1970
380	FORMAT (1H-,46X,40HGRID SPACING IN PROTOTYPE IN Y DIRECTION/47X,40	DAT1980
	1(' ')/(10',12F10.0))	DAT1990
390	FORMAT (1H-,46X,40HGRID SPACING IN PROTOTYPE IN Z DIRECTION/47X,40	DAT2000
	1(' ')/(10',12F10.0))	DAT2010
400	FORMAT ('-',50X,'PUMPING PERIOD NO.',I4,'',F10.2,' DAYS/51X,38('	DAT2020
	1-')//53X,'NUMBER OF TIME STEPS=',I6//59X,'DELT IN HOURS =',F10.3//	DAT2030
	253X,'MULTIPLIER FOR DELT =',F10.3)	DAT2040
410	FORMAT ('-',63X,I4,' WELLS/65X,9(' ')/50X,'K',9X,'I',9X,'J	DAT2050
	IMPING RATE'/)	PUDAT2060
420	FORMAT (41X,3I10,2F13.2)	DAT2070
430	FORMAT ('-',40X,' CONTINUATION - HEAD AFTER ',G20.7,' SEC PUMPING	DAT2080
	1'/42X,58(' '))	DAT2090
440	FORMAT ('1',55X,'INITIAL HEAD MATRIX, LAYER',I3/56X,30(' '))	DAT2100
450	FORMAT (4G20.10)	DAT2110
460	FORMAT (3G10.0,2(G10.0,9I1,1X),A8)	DAT2120
470	FORMAT ('0',30X,'ON ALPHAMERIC MAP:1/40X,'MULTIPLICATION FACTOR FOR	DAT2130
	1R X DIMENSION =',G15.7/40X,'MULTIPLICATION FACTOR FOR Y DIMENSION	DAT2140
	2=',G15.7/55X,'MAP SCALE IN UNITS OF ',A11/50X,'NUMBER OF ',A8,' P	DAT2150
	3ER INCH =',G15.7/43X,'MULTIPLICATION FACTOR FOR DRAWDOWN =',G15.7,	DAT2160
	4' PRINTED FOR LAYERS',9I2/47X,'MULTIPLICATION FACTOR FOR HEAD =',G	DAT2170
	515.7,' PRINTED FOR LAYERS',9I2)	DAT2180
	END	DAT2190
		DAT2200-

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SUBROUTINE STEP(PHI,STRT,OLD,T,S,TR,TC,TK,WELL,DELX,DELY,DELZ,FACTSTP 10
1,DDN,TEST3) STP 20
C -----STP 30
C INITIALIZE DATA FOR A NEW TIME STEP AND PRINT RESULTS STP 40
C -----STP 50
C STP 60
C SPECIFICATIONS: STP 70
C REAL *8PHI STP 80
C REAL *8XLABEL,YLABEL,TITLE,XN1,MESUR STP 90
C STP 100
C DIMENSION PHI(I0,J0,K0), STRT(I0,J0,K0), OLD(I0,J0,K0), T(I0,J0,K0) STP 110
1), S(I0,J0,K0), TR(I0,J0,K0), TC(I0,J0,K0), TK(IK,JK,K5), WELL(I0,STP 120
2J0,K0), DELX(J0), DELY(I0), DELZ(K0), FACT(K0,3), DDN(IMAX), TEST3STP 130
3(ITMX1), ITTO(50) STP 140
C STP 150
C COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NSTP 160
1WEL,NUMT,IFINAL,IT,KT,IMEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCSTP 170
2H,IDK1,IDK2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK STP 180
COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR STP 190
COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9) STP 200
COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT STP 210
COMMON /PR/ XLABEL(3),YLABEL(6),TITLE(6),XN1,MESUR,PRNT(122),BLANKSTP 220
1(60),DIGIT(122),VF1(6),VF2(6),VF3(7),XSCALE,DINCH,SYM(17),XN(100),STP 230
2YN(13),NA(4),N1,N2,N3,YSCALE,FACT1,FACT2 STP 240
RETURN STP 250
C .....STP 260
C *****STP 270
C ENTRY NEWSTP STP 280
C *****STP 290
C KT=KT+1 STP 300
C IT=0 STP 310
C DO 10 K=1,K0 STP 320
C DO 10 I=1,I0 STP 330
C DO 10 J=1,J0 STP 340
10 OLD(I,J,K)=PHI(I,J,K) STP 350
DELT=CDLT*DELT STP 360
SUM=SUM+DELT STP 370
SUMP=SUMP+DELT STP 380
DAYSP=SUMP/86400. STP 390
YRSP=DAYSP/365. STP 400
HRS=SUM/3600. STP 410
SMIN=HRS*60. STP 420
DAYS=HRS/24. STP 430
YRS=DAYS/365. STP 440
RETURN STP 450
C STP 460
C ---PRINT OUTPUT AT DESIGNATED TIME STEPS--- STP 470
C *****STP 480
C ENTRY OUTPUT STP 490
C *****STP 500
C IF (KT.EQ.NUMT) IFINAL=1 STP 510
C ITTO(KT)=IT STP 520
C IF (IT.LE.ITMAX) GO TO 20 STP 530
C IT=IT-1 STP 540
C ITTO(KT)=IT STP 550
C IERR=2 STP 560

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C		STP 570
C	---IF MAXIMUM ITERATIONS EXCEEDED,WRITE RESULTS ON DISK OR CARDS---	STP 580
	IF (IDK2.EQ.ICHK(5)) WRITE (4) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHST	STP 590
	1,CHDT,FLUXT,STORT,ETFLXT,FLXNT	STP 600
	IF (IPU2.EQ.ICHK(9)) WRITE (7,230) SUM,SUMP,PUMPT,CFLUXT,QRET,CHST	STP 610
	1,CHDT,FLUXT,STORT,ETFLXT,FLXNT	STP 620
C		STP 630
	20 IF (IFLO.EQ.ICHK(3)) CALL CHECK	STP 640
	IF (IERR.EQ.2) GO TO 30	STP 650
	IF (MOD(KT,KTH).NE.0.AND.IFINAL.NE.1) RETURN	STP 660
	30 WRITE (6,210) KT,DELT,SUM,SMIN,HRS,DAYS,YRS,DAYSP,YRSP	STP 670
	IF (IFLO.EQ.ICHK(3)) CALL CWRITE	STP 680
	IT=IT+1	STP 690
	WRITE (6,180) (TEST3(J),J=1,IT)	STP 700
	I3=1	
	I5=0	
352	I5=I5+40	
	I4=MIN0(KT,I5)	
	WRITE (6,240) (I,I=I3,I4)	STP 710
	WRITE (6,260)	STP 720
	WRITE (6,250) (ITTO(I),I=I3,I4)	STP 730
	WRITE (6,260)	STP 740
	IF(KT.LE.I5) GO TO 353	
	I3=I3+40	
	GO TO 352	
C		STP 750
C	---PRINT MAPS---	STP 760
	353 IF (XSCALE.EQ.0.) GO TO 70	STP 770
	IF (FACT1.EQ.0.) GO TO 50	STP 780
	DO 40 IA=1,9	STP 790
	II=LEVEL1(IA)	STP 800
	IF (II.EQ.0) GO TO 50	STP 810
	40 CALL PRNTA(1,II)	STP 820
	50 IF (FACT2.EQ.0.) GO TO 70	STP 830
	DO 60 IA=1,9	STP 840
	II=LEVEL2(IA)	STP 850
	IF (II.EQ.0) GO TO 70	STP 860
	60 CALL PRNTA(2,II)	STP 870
	70 IF (IDRAW.NE.ICHK(1)) GO TO 100	STP 880
C		STP 890
C	---PRINT DRAWDOWN---	STP 900
	DO 90 K=1,K0	STP 910
	WRITE (6,200) K	STP 920
	DO 90 I=1,I0	STP 930
	DO 80 J=1,J0	STP 940
	80 DDN(J)=STRT(I,J,K)-PHI(I,J,K)	STP 950
	90 WRITE (6,170) I,(DDN(J),J=1,J0)	STP 960
	100 IF (IHEAD.NE.ICHK(2)) GO TO 120	STP 970
C		STP 980
C	---PRINT HEAD MATRIX---	STP 990
	DO 110 K=1,K0	STP1000
	WRITE (6,190) K	STP1010
	DO 110 I=1,I0	STP1020
	110 WRITE (6,170) I,(PHI(I,J,K),J=1,J0)	STP1030
C		STP1040
C	---WRITE ON DISK---	STP1050

