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Finite-Difference Model to Simulate the Areal Flow of Salt Water
and Fresh Water Separated by an Interface

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James W. Mercer, Steven P. Larson, and Charles R. Faust

ABSTRACT

Model documentation is presented for a two-dimensional (areal) model capable of simulating ground-water flow of salt water and fresh water separated by an interface. The partial differential equations are integrated over the thicknesses of fresh water and salt water resulting in two equations describing the flow characteristics in the areal domain. These equations are approximated using finite-difference techniques and the resulting algebraic equations are solved for the dependent variables, fresh-water head and salt-water head. An iterative solution method was found to be most appropriate.

The program is designed to simulate time-dependent problems such as those associated with the development of coastal aquifers, and can treat water-table conditions or confined conditions with steady-state leakage of fresh water. The program will generally be most applicable to the analysis of regional aquifer problems in which the zone between salt water and fresh water can be considered a surface (sharp interface). Example problems and a listing of the computer code are included.

INTRODUCTION

The modeling of ground water in coastal aquifers is an important and difficult problem in water resources investigations. The primary difficulty involves the efficient and accurate simulation of the salt-water front. The convective-dispersive solute-transport equation probably best describes the movement of this front, however this equation can be difficult to solve. For certain problems where the transition zone caused by hydrodynamic dispersion is relatively narrow (when compared with the aquifer extent and thickness), the simulation can sometimes be simplified by assuming that the two fluids are immiscible and separated by a sharp interface. This assumption is particularly useful for large scale areal problems.

This interface modeling approach combined with the vertical integration was first presented by Shamir and Dagan (1971). They considered a vertical cross section and vertical integration resulted in one-dimensional equations, which were solved using a finite-difference approximation. For this one-dimensional case, they were able to track the salt-water toe and regenerate their grid for each time step; thus, solving two equations on the seaward side of the toe and only one equation on the landward side. Bonnet and Sauty (1975) extended the work of Shamir and Dagan to two dimensions. The resulting areal model was approximated using finite-difference techniques. Finally, Pinder and Page (1976) used the same equations given in Bonnet and Sauty, only approximating them using a Galerkin, finite-element approach.

In this report, the equations describing two-dimensional, areal flow of immiscible fresh water and salt water are developed by integrating the

flow equations over the vertical dimension. These equations are approximated using finite-difference techniques and the resulting nonlinear algebraic equations are linearized and are solved using an iterative method. The computer program that implements this solution scheme is described and examples are presented to demonstrate its use.

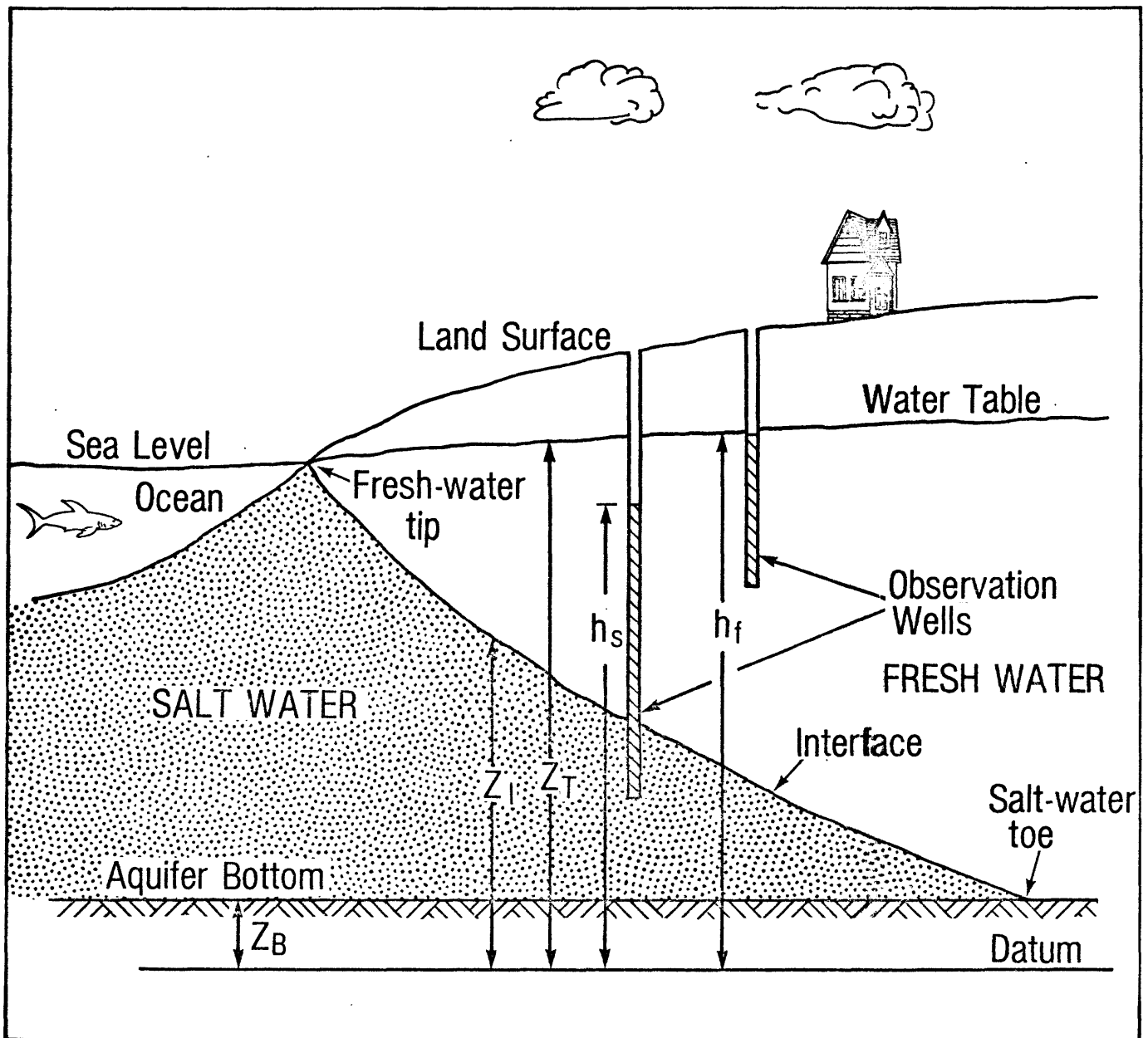


Figure 1. Diagrammatic representation of salt-water interface in a coastal aquifer.

MODEL DESCRIPTION

Governing Equations

To simulate the transient position of the salt-water interface shown in figure 1, it is necessary to solve simultaneously the equations describing the fresh-water and salt-water hydrodynamics.

Mass balance. The mass balance for salt water, s, and fresh water, f, may be written as follows:

$$S_s \frac{\partial h_s}{\partial t} + \nabla \cdot \bar{q}_s - Q_s = 0 , \quad (1)$$

and

$$S_f \frac{\partial h_f}{\partial t} + \nabla \cdot \bar{q}_f - Q_f = 0 , \quad (2)$$

where h is hydraulic head, \bar{q} is the Darcy velocity (a vector quantity), S is the specific storage, Q is a source/sink term (negative for sink), and $\nabla \equiv \frac{\partial}{\partial x} \bar{i} + \frac{\partial}{\partial y} \bar{j} + \frac{\partial}{\partial z} \bar{k}$ (where \bar{i} , \bar{j} , and \bar{k} are unit vectors in the x, y, and z directions, respectively).

Momentum balance. It is assumed that Darcy's equation may be used as simplified momentum balances. For salt water and fresh water these are

$$\bar{q}_s = - \bar{K}_s \cdot \nabla h_s , \quad (3)$$

and

$$\bar{q}_f = - \bar{K}_f \cdot \nabla h_f , \quad (4)$$

where \bar{K} is hydraulic conductivity (a tensor quantity).

