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FRISK: Computer Program For  
Seismic Risk Analysis Using  
Faults as Earthquake Sources

By  
Robin K. McGuire

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FRISK: COMPUTER PROGRAM FOR SEISMIC RISK ANALYSIS  
USING FAULTS AS EARTHQUAKE SOURCES

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## ABSTRACT

This computer program makes probabilistic seismic hazard calculations at sites affected by earthquakes occurring on faults which are defined by the user as a series of line segments. The length of rupture of the fault as a function of earthquake magnitude is accounted for, and ground motion estimates at the site are made using the magnitude of the earthquake and the closest distance from the site to the rupture zone. Uncertainty in the earthquake magnitude, in the rupture given magnitude, in the location of the rupture zone on the fault, in the maximum possible magnitude of earthquakes, and in the ground motion at the site given the earthquake, its size, rupture length, and location, are accounted for explicitly. FRISK (Fault RISK) was written to take advantage of repeated calculations, so that seismic hazard analyses for several ground motion parameters (for instance, peak ground acceleration, velocity, and displacement), and for several sites, are most efficiently made with one execution of the program rather than with repeated executions.

The program uses a step-truncated exponential distribution for earthquake magnitude, a lognormal distribution for rupture length given magnitude, a uniform distribution for rupture location on faults, and a lognormal distribution of site amplitude given magnitude of the earthquake and distance from the rupture zone to the site. The program has been structured so that other functions may easily be substituted if this is appropriate for a particular problem; for example a wide range of deterministic or probabilistic geophysical models for estimating ground motion may be incorporated, and the program will yield probabilistic estimates of seismic hazard.

## INTRODUCTION

Since the advent of seismic risk analysis methods a decade ago, much work has been done both in applying these methods to engineering problems and in revising these methods to reflect more refined information and theories about seismicity, wave propagation, and the features of seismic ground motion which are critical to engineering structures. One important advance was recognition that the length of fault rupture during an earthquake is an important consideration in probabilistic calculations of seismic hazard.

The computer program described in this document calculates seismic hazard for problems in which the length of fault rupture during an earthquake must be accounted for. Important uncertainties are included in the calculations: uncertainties in the magnitudes of future earthquakes, in the rupture length given magnitude, in the maximum possible magnitude on a fault, and in the seismic ground motion at the site of interest given the earthquake, its rupture length, and its location on the fault.

The program currently uses typical analytical functions to describe seismicity and ground motion propagation from source to site. Coding for the program and the documentation included herein have been written in a manner which will allow easy incorporation of new analytical or empirical functions when these become available, without major reprogramming. The program, as currently written, is not meant to be the final word in seismic risk analysis; it is a tool which can be revised and refined to reflect advances in the state of the art.

In any major programming effort such as this one, there are bound to be errors in coding and in documentation. The experience of users, and the notification of any discovered errors, will be gratefully received by the author. A form is provided at the back of this document to include users' names on a mailing list for notification of changes in the program which correct errors or increase its versatility.

## THEORETICAL BACKGROUND

Methods of probabilistic seismic hazard analysis have been developed and documented over the past decade (for instance, see Cornell, 1968, 1971; McGuire, 1974, 1976; Der Kiureghian and Ang, 1975, 1977). A brief description of the method used by program FRISK is given, along with the explicit and implicit assumptions. The assumptions which can easily be changed, and the re-programming necessary to effect these changes, are also described.

Throughout this documentation, the term "fault" refers to a defined zone in the earth's crust which may be the source of future earthquakes; the term "rupture" refers to the section of a fault which breaks during a specific earthquake. Faults are defined by a series of connected line segments, and earthquakes occur at random locations on these faults. The locations, sizes, and other parameters of successive earthquakes are mutually independent.

The program calculates the probability that a specific ground motion amplitude will be exceeded at the site by a numerical evaluation of the "Total Probability Theorem." (The term "amplitude" here means any quantitative ground motion measure which can be described within the assumptions of the methodology, for instance peak ground acceleration or velocity, spectral velocity, and so on. Modified Mecalli intensity may also be used with certain variations to the input as discussed below. Specifically, the probability that amplitude is exceeded given one event (of random size, rupture length, and location) on a fault, is

$$\begin{aligned}
 & P[\text{amplitude } z \text{ exceeded}] \\
 &= \iiint P[\text{amplitude } z \text{ exceeded} \mid m, l_r(m), x] \\
 & \quad f_M(m) f_L(l_r) f_X(x) \, dm \, dl_r \, dx \qquad (1)
 \end{aligned}$$

where  $M$  is magnitude,  $L_r$  is length of rupture, and  $X$  indicates rupture location on the fault. Given the location and length of rupture, the closest distance from the rupture to the site is calculated, and the probability in the integrand is evaluated. Integration over  $M$ ,  $L_r$ , and  $X$  gives the total probability that amplitude  $z$  will be exceeded due to a single event of random  $M$ ,  $L_r$  and  $X$ . To calculate the expected number of exceedances, this probability is multiplied by the mean activity rate for the time of interest. The total expected number of exceedances is calculated as the

sum of expected numbers from each fault, and the risk at the site for amplitude  $z$  (that is, the probability that  $z$  is exceeded) under the Poisson assumption is determined by

$$\text{Risk (amplitude } z) = 1 - \exp(-\text{total expected number of exceedences of amplitude } z) \quad (2)$$

Ground motion amplitudes associated with specified levels of risk are determined by interpolation using the calculated risks which are next higher and next lower, and using the associated amplitudes. This interpolation is made logarithmically for both amplitudes and risks, because risks usually decrease almost linearly with amplitude when plotted on full logarithmic paper.

The specific functions used in the program for the magnitude, rupture length, and location distributions, and for the distribution of ground motion amplitude given earthquake magnitude and closest distance from the site to the rupture, are discussed below. These distributions may easily be changed if other functions are more appropriate for a specific case.

The magnitude distribution for earthquakes on each fault is modeled by a truncated exponential distribution that is:

$$f_M(m) = k \beta \exp(-\beta(m - m_0)) \quad m_0 \leq m \leq M_1 \quad (3)$$

where  $f_M$  is the magnitude density function,  $m$  is the magnitude of the earthquake,  $m_0$  and  $M_1$  are lower and upper bounds,  $\beta$  is the slope parameter (equal to  $\ln 10$  times the Richter  $b$  value), and  $k$  is equal to  $(1 - \exp(-(M_1 - m_0)))^{-1}$ . The upper bound magnitude  $M_1$  may be given a deterministic value or a discrete distribution (that is, a set of values with associated probabilities). A magnitude distribution other than the truncated exponential is easily incorporated in the program; since integration over magnitude is done numerically in the program, it is necessary only to calculate with the desired distribution the probability that earthquakes occur with sizes in a defined magnitude range. The location in the program for making this change is indicated with comment cards.

The rupture length of an earthquake is uncertain; the distribution of rupture length is taken to be lognormal, with parameters a function of the magnitude of the event. The mean value of the logarithm of rupture length  $l_r$  is assumed to be a linear function of magnitude:

$$\text{mean } \log_{10} l_r = a_1 + b_1 m \quad (4)$$

where  $a_1$  and  $b_1$  are constants. This mean value, and the standard deviation

$\sigma \log_{10} l_r$ , are sufficient to define the rupture length distribution for magnitude  $m$ . As is the case with the magnitude distribution, alternate distributions may be used for rupture length. The appropriate place to make changes to incorporate a different rupture length distribution is indicated with comment cards in the program.

The location of the rupture length is assumed to be equally likely any place on the fault. Computationally, the energy center is defined as the point on the rupture equidistant from the two end points, and its location is assumed to be uniformly distributed any place on the fault except within  $l_r/2$  of the ends. This last restriction ensures that the earthquake cannot rupture past the end of the fault. It is possible to introduce alternate assumptions on rupture location but it may be easier and more appropriate to divide a single fault into several faults with different activity rates. Note, however, that one long fault cannot be represented exactly as several faults laid end-to-end, because earthquakes are not allowed to rupture past the end of any fault.

A myriad of assumptions are possible regarding the temporal process governing earthquake occurrences, with the program as currently written. The form of the input and output is the same, but their interpretations are different. For example, if it is assumed that earthquakes occur as a Poisson process, mean activity rates for each fault are input, and the program outputs both the expected number of times that amplitude levels of interest will be exceeded (consistent with the time period used for activity rates) and the risk associated with these amplitude levels (that is, the probability that they will be exceeded).

Alternately, if any of a wide range of recurrence processes is assumed, the mean rate of occurrence is again input, and the program again computes the expected number of times selected amplitude levels will be exceeded. In this case the total expected number is an estimate of the risk, but is a conservative and generally accurate estimate (as explained below). Finally, in the most general application, if one chooses not to assume any temporal process at all, one inputs (in place of the activity rate for each fault), the probability that an event occurs on that fault during the time of interest. If this number is low (as is generally the case), the probability of multiple events is negligible, and the "Expected Numbers" output by the program are in fact probabilities that the selected amplitudes will be exceeded by earthquakes on a single fault; the "Total Expected Numbers" are conservative and generally accurate estimates of the risk for the amplitudes of concern, for earthquakes on all faults. This last statement follows from the fact that, if  $p_i$  is the probability that an earthquake occurs on fault  $i$  and causes some amplitude level at the site to be exceeded, then

$$\sum_i p_i \gtrsim 1 - \prod_i (1-p_i) \quad (5)$$

The expression on the right is an exact calculation of risk from all faults; the summation of probabilities on the left is an accurate estimate of the risk if the total risk is less than about 0.3. This is usually the case for seismic hazard problems; that is, the amplitudes of interest generally have an associated risk less than 0.3 for the time period of interest.

The ground motion amplitude measure  $Z$  is assumed to be lognormally distributed; parameters of the distribution are a function of source size and distance. The expected value of the logarithm of  $Z$  is given by

$$E(\ln Z) = c_1 + c_2 M + c_3 \ln(R + r_0) \quad (6)$$

where  $Z$  is the amplitude of interest (peak ground acceleration, spectral velocity, etc.),  $M$  is magnitude,  $R$  is distance from the site to the closest point of rupture, and  $c_1$ ,  $c_2$ ,  $c_3$ , and  $r_0$  are constants. Uncertainty in  $\ln Z$  is assumed to be normally distributed, with standard deviation  $\sigma_{\ln Z}$ .

As alternatives to this attenuation function, it is possible to introduce a variety of models to estimate ground motion at the site. At the appropriate place in the program (during integration of equation 1 above), the location of the rupture on the fault is given with respect to the site. A ground motion model which accounts for (for instance) azimuthal and focusing effects as well as source size and distance could easily be introduced. Even a deterministic ground motion function could be introduced; the program would yield probabilistic estimates of ground motion through integration over uncertainties in magnitude, rupture length, and location.

FRISK can be used to calculate probabilities that selected values of Modified Mercalli intensity  $I_s$  will be exceeded at a site. In this case the seismicity of a region is typically described using the maximum Modified Mercalli intensity at the epicenter  $I_e$  to indicate earthquake size, and specifying the activity rate,  $\beta$ , maximum possible size, and rupture length in terms of  $I_e$ . The applicable attenuation function is

$$E(I_s) = c_1 + c_2 I_e + c_3 \ln(R+r_0) \quad (7)$$

and the specified standard deviation  $\sigma_{I_s}$  is used with a normal distribution. In calculating probabilities using Modified Mercalli intensity with the current version of FRISK, intensities are considered a continuous, not a discrete, variable. Thus the user should take care whether, for example, Modified Mercalli intensity  $V$  is correctly represented on the continuous scale as 5.0 or 5.5. When specifying amplitudes for which risks are to be calculated (on card 5 described in the section entitled "Required Input"), the user should input the quantity  $\exp(I_s)$ , because the program takes logarithms of the specified amplitudes to calculate probabilities using attenuation equation (6) or (7).

## PROGRAM OPERATION AND OPTIONS

The program calculates risk according to equation 1 with a series of nested "DO" loops. Operation of the program is shown in figure 1 in an overall sense. The loop on "Problems" allows calculation of risk for several ground motion parameters simultaneously (for instance, peak ground acceleration and displacement). The loop on sites is inside the loops on fault, magnitude, rupture length, and energy center location, so that calculations required to locate a certain rupture on the fault and determine the associated probabilities are made only once for all sites. A result of this efficiency in operation is that calculated risks for each site must be stored (in array "RISK" which has four dimensions) until all calculations are finished.

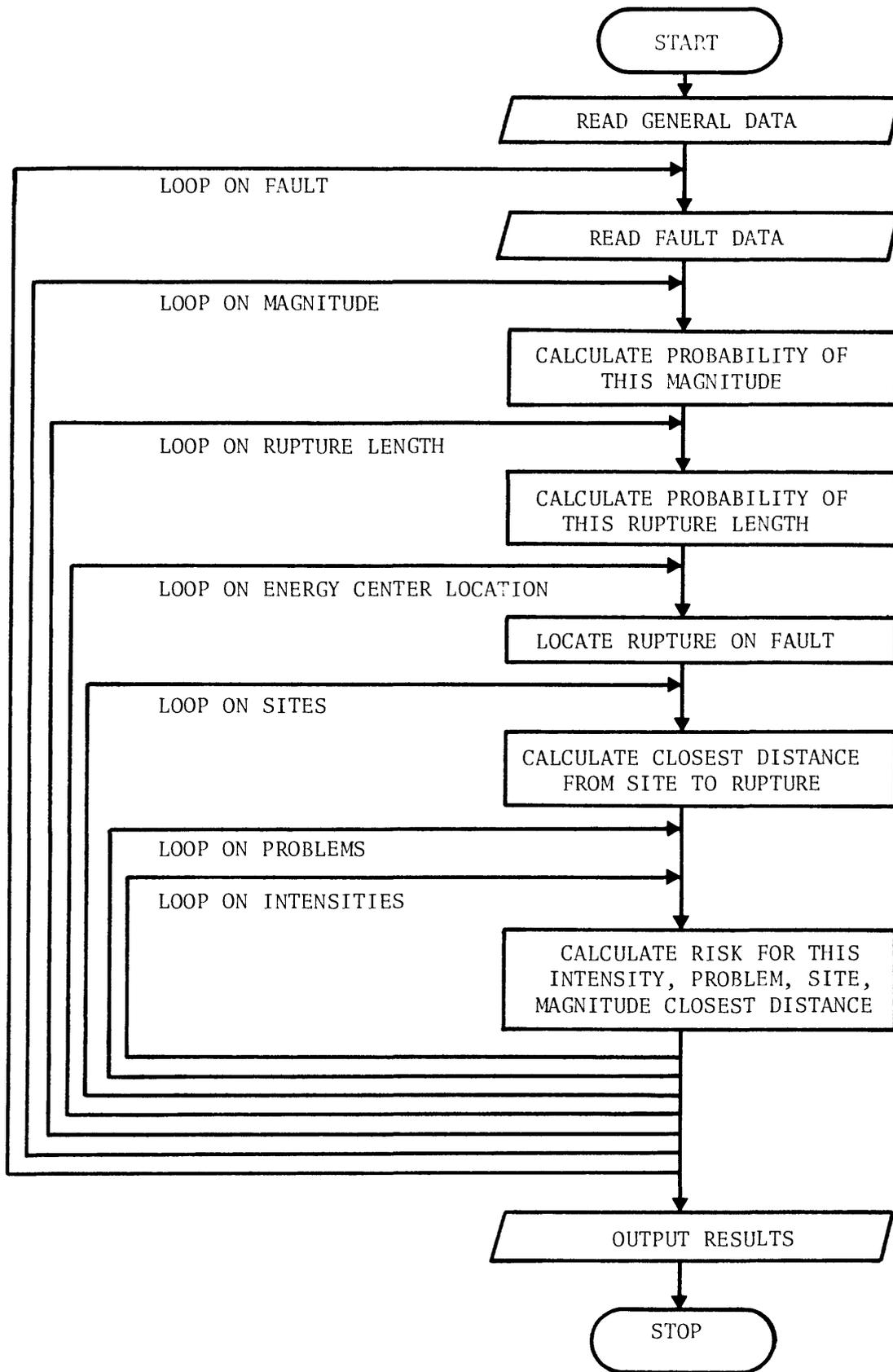


Figure 1.--Macro flowchart of program.