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120 IF (IERR.EQ.2) GO TO 130                                STP1060
    IF (KP.LT.NPER.OR.IFINAL.NE.1) RETURN                  STP1070
    IF (IDK2.EQ.ICHK(5)) WRITE (4) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHST STP1080
    1,CHDT,FLUXT,STORT,ETFLXT,FLXNT                        STP1090
C                                                           STP1100
C    ---PUNCHED OUTPUT---                                  STP1110
130 IF (IPU2.NE.ICHK(9)) GO TO 160                          STP1120
    IF (IERR.EQ.2) GO TO 140                                STP1130
    WRITE (7,230) SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETF STP1140
    1LXT,FLXNT                                              STP1150
140 DO 150 K=1,K0                                           STP1160
150 WRITE (7,220) ((PHI(I,J,K),J=1,J0),I=1,I0)             STP1170
160 IF (IERR.EQ.2) STOP                                     STP1180
    RETURN                                                  STP1190
C                                                           STP1200
C    ---FORMATS---                                         STP1210
C                                                           STP1220
C                                                           STP1230
C                                                           STP1240
170 FORMAT ('0',I4,18F7.2/(5X,18F7.2))                     STP1250
180 FORMAT ('0MAXIMUM HEAD CHANGE FOR EACH ITERATION:',' ',39(' ')/(10 STP1260
    1',10F12.4))                                           STP1270
190 FORMAT ('1',55X,'HEAD MATRIX, LAYER',I3/56X,21(' '))   STP1280
200 FORMAT ('1',55X,' DRAWDOWN, LAYER',I3/59X,18(' '))     STP1290
210 FORMAT (1H1,44X,57(' ')/45X,' ',14X,'TIME STEP NUMBER =',I9,14X,'| STP1300
    1'/45X,57(' ')/50X,29HSIZE OF TIME STEP IN SECONDS=',F14.2//55X,'|TO STP1310
    2TAL SIMULATION TIME IN SECONDS=',F14.2/80X,8HMINUTES=',F14.2/82X,6HSTP1320
    3HOURS=',F14.2/83X,5H0AYS=',F14.2/82X,'YEARS=',F14.2///45X,'DURATION STP1330
    4OF CURRENT PUMPING PERIOD IN DAYS=',F14.2/82X,'YEARS=',F14.2//) STP1340
220 FORMAT (10F8.2)                                         STP1350
230 FORMAT (4G20.10)                                        STP1360
240 FORMAT ('0TIME STEP ',40I3)                             STP1370
250 FORMAT ('0ITERATIONS:',40I3)                            STP1380
260 FORMAT (' ',10(' '))                                    STP1390
    END                                                    STP1400-

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	SUBROUTINE SOLVE(PHI,STRT,OLD,T,S,TR,TC,TK,WELL,DELX,DELY,DELZ,FACSP3	10
	1T,EL,FL,GL,V,XI,TEST3,QRE)	SP3 20
C	-----	SP3 30
C	SOLUTION BY THE STRONGLY IMPLICIT PROCEDURE	SP3 40
C	-----	SP3 50
C		SP3 60
C	SPECIFICATIONS:	SP3 70
	REAL *8PHI,RHO,B,D,F,H,Z,SU,RHOP,W,WMIN,RHO1,RHO2,RHO3,XPART,YPART	SP3 80
	1,ZPART,DMIN1,WMAX,XT,YT,ZT,DABS,DMAX1,DEN,TXM,TYM,TZM	SP3 90
	REAL *8E,AL,BL,CL,A,C,G,WU,TU,U,DL,RES,SUPH,GLXI,ZPHI	SP3 100
C		SP3 110
	DIMENSION PHI(1),STRT(1),OLD(1),T(1),S(1),TR(1),TC(1),TK(1)	SP3 120
	1,WELL(1),DELX(1),DELY(1),DELZ(1),FACT(K0,3),RHOP(20),TEST3	SP3 130
	21),EL(1),FL(1),GL(1),V(1),XI(1),QRE(1)	SP3 140
C		SP3 150
	COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NSP	SP3 160
	1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLG,IERR,I2,J2,K2,IMAX,ITMX1,NCSP	SP3 170
	2H,IDK1,IDK2,IWATER,IGRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK	SP3 180
	COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR	SP3 190
	COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9)	SP3 200
	RETURN	SP3 210
C	SP3 220
C	*****	SP3 230
	ENTRY ITER	SP3 240
C	*****	SP3 250
C	---COMPUTE AND PRINT ITERATION PARAMETERS---	SP3 260
	WRITE (6,240)	SP3 270
	WMIN=1.D0	SP3 280
	DELT=1.	SP3 290
	P2=LENGTH-1	SP3 300
	NT=I0*J0*K0	SP3 310
	NIJ=I0*J0	SP3 320
	XT=3.141593**2/(2.*J2*J2)	SP3 330
	YT=3.141593**2/(2.*I2*I2)	SP3 340
	ZT=3.141593**2/(2.*K0*K0)	SP3 350
	RHO1=0.D0	SP3 360
	RHO2=0.D0	SP3 370
	RHO3=0.D0	SP3 380
	DO 40 K=1,K0	SP3 390
	DO 40 I=2,I1	SP3 400
	DO 40 J=2,J1	SP3 410
	N=I+(J-1)*I0+(K-1)*NIJ	SP3 420
	IF (T(N).EQ.0.) GO TO 40	SP3 430
	D=TR(N-I0)/DELX(J)	SP3 440
	F=TR(N)/DELX(J)	SP3 450
	B=TC(N-1)/DELY(I)	SP3 460
	H=TC(N)/DELY(I)	SP3 470
	SU=0.D0	SP3 480
	Z=0.D0	SP3 490
	IF (K.NE.1) Z=TK(N-NIJ)/DELZ(K)	SP3 500
	IF (K.NE.K0) SU=TK(N)/DELZ(K)	SP3 510
	RHO=S(N)/DELT	SP3 520
	QR=0.	SP3 530
	IF (K.NE.K0) GO TO 10	SP3 540
	IF (IGRE.EQ.ICHK(7)) QR=QRE(I+(J-1)*I0)	SP3 550
10	CONTINUE	SP3 560