Three-dimensional equations. Substitution of equations (3) and (4) into (1) and (2) respectively yields

$$S_s \frac{\partial h_s}{\partial t} - \nabla \cdot (\bar{K}_s \cdot \nabla h_s) - Q_s = 0, \quad (5)$$

and

$$S_f \frac{\partial h_f}{\partial t} - \nabla \cdot (\bar{K}_f \cdot \nabla h_f) - Q_f = 0, \quad (6)$$

which are the three-dimensional, ground-water flow equations for salt water and fresh water.

Vertical integration. To obtain the areal two-dimensional form of equations 5 and 6, they are integrated in the vertical dimension over the regions for which they are defined (fig. 1). Integration of (5) and (6) yields

$$\int_{z_B}^{z_I} [S_s \frac{\partial h_s}{\partial t} - \nabla \cdot (\bar{K}_s \cdot \nabla h_s) - Q_s] dz = 0, \quad (7)$$

and

$$\int_{z_I}^{z_T} [S_f \frac{\partial h_f}{\partial t} - \nabla \cdot (\bar{K}_f \cdot \nabla h_f) - Q_f] dz = 0, \quad (8)$$

where z_B is the elevation of the aquifer base, z_I is the elevation of the interface, and z_T is the elevation of the top of the fresh water region. To evaluate (7) and (8) we use Leibnitz' rule in the following form to reverse the order of integration and differentiation (Korn and Korn, 1961, p. 100):

$$\begin{aligned}
\int_{z_1}^{z_2} \frac{\partial \Psi}{\partial x} dz &= \frac{\partial}{\partial x} \int_{z_1}^{z_2} \Psi dz + \Psi(x, y, z, t) \Big|_{z_1} \frac{\partial z_1}{\partial x} \\
&- \Psi(x, y, z, t) \Big|_{z_2} \frac{\partial z_2}{\partial x} .
\end{aligned} \tag{9}$$

It is also helpful to define a quantity averaged in the z-dimension as

$$\langle \Psi \rangle = \frac{1}{b} \int_{z_1}^{z_2} \Psi dz . \tag{10}$$

Application of Leibnitz' rule to the time derivative in (7) yields

$$\int_{z_B}^{z_I} S_s \frac{\partial h_s}{\partial t} dz = S_s \left(\frac{\partial}{\partial t} \int_{z_B}^{z_I} h_s dz + h_s \Big|_{z_B} \frac{\partial z_B}{\partial t} - h_s \Big|_{z_I} \frac{\partial z_I}{\partial t} \right), \tag{11}$$

where we have assumed S_s is invariant with respect to depth. In terms of averaged quantities defined by equation (10) and assuming z_B is invariant with time, equation (11) may be rewritten as

$$\int_{z_B}^{z_I} S_s \frac{\partial h_s}{\partial t} dz = S_s \left[\frac{\partial}{\partial t} (b_s \langle h_s \rangle) - h_s \right]_{z_I} \frac{\partial z_I}{\partial t}, \quad (12)$$

where $b_s = (z_I - z_B)$. Using the Dupuit approximation that the hydraulic head defined at z_B and z_I does not differ significantly from the average, $\langle h_s \rangle$, and expanding the time derivative on the right side of (12) yields

$$\begin{aligned} \int_{z_B}^{z_I} S_s \frac{\partial h_s}{\partial t} dz &= S_s \left[b_s \frac{\partial \langle h_s \rangle}{\partial t} + \langle h_s \rangle \frac{\partial b_s}{\partial t} - h_s \right]_{z_I} \frac{\partial z_I}{\partial t} \\ &= S_s \left[b_s \frac{\partial \langle h_s \rangle}{\partial t} + \langle h_s \rangle \frac{\partial z_I}{\partial t} - h_s \right]_{z_I} \frac{\partial z_I}{\partial t} \\ &= S_s b_s \frac{\partial \langle h_s \rangle}{\partial t} \end{aligned} \quad (13)$$

Integration of the x-component of $\nabla \cdot (\bar{\bar{K}}_s \cdot \nabla h_s)$ in (7) using Leibnitz rules gives

$$\begin{aligned} \int_{z_B}^{z_I} \frac{\partial}{\partial x} (K_{sx} \frac{\partial h_s}{\partial x}) dz &= \frac{\partial}{\partial x} (b_s K_{sx} \langle \frac{\partial h_s}{\partial x} \rangle) + K_{sx} \frac{\partial h_s}{\partial x} \bigg|_{z_B} \frac{\partial z_B}{\partial x} \\ &\quad - K_{sx} \frac{\partial h_s}{\partial x} \bigg|_{z_I} \frac{\partial z_I}{\partial x}, \end{aligned} \quad (14)$$

where we have assumed that the hydraulic conductivity is colinear with the coordinate axis and is invariant with depth. Similarly, the integrated y- component is

$$\int_{z_B}^{z_I} \frac{\partial}{\partial y} (K_{sy} \frac{\partial h_s}{\partial y}) dz = \frac{\partial}{\partial y} (b_s K_{sy} \langle \frac{\partial h_s}{\partial y} \rangle) + K_{sy} \frac{\partial h_s}{\partial y} \Big|_{z_B} \frac{\partial z_B}{\partial y} - K_{sy} \frac{\partial h_s}{\partial y} \Big|_{z_I} \frac{\partial z_I}{\partial y} . \quad (15)$$

For the z-component, integration leads to

$$\int_{z_B}^{z_I} \frac{\partial}{\partial z} (K_{sz} \frac{\partial h_s}{\partial z}) dz = K_{sz} \frac{\partial h_s}{\partial z} \Big|_{z_I} - K_{sz} \frac{\partial h_s}{\partial z} \Big|_{z_B} . \quad (16)$$

Substitution of (13) through (16) into (7) and use of equation (3) gives

$$\begin{aligned} & s_s b_s \frac{\partial \langle h_s \rangle}{\partial t} - \frac{\partial}{\partial x} (b_s K_{sx} \langle \frac{\partial h_s}{\partial x} \rangle) - \frac{\partial}{\partial y} (b_s K_{sy} \langle \frac{\partial h_s}{\partial y} \rangle) - b_s \langle Q_s \rangle \\ & - q_{sx} \Big|_{z_I} \frac{\partial z_I}{\partial x} - q_{sy} \Big|_{z_I} \frac{\partial z_I}{\partial y} + q_{sz} \Big|_{z_I} \\ & + q_{sx} \Big|_{z_B} \frac{\partial z_B}{\partial x} + q_{sy} \Big|_{z_B} \frac{\partial z_B}{\partial y} - q_{sz} \Big|_{z_B} = 0, \end{aligned} \quad (17)$$

which is the vertically-integrated flow equation for salt water. Note that the source/sink term has also been integrated.

Using a similar development, the vertically-integrated fresh-water equation is

$$\begin{aligned}
& S_f b_f \frac{\partial \langle h_f \rangle}{\partial t} - \frac{\partial}{\partial x} (b_f K_{fx} \langle \frac{\partial h_f}{\partial x} \rangle) - \frac{\partial}{\partial y} (b_f K_{fy} \langle \frac{\partial h_f}{\partial y} \rangle) - b_f \langle Q_f \rangle \\
& + q_{fx} \Big|_{z_I} \frac{\partial z_I}{\partial x} + q_{fy} \Big|_{z_I} \frac{\partial z_I}{\partial y} - q_{fz} \Big|_{z_I} \\
& - q_{fx} \Big|_{z_T} \frac{\partial z_T}{\partial x} - q_{fy} \Big|_{z_T} \frac{\partial z_T}{\partial y} + q_{fz} \Big|_{z_T} = 0,
\end{aligned} \tag{18}$$

where $b_f = z_T - z_I$. It can be shown (Hantush, 1964, p. 300) that

$$q_{sx} \Big|_{z_B} \frac{\partial z_B}{\partial x} + q_{sy} \Big|_{z_B} \frac{\partial z_B}{\partial y} - q_{sz} \Big|_{z_B} = 0 \tag{19}$$

for an impermeable base and thus these terms can be eliminated from (17).