Changes to incorporate a more sophisticated ground motion model than that currently adopted in the program (which uses only magnitude and closest distance to rupture as the controlling variables), are easily accomplished. Within the loop on sites, the location of the rupture on the fault is defined as a series of line segments (the number of which is contained in variable NSRL) with end point coordinates contained in arrays RLX and RLY, from elements 1 through NSRL+1. The site under consideration is located at SITEX(2,JK) and SITEY(2,JK). A visual example is given in figure 2. Site and rupture locations are given in a Cartesian coordinate system; this is the user's system if Cartesian locations were input, and it is a system with origin at the average latitude and longitude of all sites if latitudes and longitudes were used to identify site and fault locations by the user. With the location of the rupture thus defined, virtually any mathematical ground motion model for strike-slip or other faulting can be used to estimate ground motion at the site. Once this model is implemented, the program will integrate over rupture location, rupture length, and magnitude to yield a probabilistic estimate of the ground motion measure of interest.

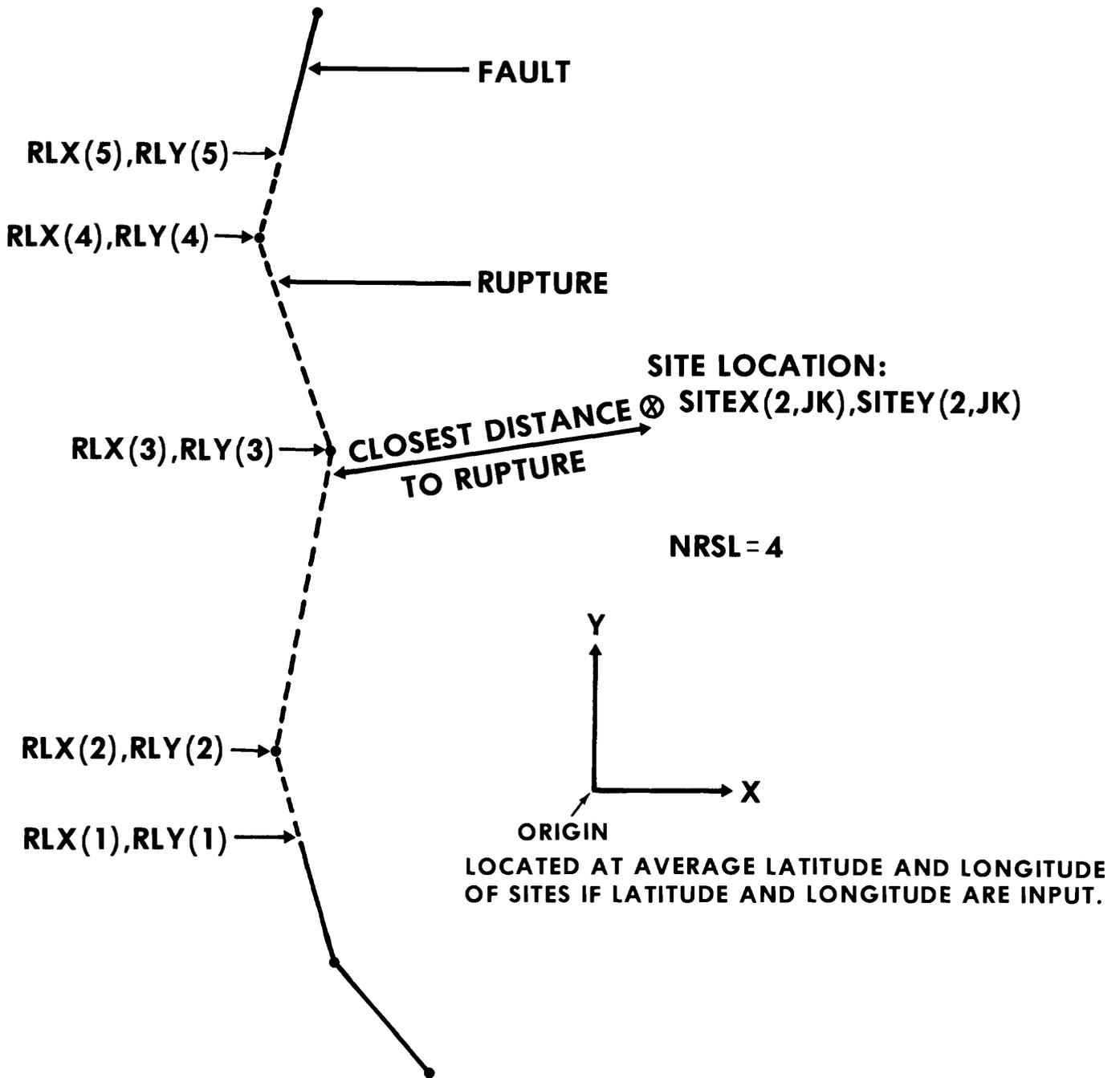


Figure 2.--Typical site and rupture location showing meaning of program variables.

If the risk from a normal or reverse fault were to be calculated, this could be accomplished by changing the program to allow specification of the dip angle (and direction of dip) of the fault. Using the fault line segments to represent the surface expression of faulting, the closest distance to the rupture surface, or any other geometrical variables, could then be computed and used to estimate ground motion at the site; the program would, as usual, integrate over earthquake size and location to calculate seismic hazard.

For a given magnitude the program integrates over possible rupture lengths using equation (3) to determine the mean logarithm of rupture length and assuming a lognormal distribution with standard deviation specified by the user. Computationally, integration is done over the logarithm of rupture length; in general the integration is from the mean value minus two standard deviations, to the mean value plus two standard deviations of  $\log_{10} l_r$ . When the latter value exceeds the total length of the fault, a truncated lognormal distribution is used, and integration is done from the lower value up to the total fault length. When the mean value minus two standard deviations exceeds the fault length, a warning message is printed and all earthquakes of that magnitude are assumed to rupture the entire fault with probability unity.

As noted in the input documentation, as many as five attenuation equations can be input, and risks can be calculated simultaneously for as many as five ground motion measures. These features can be used in several ways. For instance, two attenuation equations (possibly representing peak ground acceleration and peak ground velocity) can be specified, and the program will compute risks for specific values of acceleration and velocity. Alternately, two or more attenuation equations can be input, one for a set of faults and the others for the remaining faults, and risks will be calculated for one ground motion variable using the appropriate attenuation equation for each fault. Combinations of the above applications are also possible. A third use is to specify one attenuation equation and several "problems;" this allows calculation of risk for many amplitude levels. The maximum number of amplitude levels per problem is ten, which results from the standard width of a line printer page.

The program allows input of the maximum possible magnitude  $M_1$  for each fault as a variable with an associated discrete distribution, rather than as a point estimate. Thus the user can account for statistical or professional uncertainty in this variable. (See, for example, McGuire, 1977.) The risk calculated by the program is virtually the same as the weighted risk which would be calculated at a site from a series of faults all identical except for  $M_1$ , with the risk from each fault weighted by the probability associated with its  $M_1$ . (To be theoretically correct, the second approach should be followed. The method used here, replacing a point estimate of  $M_1$ , by a Bayesian or predictive distribution, gives accurate estimates for risks less than about 0.1, when the calculation of risk can be made by multiplying the probability of exceedance from one event by the mean activity rate. The advantage in using a Bayesian distribution for  $M_1$  is efficiency; integration over magnitude is done only once.)

When a distribution for  $M_1$  is specified, the density function and complementary cumulative function for magnitude are:

$$f_M(m) = \beta \exp(-\beta(m-m_0)) \sum_j p_j k_j \quad (8)$$

$$G_M(m) = 1 - [1 - \exp(-\beta(m-m_0))] \sum_j p_j k_j \quad (9)$$

where  $p_j$  is the probability associated with maximum magnitude  $M_{1j}$  when  $m$  is between  $m_0$  and  $M_{1j}$  ( $p_j$  is zero otherwise),  $k_j$  is  $(1 - \exp(-\beta(M_{1j} - m_0)))^{-1}$ , and other variables are as previously defined. The density function and complementary cumulative function are plotted on figures 3 and 4 for the case where  $m_0 = 5.0$ ,  $\beta = 2.0$ , and  $M_1$  is assigned values of 7.0 and 8.0 with equal weights (probability 0.5). This "step-truncated exponential distribution" is compared to the "truncated exponential distribution" obtained if either magnitude 7.0 or 8.0 is selected as a deterministic upper bound.

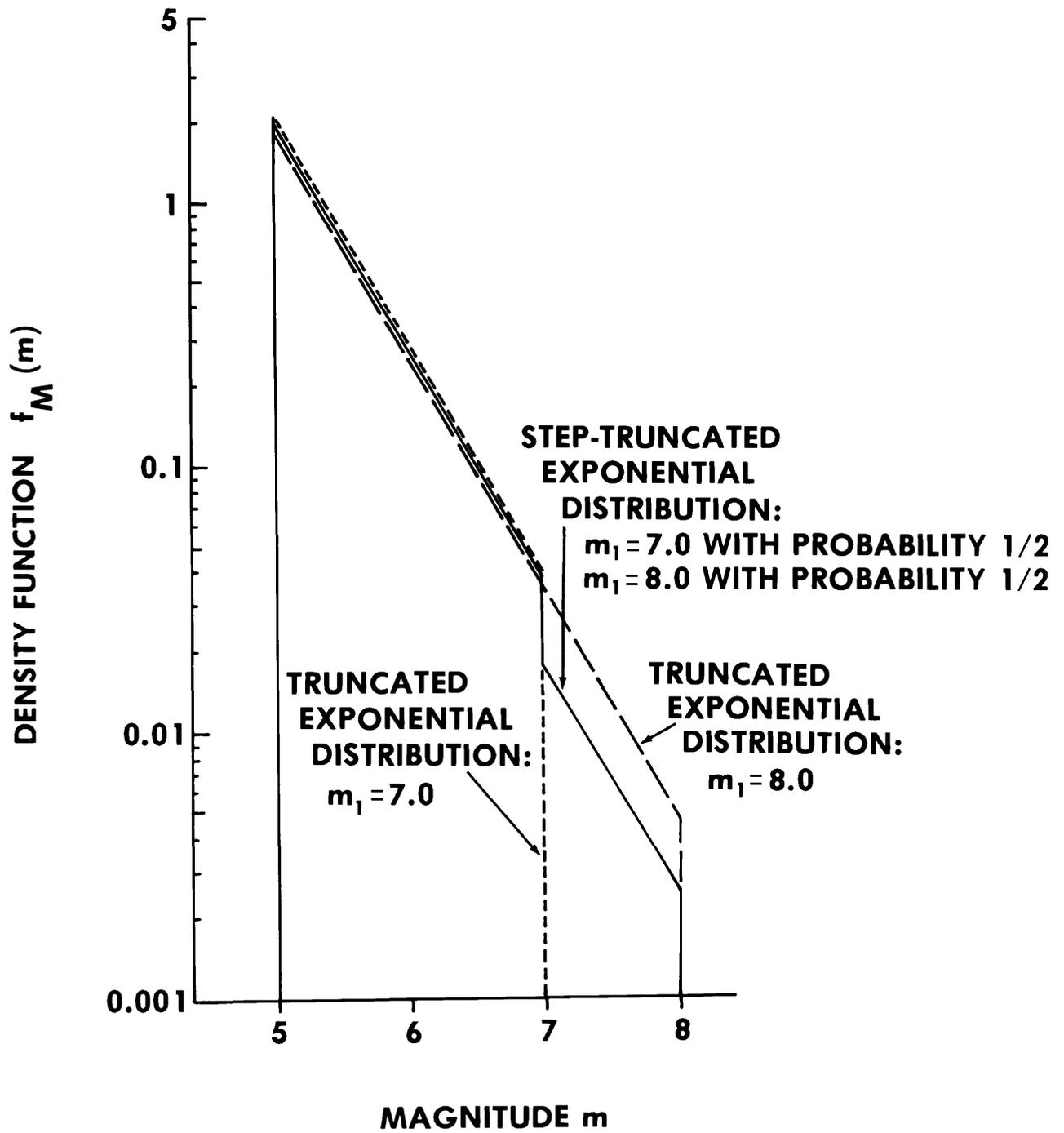


Figure 3.--Density functions for truncated and step-truncated exponential distributions.