TXM=DMAX1(D,F)	SP3 570
TYM=DMAX1(B,H)	SP3 580
TZM=DMAX1(SU,Z)	SP3 590
DEN=DMIN1(D,F)	SP3 600
IF (DEN.EQ.0.D0) DEN=TXM	SP3 610
IF (DEN.EQ.0.D0) GO TO 20	SP3 620
RHO1=DMAX1(RHO1,TYM/DEN)	SP3 630
20 DEN=DMIN1(B,H)	SP3 640
IF (DEN.EQ.0.D0) DEN=TYM	SP3 650
IF (DEN.EQ.0.D0) GO TO 30	SP3 660
RHO2=DMAX1(RHO2,TXM/DEN)	SP3 670
30 DEN=DMIN1(SU,Z)	SP3 680
IF (DEN.EQ.0.D0) DEN=TZM	SP3 690
IF (DEN.EQ.0.D0) GO TO 40	SP3 700
RHO3=DMAX1(RHO3,TXM/DEN)	SP3 710
40 CONTINUE	SP3 720
XPART=XT/(1.D0+RHO1)	SP3 730
YPART=YT/(1.D0+RHO2)	SP3 740
ZPART=ZT/(1.D0+RHO3)	SP3 750
WMIN=DMIN1(WMIN,XPART,YPART,ZPART)	SP3 760
WMAX=1.D0-WMIN	SP3 770
PJ=-1.	SP3 780
DO 50 I=1,LENGTH	SP3 790
PJ=PJ+1.	SP3 800
50 RHOP(I)=1.D0-(1.D0-WMAX)**(PJ/P2)	SP3 810
WRITE (6,230) LENGTH,(RHOP(J),J=1,LENGTH)	SP3 820
RETURN	SP3 830
C	SP3 840
C	SP3 850
C ---INITIALIZE DATA FOR A NEW ITERATION---	SP3 860
60 IT=IT+1	SP3 870
IF (IT.LE.ITMAX) GO TO 70	SP3 880
WRITE (6,220)	SP3 890
CALL OUTPUT	SP3 900
70 IF (MOD(IT,LENGTH)) 80,80,90	SP3 910
C *****	SP3 920
C ENTRY NEWITA	SP3 930
C *****	SP3 940
80 NTH=0	SP3 950
90 NTH=NTH+1	SP3 960
W=RHOP(NTH)	SP3 970
TEST3(IT+1)=0.	SP3 980
TEST=0.0	SP3 990
BIG=0.	SP31000
DO 100 I=1,NT	SP31010
EL(I)=0.	SP31020
FL(I)=0.	SP31030
GL(I)=0.	SP31040
V(I)=0.	SP31050
100 XI(I)=0.	SP31060
C	SP31070
C ---COMPUTE TRANSMISSIVITY AND T COEFFICIENTS FOR UPPER	SP31080
C HYDROLOGIC UNIT WHEN IT IS UNCONFINED---	SP31090
C IF (IWATER.NE.ICHK(6)) GO TO 110	SP31100
CALL TRANS(0)	SP31110
C	SP31120

C	---CHOOSE SIP NORMAL OR REVERSE ALGORITHM---	SP31130
110	IF (MOD(IT,2)) 120,120,170	SP31140
120	DO 150 K=1,K0	SP31150
	DO 150 I=2,I1	SP31160
	DO 150 J=2,J1	SP31170
	N=I+(J-1)*I0+(K-1)*NIJ	SP31180
	NIA=N+1	SP31190
	NIB=N-1	SP31200
	NJA=N+I0	SP31210
	NJB=N-I0	SP31220
	NKA=N+NIJ	SP31230
	NKB=N-NIJ	SP31240
C		SP31250
C	---SKIP COMPUTATIONS IF NODE OUTSIDE MODEL---	SP31260
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 150	SP31270
C		SP31280
C	---COMPUTE COEFFICIENTS---	SP31290
	D=TR(NJB)/DELX(J)	SP31300
	F=TR(N)/DELX(J)	SP31310
	B=TC(NIB)/DELY(I)	SP31320
	H=TC(N)/DELY(I)	SP31330
	SU=0.D0	SP31340
	Z=0.D0	SP31350
	IF (K.NE.1) Z=TK(NKB)/DELZ(K)	SP31360
	IF (K.NE.K0) SU=TK(N)/DELZ(K)	SP31370
	RHO=S(N)/DELT	SP31380
	QR=0.	SP31390
	IF (K.NE.K0) GO TO 130	SP31400
	IF (IQRE.EQ.ICHECK(7)) QR=QRE(I+(J-1)*I0)	SP31410
C		SP31420
C	---SIP NORMAL ALGORITHM---	SP31430
C	---FORWARD SUBSTITUTE, COMPUTING INTERMEDIATE VECTOR V---	SP31440
130	E=-B-D-F-H-SU-Z-RHO	SP31450
	BL=B/(1.+W*(EL(NIB)+GL(NIB)))	SP31460
	CL=D/(1.+W*(FL(NJB)+GL(NJB)))	SP31470
	C=BL*EL(NIB)	SP31480
	G=CL*FL(NJB)	SP31490
	WU=CL*GL(NJB)	SP31500
	U=BL*GL(NIB)	SP31510
	IF (K.EQ.1) GO TO 140	SP31520
	AL=Z/(1.+W*(EL(NKB)+FL(NKB)))	SP31530
	A=AL*EL(NKB)	SP31540
	TU=AL*FL(NKB)	SP31550
	DL=E+W*(A+C+G+WU+TU)-CL*EL(NJB)-BL*FL(NIB)-AL*GL(NKB)	SP31560
	EL(N)=(F-W*(A+C))/DL	SP31570
	FL(N)=(H-W*(G+TU))/DL	SP31580
	GL(N)=(SU-W*(WU+U))/DL	SP31590
	SUPH=0.D0	SP31600
	IF (K.NE.K0) SUPH=SU*PHI(NKA)	SP31610
	RES=-B*PHI(NIB)-D*PHI(NJB)-E*PHI(N)-F*PHI(NJA)-H*PHI(NIA)-SUPH-Z*P	SP31620
	1HI(NKB)-WELL(N)-RHO*OLD(N)-QR	SP31630
	V(N)=(RES-AL*V(NKB)-BL*V(NIB)-CL*V(NJB))/DL	SP31640
	GO TO 150	SP31650
140	DL=E+W*(C+G+WU+U)-CL*EL(NJB)-BL*FL(NIB)	SP31660
	EL(N)=(F-W*C)/DL	SP31670
	FL(N)=(H-W*G)/DL	SP31680

	GL(N)=(SU-W*(WU+U))/DL	SP31690
	SUPH=0.D0	SP31700
	IF (K.NE.K0) SUPH=SU*PHI(NKA)	SP31710
	RES=-B*PHI(NIB)-D*PHI(NJB)-E*PHI(N)-F*PHI(NJA)-H*PHI(NIA)-SUPH-WEL	SP31720
	IL(N)=RHO*OLD(N)-QR	SP31730
	V(N)=(RES-BL*V(NIB)-CL*V(NJB))/DL	SP31740
150	CONTINUE	SP31750
C		SP31760
C	---BACK SUBSTITUTE FOR VECTOR XI---	SP31770
	DO 160 K=1,K0	SP31780
	K3=K0-K+1	SP31790
	DO 160 I=1,I2	SP31800
	I3=I0-I	SP31810
	DO 160 J=1,J2	SP31820
	J3=J0-J	SP31830
	N=I3+(J3-1)*I0+(K3-1)*NIJ+I-I	SP31840
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 160	SP31850
	GLXI=0.D0	SP31860
	IF (K3.NE.K0) GLXI=GL(N)*XI(N+NIJ)	SP31870
	XI(N)=V(N)-EL(N)*XI(N+I0)-FL(N)*XI(N+1)-GLXI	SP31880
C		SP31890
C	---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERIA---	SP31900
	TCHK=ABS(XI(N))	SP31910
	IF (TCHK.GT.BIG) BIG=TCHK	SP31920
	PHI(N)=PHI(N)+XI(N)	SP31930
160	CONTINUE	SP31940
	IF (BIG.GT.ERR) TEST=1.	SP31950
	TEST3(IT+1)=BIG	SP31960
	IF (TEST.EQ.0.) RETURN	SP31970
	GO TO 60	SP31980
C	SP31990
170	DO 200 KK=1,K0	SP32000
	K=K0-KK+1	SP32010
	DO 200 II=1,I2	SP32020
	I=I0-II	SP32030
	DO 200 J=2,J1	SP32040
	N=I+(J-1)*I0+(K-1)*NIJ	SP32050
	NIA=N+1	SP32060
	NIB=N-1	SP32070
	NJA=N+I0	SP32080
	NJB=N-I0	SP32090
	NKA=N+NIJ	SP32100
	NKB=N-NIJ	SP32110
C		SP32120
C	---SKIP COMPUTATIONS IF NODE OUTSIDE AQUIFER---	SP32130
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 200	SP32140
C		SP32150
C	---COMPUTE COEFFICIENTS---	SP32160
	D=TR(NJB)/DELX(J)	SP32170
	F=TR(N)/DELX(J)	SP32180
	B=TC(NIB)/DELY(I)	SP32190
	H=TC(N)/DELY(I)	SP32200
	SU=0.D0	SP32210
	Z=0.D0	SP32220
	IF (K.NE.1) Z=TK(NKB)/DELZ(K)	SP32230
	IF (K.NE.K0) SU=TK(N)/DELZ(K)	SP32240