Also, it can be shown (Faust and Mercer, 1979, p. 27) that the average

of the derivative ($\langle \frac{\partial h_s}{\partial x} \rangle$) will be equal to the derivative of the

average $\left(\frac{\partial \langle h_s \rangle}{\partial x} \right)$ if the Dupuit approximation is used (i.e.

$\langle h_s \rangle \cong h_s \Big|_{z_B}$). The remaining terms that are evaluated at z_I and z_T

can be replaced by considering the conditions of a material surface (the interface or the water table).

Surface conditions. To evaluate the movement of the water table and the interface, the following relationships are necessary. Suppose the surface at time t is represented by

$$F(x,y,z,t) = 0.$$

At a later time, $t+\delta t$, a particle at point (x,y,z) will be displaced to $(x+\delta x, y+\delta y, z+\delta z) = (x+v_x \delta t, y+v_y \delta t, z+v_z \delta t)$ where v_x , v_y , and v_z are the velocity components at (x,y,z) on the interface. The new interface is, therefore, given by

$$F(x+v_x \delta t, y+v_y \delta t, z+v_z \delta t, t+\delta t) = 0 = F(x,y,z,t)$$

and therefore,

$$\frac{DF}{Dt} = \frac{\partial F}{\partial t} + \vec{v} \cdot \nabla F = 0, \quad (20)$$

where $\frac{D}{Dt}$ is the material (substantial) derivative or derivative following the motion. Equation (20) is known as the Kelvin relation governing the the motion in a liquid on a surface containing a given set of particles.

For the salt water-fresh water interface, $F = z(t) - z_I(x,y,t)$, which when substituted into (20) yields

$$\left. \frac{D}{Dt} (z - z_I) \right|_{z_I} = \left(v_z \frac{\partial z_I}{\partial t} - v_x \frac{\partial z_I}{\partial x} - v_y \frac{\partial z_I}{\partial y} \right) \bigg|_{z_I} = 0. \quad (21)$$

Multiplying (21) by porosity, ϕ , and rearranging terms gives

$$\phi \frac{\partial z_I}{\partial t} = q_z \bigg|_{z_I} - q_x \bigg|_{z_I} \frac{\partial z_I}{\partial x} - q_y \bigg|_{z_I} \frac{\partial z_I}{\partial y}. \quad (22)$$

Thus, this equation can be used to replace terms in (17) and (18) that are evaluated at z_I .

Let us temporarily define the top surface as $H(x,y,z,t)$ recognizing that $H = z_T(x,y)$ for confined problems and $H = h_f(x,y,z,t)$ for unconfined problems. The surface is thus described as, $F = z(t) - H(x,y,z,t)$, and taking the material derivative,

$$\frac{DF}{Dt} = \frac{Dz}{Dt} - \frac{DH}{Dt} = 0$$

or

$$\frac{dz}{dt} = \frac{\partial H}{\partial t} + \frac{\partial H}{\partial x} \frac{dx}{dt} + \frac{\partial H}{\partial y} \frac{dy}{dt} + \frac{\partial H}{\partial z} \frac{dz}{dt},$$

and thus,

$$v_z = \frac{\partial H}{\partial t} + v_x \frac{\partial H}{\partial x} + v_y \frac{\partial H}{\partial y} + v_z \frac{\partial H}{\partial z} .$$

Multiplying by porosity, ϕ , and introducing α to distinguish between confined and unconfined conditions ($\alpha = 1$ for unconfined, $\alpha = 0$ for confined) gives

$$\phi v_z \left(1 - \frac{\partial H}{\partial z}\right) \Big|_H - \alpha \phi \frac{\partial h_f}{\partial t} \Big|_H = q_x \frac{\partial H}{\partial x} \Big|_H + q_y \frac{\partial H}{\partial y} \Big|_H \quad (23)$$

Note that we have substituted $h_f \Big|_H$ for the time derivative of H .

Recall that for confined problems this term vanishes (because it is not a function of time) and for unconfined problems, this term becomes the time derivative of h_f . By introducing α , we obtain these desired results. Also, from the Dupuit approximation, the derivative $\frac{\partial H}{\partial z}$ can be considered negligible for the unconfined case and is zero for the confined case; therefore, the term containing this derivative is ignored. Finally, the term ϕv_z represents the total velocity of a particle at the surface H and is composed of $q_z \Big|_H$ and recharge or leakage if they exist. Thus,

$$\phi v_z = q_z \Big|_H - \alpha R + (1-\alpha) K'/b' (\langle h_f \rangle - h'), \quad (24)$$

where R is the rate of recharge to the water table, K' is the hydraulic conductivity of an overlying confining bed, b' is its thickness and h' is the head on the opposite side of the confining bed. Substituting (24) into (23) and recalling from the Dupuit approximation that $h_f \Big|_H \cong \langle h_f \rangle$ gives

$$q_z \Big|_H - q_x \Big|_H \frac{\partial H}{\partial x} - q_y \Big|_H \frac{\partial H}{\partial y} = \alpha R - (1-\alpha) \frac{K'}{b'} (\langle h_f \rangle - h') + \alpha \phi \frac{\partial \langle h_f \rangle}{\partial t}. \quad (25)$$

Substituting (22) and (25) into (18) gives

$$\begin{aligned} & S_f b_f \frac{\partial \langle h_f \rangle}{\partial t} - \frac{\partial}{\partial x} (b_f K_{fx} \frac{\partial \langle h_f \rangle}{\partial x}) - \frac{\partial}{\partial y} (b_f K_{fy} \frac{\partial \langle h_f \rangle}{\partial y}) - b_f \langle Q_f \rangle \\ & - \phi \frac{\partial z_I}{\partial t} + \alpha R - (1-\alpha) \frac{K'}{b'} (\langle h_f \rangle - h') + \alpha \phi \frac{\partial \langle h_f \rangle}{\partial t} = 0. \end{aligned} \quad (26)$$

Also, substituting (19) and (22) into (17) gives

$$\begin{aligned} & S_s b_s \frac{\partial \langle h_s \rangle}{\partial t} - \frac{\partial}{\partial x} (b_s K_{sx} \frac{\partial \langle h_s \rangle}{\partial x}) - \frac{\partial}{\partial y} (b_s K_{sy} \frac{\partial \langle h_s \rangle}{\partial y}) - b_s \langle Q_s \rangle \\ & + \phi \frac{\partial z_I}{\partial t} = 0. \end{aligned} \quad (27)$$

Final equations. The last terms that need to be evaluated are the time derivatives of the interface. A stability requirement (what keeps one fluid from pushing into the other) is that the pressures of the two fluids at the interface are equal:

$$\rho_s g (h_s - z_I) = \rho_f g (h_f - z_I), \quad (28)$$

where g is the gravitational constant and ρ_f and ρ_s are fresh-water and salt-water densities, respectively. Rearranging terms, recalling the assumption that head is uniform with depth and solving for z_I gives

$$z_I = \frac{\langle h_f \rangle \rho_f - \langle h_s \rangle \rho_s}{\rho_f - \rho_s}. \quad (29)$$

Taking the time derivative gives

$$\frac{\partial z_I}{\partial t} = \rho_f^* \frac{\partial \langle h_f \rangle}{\partial t} - \rho_s^* \frac{\partial \langle h_s \rangle}{\partial t}, \quad (30)$$

where $\rho_f^* = \rho_f / (\rho_f - \rho_s)$ and $\rho_s^* = \rho_s / (\rho_f - \rho_s)$.