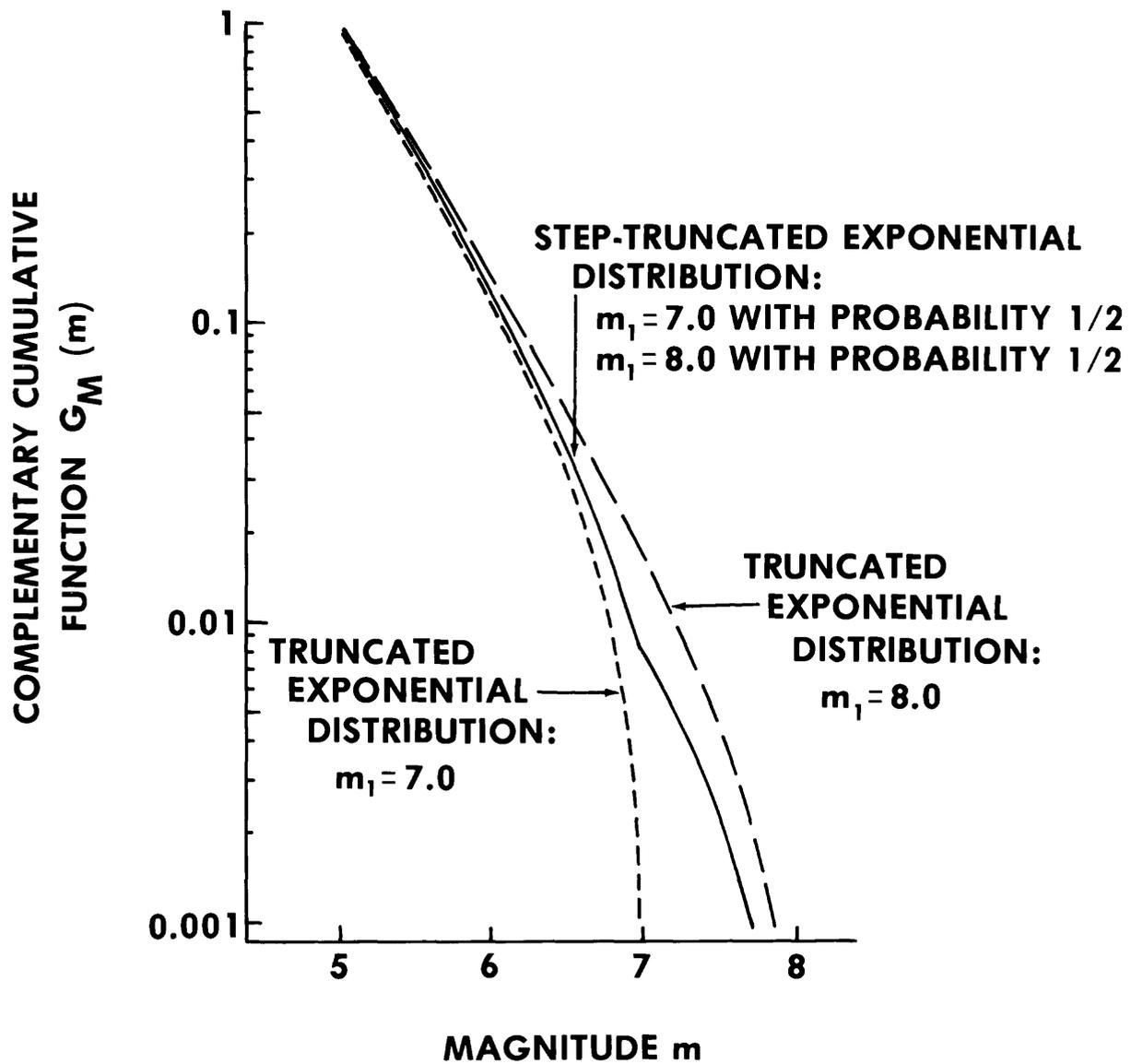


Figure 4.--Complementary cumulative functions for truncated and step-truncated exponential distributions.

## REQUIRED INPUT

Input required for operation of program FRISK is described in this section along with limits on the variables, if any:

CARD 1, FORMAT (20A4). TITLE

This card offers a convenient method of describing the individual seismic risk case being addressed. This title will be printed on the data listing, and on the program output listing. Any 80 characters may be used for this description.

CARD 2, FORMAT (5I3). NFLT, NSITE, NPROB, NATT, LCD.

NFLT indicates the number of faults. It must be between 1 and 10.

NSITE is the number of grids of sites at which risks are to be calculated (see card 7 below for further explanation). The total number of sites (either generated by grids or individually specified) cannot exceed 50 unless dimension statements in the program are changed.

NPROB is the number of ground motion variables for which risks are to be calculated at each site. For example, risks may be calculated for ground acceleration, velocity, and displacement simultaneously with one execution of this program. This variable must be between 1 and 5.

NATT is the number of attenuation functions used in the study. Ordinarily NATT will be greater than or equal to NPROB. In any case, NATT must be between 1 and 5.

LCD indicates whether site and fault coordinates will be input in longitude-latitude (LCD=1) or in an x-y cartesian system (LCD=2). If a longitude-latitude system is used, the program calculates site and fault locations in a cartesian system with the average latitude and longitude of the sites as the origin, assuming a locally flat earth. Units used for the generated cartesian system are kilometers, so if LCD=1, the attenuation functions, rupture length-magnitude relations, and source depths, must use kilometers as the distance measure.

There must be NATT of the following cards:

CARD 3, FORMAT (5F6.3). C1, C2, C3, RZERO, SIGA.

These variables are parameters in the attenuation function:

$$\ln(z) = C1 + C2 * M + C3 * \ln(\sqrt{\Delta^2 + h^2} + RZERO)$$

where z is the ground motion amplitude of interest, M is magnitude,  $\Delta$  is epicentral distance, and h is source depth. SIGA is the standard deviation of this estimation (that is, the standard deviation of  $\ln(z)$ ). If no dispersion is desired, set SIGA to a small number (for example, 0.01) rather than exactly zero.

Cards 4 and 5 form a set; there must be NPROB of these sets:

CARD 4, FORMAT (4A4). DESC.

This card offers the user an opportunity to distinguish among various attenuation equations by labeling them with a 16 character description such as "acceleration" or "velocity." A blank card is required if the user does not wish to use this device.

CARD 5, FORMAT (I3, 3X,10F6.3). NLEI, ATI(1), ATI(2),..ATI(NLEI).

NLEI indicates the number of ground motion amplitudes (for example, acceleration values) to be studied in this problem. This variable must be between 1 and 10.

ATI(1),...

ATI(NLEI) are amplitudes for which expected numbers and risks are calculated at each site. Input values should be, for example, accelerations or velocities, not the logarithms of these quantities. They must be specified in increasing order. If Modified Mercalli intensities are used, the values of ATI must be exponents of intensities, as discussed elsewhere in this documentation.

CARD 6, FORMAT (I3, 3X, 10F6.3). NRSKD, RISKD(1),...RISKD(NRSKD)

NRSKD indicates the number of risks for which the corresponding amplitudes are desired, and RISKD(1),...

RISKD(NRSKD) are the risks. These may be specified in any order. The program calculates amplitudes for each value of RISKD by interpolation from the risks calculated for the input values of ATI; interpolation is done on a logarithmic scale for both risk and intensity. No extrapolation is made for risks outside the range of risks calculated for the amplitudes in ATI. Therefore, if asterisks are obtained for an input value of RISKD(i), the program must be re-run with a wider range of values specified for array ATI (card 5), to obtain the amplitudes corresponding to that RISKD(i).

There must be NSITE of the following cards:

CARD 7, FORMAT (2F6.3,2I3,2F6.3). SX,SY,NX,NY,DX,DY.

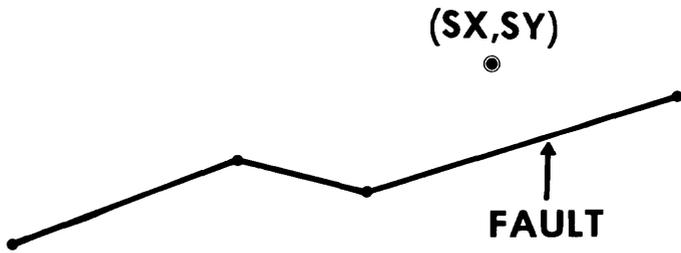
SX,SY are the X and Y coordinates for the site location. They must be in longitude/latitude or Cartesian form according to the value input for variable LCD on card 2.

NX,NY indicate the grid size (number of grid points) in the X (longitude) and Y (latitude) directions, for the site grid. If a grid of sites is not desired, NX and NY should be 0 or 1; in this case risk calculations will be made at only a single site located at SX, SY.

DX,DY indicate the spacing between grid points in the X and Y directions. If no grid is desired, values for these variables may be left blank.

Figure 5 gives a visual explanation of how these variables are used. The total number of sites (that is, number of grid points if a grid is used) cannot exceed 50 without changing dimension statements in the program. Note that in the Western hemisphere longitudes increase to the west, so a specified grid will be generated to the north and west from a site located at SX, SY north of the equator.

**INDIVIDUAL SITE:**



**SITE WITH GENERATED GRID:**

**NX=4**  
**NY=3**

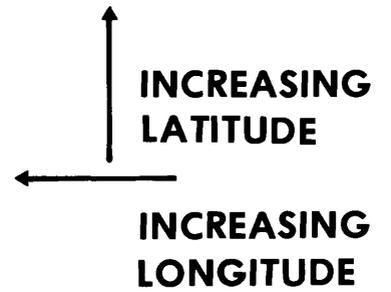
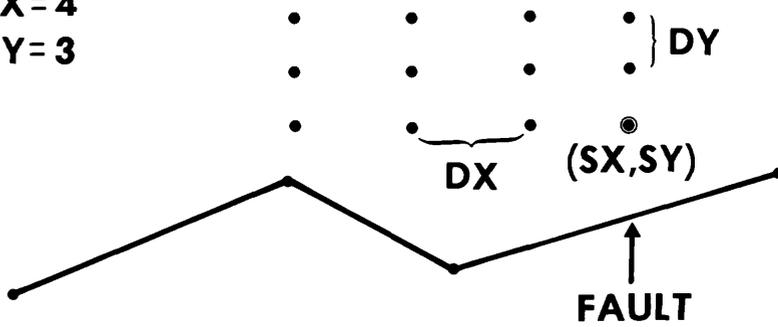


Figure 5.--Examples of site data input on card 7.

Cards 8 through 12 form a set; there must be NFLT of these sets.

CARD 8, FORMAT (12I3). NFP, NRL, IACD(1)...IACD(NPROB).

NFP is the number of points which define this fault as a series of straight line segments. NFP must be between 2 and 20.

NRL is the number of steps to be used in the numerical integration over rupture length. The program integrates from the mean minus 2 standard deviations to the mean plus 2 standard deviations of log 10 (rupture length) dividing this interval into NRL steps. If no dispersion in the rupture length-magnitude relation is desired (that is, SIGL is set to a small number on card 11), NRL should be specified as 1. Otherwise, a larger value (typically 4) must be used. Execution time is proportional to the value input for NRL.

IACD(1)...

IACD(NPROB) indicate, for this fault, which of the attenuation functions is to be used in calculating risks for each of the problems examined in this execution of the program. Typically, if ground acceleration and velocity are to be examined, IACD(1) will indicate an acceleration attenuation function and IACD(2) a velocity attenuation function. Alternately, two or more acceleration attenuation functions may be specified with card 3; then IACD(1) indicates which of these functions apply to this fault.

CARD 9, FORMAT (7F6.3). AMMIN, AMSTEP, RATE, BETA, ECIN, DEPTH, COEF.

AMMIN is the minimum magnitude to be used in calculations for this fault.

AMSTEP is the step size used in numerical integration over magnitude. Execution time is inversely proportional to the value input for AMSTEP. A value between 0.1 and 0.5 should be adequate for most problems.

RATE is the mean number of events per year occurring on this fault, between AMMIN and the maximum magnitude.

BETA is the parameter of the exponential magnitude distribution; it is  $\ln(10)$  times the "Richter b" value of the log number versus magnitude relation.

ECIN is the distance between successive locations of the earthquake rupture zone, as the rupture zone is moved (computationally) along the fault to account for all possible locations. Execution time of the program is inversely proportional to the value input for ECIN. A value between 1 and 10 kilometers should be adequate for most problems.

DEPTH

is the depth of the source. Closest distance to the rupture is calculated using this depth, so if surface rupture is anticipated, a value of zero for depth may be appropriate. On the other hand, if the primary source of seismic energy is thought to be at some depth, a value greater than zero is appropriate even if surface rupture is expected.

COEF

is a weighting coefficient for this fault. Its typical value is unity; however, a value between zero and one may be used to indicate subjective probability on the existence of this fault. (As in the case of probabilities associated with maximum magnitudes discussed above, multiplying expected numbers by the value of COEF results in accurate calculations of risks only when the risks are less than about 0.1. This includes the vast majority of situations for which seismic risk analyses are performed.)

CARD 10, FORMAT (I3,3X,10F6.3). NMAX,AMMAX(1),PMAX(1),...AMMAX(NMAX), PMAX(NMAX).

This card allows a discrete distribution on maximum magnitude to be specified for this fault.

NMAX is the number of maximum magnitudes used to specify this distribution. NMAX must be between 1 and 5.

AMMAX(1) is the lowest magnitude which is considered possible for the maximum magnitude on this fault, and

PMAX(1) is the associated probability.

AMMAX(NMAX) is the highest magnitude which is considered possible for the maximum magnitude on this fault, and

PMAX(NMAX) is its probability.

Values for array AMMAX for elements between 1 and NMAX indicate other possible maximum magnitudes, in increasing order, and elements of array PMAX between 1 and NMAX contain the associated probabilities. The sum of probabilities in array PMAX must be unity.

When choosing values for array AMMAX and for variables AMMIN and AMSTEP on card 8, the magnitude step size AMSTEP should be evenly divisible into the magnitude ranges AMMAX(1)-AMMIN,AMMAX(2)-AMMIN,... AMMAX(NMAX)-AMMIN. Otherwise, small errors will be made by the program in calculating risks.

CARD 11, FORMAT (3F6.3). AL,BL,SIGL.

These variables are parameters in the  
log rupture versus magnitude relation:

$$\text{mean } \log_{10} L_r = AL + BL * M$$

where  $L_r$  is rupture length (in units  
consistent with the distance used in the  
attenuation functions and with the X-Y  
locations of fault points), and M is  
magnitude. SIGL indicates the standard  
deviation of the uncertainty in this  
relationship (that is, SIGL is the  
standard deviation of  $\log_{10} (L_r)$ ). If  
no uncertainty is desired, specify a  
small value (0.01) for SIGL, rather than  
exactly zero, or set NRL=1 on card 8.  
If SIGL is specified to be less than 0.02,  
NRL will be set to 1 automatically by the  
program.