	RHO=S(N)/DELT	SP32250
	QR=0.	SP32260
	IF (K.NE.K0) GO TO 180	SP32270
	IF (IGRE.EQ.ICHECK(7)) QR=QRE(I+(J-1)*I0)	SP32280
C		SP32290
C	---SIP REVERSE ALGORITHM---	SP32300
C	---FORWARD SUBSTITUTE, COMPUTING INTERMEDIATE VECTOR V---	SP32310
180	E=-B-D-F-H-SU-Z-RHO	SP32320
	BL=H/(1.+W*(EL(NIA)+GL(NIA)))	SP32330
	CL=D/(1.+W*(FL(NJB)+GL(NJB)))	SP32340
	C=BL*EL(NIA)	SP32350
	G=CL*FL(NJB)	SP32360
	WU=CL*GL(NJB)	SP32370
	U=BL*GL(NIA)	SP32380
	IF (K.EQ.K0) GO TO 190	SP32390
	AL=SU/(1.+W*(EL(NKA)+FL(NKA)))	SP32400
	A=AL*EL(NKA)	SP32410
	TU=AL*FL(NKA)	SP32420
	DL=E+W*(C+G+A+WU+U)-AL*GL(NKA)-BL*FL(NIA)-CL*EL(NJB)	SP32430
	EL(N)=(F-W*(C+A))/DL	SP32440
	FL(N)=(B-W*(G+U))/DL	SP32450
	GL(N)=(Z-W*(WU+U))/DL	SP32460
	ZPHI=0.D0	SP32470
	IF (K.NE.1) ZPHI=Z*PHI(NKB)	SP32480
	RES=-B*PHI(NIB)-D*PHI(NJB)-E*PHI(N)-F*PHI(NJA)-H*PHI(NIA)-SU*PHI(N	SP32490
	KA)-ZPHI-WELL(N)-RHO*OLD(N)-QR	SP32500
	V(N)=(RES-AL*V(NKA)-BL*V(NIA)-CL*V(NJB))/DL	SP32510
	GO TO 200	SP32520
190	DL=E+W*(C+G+WU+U)-BL*FL(NIA)-CL*EL(NJB)	SP32530
	EL(N)=(F-W*C)/DL	SP32540
	FL(N)=(B-W*G)/DL	SP32550
	GL(N)=(Z-W*(WU+U))/DL	SP32560
	ZPHI=0.D0	SP32570
	IF (K.NE.1) ZPHI=Z*PHI(NKB)	SP32580
	RES=-B*PHI(NIB)-D*PHI(NJB)-E*PHI(N)-F*PHI(NJA)-H*PHI(NIA)-ZPHI-WEL	SP32590
	IL(N)-RHO*OLD(N)-QR	SP32600
	V(N)=(RES-BL*V(NIA)-CL*V(NJB))/DL	SP32610
200	CONTINUE	SP32620
C		SP32630
C	---BACK SUBSTITUTE FOR VECTOR XI---	SP32640
	DO 210 K=1,K0	SP32650
	DO 210 I=2,I1	SP32660
	DO 210 J=1,J2	SP32670
	J3=J0-J	SP32680
	N=I+(J3-1)*I0+(K-1)*NIJ	SP32690
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 210	SP32700
	GLXI=0.D0	SP32710
	IF (K.NE.1) GLXI=GL(N)*XI(N-NIJ)	SP32720
	XI(N)=V(N)-EL(N)*XI(N+I0)-FL(N)*XI(N-1)-GLXI	SP32730
C		SP32740
C	---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERIA---	SP32750
	TCHK=ABS(XI(N))	SP32760
	IF (TCHK.GT.BIG) BIG=TCHK	SP32770
	PHI(N)=PHI(N)+XI(N)	SP32780
210	CONTINUE	SP32790
	IF (BIG.GT.ERR) TEST=1.	SP32800

	TEST3(IT+1)=BIG	SP32810
	IF (TEST.EQ.0.) RETURN	SP32820
	GO TO 60	SP32830
C	SP32840
C		SP32850
C	---FORMATS---	SP32860
C		SP32870
C		SP32880
C		SP32890
	220 FORMAT ('0EXCEEDED PERMITTED NUMBER OF ITERATIONS'/ ' 1,39(' * '))	SP32900
	230 FORMAT (///1H0,I5,22H ITERATION PARAMETERS:,6E15.7/(/28X,6E15.7/))	SP32910
	240 FCRMAT ('-' ,44X,'SOLUTION BY THE STRONGLY IMPLICIT PROCEDURE',/45X,	SP32920
	143(' _ '))	SP32930
	END	SP32940


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SUBROUTINE CDEF (PHI,STRT,OLD,T,S,TR,TC,TK,WELL,DELX,DELY,DELZ,FACTCOF 10
1,PERM,BOTTOM,GRE) COF 20
C ----- COF 30
C COMPUTE COEFFICIENTS COF 40
C ----- COF 50
C SPECIFICATIONS: COF 60
C REAL *8PHI COF 70
C COF 80
C COF 90
    DIMENSION PHI(I0,J0,K0), STRT(I0,J0,K0), OLD(I0,J0,K0), T(I0,J0,K0) COF 100
1), S(I0,J0,K0), TR(I0,J0,K0), TC(I0,J0,K0), TK(IK,JK,K5), WELL(I0, COF 110
2J0,K0), DELX(J0), DELY(I0), DELZ(K0), FACT(K0,3), PERM(IP,JP), BOT COF 120
3TOM(IP,JP), GRE(IQ,JQ) COF 130
C COF 140
    COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NCOF 150
1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCCOF 160
2H,IDK1,IDK2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK COF 170
    COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR COF 180
    COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9) COF 190
    RETURN COF 200
C ..... COF 210
C ---COMPUTE TRANSMISSIVITY FOR UPPER HYDROLOGIC UNIT WHEN COF 220
C IT IS UNCONFINED--- COF 230
C ***** COF 240
    ENTRY TRANS(N3) COF 250
C ***** COF 260
    DO 10 I=2,I1 COF 270
    DO 10 J=2,J1 COF 280
    IF (PERM(I,J).EQ.0.) GO TO 10 COF 290
    T(I,J,K0)=PERM(I,J)*(PHI(I,J,K0)-BOTTOM(I,J)) COF 300
    IF (T(I,J,K0).GT.0.) GO TO 10 COF 310
    IF (WELL(I,J,K0).LT.0.) WRITE (6,60) I,J,K0 COF 320
    IF (WELL(I,J,K0).GE.0.) WRITE (6,70) I,J,K0 COF 330
    PERM(I,J)=0. COF 340
    T(I,J,K0)=0. COF 350
    TR(I,J=1,K0)=0. COF 360
    TR(I,J,K0)=0. COF 370
    TC(I,J,K0)=0. COF 380
    TC(I=1,J,K0)=0. COF 390
    IF (K0.NE.1) TK(I,J,K1)=0. COF 400
    PHI(I,J,K0)=1.D30 COF 410
10 CONTINUE COF 420
    IF (N3.EQ.1) RETURN COF 430
    N1=K0 COF 440
    N2=K0 COF 450
    N4=K1 COF 460
    GO TO 20 COF 470
C ---COMPUTE T COEFFICIENTS--- COF 480
C ***** COF 490
    ENTRY TCOF COF 500
C ***** COF 510
    N1=1 COF 520
    N2=K0 COF 530
    N4=1 COF 540
20 DO 40 K=N1,N2 COF 550
    DO 40 I=1,I1 COF 560