Equation (30) indicates that the rate of change in the elevation of the interface is proportional to the rates of change in heads. Changes in fresh-water and salt-water heads could be off setting, resulting in little or no change in the interface.

We assume that hydraulic conductivity is measured in terms of fresh water, therefore, $K_f = K = k\rho_f g / \mu_f$ and $K_s = k\rho_s g / \mu_s$, where k is the intrinsic permeability and μ_f and μ_s are the fresh-water and salt-water dynamic viscosities, respectively. Combining these and rearranging terms gives

$$K_s = K_f \mu_f \rho_s / \rho_f \mu_s, \quad (31)$$

Similarly for specific storage, $S_f = \rho_f g (\alpha' + \phi\beta)$ and $S_s = \rho_s g (\alpha' + \phi\beta)$, and

$$S_s = S_f \rho_s / \rho_f, \quad (32)$$

where we have assumed that the vertical compressibility coefficient of the medium, α' , and the compressibility coefficient of the fluid, β , are approximately the same for salt water and fresh water. Substitution of (30), (31) and (32) into (27), and (30) into (26) yields for the salt-water and fresh-water equations respectively,

$$\begin{aligned}
& \frac{\rho_s}{\rho_f} S_f b_s \frac{\partial h_s}{\partial t} + \phi (\rho_f^* \frac{\partial h_f}{\partial t} - \rho_s^* \frac{\partial h_s}{\partial t}) \\
& - \frac{\partial}{\partial x} (b_s K_{fx} \frac{\mu_f}{\rho_f} \frac{\rho_s}{\mu_s} \frac{\partial h_s}{\partial x}) - \frac{\partial}{\partial y} (b_s K_{fy} \frac{\mu_f}{\rho_f} \frac{\rho_s}{\mu_s} \frac{\partial h_s}{\partial y}) \\
& - Q_{ws} \delta(x-x_i, y-y_i) = 0,
\end{aligned} \tag{33}$$

and

$$\begin{aligned}
& S_f b_f \frac{\partial h_f}{\partial t} - \phi (\rho_f^* \frac{\partial h_f}{\partial t} - \rho_s^* \frac{\partial h_s}{\partial t}) + \alpha \phi \frac{\partial h_f}{\partial t} \\
& - \frac{\partial}{\partial x} (b_f K_{fx} \frac{\partial h_f}{\partial x}) - \frac{\partial}{\partial y} (b_f K_{fy} \frac{\partial h_f}{\partial y}) \\
& - Q_{wf} \delta(x-x_i, y-y_i) + \alpha R - (1-\alpha) \frac{K'}{b'} (h_f - h') = 0,
\end{aligned} \tag{34}$$

which are the final vertically-integrated equations, where the averaging brackets $\langle \rangle$ have been omitted. Equations (33) and (34) are formulated in terms of h_f and h_s to facilitate treatment of constant head boundaries. However, had we solved (28) for h_s , our final equations could have been formulated in terms of h_f and z_I . Similarly, the final equations could have been formulated in terms of h_s and z_I . Note that for free surface conditions, S_f and S_s are generally very small compared with porosity. Also, $b_f \langle Q_f \rangle$ has been replaced with a source-sink term $Q_{wf} \delta(x-x_i, y-y_i)$, where $\delta(x,y)$ is the Dirac delta function.

Numerical Development

The technique used to solve equations (33) and (34) is based on the finite-difference method. For this method the areal extent of the reservoir is subdivided into rectangular grid blocks in which the fluid and reservoir properties are assumed uniform. The continuous derivatives in equations (33) and (34) are approximated by finite-difference expressions at points (nodes) in the centers of the blocks. This results in a nonlinear system of 2NB equations with 2NB unknowns (the values of fresh-water and salt-water heads at the nodes) where NB is the number of nodes. The general finite-difference representation and solution procedure for this system of nonlinear equations are outlined below.

Finite difference representation. Equations (33) and (34) may be written in compact, implicit finite-difference form as

$$\begin{aligned} \Delta_x (T_{sx} \Delta_x h_s^{n+1}) + \Delta_y (T_{sy} \Delta_y h_s^{n+1}) + AQ_{ws} \\ - C\Delta_t h_f - D\Delta_t h_s = 0, \end{aligned} \quad (35)$$

and

$$\begin{aligned} \Delta_x (T_{fx} \Delta_x h_f^{n+1}) + \Delta_y (T_{fy} \Delta_y h_f^{n+1}) + AQ_{wf} \\ - A\alpha R - A(1-\alpha) \frac{K'}{b'} (h_{i,j}^{n+1} - h'_{i,j}) \\ - F\Delta_t h_f - B\Delta_t h_s = 0, \end{aligned} \quad (36)$$

where i and j are indices in the x - and y -directions, n is the index for the time level, and the grid block area is defined as $A = \Delta x \Delta y$, where Δx and Δy are the spacings in the x - and y -directions, respectively. The equations have been multiplied by the grid block area to produce equations having units of volumetric rate. It can be shown that the resulting equations have a block symmetric form, which is an important consideration with regard to the application of solution procedures. The transmissive terms are given by

$$T_{sx} = (K_{fx}/\Delta x)b_s \Delta y \mu_f \rho_s / \rho_f \mu_s, \quad (37a)$$

$$T_{sy} = (K_{fy}/\Delta y)b_s \Delta x \mu_f \rho_s / \rho_f \mu_s, \quad (37b)$$

$$T_{fx} = (K_{fx}/\Delta x)b_f \Delta y, \quad (37c)$$

$$T_{fy} = (K_{fy}/\Delta y)b_f \Delta x. \quad (37d)$$

The difference operator acts as follows in the x - direction:

$$\begin{aligned} \Delta_x (T_{sx} \Delta_x h_s^{n+1}) &= T_{sx_{i+\frac{1}{2},j}} (h_{s_{i+1,j}}^{n+1} - h_{s_{i,j}}^{n+1}) \\ &\quad - T_{sx_{i-\frac{1}{2},j}} (h_{s_{i,j}}^{n+1} - h_{s_{i-1,j}}^{n+1}). \end{aligned} \quad (38)$$

The interblock transmissive terms (values at $i \pm \frac{1}{2}$ and $j \pm \frac{1}{2}$) are composed of two parts: that which is a function of space only (for example, $K_{fx}/\Delta x$) and that which is a function of head (for example, b_s).

To approximate these terms requires averaging or weighting of the various components over each grid block. For the space dependent part, this is accomplished by using a harmonic mean, for example,

$$(K_{fx}/\Delta x)_{i+\frac{1}{2}} = 2K_{fx_{i+1}} K_{fx_i} / (K_{fx_i} \Delta x_{i+1} + K_{fx_{i+1}} \Delta x_i). \quad (39)$$

The head dependent part of the these terms is computed by a weighted arithmetic average, for example,

$$b_{s_{i+\frac{1}{2}}} = \beta b_{s_{i+1}} + (1-\beta)b_{s_i}, \quad (40)$$

where β may be determined such that the upstream value is used.