There must be NFP of the following cards:

CARD 12, FORMAT (2F6.3). FX,FY.

FX and FY are locations of the points which define the straight line segments comprising the fault. Two successive points cannot be coincident.

## GUIDELINES FOR PROGRAM USE

Experience with running FRISK to determine seismic risk for a wide variety of problems has lead to several guidelines which users should consider, to avoid unnecessarily long computer runs and inaccurate assessments of seismic hazard. These guidelines apply to typical problems in seismic hazard analysis, and may have to be altered in special cases.

FRISK was designed to be efficient for hazard calculations which model the seismic energy source as a rupture length; as a result, this program is inefficient (but accurate) when used to model point energy sources (that is, sources with rupture lengths of zero). If the source of energy release during an earthquake is modeled as a point rather than as a rupture zone, the user should probably use a program other than FRISK to calculate seismic hazard. Several programs are available (for instance, McGuire, 1976) which make hazard calculations for point sources more efficiently, because (a) numerical integration on magnitude is done inside, rather than outside, numerical integration on location, and (b) if certain typical conditions on the magnitude distribution and attenuation function are met, integration on magnitude can be done analytically for point sources rather than numerically.

Much development work has been done to determine the "best" values for variables NRL, AMSTEP, and ECIN, which control the numerical integrations (see the section on "Required Input"). "Best" in this context means values of the variables which allow accurate calculations with maximum efficiency (lowest computer run time). Suggested values are NRL=4, AMSTEP=0.5, and ECIN=10. A typical seismic hazard problem is shown in figure 6, and the acceleration with 0.01 annual risk at each site was determined using the above suggested values for NRL, AMSTEP, and ECIN. These accelerations are shown in figure 7. Differences in accelerations obtained using other values for NRL, AMSTEP, and ECIN are shown in figure 8. Larger values of ECIN may be used, with little decrease in accuracy; however, it is suggested that the ratio of fault length to ECIN should exceed 20. Similarly, the ratio of the magnitude range to AMSTEP should be five or larger.

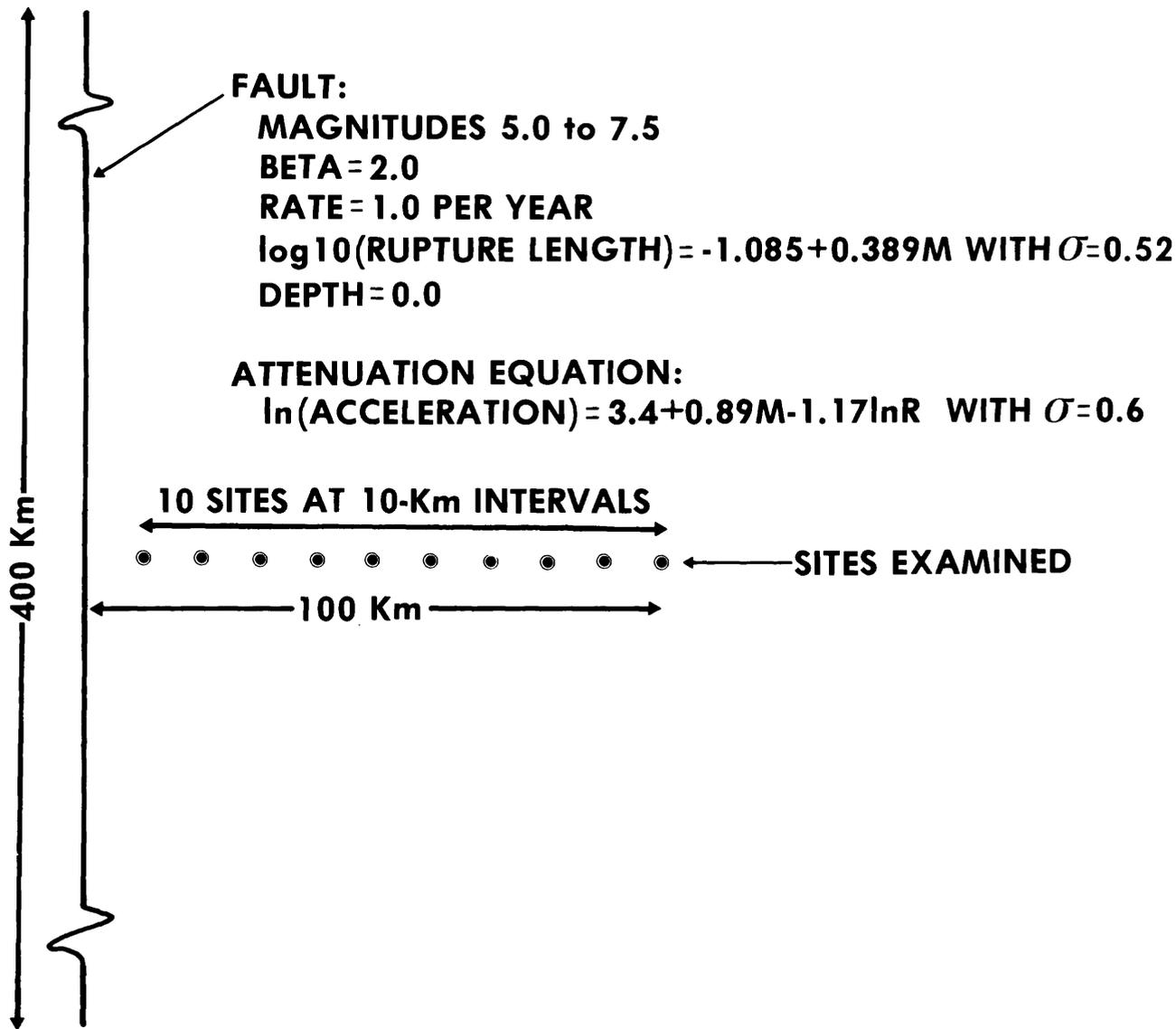


Figure 6.--Geometry and parameters of seismic risk problem used to examine sensitivity of program to NRL-AMSTEP, and ECIN.

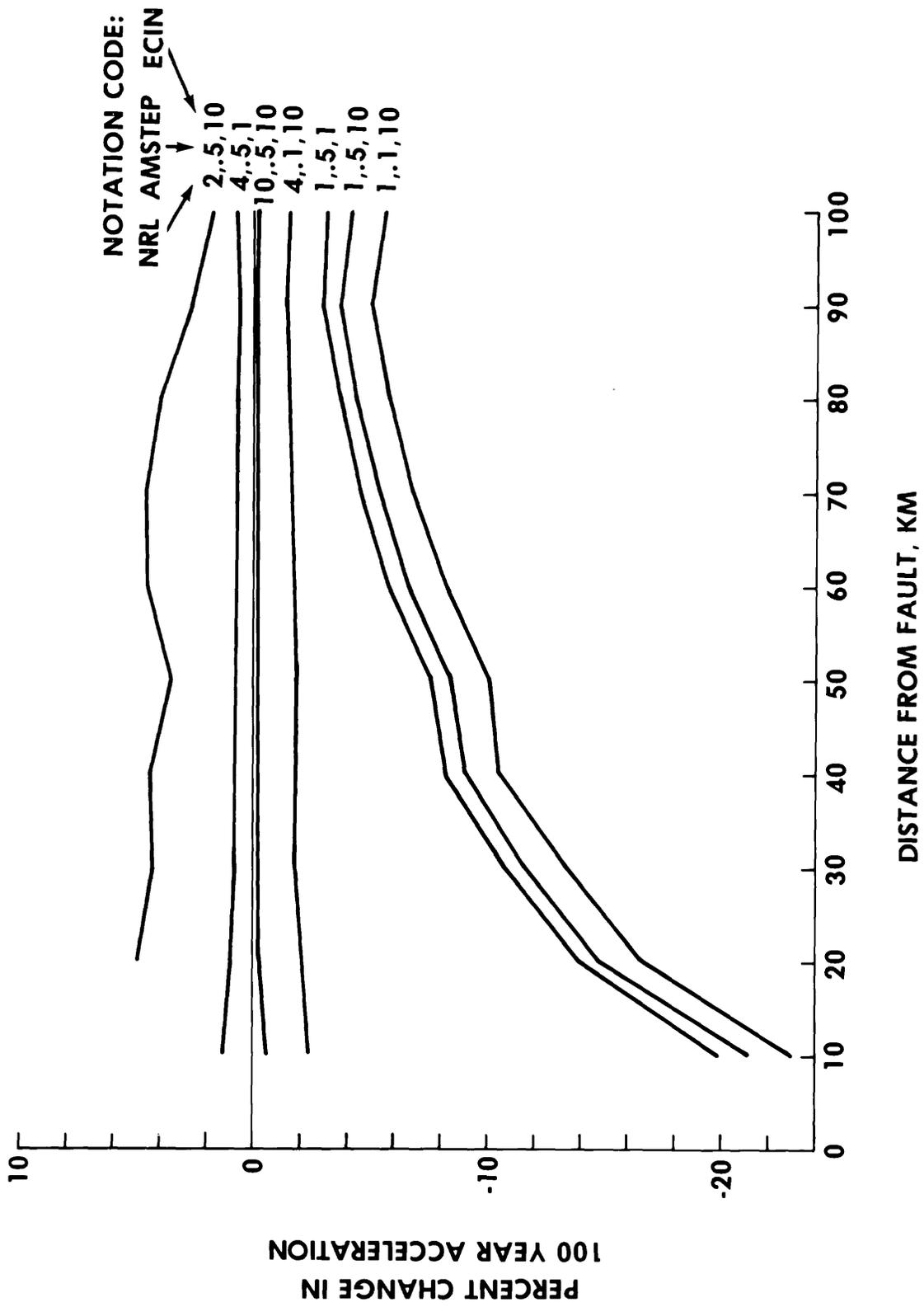


Figure 8.--Changes in 100-year accelerations using alternate values for NRL, AMSTEP, and ECIN.

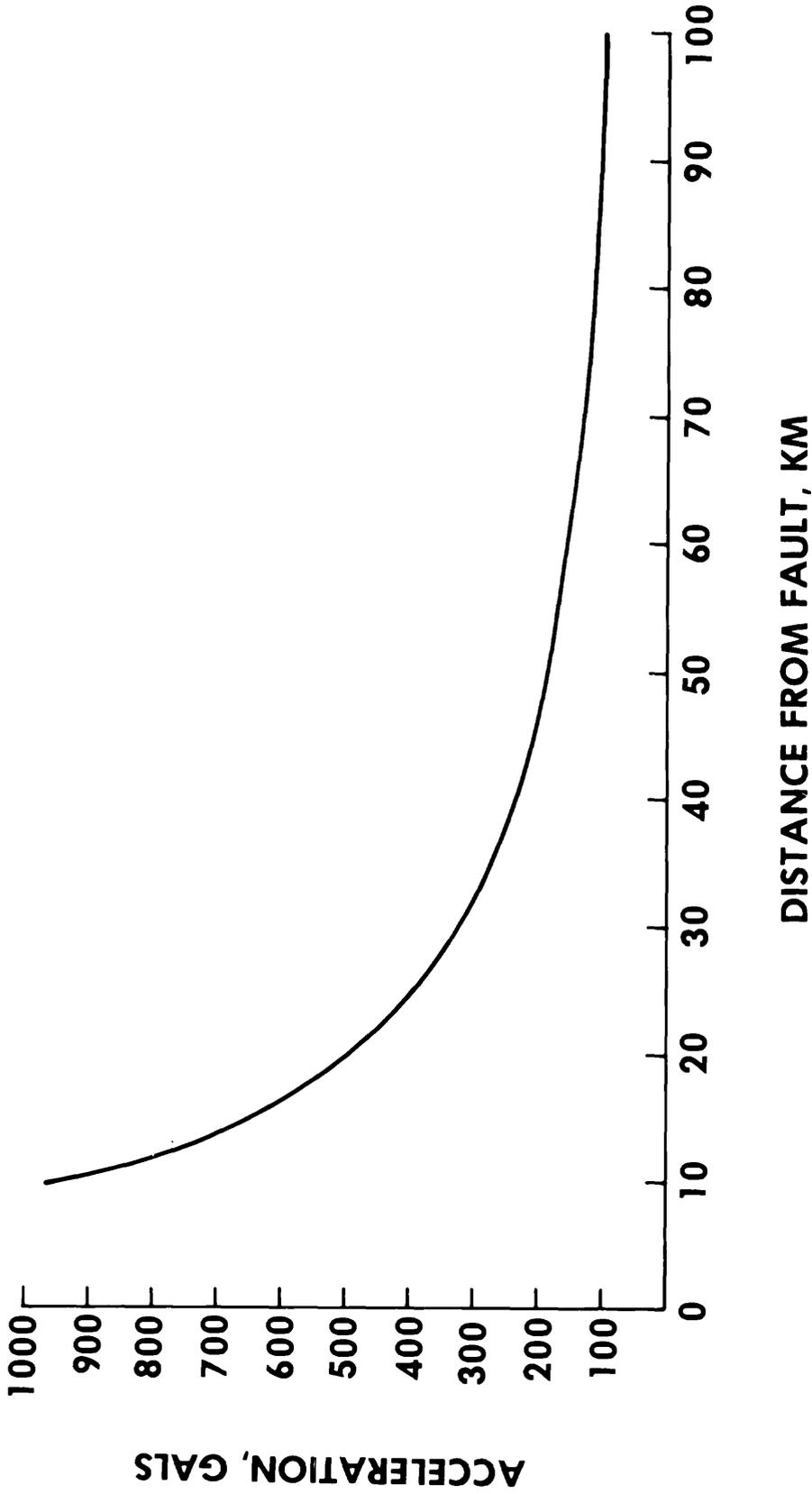


Figure 7.--Acceleration with 0.01 probability of being exceeded at sites 10 to 100 km from fault, using NRL=4, AMSTEP=0.5, and ECIN=10.