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DO 40 J=1,J1	COF 570
IF (T(I,J,K).EQ.0.) GO TO 40	COF 580
IF (T(I,J+1,K).EQ.0.) GO TO 30	COF 590
TR(I,J,K)=(2.*T(I,J+1,K)*T(I,J,K))/(T(I,J,K)*DELX(J+1)+T(I,J+1,K)*	COF 600
1DELX(J))*FACT(K,1)	COF 610
30 IF (T(I+1,J,K).EQ.0.) GO TO 40	COF 620
TC(I,J,K)=(2.*T(I+1,J,K)*T(I,J,K))/(T(I,J,K)*DELY(I+1)+T(I+1,J,K)*	COF 630
1DELY(I))*FACT(K,2)	COF 640
40 CONTINUE	COF 650
IF (K0.EQ.1.OR.ITK.EQ.1CHK(10).OR.N3.EQ.0) RETURN	COF 660
DO 50 K=N4,K1	COF 670
DO 50 I=2,I1	COF 680
DO 50 J=2,J1	COF 690
IF (T(I,J,K+1).EQ.0.) GO TO 50	COF 700
T1=T(I,J,K)*FACT(K,3)	COF 710
T2=T(I,J,K+1)*FACT(K+1,3)	COF 720
TK(I,J,K)=(2.*T2*T1)/(T1*DELZ(K+1)+T2*DELZ(K))	COF 730
50 CONTINUE	COF 740
RETURN	COF 750
	COF 760
	COF 770
60 FORMAT ('- ',20('*'),'WELL',2I3,' IN LAYER',I3,' GOES DRY',20('*'))	COF 780
70 FORMAT ('- ',20('*'),'NODE',2I3,' IN LAYER',I3,' GOES DRY',20('*'))	COF 790
END	COF 800

C
C

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SUBROUTINE CHECKI(PHI,STRT,OLD,T,S,TR,TC,TK,WELL,DELX,DELY,DELZ,FACHK 10
1CT,JFLO,FLOW,QRE)-----CHK 20
C-----CHK 30
C COMPUTE A VOLUMETRIC BALANCE-----CHK 40
C-----CHK 50
C-----CHK 60
C SPECIFICATIONS:-----CHK 70
C REAL *8PHI-----CHK 80
C-----CHK 90
C DIMENSION PHI(I0,J0,K0), STRT(I0,J0,K0), OLD(I0,J0,K0), T(I0,J0,K0)CHK 100
1), S(I0,J0,K0), TR(I0,J0,K0), TC(I0,J0,K0), TK(IK,JK,K5), WELL(I0,CHK 110
2J0,K0), DELX(J0), DELY(I0), DELZ(K0), FACT(K0,3), JFLO(NCH,3), FLOCHK 120
3W(NCH), QRE(IQ,JQ), IQQ(40,38)-----CHK 130
C-----CHK 140
C COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NCHK 150
1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCCHK 160
2H,IDK1,IDK2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK-----CHK 170
COMMON /SPARAM/ TMAX,CDLT,DELT,ERR,TEST,SUM,SUMP,QR-----CHK 180
COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9)-----CHK 190
COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT-----CHK 200
RETURN-----CHK 210
C-----CHK 220
C-----CHK 230
C ENTRY CHECK-----CHK 240
C-----CHK 250
C ---INITIALIZE VARIABLES---CHK 260
C PUMP=0.-----CHK 270
C STOR=0.-----CHK 280
C FLUXS=0.0-----CHK 290
C CHD1=0.0-----CHK 300
C CHD2=0.0-----CHK 310
C QREFLX=0.-----CHK 320
C CFLUX=0.-----CHK 330
C FLUX=0.-----CHK 340
C ETFLUX=0.-----CHK 350
C FLXN=0.0-----CHK 360
C II=0-----CHK 370
C-----CHK 380
C-----CHK 390
C ---COMPUTE RATES,STORAGE AND PUMPAGE FOR THIS STEP---CHK 400
C DO 220 K=1,K0-----CHK 410
C DO 220 I=2,I1-----CHK 420
C DO 220 J=2,J1-----CHK 430
C IF (T(I,J,K).EQ.0.) GO TO 220-----CHK 440
C AREA=DELX(J)*DELY(I)-----CHK 450
C IF (S(I,J,K).GE.0.) GO TO 180-----CHK 460
C-----CHK 470
C ---COMPUTE FLOW RATES TO AND FROM CONSTANT HEAD BOUNDARIES---CHK 480
C II=II+1-----CHK 490
C FLOW(II)=0.-----CHK 500
C JFLO(II,1)=K-----CHK 510
C JFLO(II,2)=I-----CHK 520
C JFLO(II,3)=J-----CHK 530
C IF (S(I,J-1,K).LT.0..OR.T(I,J-1,K).EQ.0.) GO TO 30-----CHK 540
C X=(PHI(I,J,K)-PHI(I,J-1,K))*TR(I,J-1,K)*DELY(I)-----CHK 550
C FLOW(II)=FLOW(II)+X-----CHK 560