The upstream node is located by comparing the heads at nodes i and $i+1$, and β is set to give b_s the value at the node having the larger head. Alternatively, other values of β can be used; for example, $\beta = \frac{1}{2}$ produces a midpoint weighting. Of the two procedures, upstream weighting yields a lower-order approximation of the spatial derivatives but exhibits a more stable solution. The time coefficients in equations (35) and (36) are given by

$$C = \Delta x \Delta y \phi \rho_f^*, \quad (41a)$$

$$D = \Delta x \Delta y (S_f b_s \rho_s / \rho_f - \phi \rho_s^*), \quad (41b)$$

$$F = \Delta x \Delta y (S_f b_f - \phi \rho_f^* + \alpha \phi), \quad (41c)$$

$$B = \Delta x \Delta y \phi \rho_s^*. \quad (41d)$$

The difference operator acts over the time domain as follows:

$$C\Delta_t h_f = C_{i,j} (h_{f,i,j}^{n+1} - h_{f,i,j}^n) / \Delta t, \quad (42)$$

which is a backward difference approximation.

Solution procedure. A block form of the line-successive over-relaxation technique (Varga, 1962), is used to solve the set of algebraic equations. A block consists of the pair of equations at each node. The 2 by 2 sub-matrices multiplying dependent variables in rows $j-1$ and $j+1$ are treated explicitly resulting in a reduced coefficient matrix of block tri-diagonal form. The set of matrix equations for each row are solved sequentially to produce new estimates of h_f and h_s . The explicit terms are updated and the process repeated until satisfactory convergence is achieved. Rewriting equations (35) and (36) in matrix form gives

$$[A]_j \{h^{n+1}\}_j^T = \{Q^n\}_j - [B]_{j-1} \{h^{n+1}\}_{j-1}^{k+1} - [B]_{j+1} \{h^{n+1}\}_{j+1}^k, \quad j = 1, \dots, NY \quad (43)$$

where NY is the number of rows. Matrix $[A]_j$ is block tri-diagonal and is composed of coefficients multiplying values of the dependent variable within row j . Matrices $[B]_{j-1}$ and $[B]_{j+1}$ are block diagonal and are composed of coefficients multiplying the dependent variables in rows $j-1$ and $j+1$, respectively. Note that h for row $j-1$ appears at iteration $k+1$ and h for row $j+1$ is at iteration level k . Both terms are known, either from the solution of equation (43) for the previous row ($j-1$) or from the previous iteration (k). Vector $\{Q^n\}_j$ is composed of source-sink terms and other

terms in (35) and (36) that are not functions of h_f or h_s .

Thus all terms on the right hand side of equation (43) are known and the equation can be solved for $\{h^{n+1}\}_j^\tau$. For improved accuracy, differences in head may be solved. Introducing

$$\{\Delta h^{n+1}\} = \{h^{n+1}\} - \{h^n\}, \quad (44)$$

equation (43) becomes

$$\begin{aligned} [A]_j \{\Delta h^{n+1}\}_j^\tau &= \{\text{Res}^n\}_j - [B]_{j-1} \{\Delta h^{n+1}\}_{j-1}^{k+1} \\ &\quad - [B]_{j+1} \{\Delta h^{n+1}\}_{j+1}^k, \quad j = 1, \dots, NY \end{aligned} \quad (45)$$

where $\{\text{Res}^n\}_j$ is the residual of the difference equations at time level n . Iteration level τ is an intermediate level (between k and $k+1$) prior to over-relaxation. Over-relaxation is used to accelerate convergence and takes the form

$$\{\Delta h^{n+1}\}_j^{k+1} = \omega \{\Delta h^{n+1}\}_j^\tau + (1-\omega) \{\Delta h^{n+1}\}_j^k \quad (46)$$

where ω is a relaxation parameter ($0 < \omega < 2$). Values of ω are commonly determined by trial and are generally between 1.6 and 1.9. The solution of equation (45) followed by (46) for each row (in sequence) completes an iteration. Iterations are terminated when successive estimates of Δh are acceptably similar.

Well terms. For general problems, a well may penetrate both salt and fresh water, and pumping removes both fluids. The amount of each fluid removed is, in part, determined by the interface elevation in the well, because this determines what portion of the well's open interval is occupied by each fluid. As the interface elevation changes with changes in head (hence, with time) the relative quantities of fluids removed also changes.

A simple approximation for allocating the relative amounts of each fluid that are discharged is to linearly apportion the total discharge by the relative length of open interval that is exposed to each fluid.

In the model, these terms could be determined explicitly, that is, using the interface elevation in the well at the beginning of the time step (time level n) to determine the amount of each fluid removed. Because the interface elevation changes over the time step, this explicit approach gives mass balance errors that may become unstable (the errors grow rapidly with time) unless the time step is sufficiently small.

In order to obtain stable solutions without having a restrictive time step limitation, it is necessary to treat the well terms more implicitly, that is, evaluate them closer to the $n+1$ time level. One way to accomplish this is to incorporate the changes in fluid discharge with respect to salt-water and fresh-water head as follows:

$$Q_{wf}^{n+1} = Q_{wf}^n + \frac{\partial Q_{wf}^n}{\partial h_f} \Delta h_f + \frac{\partial Q_{wf}^n}{\partial h_s} \Delta h_s, \quad (47a)$$

and

$$Q_{ws}^{n+1} = Q_{ws}^n + \frac{\partial Q_{ws}^n}{\partial h_f} \Delta h_f + \frac{\partial Q_{ws}^n}{\partial h_s} \Delta h_s, \quad (47b)$$

where the derivatives are computed at the beginning of the time step and incorporated into the main diagonal block of appropriate equations (45). In order to compute the derivatives, consider figure 2, which shows a well penetrating both salt and fresh water. Note that both confined or water-table conditions are considered. For water-table conditions, it is assumed that the well is completely open to the top of the water table. Assuming that total flow contributions from salt and fresh water are determined linearly

$$QWF = (TWS - ZI)QT/LS \quad (48a)$$

and

$$QWS = (ZI - WB)QT/LS, \quad (48b)$$

where QT is the total well discharge, $TWS = [\alpha HF + (1-\alpha)WT1]$ is the top of the well's screened or open interval, $LS = TWS - WB$ is the total length of the screened or open interval, $QWF = AQ_{wf}$, and $QWS = AQ_{ws}$. Recall that $\alpha = 0$ implies confined conditions ($TWS = WT1$) and $\alpha = 1$ implies water-table or unconfined conditions ($TWS = HF$). Using equation (29) and substituting for the interface elevation (ZI) in equations (48) gives

$$QWF = (TWS - \rho_f^* HF + \rho_s^* HS)QT/LS \quad (49a)$$

and

$$QWS = (\rho_f^* HF - \rho_s^* HS - WB)QT/LS \quad (49b)$$

where HF and HS are the array names for fresh-water and salt-water heads, respectively, that are used in the FORTRAN computer program. Taking the derivatives gives

$$\frac{\partial QWF}{\partial HF} = \{LS(\alpha - \rho_f^*) - (TWS - \rho_f^* HF + \rho_s^* HS)\alpha\}QT/LS^2 \quad (50a)$$

$$\frac{\partial QWF}{\partial HS} = \rho_s^* QT/LS, \quad (50b)$$

and

$$\frac{\partial QWS}{\partial HF} = \{LS\rho_f^* - (\rho_f^* HF - \rho_s^* HS - WB)\alpha\}QT/LS^2 = - \frac{\partial QWF}{\partial HF} \quad (51a)$$

$$\frac{\partial QWS}{\partial HS} = - \rho_s^* QT/LS = - \frac{\partial QWF}{\partial HS} . \quad (51b)$$

The derivatives (equations (50) and (51)) are added to the diagonal blocks of $[A]_j$ in equation (45) and the known terms (Q_{wf}^n and Q_{ws}^n) become part of the residual ($\{Res^n\}_j$). Implicit treatment of well terms is discussed in more detail in Mercer and others [1980].