On the U.S. Geological Survey's Honeywell Multics<sup>1</sup> computer, execution time of the program can be estimated with the following equation:

$$\begin{aligned} & \text{Execution Time (C.P.U. seconds)} \\ & = \left( \frac{\text{Fault length}}{\text{ECIN}} \right) \left( \frac{\text{Mag. Range}}{\text{AMSTEP}} \right) (\text{NRL}) (\text{NPROB})^{0.7} (\text{NLEI})^{0.5} (\text{NSITE})^{0.9} \frac{1}{500} \quad (10) \end{aligned}$$

Equation 10 assumes that all problems have the same value input for variable NLEI. For more than one fault, the right side of equation 10 should be summed for all faults to estimate execution time. From the form of this equation, it is evident that changes in run time are proportional to changes in values of variables NRL, AMSTEP, and ECIN. Thus these variables should be changed only with extreme caution. Changing each by a factor of 10 could increase execution time by a factor of one thousand! For other computers the constant 1/500 in equation 10 will change, but the influences of the variables will not. Execution time increases less than proportionately to NPROB, NLEI, and NSITE, because integrations over magnitude, location, and length of rupture are done only once for all problems, amplitudes, and sites. Faults specified by a large number of line segments require somewhat more execution time than faults of the same length which are straight.

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<sup>1</sup>Use of brand names in this report is for descriptive purposes only and does not constitute endorsement by the U.S. Geological Survey.

A note of caution should be expressed with regard to including uncertainty in the magnitude-rupture-length equation. While such uncertainty may be inherent in available data, including it in seismic hazard analyses can, in certain instances, result in excessive conservatism. If the variable of interest is peak ground acceleration, a longer-than-expected rupture length for a given magnitude earthquake may correspond to a smaller-than-expected average stress drop over the fault. If this low average stress drop could be expected to generate lower-than-average peak accelerations at a site, not accounting for these lower accelerations in the attenuation equation would result in conservative estimates of the risk, at acceleration levels which are generally of interest. Thus it may be more accurate to ignore the uncertainty in rupture length given magnitude, and do the hazard analysis as if the magnitude-rupture length relationship were a deterministic one.

FRISK was written to take advantage of repeated calculations. Thus, to solve seismic hazard problems, it is most efficiently used when calculations are made during one execution for multiple sites and for all problems and ground motion amplitudes of interest (peak-ground acceleration, velocity, displacement, spectral velocity, and so on), rather than making repeated executions.

## EXAMPLE PROBLEM

An example problem is described in this section, to illustrate the use of various features of program FRISK. Input and output are listed in Appendix A below.

The geometry of the faults and the site are shown in figure 9, along with the values of parameters used to define seismicity on the faults. For both faults the rupture length-magnitude relation used is

$$\text{mean } \log_{10} L_r = -1.085 + 0.389 M \quad (11)$$

with a standard deviation of 0.52.

Four attenuation equations are specified and are used to calculate probabilities for three problems: two for acceleration and one for velocity. In the first problem (labeled "McGuire 78 Accel") the first attenuation equation (which is for ground acceleration) is used for both faults. In the second problem (labeled "Donovan 73 Accel") the second attenuation equation is used. Thus the only difference between the two problems is the attenuation equation. In the third problem, which calculates risks associated with ground velocities, the third attenuation equation is used for fault 1 and the fourth equation for fault 2, to model different velocities that these faults are thought to produce.

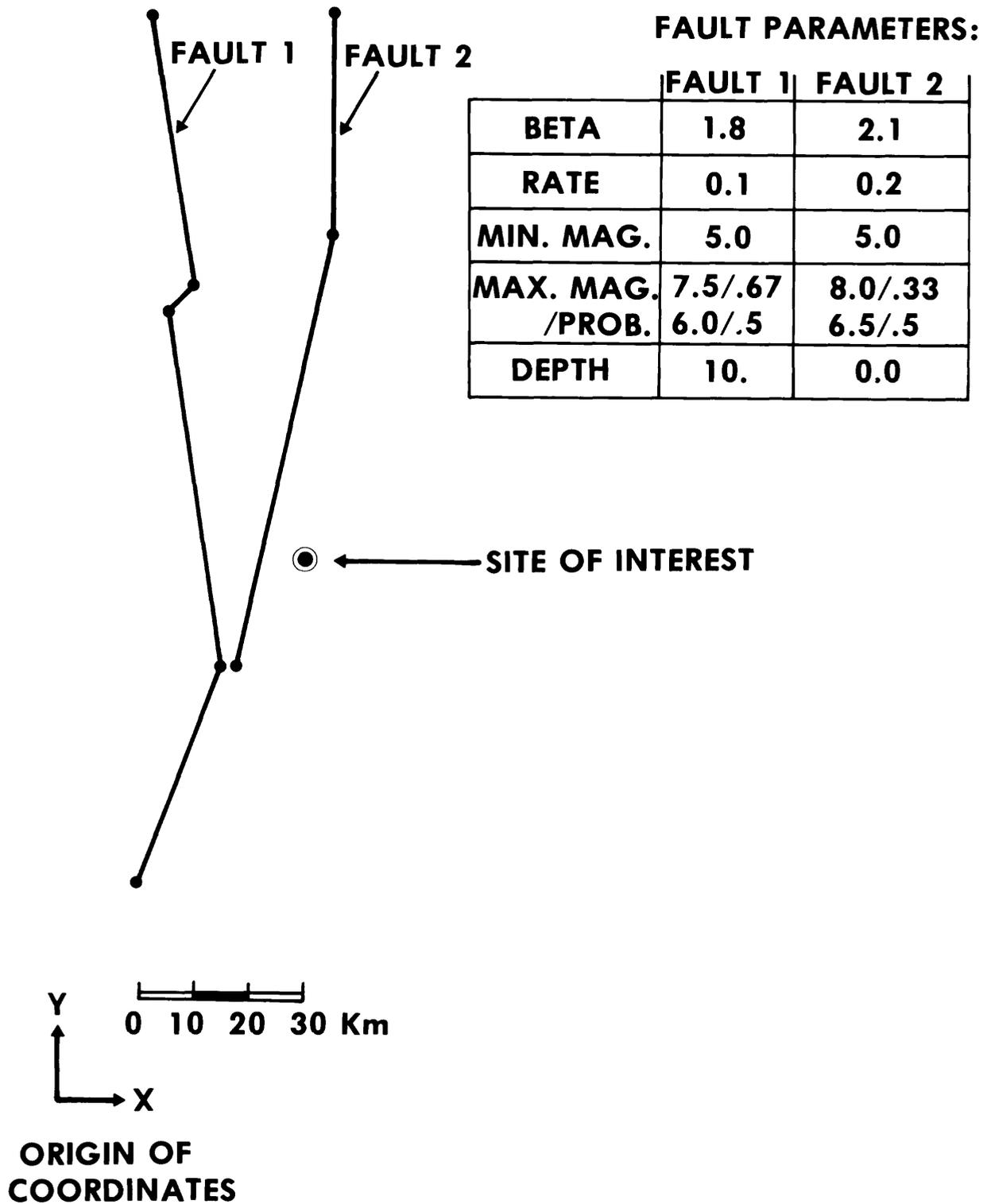


Figure 9.--Faults and site in example problem.

For both faults, step-truncated exponential distributions (figures 3 and 4) are used to describe the distribution of magnitudes, with steps at magnitudes 7.5 and 8 for fault 1 and at 6.0 and 6.5 for fault 2. The minimum magnitude for both faults is magnitude 5.

Output from the program is shown in Appendix A. Risks are calculated for the specified levels of amplitude (acceleration in the first two problems, and velocity in the third). Additionally, amplitude levels are estimated for annual risks of 0.01, 0.002, and 0.001 by interpolation, as described in the section on "Theoretical Background."

Execution time for this problem was 12.5 seconds on a Honeywell Multics computer.

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- Der Kiureghian, Armen, and Ang, A. H-S. (1975), "A Line Source Model for Seismic Risk Analysis," University of Illinois Technological Report, UILU-ENG-75-2023, Ureana, 134 pp, October.
- \_\_\_\_\_ (1977), "A Fault-Rupture Model for Seismic Risk Analysis," Bulletin Seismological Society of America, v. 67, no. 4, pp 1173-1194, August.
- McGuire, R. K. (1974), "Seismic Structural Response Risk Analysis, Incorporating Peak Response Regressions on Earthquake Magnitude and Distance," Massachusetts Institute of Technology, Department of Civil Engineering Report, R74-51, Cambridge, 371 pp, August.
- \_\_\_\_\_ (1976). "Fortran Computer Program for Seismic Risk Analysis," U.S. Geological Survey Open-File Report 76-67, 90 pp.
- \_\_\_\_\_ (1977). "Effects of Uncertainty in Seismicity on Estimates of Seismic Hazard for the East Coast of the United States," Bulletin Seismological Society of America, v. 67, no. 3, pp 827-848, June.

APPENDIX A, EXAMPLE PROBLEM INPUT AND OUTPUT

example problem for open-file report

2	1	3	4	2								
5.85	.961	-1.77	25.	.630								
6.98	0.5	-1.32	25.	.707								
-2.55	1.17	-.729	0.	.657								
-1.41	1.21	-1.01	10.	.649								
McGuire	78	accel										
10	50.	100.	150.	200.	300.	400.	500.	600.	800.	1000.		
Donovan	73	accel										
10	50.	100.	150.	200.	300.	400.	500.	600.	800.	1000.		
velocity	(comb.)											
10.	5.	10.	15.	20.	25.	30.	40.	50.	60.	80.		
3	0.01	0.002	0.001									
50.	100.											
5	4	1	2	3								
5.	.5	.1	1.8	10.	10.	1.0						
2	7.5	.67	8.0	.33								
-1.085	0.389	.52										
15.	40.											
30.	80.											
20.	145.											
25.	150.											
17.	200.											
3	4	1	2	4								
5.0	0.25	0.2	2.1	5.	0.0	1.0						
2	6.0	0.5	6.5	0.5								
-1.085	0.389	0.52										
33.	80.											
50.	160.											
50.	200.											

title: example problem for open-file report

nflt	nsite	nprob	natt	lcd					
2	1	3	4	2					
	c1	c2	c3	czero	siqa				
1	5.850	0.961	-1.770	25.000	0.636				
2	6.980	0.500	-1.320	25.000	0.707				
3	-2.550	1.170	-0.729	0.000	0.657				
4	-1.410	1.210	-1.010	10.000	0.649				

problem data:

McGuire 78 accel amplitudes:									
10	50.000	100.000	150.000	200.000	300.000	400.000	500.000	600.000	800.000 1000.000
Donovan 73 accel amplitudes:									
10	50.000	100.000	150.000	200.000	300.000	400.000	500.000	600.000	800.000 1000.000

velocity (comb.) amplitudes:									
10	5.000	10.000	15.000	20.000	25.000	30.000	40.000	50.000	60.000 80.000

risks specified:  
3 0.0100 0.0020 0.0010

site coordinates:  
1 50.000 100.000

fault information:

-----

fault 1

nfp	nr1	attenuation codes:							
5	4	1 2 3							
brmin	amstep	rate	beta	ecin	depth	coef			
5.000	0.500	0.100	1.600	10.000	10.000	1.000			

nmax ammax pmax  
2 7.50 0.67  
8.00 0.33

a1	b1	sig1
-1.085	0.389	0.520

fault segment coordinates

1	15.000	40.000
2	50.000	80.000
3	20.000	145.000
4	25.000	150.000
5	17.000	200.000

-----

fault 2

nfp nr1 attenuation codes:  
 3 4 1 2 4  
 ammin amstep rate beta ecin depth coef  
 5.000 0.250 0.200 2.100 5.000 0.000 1.000

nmax ammax pmax  
 2 6.00 0.50  
 6.50 0.50

al bl sigl  
 -1.085 0.589 0.520

fault segment coordinates

1 33.000 80.000  
 2 50.000 160.000  
 3 50.000 200.000

site 1 coordinates: 50.000 100.000

McGuire 7d accel amp.: 50.00 100.00 150.00 200.00 300.00 400.00 500.00 600.00 800.00 1000.00  
 log (amplitude): 3.91 4.61 5.01 5.30 5.70 5.99 6.21 6.40 6.68 6.91  
 fault 1 e(no/yr) 0.476e-01 0.230e-01 0.129e-01 0.814e-02 0.593e-02 0.223e-02 0.139e-02 0.927e-03 0.463e-03 0.257e-03  
 fault 2 e(no/yr) 0.104e+00 0.601e-01 0.371e-01 0.239e-01 0.110e-01 0.555e-02 0.303e-02 0.176e-02 0.676e-03 0.293e-03  
 total e(no/yr) 0.152e+00 0.830e-01 0.501e-01 0.321e-01 0.149e-01 0.778e-02 0.443e-02 0.269e-02 0.114e-02 0.553e-03  
 total risk 0.141e+00 0.797e-01 0.488e-01 0.316e-01 0.148e-01 0.775e-02 0.442e-02 0.268e-02 0.114e-02 0.552e-03

specified risks: 0.010000 0.002000 0.001000  
 estimated log amp.: 5.876 6.496 6.725  
 estimated amplitude: 357.127 662.169 832.609

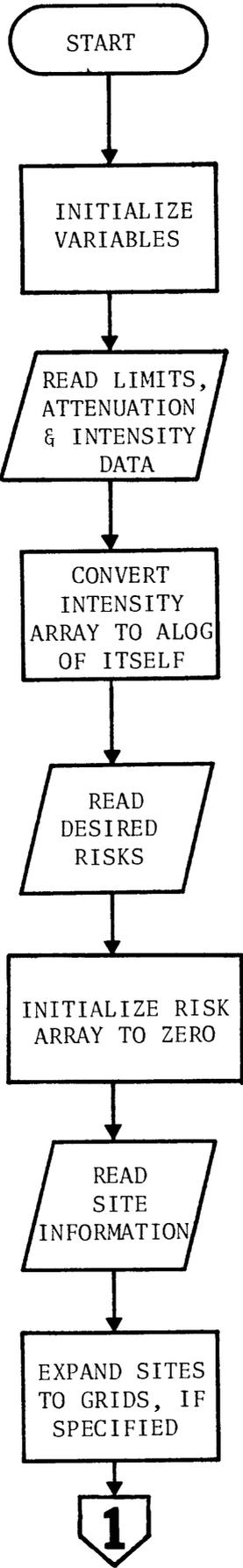
Donovan 73 accel amp.: 50.00 100.00 150.00 200.00 300.00 400.00 500.00 600.00 800.00 1000.00  
 log (amplitude): 3.91 4.61 5.01 5.30 5.70 5.99 6.21 6.40 6.68 6.91  
 fault 1 e(no/yr) 0.667e-01 0.364e-01 0.210e-01 0.128e-01 0.549e-02 0.269e-02 0.145e-02 0.837e-03 0.325e-03 0.146e-03  
 fault 2 e(no/yr) 0.138e+00 0.848e-01 0.549e-01 0.308e-01 0.181e-01 0.966e-02 0.551e-02 0.330e-02 0.133e-02 0.606e-03  
 total e(no/yr) 0.205e+00 0.121e+00 0.758e-01 0.497e-01 0.236e-01 0.124e-01 0.696e-02 0.414e-02 0.166e-02 0.751e-03  
 total risk 0.185e+00 0.114e+00 0.730e-01 0.484e-01 0.233e-01 0.123e-01 0.693e-02 0.413e-02 0.166e-02 0.751e-03