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IF (X) 10,30,20	CHK 570
10 CHD1=CHD1+X	CHK 580
GO TO 30	CHK 590
20 CHD2=CHD2+X	CHK 600
30 IF (S(I,J+1,K).LT.0..OR.T(I,J+1,K).EQ.0.) GO TO 60	CHK 610
X=(PHI(I,J,K)-PHI(I,J+1,K))*DELY(I)*TR(I,J,K)	CHK 620
FLOW(II)=FLOW(II)+X	CHK 630
IF (X) 40,60,50	CHK 640
40 CHD1=CHD1+X	CHK 650
GO TO 60	CHK 660
50 CHD2=CHD2+X	CHK 670
60 IF (K.EQ.1) GO TO 90	CHK 680
IF (S(I,J,K-1).LT.0..OR.T(I,J,K-1).EQ.0.) GO TO 90	CHK 690
X=(PHI(I,J,K)-PHI(I,J,K-1))*TK(I,J,K-1)*AREA*2./(DELZ(K)+DELZ(K-1))	CHK 700
1) FLOW(II)=FLOW(II)+X	CHK 710
IF (X) 70,90,80	CHK 720
70 CHD1=CHD1+X	CHK 730
GO TO 90	CHK 740
80 CHD2=CHD2+X	CHK 750
90 IF (K.EQ.K0) GO TO 120	CHK 760
IF (S(I,J,K+1).LT.0..OR.T(I,J,K+1).EQ.0.) GO TO 120	CHK 770
X=(PHI(I,J,K)-PHI(I,J,K+1))*TK(I,J,K)*AREA*2./(DELZ(K)+DELZ(K+1))	CHK 780
FLOW(II)=FLOW(II)+X	CHK 790
IF (X) 100,120,110	CHK 800
100 CHD1=CHD1+X	CHK 810
GO TO 120	CHK 820
110 CHD2=CHD2+X	CHK 830
120 IF (S(I-1,J,K).LT.0..OR.T(I-1,J,K).EQ.0.) GO TO 150	CHK 840
X=(PHI(I,J,K)-PHI(I-1,J,K))*TC(I-1,J,K)*DELX(J)	CHK 850
FLOW(II)=FLOW(II)+X	CHK 860
IF (X) 130,150,140	CHK 870
130 CHD1=CHD1+X	CHK 880
GO TO 150	CHK 890
140 CHD2=CHD2+X	CHK 900
150 IF (S(I+1,J,K).LT.0..OR.T(I+1,J,K).EQ.0.) GO TO 220	CHK 910
X=(PHI(I,J,K)-PHI(I+1,J,K))*TC(I,J,K)*DELX(J)	CHK 920
FLOW(II)=FLOW(II)+X	CHK 930
IF (X) 160,220,170	CHK 940
160 CHD1=CHD1+X	CHK 950
GO TO 220	CHK 960
170 CHD2=CHD2+X	CHK 970
GO TO 220	CHK 980
C	CHK 990
C ---RECHARGE AND WELLS---	CHK1000
180 IF (K.EQ.K0.AND.IGRE.EQ.1CHK(7)) GREFLX=GREFLX+GRE(I,J)*AREA	CHK1010
IF (WELL(I,J,K)) 190,210,200	CHK1020
190 PUMP=PUMP+WELL(I,J,K)*AREA	CHK1030
GO TO 210	CHK1040
200 CFLUX=CFLUX+WELL(I,J,K)*AREA	CHK1050
C	CHK1060
C ---COMPUTE VOLUME FROM STORAGE---	CHK1070
210 STOR=STOR+S(I,J,K)*(OLD(I,J,K)-PHI(I,J,K))*AREA	CHK1080
220 CONTINUE	CHK1090
C	CHK1100
C	CHK1110
C	CHK1120

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C      ---COMPUTE CUMULATIVE VOLUMES, TOTALS, AND DIFFERENCES---      CHK1130
      FLXPT=0.0                                                         CHK1140
      STORT=STORT+STOR                                                  CHK1150
      STOR=STOR/DELT                                                    CHK1160
      QRET=QRET+QREFLX*DELT                                             CHK1170
      CHDT=CHDT-CHD1*DELT                                              CHK1180
      CHST=CHST+CHD2*DELT                                              CHK1190
      PUMPT=PUMPT-PUMP*DELT                                            CHK1200
      CFLUXT=CFLUXT+CFLUX*DELT                                         CHK1210
      TOTL1=STORT+QRET+CFLUXT+CHST+FLXPT                               CHK1220
      TOTL2=CHDT+PUMPT+ETFLXT+FLXNT                                    CHK1230
      SUMR=QREFLX+CFLUX+CHD2+CHD1+PUMP+ETFLUX+FLUXS+STOR              CHK1240
      DIFF=TOTL2-TOTL1                                                 CHK1250
      PERCNT=0.0                                                        CHK1260
      IF (TOTL2.EQ.0.) GO TO 230                                       CHK1270
      PERCNT=DIFF/TOTL2*100.                                           CHK1280
230  RETURN                                                            CHK1290
C      .....CHK1300
C      .....CHK1310
C      ---PRINT RESULTS---      CHK1320
C      *****CHK1330
C      ENTRY CWRITE      CHK1340
C      *****CHK1350
C      .....CHK1360
      WRITE (6,260) STOR,QREFLX,STORT,CFLUX,QRET,PUMP,CFLUXT,ETFLUX,CHST,CHK1370
1,FLXPT,CHD2,TOTL1,CHD1,FLUX,FLUXS,ETFLXT,CHDT,SUMR,PUMPT,FLXNT,TOTCHK1380
2L2,DIFF,PERCNT      CHK1390
      IF (NCH.EQ.0) GO TO 240      CHK1400
      WRITE (6,270)      CHK1410
      WRITE (6,280) ((JFLO(I,J),J=1,3),FLOW(I),I=1,NCH)      CHK1420
C      .....CHK1430
C      ---COMPUTE VERTICAL FLOW---      CHK1440
240  X=0.      CHK1450
      Y=0.      CHK1460
      IF (K0.EQ.1) RETURN      CHK1470
      DO 250 I=2,I1      CHK1480
      DO 250 J=2,J1      CHK1490
      X=X+(PHI(I,J,1)-PHI(I,J,2))*TK(I,J,1)*DELX(J)*DELY(I)*2./(DELZ(1)+CHK1500
1DELZ(2))      CHK1510
250  Y=Y+(PHI(I,J,K1)-PHI(I,J,K0))*TK(I,J,K1)*DELX(J)*DELY(I)*2./(DELZ(CHK1520
1K1)*DELZ(K0))      CHK1530
      WRITE (6,290) Y,X      CHK1540
      RETURN      CHK1550
C      .....CHK1560
C      ---FORMATS---      CHK1570
C      .....CHK1580
C      .....CHK1590
C      .....CHK1600
C      .....CHK1610
C      .....CHK1620
260  FORMAT ('0',10X,'CUMULATIVE MASS BALANCE:',16X,'L**3',23X,'RATES FCHK1630
1OR THIS TIME STEP:',16X,'L**3/T'/11X,24(' '),43X,25(' ')/20X,'SOUCHK1640
2RCES:',69X,'STORAGE =',F20.4/20X,8(' '),68X,'RECHARGE =',F20.4/27XCHK1650
3,'STORAGE =',F20.2,35X,'CONSTANT FLUX =',F20.4/26X,'RECHARGE =',F2CHK1660
40.2,41X,'PUMPING =',F20.4/21X,'CONSTANT FLUX =',F20.2,30X,'EVAPOTRCHK1670
5ANSPIRATION =',F20.4/21X,'CONSTANT HEAD =',F20.2,34X,'CONSTANT HEACHK1680

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60:1/27X,'LEAKAGE =' ,F20.2,46X,'IN =' ,F20.4/21X,'TOTAL SOURCES =' ,FCHK1690
720.2,45X,'OUT =' ,F20.4/96X,'LEAKAGE1/20X,'DISCHARGES1',45X,'FROM CHK1700
8PREVIOUS PUMPING PERIOD =' ,F20.4/20X,11(' - '),68X,'TOTAL =' ,F20.4/1CHK1710
96X,'EVAPOTRANSPIRATION =' ,F20.2/21X,'CONSTANT HEAD =' ,F20.2,36X,'SCHK1720
SUM OF RATES =' ,F20.4/19X'QUANTITY PUMPED =' ,F20.2/27X,'LEAKAGE =' ,CHK1730
$F20.2/19X,'TOTAL DISCHARGE =' ,F20.2//17X,'DISCHARGE-SOURCES =' ,F20CHK1740
$.2/15X,'PER CENT DIFFERENCE =' ,F20.2//) CHK1750
270 FORMAT ('FLOW RATES TO CONSTANT HEAD NODES:'/' ',34(' - ')/' ',3(9CHK1760
1X,'K',4X,'I',4X,'J',5X,'RATE (L**3/T)')/' ',3(9X,' - ',4X,' - ',4X,' - 'CHK1770
2,5X,13(' - '))/) CHK1780
280 FORMAT (/(1X,3(I10,2I5,G18.7))) CHK1790
290 FORMAT ('FLOW TO TOP LAYER =' ,G15.7,' FLOW TO BOTTOM LAYER =' ,GCHK1800
115.7,' POSITIVE UPWARD') CHK1810
END CHK1820