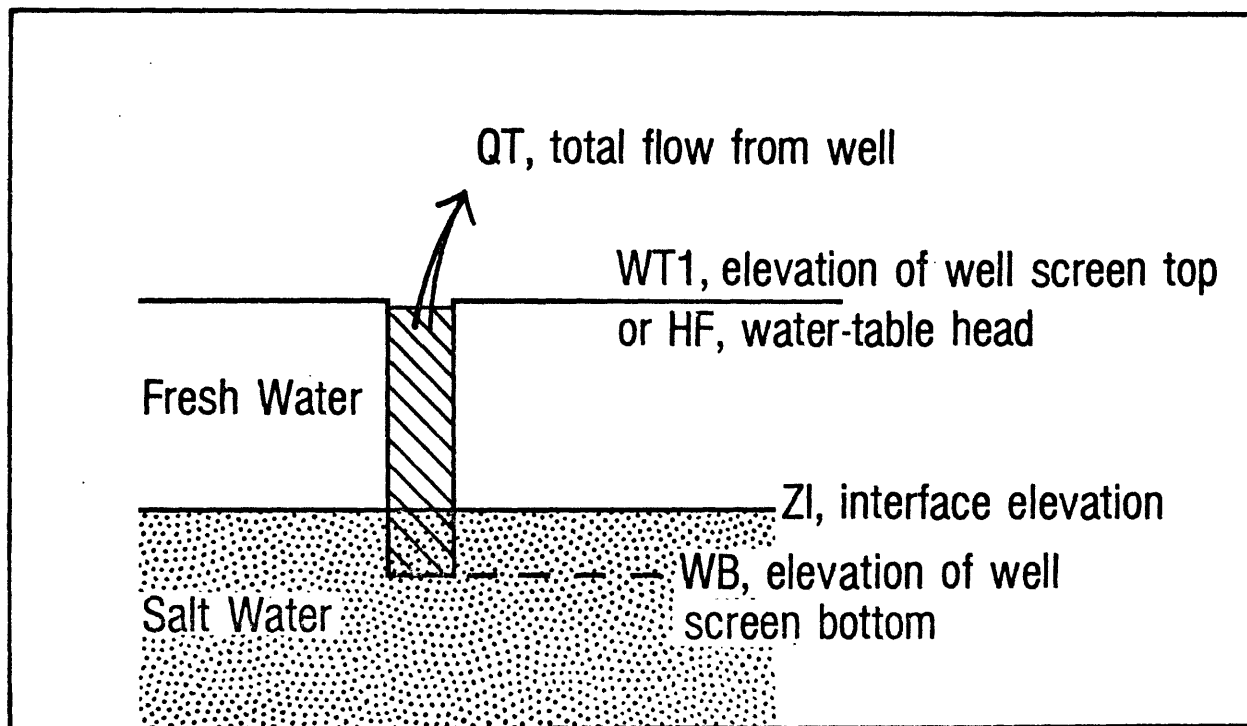


Figure 2. Well with opening to both salt water and fresh water.

MODEL DOCUMENTATION

Notes on use of program. The user may find the following comments helpful in understanding the program:

(1) Although calculations are performed in terms of salt-water and fresh-water heads, the initial input data required is fresh-water head and interface elevation. The reason being that these latter two variables are generally measured in a field situation. Salt water head is then calculated using equation (28).

(2) Well terms are considered positive for injection and negative for withdrawal. As indicated previously, the volume of salt water and fresh water removed (or injected) is determined linearly using the location of the interface and the length and position of the well's open interval. If one wishes to withdraw (or inject) only fresh water, the elevation of the well screen bottom must be set above the interface elevation. For withdrawal (or injection) of salt water only, the top of the well screen must be set below the interface elevation. Also, note that for unconfined conditions, the fresh-water head, H_F , is assumed to be the top of the open interval. If this is not the case, adjustments should be made to the computer program.

(3) Both well terms and recharge are input in L^3/T units.

(4) For steady-state simulations, small values of specific storage and porosity can be used to increase the rate of interface translation and thus reduce the computational effort required to obtain the steady-state solution. There will be a limit, however, on how much these parameters can be reduced for a particular time step size.

If these parameters are chosen such that there is an attempt to translate the fresh-water tip or salt-water toe more than one grid location from their current position, the solution may become unstable. This condition can also produce instability in the well allocation scheme. If these conditions occur, the time step size must be decreased or the porosity (and possibly the specific storage) must be increased.

(5) Computer storage arrays must be sufficiently dimensioned (the code in the appendix is dimensioned for 34 columns and 32 rows). Note that variables AX, AY, BX, BY, TX, and TY require an extra row or column. To minimize core requirements, the dimensions of several arrays should be adjusted to their minimum values as follows

<u>Array</u>	<u>Dimension</u>
AF, AS	$4 \times NB$
RF, RS, DELHF, DELHS, CI11, CI12, CI21, CI22	NB
NFE	$NX + 1$
RFT, RST	NX

where NB is the number of active grid points (equations) and NX is the number of columns in the grid. The total number of words required to store most of the program variables is approximately $48NB$.

(6) The time required for the program to execute will depend upon the characteristics of the simulation (number of time steps, number of iterations required per step, etc.) and upon the type of computer being used. Some example processing times (per node per iteration) are: Cyber 175, 10^{-4} seconds; IBM 370/155, 6×10^{-4} seconds; and Harris S135, 10^{-3} seconds.

(7) The convergence criterion for iteration sequence is specified as 10^{-6} , (card A1620) that is, the maximum change in head during the iteration must be less than 10^{-6} for convergence. This number was found to be satisfactory for test problems, but if necessary, this value may easily be changed by repunching the card where this check is performed.

(8) To improve convergence, an over-relaxation factor, $W\phi$, (see equation 46, p. 22) is read. This value may be varied by trial and error to determine the value that gives optimal convergence rate. In most problems, the optimal value was found to range between 1.6 to 1.9.

(9) A weighting factor, WT , (see equation 40, p. 20) is also read that weights the thicknesses of the salt and fresh water used in the transmissive terms between blocks. A value of 1.0 weights the thickness using the value from the upstream block, whereas a value of 0.5 weights the two blocks equally (midpoint or central weighting). The upstream weighting gives a less accurate solution, but may be more stable for certain problems.

(10) To reduce the number of lines in the output, only computed fresh-water head and interface elevation are printed every ITP time step, where ITP is read. If salt-water head is also desired, IPT must be input as 1.0. In addition, if the matrix information is desired, ID4 must be input as 1.0.

(11) The time step may either be uniform ($IDELT = 1.0$) or increase with time ($IDELT = 0.0$). The increase is computed automatically in MAIN using ZMAX, which is input with IDELT. The program allows a maximum increase factor of 1.2. To change this restriction, the appropriate cards must be repunched (cards A570 and A600).

(12) The program uses feet and seconds as the units for labelling output. However, any consistent set of units may be used if the output is interpreted appropriately.

Description of the subroutines. The FORTRAN IV code contains a main program and 8 subroutines, which are shown diagrammatically in figure 3. The purpose of each subroutine is listed below.

MAIN Driving program for the subroutines. In addition, the final space coefficients are computed and both the time loop and iteration loop are executed.

GDATA Reads and writes problem information according to the formats listed in the input section of this report.

READ Reads the two dimensional arrays containing data for each finite-difference block.

TCALC Computes harmonic part of transmissive terms. Also initializes boundary transmissive terms to zero.

CØEF Computes the thickness part of the transmissive terms and the time derivative coefficients.