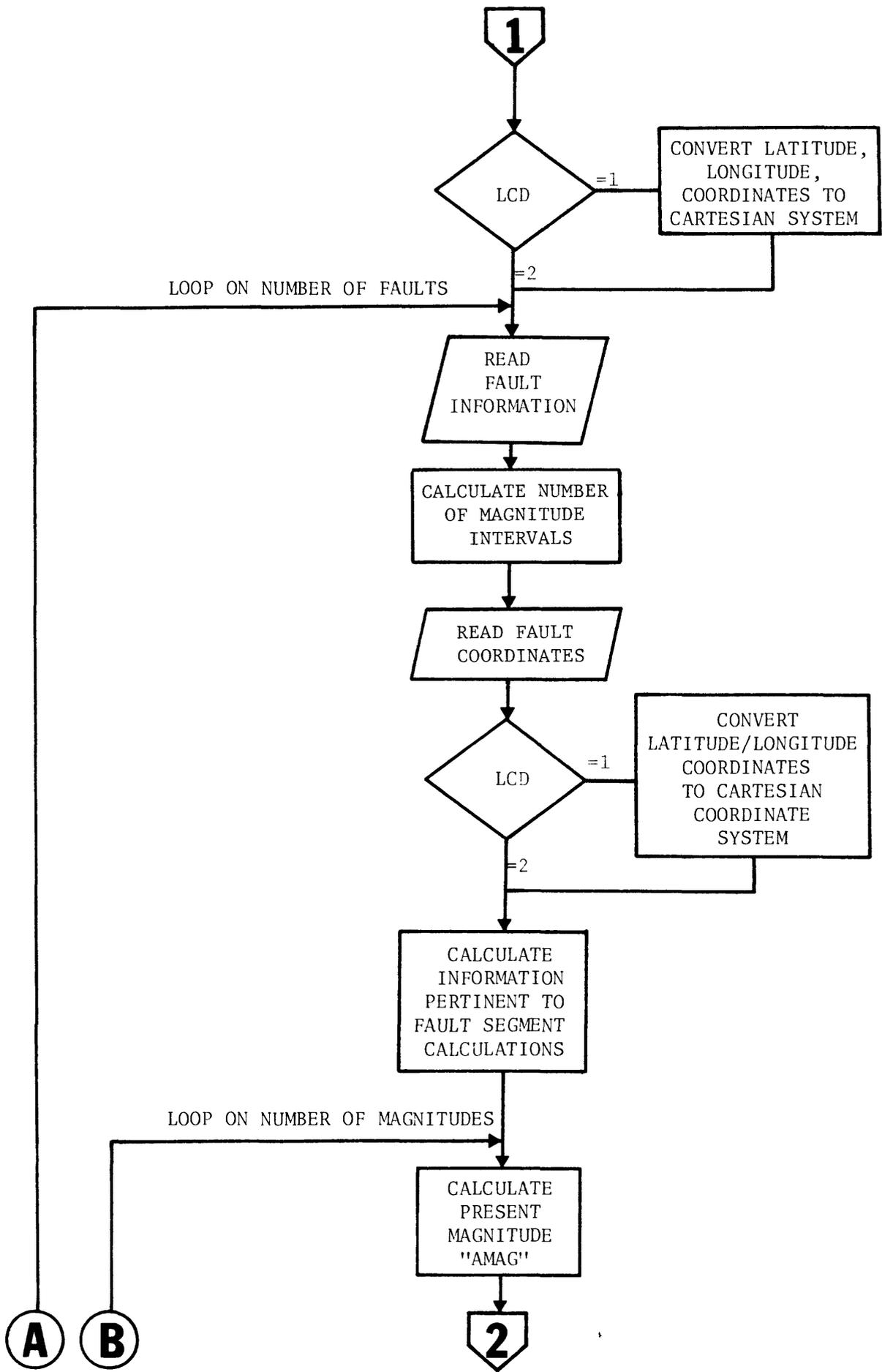
specified risks: 0.010000 0.002000 0.001000  
 estimated log amp.: 6.072 6.625 6.827  
 estimated amplitude: 435.537 754.026 922.428

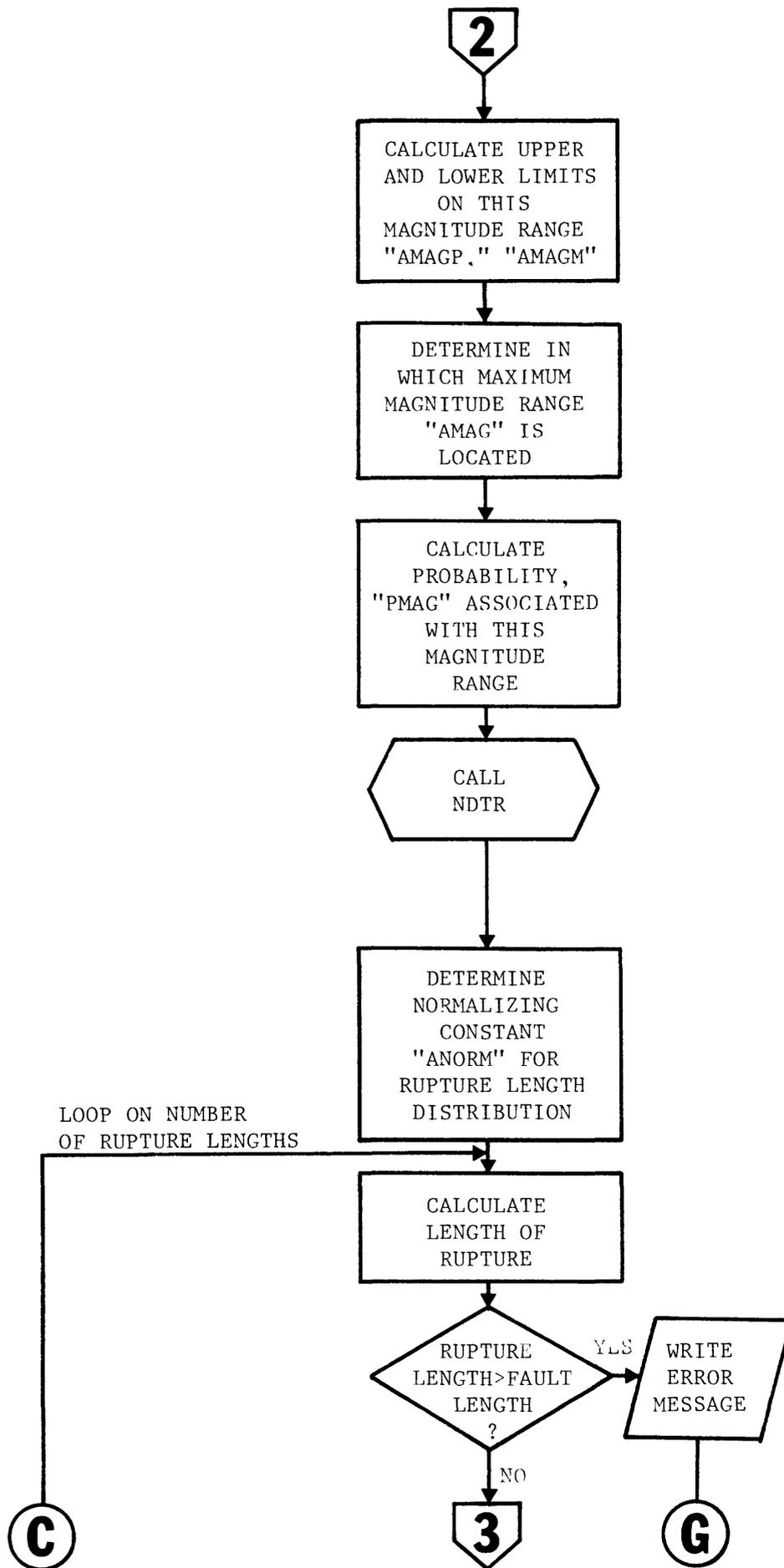
velocity (comb.) amp.: 5.00 10.00 15.00 20.00 25.00 30.00 40.00 50.00 60.00 80.00  
 log (amplitude): 1.61 2.30 2.71 3.00 3.22 3.40 3.69 3.91 4.09 4.38  
 fault 1 e(no/yr) 0.372e-01 0.102e-01 0.907e-02 0.582e-02 0.405e-02 0.298e-02 0.176e-02 0.116e-02 0.603e-03 0.428e-03  
 fault 2 e(no/yr) 0.687e-01 0.438e-01 0.245e-01 0.146e-01 0.946e-02 0.631e-02 0.310e-02 0.168e-02 0.971e-03 0.377e-03  
 total e(no/yr) 0.126e+00 0.600e-01 0.336e-01 0.206e-01 0.135e-01 0.929e-02 0.488e-02 0.284e-02 0.177e-02 0.805e-03  
 total risk 0.118e+00 0.582e-01 0.330e-01 0.204e-01 0.134e-01 0.925e-02 0.487e-02 0.283e-02 0.177e-02 0.805e-03

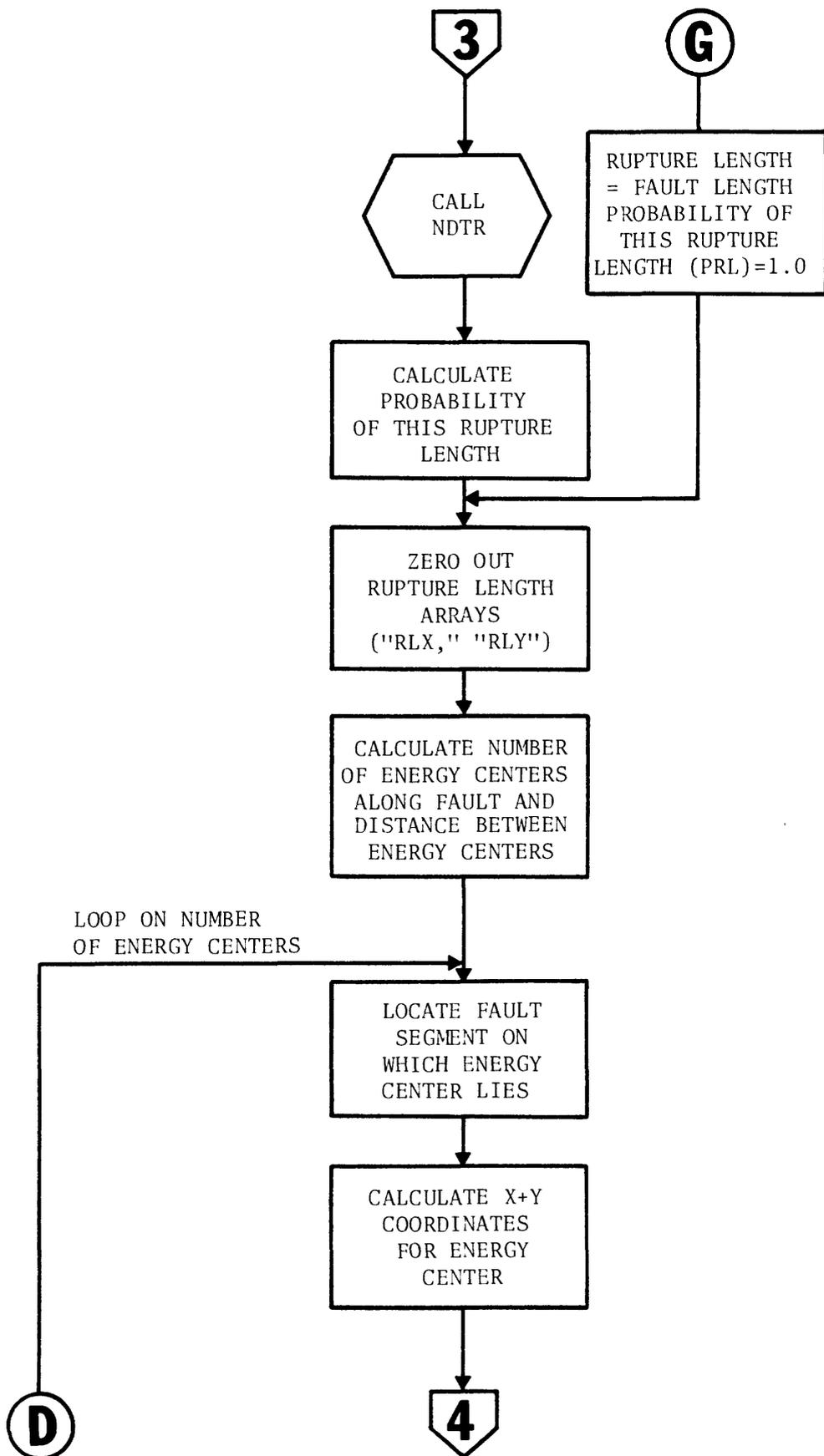
specified risks: 0.010000 0.002000 0.001000  
 estimated log amp.: 3.363 4.047 4.503  
 estimated amplitude: 28.872 57.248 73.918