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	SUBROUTINE PRNTAI(PHI,STRT,T,S,WELL,DELX,DELY)	PRN 10
C	-----	PRN 20
C	PRINT MAPS OF DRAWDOWN AND HYDRAULIC HEAD	PRN 30
C	-----	PRN 40
C		PRN 50
C	SPECIFICATIONS:	PRN 60
	REAL *8PHI,Z,XLABEL,YLABEL,TITLE,XN1,MESUR	PRN 70
	REAL *4K	PRN 80
C		PRN 90
	DIMENSION PHI(I0,J0,K0), STRT(I0,J0,K0), S(I0,J0,K0), WELL(I0,J0,K0),	PRN 100
	10), DELX(J0), DELY(I0), T(I0,J0,K0)	PRN 110
C		PRN 120
	COMMON /INTEGR/ I0,J0,K0,I1,J1,K1,I,J,K,NPER,KTH,ITMAX,LENGTH,KP,NPRN	PRN 130
	1WEL,NUMT,IFINAL,IT,KT,IHEAD,IDRAW,IFLO,IERR,I2,J2,K2,IMAX,ITMX1,NCPRN	PRN 140
	2H,IDK1,IDK2,IWATER,IQRE,IP,JP,IQ,JQ,IK,JK,K5,IPU1,IPU2,ITK	PRN 150
	COMMON /PR/ XLABEL(3),YLABEL(6),TITLE(6),XN1,MESUR,PRNT(122),BLANK	PRN 160
	1(60),DIGIT(122),VF1(6),VF2(6),VF3(7),XSCALE,DINCH,SYM(17),XN(100),	PRN 170
	2YN(13),NA(4),N1,N2,N3,YSCALE,FACT1,FACT2	PRN 180
	RETURN	PRN 190
C	PRN 200
C		PRN 210
C	---INITIALIZE VARIABLES FOR PLOT---	PRN 220
C	*****	PRN 230
	ENTRY MAP	PRN 240
C	*****	PRN 250
	YDIM=0.	PRN 260
	WIDTH=0.	PRN 270
	DO 10 J=2,J1	PRN 280
10	WIDTH=WIDTH+DELX(J)	PRN 290
	DO 20 I=2,I1	PRN 300
20	YDIM=YDIM+DELY(I)	PRN 310
30	XSF=DINCH*XSCALE	PRN 320
	YSF=DINCH*YSCALE	PRN 330
	NYD=YDIM/YSF	PRN 340
	IF (NYD*YSF.LE.YDIM-DELY(I1)/2.) NYD=NYD+1	PRN 350
	IF (NYD.LE.12) GO TO 40	PRN 360
	DINCH=YDIM/(12.*YSCALE)	PRN 370
	WRITE (6,330) DINCH	PRN 380
	IF (YSCALE.LT.1.0) WRITE (6,340)	PRN 390
	GO TO 30	PRN 400
40	NXD=WIDTH/XSF	PRN 410
	IF (NXD*XSF.LE.WIDTH-DELX(J1)/2.) NXD=NXD+1	PRN 420
	N4=NXD*N1+1	PRN 430
	N5=NXD+1	PRN 440
	N6=NYD+1	PRN 450
	N8=N2*NYD+1	PRN 460
	NA(1)=N4/2-1	PRN 470
	NA(2)=N4/2	PRN 480
	NA(3)=N4/2+3	PRN 490
	NC=(N3-N8-10)/2	PRN 500
	ND=NC+N8	PRN 510
	NE=MAX0(N5,N6)	PRN 520
	VF1(3)=DIGIT(ND)	PRN 530
	VF2(3)=DIGIT(ND)	PRN 540
	VF3(3)=DIGIT(NC)	PRN 550
	XLABEL(3)=MESUR	PRN 560

	YLABEL(6)=MESUR	PRN 570
	DO 60 I=1,NE	PRN 580
	NNX=N5-I	PRN 590
	NNY=I-1	PRN 600
	IF (NNY.GE.N6) GO TO 50	PRN 610
	YN(I)=YSF*NNY/YSCALE	PRN 620
50	IF (NNX.LT.0) GO TO 60	PRN 630
	XN(I)=XSF*NNX/YSCALE	PRN 640
60	CONTINUE	PRN 650
	RETURN	PRN 660
C	PRN 670
C		PRN 680
C	*****	PRN 690
	ENTRY PRNTA(NG,LA)	PRN 700
C	*****	PRN 710
C	---VARIABLES INITIALIZED EACH TIME A PLOT IS REQUESTED---	PRN 720
	DIST=WIDTH-DETX(J1)/2.	PRN 730
	JJ=J1	PRN 740
	LL=1	PRN 750
	Z=NXD*XSF	PRN 760
	IF (NG.EQ.1) WRITE (6,300) (TITLE(I),I=1,3),LA	PRN 770
	IF (NG.EQ.2) WRITE (6,300) (TITLE(I),I=4,6),LA	PRN 780
	DO 290 I=1,N4	PRN 790
C		PRN 800
C	---LOCATE X AXES---	PRN 810
	IF (I.EQ.1.OR.I.EQ.N4) GO TO 70	PRN 820
	PRNT(1)=SYM(12)	PRN 830
	PRNT(N8)=SYM(12)	PRN 840
	IF ((I-1)/N1*N1.NE.I-1) GO TO 90	PRN 850
	PRNT(1)=SYM(14)	PRN 860
	PRNT(N8)=SYM(14)	PRN 870
	GO TO 90	PRN 880
C		PRN 890
C	---LOCATE Y AXES---	PRN 900
70	DO 80 J=1,N8	PRN 910
	IF ((J-1)/N2*N2.EQ.J-1) PRNT(J)=SYM(14)	PRN 920
80	IF ((J-1)/N2*N2.NE.J-1) PRNT(J)=SYM(13)	PRN 930
C		PRN 940
C	---COMPUTE LOCATION OF NODES AND DETERMINE APPROPRIATE SYMBOL---	PRN 950
90	IF (DIST.LT.0..OR.DIST.LT.Z-XN1*XSF) GO TO 240	PRN 960
	YLEN=DELY(2)/2.	PRN 970
	DO 220 L=2,I1	PRN 980
	J=YLEN*N2/YSF+1.5	PRN 990
	IF (T(L,JJ,LA).EQ.0.) GO TO 160	PRN1000
	IF (S(L,JJ,LA).LT.0.) GO TO 210	PRN1010
	INDX3=0	PRN1020
	GO TO (100,110), NG	PRN1030
100	K=(STRT(L,JJ,LA)-PHI(L,JJ,LA))*FACT1	PRN1040
C	-TO CYCLE SYMBOLS FOR DRAWDOWN, REMOVE C FROM COL. 1 OF NEXT CARD-	PRN1050
C	K=AMOD(K,10.)	PRN1060
	GO TO 120	PRN1070
110	K=PHI(L,JJ,LA)*FACT2	PRN1080
120	IF (K) 130,160,140	PRN1090
130	IF (J-2.GT.0) PRNT(J-2)=SYM(13)	PRN1100
	N=-K+.5	PRN1110
	IF (N.LT.100) GO TO 150	PRN1120