FØRMEQ Forms the components of the reduced matrix equations for the iterative scheme.

BSBAND Solves reduced matrix equation for one row using the Gauss-Doolittle method.

PDATA Prints time step information and computed salt-water head, fresh-water head and interface elevation, if desired.

BAL Computes and prints salt and fresh water mass balance.

A generalized flow chart showing the approximate order that the subroutines are used is shown in figure 4.

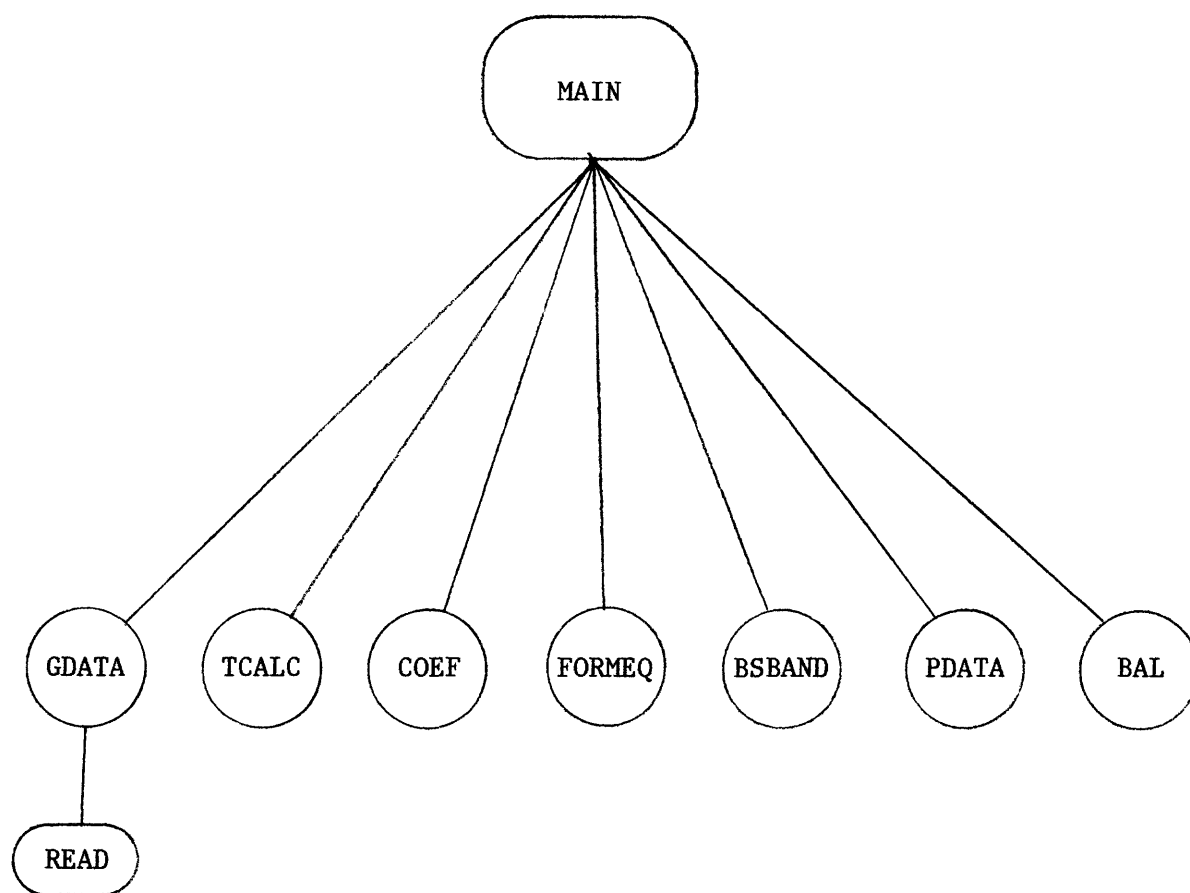


Figure 3. Program subroutines showing order and link of calling.

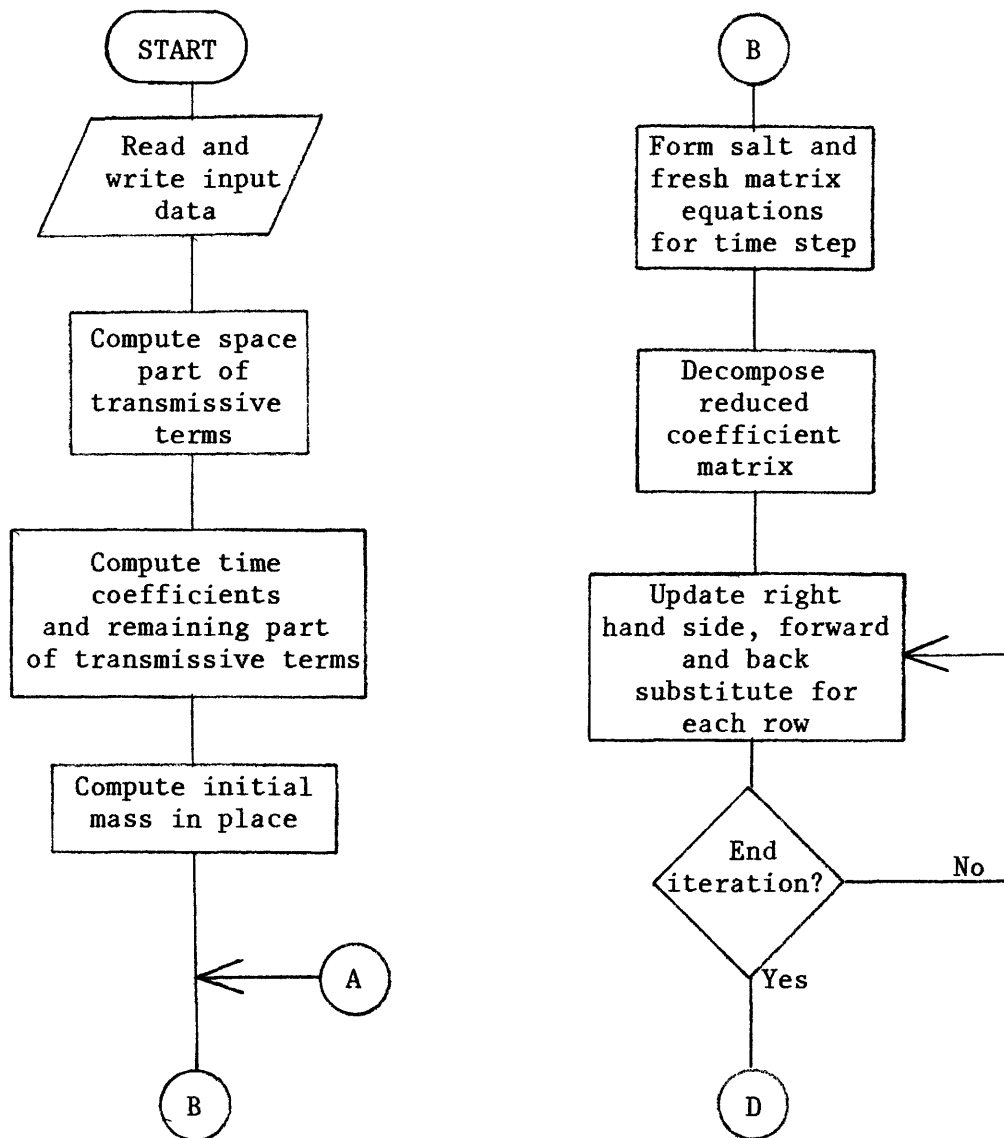


Figure 4. Generalized flow chart.