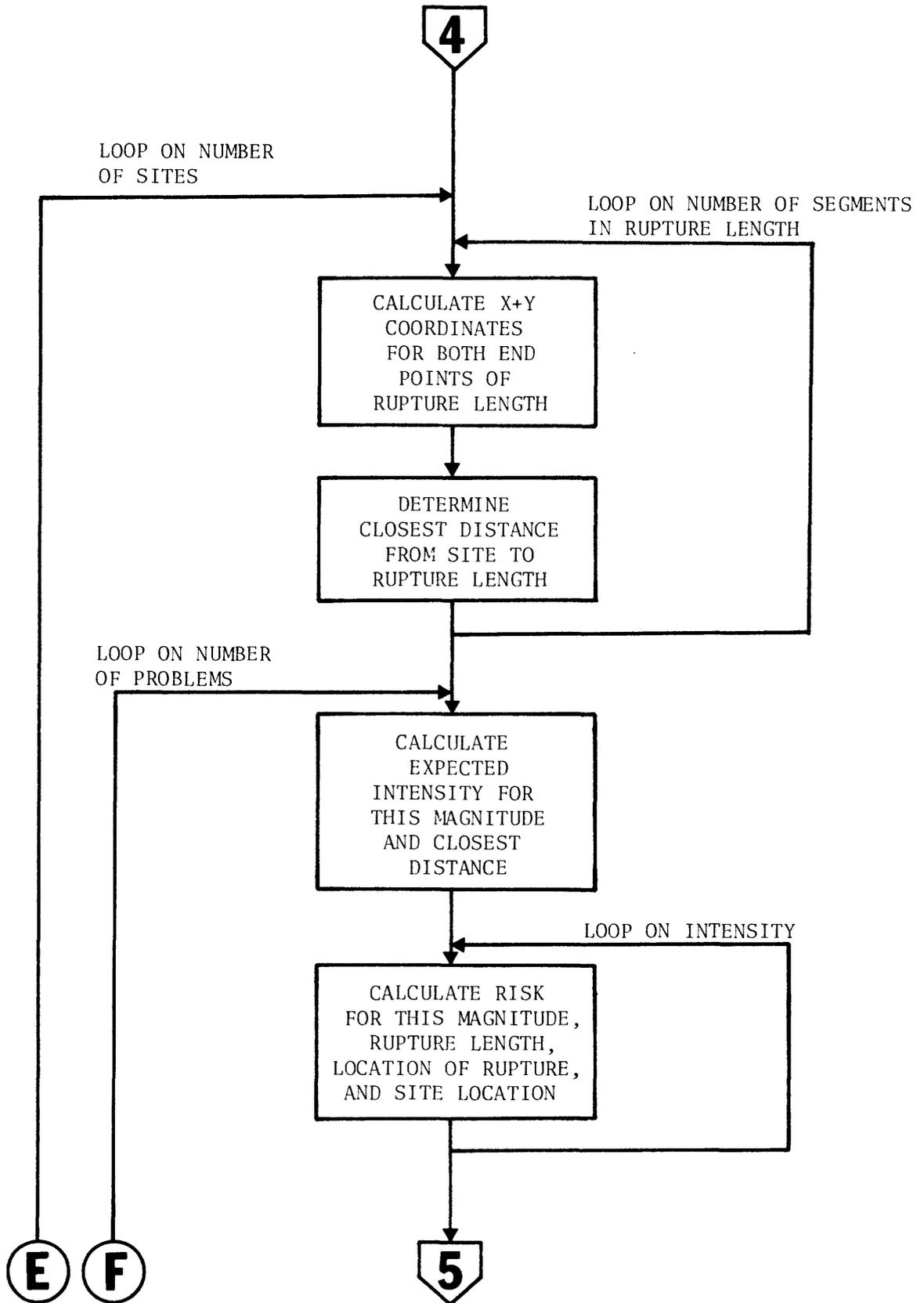
APPENDIX B, PROGRAM FLOW CHART

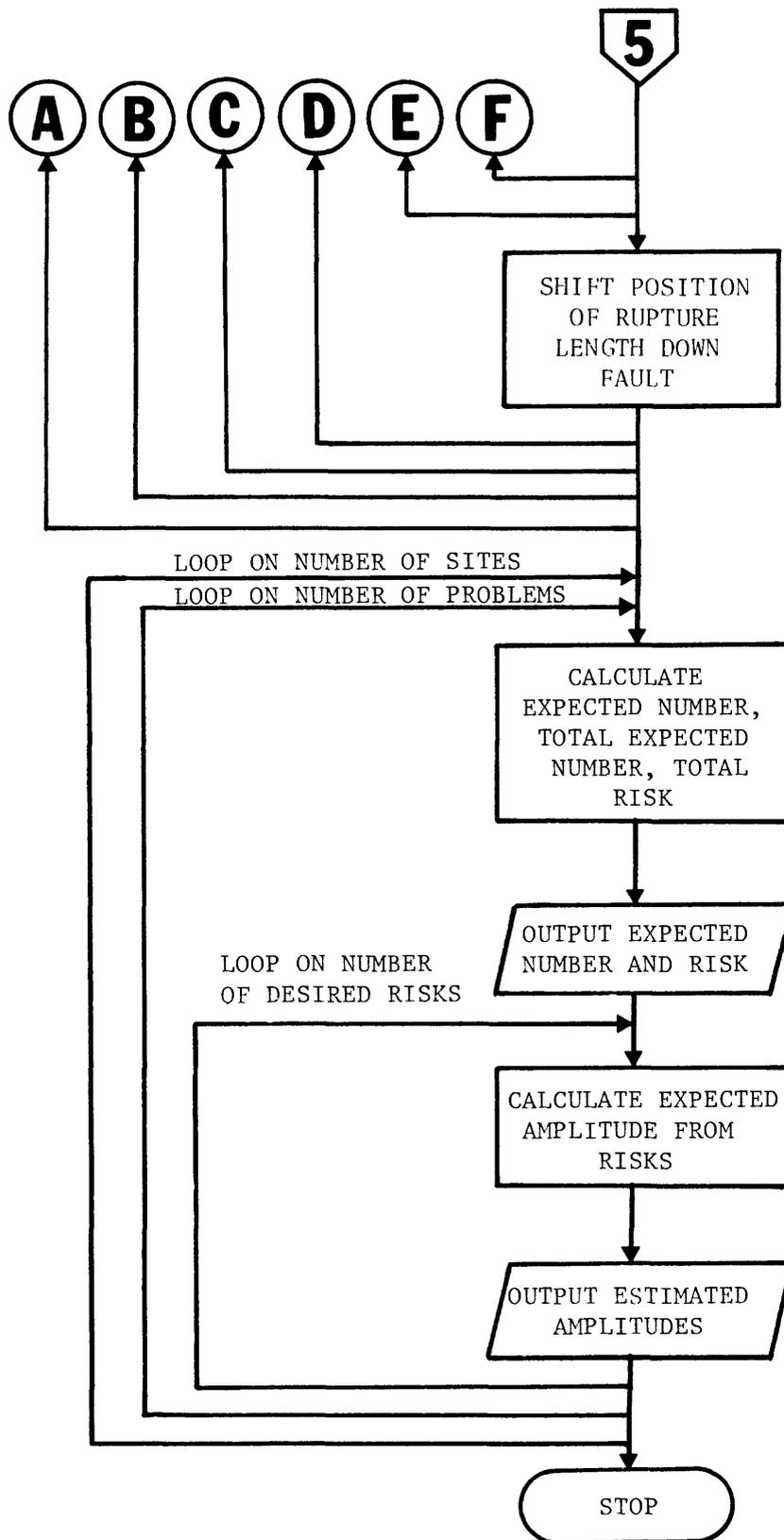












APPENDIX C. PROGRAM LISTING

```

1 c program "frisk" for fault risk analysis
2 c designed by r.k. mc guire
3 c coded by v.l. offer
4 c u.s.g.s. december, 1977 golden colorado
5     dimension sitex(2,50),sitey(2,50),fx(2,20),fy(2,20)
6     dimension xf(2),risk(10,5,50,12),ti(5,10),tif(10),riskd(10)
7     dimension fsl(20),fsa(20),fsb(20),ind(20),ati(5,10)
8     dimension cuml(20),alp(20),clp(20),rlx(20),rly(20),x3(2),y3(2)
9     dimension desc(6,4),c1(5),c2(5),c3(5),siga(5),iacd(5),nlei(5)
10    dimension rzero(5),title(20),amax(5),omax(5)
11 c **the above array sizes were chosen to minimize excess storage. if
12 c larger arrays are needed, the subscripts are organized as follows:
13 c risk(nlei,nprob,nsite,nflt)  ati(nprob,nlei)
14 c sitex(lcd,nsite)  sitey(lcd,nsite)  fx(lcd,nfp)  fy(lcd,nfp)
15 c ti(nprob,nlei)  desc(nprob,1-4)  *****
16 c *****
17 c if you have problems fitting this program on your computer,
18 c change dimension in array "risk" to suit your needs (e.g. if
19 c you are analyzing only 1 site, change the 3rd dimension from
20 c 50 to 1)
21 c *****
22 c the limitations on fsl,fsa,fsb, and other arrays dimensioned
23 c to 20 are the number of fault segment coordinates used to
24 c describe the fault.
25 c "rd" is input device number  "wr" is output device number
26 c "data" is output number for data echo output
27     nrd=2
28     nwr=3
29     ndata=3
30     isite=0
31     c=0.01745329252
32     r=6371.0
33     cr=c*r
34     cuml(1)=0
35     read(nrd,10)(title(i),i=1,20)
36 c title is the actual title given to the output file
37 10     format(20a4)
38     write(ndata,12)(title(i),i=1,20)
39 12     format(//1x,"title: ",20a4)
40     if(wr.eq.data)go to 15
41     write(nwr,12)(title(i),i=1,20)
42 15     read(nrd,20)nflt,nsite,nprob,natt,lcd
43 c nflt=number of faults to be studied.  nsite=number of sites
44 c nprob=number of problems  natt=number of attenuation functions
45 c lcd=1 means data is in lat, long form. lcd=2 indicates x y input.
46 20     format(20i3)
47     write(ndata,30)nflt,nsite,nprob,natt,lcd
48 30     format(/" nflt  nsite  nprob  natt  lcd",/i3,5x,i2,3(6x,i2))
49     write(ndata,40)
50     do 50 i=1,natt
51     read(nrd,35)c1(i),c2(i),c3(i),rzero(i),siga(i)
52 35     format(10f6.3)
53 40     format(/8x,"c1",8x,"c2",8x,"c3",5x," rzero  siga")
54 50     write(ndata,60)i,c1(i),c2(i),c3(i),rzero(i),siga(i)
55 60     format(1x,i2,5f10.3,2x)
56     write(ndata,70)
57 70     format(/" problem data:")
58     do 100 i=1,nprob
59     read(nrd,10)(desc(i,j1),j1=1,4)
60     write(ndata,80)(desc(i,j1),j1=1,4)

```

```

61 80      format(/1x,4a4," amplitudes:")
62 c desc is the description of the attenuation function
63 c example: velocity, or acceleration
64      read(nrd,85)nlei(i),(ati(i,j),j=1,nlei(i))
65 c nlei is number of intensities to be studied, ati contains
66 c the intensities.
67 85      format(i3,3x,10f6.3)
68      write(ndata,90)nlei(i),(ati(i,j),j=1,nlei(i))
69 90      format(3x,i4,4x,10f9.3)
70      do 100 j1=1,nlei(i)
71 100     ti(i,j1)=alog(ati(i,j1))
72 c read in desired risks:
73      read(nrd,85)nrskd,(riskd(ik),ik=1,nrskd)
74      write(ndata,105)nrskd,(riskd(ik),ik=1,nrskd)
75 105     format(/" risks specified:"/,1x,i3,3x,8f10.4)
76      do 110 i1=1,nsite
77      do 110 i2=1,nprob
78      do 110 i3=1,nflt+1
79      do 110 i4=1,nlei(i2)
80 110     risk(i4,i3,i2,i1)=0.0
81 c read in site file
82      write(ndata,120)
83 120     format(/" site coordinates:")
84      do 175 i=1,nsite
85      read(nrd,160)sx,sy,nx,ny,dx,dy
86      if(nx.eq.0)nx=1
87      if(ny.eq.0)ny=1
88      do 140 j=1,ny
89      do 140 k=1,nx
90      isite=isite+1
91      sitey(lcd,isite)=sy+dy*(j-1)
92      sitex(lcd,isite)=sx+dx*(k-1)
93 140     write(ndata,150)isite,sitex(lcd,isite),sitey(lcd,isite)
94 150     format(1x,i2,3x,2f10.3)
95 160     format(2f6.2,2i3,2f6.2)
96 175     continue
97      if(lcd.ne.1)go to 200
98 c calculate site coordinates in cartesian form
99      do 180 i2=1,isite
100      avx=avx+sitex(1,i2)
101 180     avy=avy+sitey(1,i2)
102      t=isite
103      avx=avx/t
104      avy=avy/t
105      zz=cos(avy*c)*cr
106      do 190 i2=1,isite
107      sitex(2,i2)=(sitex(1,i2)-avx)*zz
108 190     sitey(2,i2)=(sitey(1,i2)-avy)*cr
109 200     write(ndata,210)
110 210     format(/" fault information:")
111 c "do 900" is the loop in faults
112      do 900 jf=1,nflt
113      write(ndata,220)jf
114 220     format(/1x,77("-=")//" fault",i2)
115      read(nrd,20)nfp,nrl,(iacd(i),i=1,nprob)
116      write(ndata,240)nfp,nrl,(iacd(i),i=1,nprob)
117 240     format(/" nfp nrl attenuation codes:"/,1x,i2,i7,4x,10i3)
118      do 250 kk=1,nprob
119      if(iacd(kk).gt.natt)write(ndata,260)iacd(kk)
120 250     if(iacd(kk).gt.natt)iacd(kk)=0