	GO TO 190	PRN1130
140	N=N+.5	PRN1140
	IF (N.LT.100) GO TO 150	PRN1150
	IF (N.GT.999) GO TO 190	PRN1160
	INDX3=N/100	PRN1170
	IF (J-2.GT.0) PRNT(J-2)=SYM(INDX3)	PRN1180
	N=N-INDX3*100	PRN1190
150	INDX1=MOD(N,10)	PRN1200
	IF (INDX1.EQ.0) INDX1=10	PRN1210
C	-TO CYCLE SYMBOLS FOR DRAWDOWN, REMOVE C FROM COL. 1 OF NEXT CARD-	PRN1220
C	IF (NG.EQ.1) GO TO 170	PRN1230
	INDX2=N/10	PRN1240
	IF (INDX2.GT.0) GO TO 180	PRN1250
	INDX2=10	PRN1260
	IF (INDX3.EQ.0) INDX2=15	PRN1270
	GO TO 180	PRN1280
160	INDX1=15	PRN1290
170	INDX2=15	PRN1300
180	IF (J-1.GT.0) PRNT(J-1)=SYM(INDX2)	PRN1310
	PRNT(J)=SYM(INDX1)	PRN1320
	GO TO 220	PRN1330
190	DO 200 I=1,3	PRN1340
	JI=J-3+I	PRN1350
200	IF (JI.GT.0) PRNT(JI)=SYM(11)	PRN1360
210	IF (S(L,JJ,LA).LT.0.) PRNT(J)=SYM(16)	PRN1370
220	YLEN=YLEN+(DELY(L)+DELY(L+1))/2.	PRN1380
230	DIST=DIST-(DELX(JJ)+DELX(JJ-1))/2.	PRN1390
	JJ=JJ-1	PRN1400
	IF (JJ.EQ.0) GO TO 240	PRN1410
	IF (DIST.GT.Z-XN1*XSF) GO TO 230	PRN1420
240	CONTINUE	PRN1430
C		PRN1440
C	---PRINT AXES, LABELS, AND SYMBOLS---	PRN1450
	IF (I-NA(LL).EQ.0) GO TO 260	PRN1460
	IF ((I-1)/N1*N1-(I-1)) 270,250,270	PRN1470
250	WRITE (6,VF1) (BLANK(J),J=1,NC), (PRNT(J)+J=1,N8),XN(1+(I-1)/6)	PRN1480
	GO TO 280	PRN1490
260	WRITE (6,VF2) (BLANK(J),J=1,NC), (PRNT(J)+J=1,N8),XLABEL(LL)	PRN1500
	LL=LL+1	PRN1510
	GO TO 280	PRN1520
270	WRITE (6,VF2) (BLANK(J),J=1,NC), (PRNT(J)+J=1,N8)	PRN1530
C		PRN1540
C	---COMPUTE NEW VALUE FOR Z AND INITIALIZE PRNT---	PRN1550
280	Z=Z-2.*XN1*XSF	PRN1560
	DO 290 J=1,N8	PRN1570
290	PRNT(J)=SYM(15)	PRN1580
C		PRN1590
C	---NUMBER AND LABEL Y AXIS AND PRINT LEGEND---	PRN1600
	WRITE (6,VF3) (BLANK(J),J=1,NC), (YN(I),I=1,N6)	PRN1610
	WRITE (6,320) (YLABEL(I),I=1,6)	PRN1620
	IF (NG.EQ.1) WRITE (6,310) FACT1	PRN1630
	IF (NG.EQ.2) WRITE (6,310) FACT2	PRN1640
	RETURN	PRN1650
C		PRN1660
C	---FORMATS---	PRN1670
C		PRN1680

C	-----	PRN1690
C		PRN1700
C		PRN1710
	300 FORMAT ('1',49X,3A8,'LAYER',I4//)	PRN1720
	310 FORMAT ('0EXPLANATION'/' '11(''-')// ' R = CONSTANT HEAD BOUNDARY' /	PRN1730
	1' *** = VALUE EXCEEDED 3 FIGURES'/' MULTIPLICATION FACTOR =',F8.3)	PRN1740
	320 FORMAT ('0',39X,6A8)	PRN1750
	330 FORMAT ('0',25X,10('*'), ' TO FIT MAP WITHIN 12 INCHES, DINCH REVIS	PRN1760
	1ED TO',G15.7,1X,10('*'))	PRN1770
	340 FORMAT ('0',45X,'NOTE: GENERALLY SCALE SHOULD BE > OR = 1.0')	PRN1780
	END	PRN1790-

	BLOCK DATA	BLK 10
C	-----	BLK 20
C		BLK 30
C	SPECIFICATIONS:	BLK 40
	REAL *8XLABEL,YLABEL,TITLE,XN1,MESUR	BLK 50
C		BLK 60
	COMMON /SARRAY/ ICHK(13),LEVEL1(9),LEVEL2(9)	BLK 70
	COMMON /PR/ XLABEL(3),YLABEL(6),TITLE(6),XN1,MESUR,PRNT(122),BLANK	BLK 80
	1(60),DIGIT(122),VF1(6),VF2(6),VF3(7),XSCALE,DINCH,SYM(17),XN(100),	BLK 90
	2YN(13),NA(4),N1,N2,N3,YSCALE,FACT1,FACT2	BLK 100
C	*****	BLK 110
C		BLK 120
	DATA ICHK/'DRAW','HEAD','MASS','DK1','DK2','WATE','RECH','PUN1','PBLK	BLK 130
	1UN2','ITKR',3*0/	BLK 140
	DATA SYM/'1','2','3','4','5','6','7','8','9','10','11','12','13','14','15'	BLK 150
	1 'R','W'/	BLK 160
	DATA PRNT/122* ' ',N1,N2,N3,XN1/6,10,133,.833333333D-1/,BLANK/60*'	BLK 170
	1 ' ',NA(4)/1000/	BLK 180
	DATA XLABEL/' X DIS- ',TANCE IN', ' MILES '//,YLABEL/'DISTANCE', ' BLK	BLK 190
	1FROM OR',IGIN IN ',Y DIRECT',ION, IN ',MILES '//,TITLE/'PLOT BLK	BLK 200
	2OF ',DRAWDOWN', ' ',PLOT OF ',HYDRAULI',C HEAD'/	BLK 210
	DATA DIGIT/'1','2','3','4','5','6','7','8','9','10','11','12','13'	BLK 220
	1,'14','15','16','17','18','19','20','21','22','23','24','25','26',	BLK 230
	2'27','28','29','30','31','32','33','34','35','36','37','38','39',	BLK 240
	340','41','42','43','44','45','46','47','48','49','50','51','52',	BLK 250
	43','54','55','56','57','58','59','60','61','62','63','64','65',	BLK 260
	5','67','68','69','70','71','72','73','74','75','76','77','78',	BLK 270
	6','80','81','82','83','84','85','86','87','88','89','90','91',	BLK 280
	7,'93','94','95','96','97','98','99','100','101','102','103',	BLK 290
	8,'105','106','107','108','109','110','111','112','113','114',	BLK 300
	9,'116','117','118','119','120','121','122'/	BLK 310
	DATA VF1/'(1H ',',',', ' ',A1,F',10.2',')'/	BLK 320
	DATA VF2/'(1H ',',',', ' ',A1,1',X,A8',')'/	BLK 330
	DATA VF3/'(1H0',',', ' ',A1,F',3.1',',12F1',0.2')'/	BLK 340
C	*****	BLK 350
	END	BLK 360-