```

```

121 260   format(// " ***invalid attenuation code",i2,
122       1 " will default to zero and continue***"//)
123       read(nrd,35)ammin,amstep,rate,beta,ecin,depth,coef
124       write(ndata,270)ammin,amstep,rate,beta,ecin,depth,coef
125 270   format(// " ammin  amstep  rate  beta  ecin  depth",
126       1 "  coef",/1x,f5.3,2f8.3,2f7.3,f8.3,f7.3)
127       read(nrd,85)nmax,(amax(i),pmax(i),i=1,nmax)
128       write(ndata,290)nmax,(amax(i),pmax(i),i=1,nmax)
129 290   format(// " nmax  amax  pmax"/,1x,i2,2x,2(1x,f5.2)/,9(5x,2(1x,f5.2),
130       1 /))
131       read(nrd,35)a1,b1,sig1
132       write(ndata,300)a1,b1,sig1
133 300   format(// "    a1",9x,"b1    sig1",/1x,f7.3,2f10.3)
134       if(sig1.le.0.02)nrl=1
135       if(sig1.le.0.02)write(ndata,280)
136 280   format(// " small uncertainty in rupture length, nrl set = 1")
137       nmaq=(amax(nmax)-ammin+0.01)/amstep
138 c   srl indicates limits on integration over uncertainty in log10
139 c   (rupture length), in standard deviations.
140       srl=2.0
141       anrl=nrl
142       delr1=2.*srl/anrl
143 c   read in fault segment coordinates
144       write(ndata,310)
145 310   format(// " fault segment coordinates")
146       do 320 i=1,nfp
147       read(nrd,35)fx(lcd,i),fy(lcd,i)
148       write(ndata,150)i,fx(lcd,i),fy(lcd,i)
149       if(lcd.ne.1)go to 320
150 c   calculate fault point coordinates in cartesian form
151       fx(2,i)=(avx-fx(1,i))*zz
152       fy(2,i)=(avy-fy(1,i))*cr
153 320   continue
154 350   do 360 i=2,nfp
155       xdelta=fx(2,i)-fx(2,i-1)
156       ydelta=fy(2,i)-fy(2,i-1)
157 c   calculate distance between points, slope of line equation
158       fsl(i)=(xdelta*xdelta+ydelta*ydelta)**.5
159       if(abs(xdelta).lt.0.0001)go to 355
160 c   fsa is the slope of the segment line equation
161 c   fsb is the x y intercept of the segment line equation.
162       fsa(i)=ydelta/xdelta
163       fsb(i)=fy(2,i-1)-fsa(i)*fx(2,i-1)
164 355   ind(i)=1
165       if(abs(xdelta).lt.0.0001)ind(i)=2
166       if(abs(ydelta).lt.0.0001)ind(i)=0
167 c   ind=0 indicates 0 slope.
168 c   ind=1 indicates normal slope
169 c   ind=2 indicates infinite slope
170       cuml(i)=cuml(i-1)+fsl(i)
171 360   continue
172 c   calculate segment distance as percentage of entire fault length,
173 c   and cum distance percent
174       do 370 i=2,nfp
175       alp(i)=fsl(i)/cuml(nfp)*100.0
176 370   clp(i)=cuml(i)/cuml(nfp)*100.0
177 c   "do 800" is numerical integration over magnitude
178       do 800 im=1,nmag
179       a=im
180       amaq=ammin+a*amstep-amstep/2.

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181      amp=amag+amstep/2.
182      amm=amag-amstep/2.
183      do 380 i=1,nmax
184      mrang=i
185 c   mrang indicates magnitude range with respect to max. magnitudes.
186 380      if(amag.le.ammmax(i))go to 390
187 390      ak=0.0
188      do 400 i=mrang,nmax
189 400      ak=ak+pmax(i)/(1.-exp(-beta*(ammmax(i)-ammin)))
190 c   pmag is probability of magnitude between amp and amm.
191 c   Insert an alternative function if the step-truncated
192 c   exponential is not desired.
193      pmag=ak*(exp(-beta*(amm-ammin))-exp(-beta*(amp-ammin)))
194      all=log10(cuml(nfp))
195      aa=(all-a1-b1*amag)/sig1
196      call ndtr(aa,f0,d)
197      if(f0.eq.1.0)anorm=0.0
198      if(f0.eq.1.0)go to 410
199      anorm=1./(1.-f0)
200 c   "do 700" is numerical integration over length of rupture
201 410      do 700 ir1=1,nr1
202      ar1=-sr1+ir1*delr1-delr1/2.
203      arlp=ar1+delr1/2.
204      arlm=ar1-delr1/2.
205      r1=10.0**((a1+b1*amag+ar1*sig1)
206      if(r1.le.cuml(nfp))go to 430
207      if(ir1.gt.1)go to 800
208      pr1=1.0
209      write(nwr,420)r1,jf,cuml(nfp),amag
210 420      format(" **caution** mean-2 sigma rupture length (" ,f7.3," ) is",
211      1 " greater than fault",i2," length (" ,f7.3," ). for magnitude:"
212      1 ,f5.3)
213      r1=cuml(nfp)
214      go to 440
215 430      call ndtr(arlm,f1,d)
216      call ndtr(arlp,f2,d)
217      if(ir1.eq.1)f1=1.0
218      if(ir1.eq.nr1)f2=f0
219 c   pr1 is probability of rupture length between
220 c   10.**((a1+b1*amag+arlm) and
221 c   10.**((a1+b1*amag+arlp).
222 c   Insert an alternative function if the lognormal is not desired.
223      pr1=(f1-f2)*anorm
224 c   zero out rupture length arrays:
225 440      do 450 kj=1,20
226      rlx(kj)=0
227 450      rly(kj)=0
228 c   calculate number of energy centers along fault and the distance
229 c   between energy centers
230      in=(cuml(nfo)-r1)/ecint+1.999
231      if(in.eq.1)in=2
232 c   stsz is energy center step size in percent
233      stsz=(100.0-((r1)/cuml(nfp))*100.0)/(in-1)
234 c   xf(1) is the location in percentage along the fault where the
235 c   rupture length begins, and xf(2) is the end point, also in %
236      xf(1)=0.0
237      xf(2)=(r1/cuml(nfp))*100.0
238      kseq=1
239 c   kseq is fault segment on which energy center is located.
240 c   "do 600" is numerical integration over rupture location

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241      do 600 ik=1,in
242 c   ecp is the energy center location as a percent along the fault length
243     ecp=(xf(2)-xf(1))/2,+xf(1)
244 c   locate segment on which energy center is located
245     do 460 kt=kseg,nfp-1
246       kseg1=kt+1
247 460     if(ecp.le.clp(kseg1))go to 470
248 470     kseg=kt
249       b=clp(kseg1)-ecp
250       a=alp(kseg1)-b
251 c   calculate energy center x and y coordinates
252     ecx=(b*fx(2,kseg)+a*fx(2,kseg1))/(a+b)
253     ecy=(b*fy(2,kseg)+a*fy(2,kseg1))/(a+b)
254     do 475 m=1,2
255       do 475 n=1,nfp-1
256         if(xf(m).gt.clp(n+1))go to 475
257         b=clp(n+1)-xf(m)
258         a=alp(n+1)-b
259 c   ns1 is segment on which beginning of rupture length lies
260 c   ns2 is segment on which end of rupture length lies.
261     if(m.eq.1)ns1=n
262     if(m.eq.2)ns2=n
263 c   calculate x and y coordinates for both end points of rupture length
264     x3(m)=(b*fx(2,n)+a*fx(2,n+1))/(a+b)
265     y3(m)=(b*fy(2,n)+a*fy(2,n+1))/(a+b)
266 475     continue
267 c   nsr1 is number of segments in rupture length
268     nsr1=ns2-ns1+1
269     rlx(1)=x3(1)
270     rlx(nsr1+1)=x3(2)
271     rly(1)=y3(1)
272     rly(nsr1+1)=y3(2)
273     if (nsr1.eq.1)go to 490
274     ji=0
275     do 480 j=2,nsr1-1
276       ji=ji+1
277       rlx(j)=fx(2,ns1+ji)
278 480     rly(j)=fy(2,ns1+ji)
279 c*****
280 c   coding between asteriks calculates closest distance to this
281 c   rupture for site jk
282 c   there are nsr1 line segments in this rupture length. points
283 c   defining rupture are contained in arrays rlx(i) and rly(i) from
284 c   elements 1 to nsr1 + 1.
285 c   probability of this magnitude is pmag
286 c   probability of this rupture length is prl
287 c   probability of this location of rupture length is 1/in
288 c   site coordinates (x,y) are in arrays sitex(2,jk) and sitey(2,jk)
289 c   sitex(1,jk) and sitey(1,jk) contain latitude,longitude coordinates,
290 c   if used.
291 c   energy center is located at ecx,ecy
292 490     do 570 jk=1,site
293       cd=99999.
294       do 550 k=1,nsr1
295         k1=k+1
296 c   calculate distance from site to both end points of rupture
297 c   length segment and distance from site to perpendicular dropped
298 c   on segment length
299       s1=((rlx(k)-sitex(2,jk))**2+(rly(k)-sitey(2,jk))**2)**.5
300       s2=((rlx(k1)-sitex(2,jk))**2+(rly(k1)-sitey(2,jk))**2)**.5

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301      a=fsa(k1)
302      if(ind(k1).eq.2)go to 500
303      if(ind(k1).ne.0)go to 510
304      xp=sitex(2,jk)
305      yp=rly(k)
306      go to 520
307 c   xp and yp are the x & y intercepts of the perpendicular from the
308 c   site to the rupture length.
309 500   yp=sitey(2,jk)
310       xp=rlx(k)
311       go to 520
312 510   xp=(sitey(2,jk)+(sitex(2,jk)/a)-fsb(k1))/(a+(1/a))
313       yp=((sitex(2,jk)-xp)/a)+sitey(2,jk)
314 520   perp1=(((sitex(2,jk)-xp)**2+(sitey(2,jk)-yp)**2)**.5
315 c   determine closest distance and store it
316 c   cd is the closest distance from the site to the rupture length.
317       cd=amin1(s1,s2,cd)
318       if(ind(k1).eq.2)go to 530
319       if(xp.ge.rlx(k).and.xp.le.rlx(k1))cd=amin1(perp1,cd)
320       if(xp.ge.rlx(k1).and.xp.le.rlx(k))cd=amin1(perp1,cd)
321       go to 550
322 530   if(yp.ge.rly(k).and.yp.le.rly(k1))cd=amin1(perp1,cd)
323       if(yp.ge.rly(k1).and.yp.le.rly(k))cd=amin1(perp1,cd)
324 550   continue
325 c*****
326 c   "eti" is expected intensity for this magnitude and closest distance
327       do 560 jj=1,nprob
328         if(iacd(jj).eq.0)go to 560
329         eti=c1(iacd(jj))+c2(iacd(jj))*amag+c3(iacd(jj))*alog((cd*cd
330 1 +depth*depth)**.5+rzero(iacd(jj)))
331         do 560 i=1,nlei(jj)
332           w=(ti(jj,i)-eti)/siqa(iacd(jj))
333           call ndtr(w,g,d)
334           ain=in
335           risk(i,jj,jf,jk)=risk(i,jj,jf,jk)+coef*rate*g*pmag*prl/ain
336 560   continue
337 570   continue
338       xf(1)=xf(1)+stsz
339       xf(2)=xf(2)+stsz
340 600   continue
341 700   continue
342 800   continue
343 900   continue
344       do 1000 i=1,site
345         write(nwr,910)i,sitex(1cd,i),sitey(1cd,i)
346 910   format(//,115("-"),// " site",i2," coordinates: ",2f9.3)
347       do 1000 j=1,nprob
348 919   format(" log (amplitude):",7x,10f10.2)
349       write(nwr,920)(desc(j,j1),j1=1,4),(ati(j,j2),j2=1,nlei(j))
350       write(nwr,919)(ti(j,j2),j2=1,nlei(j))
351 920   format(/,1x,4a4,1x,"amp.:",1x,10f10.2)
352       do 940 k=1,nflt
353         do 930 l=1,nlei(j)
354 930   risk(l,j,nflt+1,i)=risk(l,j,nflt+1,i)+risk(l,j,k,i)
355 940   write(nwr,950)k,(risk(m,j,k,i),m=1,nlei(j))
356 950   format(" fault",i2," e(no/yr)",5x,10e10.3)
357       write(nwr,960)(risk(m,j,nflt+1,i),m=1,nlei(j))
358 960   format(" total e(no/yr)",5x,10e10.3)
359       do 970 m1=1,nlei(j)
360       if(risk(m1,j,nflt+1,i).lt.0.0001)risk(m1,j,nflt+2,i)=

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361      1 risk(m1,j,nflt+1,i)
362      if(risk(m1,j,nflt+1,i).lt.0.0001)go to 970
363      risk(m1,j,nflt+2,i)=(1-exp(-risk(m1,j,nflt+1,i)))
364 970      continue
365      write(nwr,975)(risk(m,j,nflt+2,i),m=1,nlei(j))
366 975      format("      total risk",11x,10e10.3)
367      if (riskd(1).eq.0.0)go to 1000
368      do 985 kk=1,nrskd
369      do 980 ll=1,nlei(j)-1
370      if(risk(ll+1,j,nflt+2,i).eq.0.0)go to 981
371 980      if(riskd(kk).lt.risk(ll,j,nflt+2,i).and.riskd(kk).
372      1 gt.risk(ll+1,j,nflt+2,i))go to 982
373 981      tif(kk)=1000000.0
374      go to 985
375 982      tif(kk)=(alog(risk(ll,j,nflt+2,i)/riskd(kk)))/
376      1 (alog(risk(ll,j,nflt+2,i)/risk(ll+1,j,nflt+2,i)))
377      tif(kk)=ti(j,ll)+tif(kk)*(ti(j,ll+1)-ti(j,ll))
378 985      continue
379      write(nwr,986)(riskd(ik),ik=1,nrskd)
380      write(nwr,987)(tif(ij),ij=1,nrskd)
381 986      format("/      specified risks:",6x,10f10.6)
382 987      format("      estimated log amp. :",1x,10(1x,f9.3))
383      do 999 il=1,nrskd
384      if(tif(il).eq.1000000.0)go to 999
385      tif(il)=exp(tif(il))
386 999      continue
387      write(nwr,998)(tif(im),im=1,nrskd)
388 998      format("      estimated amolitude:",1x,10(1x,f9.3)/)
389 1000     continue
390      stop
391      end

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```

1      subroutine ndtr(x,p,d)
2 c          x is no. of standardized normal deviates.
3 c          p is comp. cumulative value (output).
4 c          d is density value (output)
5      if (x) 1,2,2
6          1  ax=-x
7          go to 3
8          2  ax=x
9          3  if (ax-6.0) 5,4,4
10         4  p=1.
11         d=0.
12         go to 6
13         5  t=1./(1.0+.2316419*ax)
14         d=0.3989423*exp(-x*x/2.0)
15         p = 1.0 - d*t*(((1.330274*t - 1.821256)*t + 1.781478)*t -
16         1  0.3565638)*t + 0.3193815)
17         6  if (x) 8,7,7
18         7  p=1.0-p
19         8  return
20        end

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Send to: R. K. McGuire  
Office of Earthquake Studies  
U.S. Geological Survey  
Mail Stop 966, Box 25046  
Denver Federal Center  
Denver, Colorado 80401  
U.S.A.

Please include my name on the mailing list for corrections/  
improvements to computer program FRISK.

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