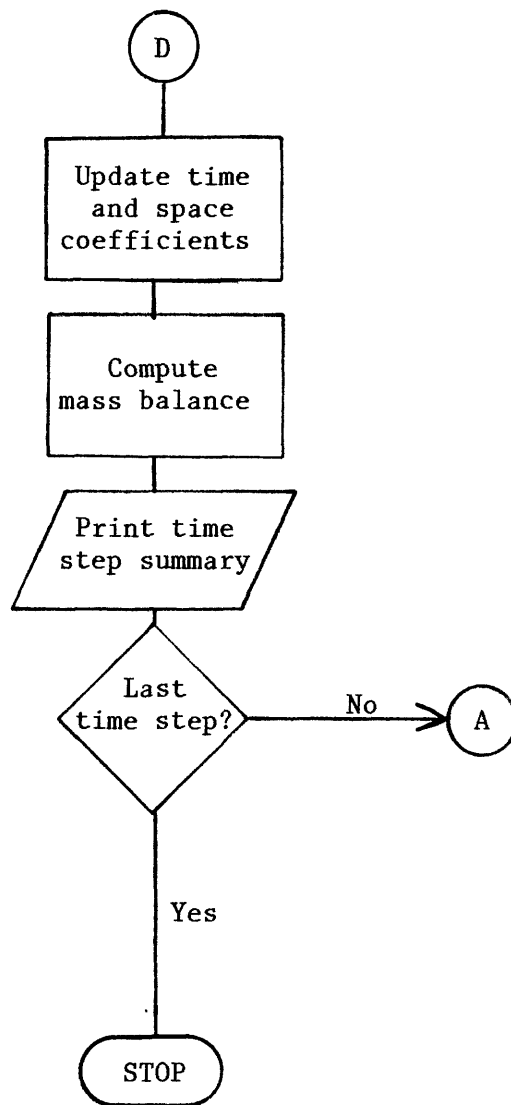


Figure 4. Generalized flow chart (cont.).

Input

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
Card 1 - Title			
1 - 60	20A3	TITLE	Problem title
Card 2 - Finite difference data			
1-4	I4	NX	Number of columns (x-direction)
5-8	I4	NY	Number of rows (y-direction)
9-12	I4	NB	Number of active (nonzero porosity) grid blocks
13-16	I4	MBE	Not used.
17-20	I4	NT	Number of time steps
21-24	I4	NF	Number of sources and sinks
25-28	I4	NHSC	Number of constant salt-water head nodes
29-32	I4	NHFC	Number of constant fresh-water head nodes
33-36	I4	NIT	Maximum number of iterations allowed
Card 3 - Time parameters			
1-10	G10.0	DELT	Initial time step (seconds)
11-20	G10.0	WT	Weighting factor (1.0 for upstream)
21-30	G10.0	WØ	Over-relaxation factor

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
Card 4			
1-10	G10.0	ALPHA	Read 1.0 for water-table; 0.0 for confined
11-14	I4	IPT	Read 1 to print salt-water heads
15-18	I4	ILK	Read 1 for leakage
19-22	I4	ITP	Number of time steps between printing output
23-26	I4	ID4	Read 1 to print matrix information
Card 5 - Data codes			
1-4	I4	K1	Read 1 if x-spacing is uniform
5-8	I4	K2	Read 1 if y-spacing is uniform
9-12	I4	K3	Read 1 if initial fresh-water head is uniform
13-16	I4	K4	Read 1 if initial interface elevation is uniform
17-20	I4	K5	Read 1 if x-hydraulic conductivity is uniform
21-24	I4	K6	Read 1 if y-hydraulic conductivity is uniform
25-28	I4	K7	Read 1 if specific storage is uniform
29-32	I4	K8	Read 1 if elevation of aquifer base is uniform
33-36	I4	K9	Read 1 if porosity is uniform
37-40	I4	K10	Read 1 if aquifer thickness is uniform
Card 6 - Multiplication factors			
1-10	G10.0	F1	Multiplication factor for x-spacing
11-20	G10.0	F2	Multiplication factor for y-spacing

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
21-30	G10.0	F3	Multiplication factor for initial fresh-water head
31-40	G10.0	F4	Multiplication factor for initial interface elevation
41-50	G10.0	F5	Multiplication factor for x-hydraulic conductivity
51-60	G10.0	F6	Multiplication factor for y-hydraulic conductivity
61-70	G10.0	F7	Multiplication factor for specific storage
71-80	G10.0	F8	Multiplication factor for elevation of aquifer base

Card 7 - Multiplication factors (continued)

1-10	G10.0	F9	Multiplication factor for porosity
11-20	G10.0	F10	Multiplication factor for aquifer thickness

Data set 1 - X-spacing

1-80	8G10.0	DX(I)	Spacing in the x-direction (NX values); if uniform, K1 = 1 and only read one value
------	--------	-------	---

Data set 2 - Y-spacing

1-80	8G10.0	DY(J)	Spacing in the y-direction (NY values); if uniform, K2 = 1 and only read one value
------	--------	-------	---

Data set 3 - Initial fresh water heads^{1/}

1-80	8G10.0	HF(I,J)	Initial fresh water heads; if uniform, K3 = 1 and only read one value
------	--------	---------	--

^{1/} Start new card for the beginning of each new row leaving blanks for missing blocks.

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
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Data Set 4 - Initial interface elevation^{1/}

1-80	8G10.0	ZI(I,J)	Initial interface elevation; if uniform, K4 = 1 and only read one value
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Data set 5 - X-hydraulic conductivity^{1/}

1-80	8G10.0	XK(I,J)	X-hydraulic conductivity; if uniform, K5 = 1 and only read one value
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Data set 6 - Y-hydraulic conductivity^{1/}

1-80	8G10.0	YK(I,J)	Y-hydraulic conductivity; if uniform, K6 = 1 and only read one value
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Data set 7 - Specific storage^{1/}

1-80	8G10.0	S(I,J)	Specific storage; if uniform, K7 = 1 and only read one value
------	--------	--------	---

Data set 8 - Elevation of aquifer base^{1/}

1-80	8G10.0	ZB(I,J)	Elevation of aquifer base; if uniform, K8 = 1 and only read one value
------	--------	---------	--

^{1/} Start new card for the beginning of each new row leaving blanks for missing blocks.

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
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Data set 9 - Porosity^{1/}

1-80	8G10.0	PØR(I,J)	Porosity; if uniform, K9 = 1 and only read one value. Note, porosity is used to key in on inactive blocks - a porosity of zero must be read for these blocks.
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Data set 10 - Aquifer thickness^{1/ 2/}

1-80	8G10.0	TH(I,J)	Aquifer thickness; if uniform, K10 = 1 and only read one value
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Card 8 Data codes (continued)^{3/}

1-4	I4	K11	Read 1 if head in overlying aquifer is uniform
5-8	I4	K12	Read 1 if leakance (K'/b') is uniform

Card 9 Multiplication factors (continued)^{3/}

1-10	G10.0	F11	Multiplication factor for confining bed head
11-20	G10.0	F12	Multiplication factor for confining bed leakance

^{1/} Start new card for the beginning of each new row leaving blanks
for missing blocks.

^{2/} Read only if ALPHA = 0.0, confined conditions.

^{3/} Read only if ALPHA = 0.0 and ILK = 1 (card 4), indicating that
leakage is included.

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
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Data set 11 - Head in overlying aquifer^{1/} ^{2/}

1-80	8G10.0	BH(I,J)	Head in overlying aquifer; if uniform, K11 = 1 and only read one value
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Data set 12 - Confining bed leakance^{1/} ^{2/}

1-80	8G10.0	BL(I,J)	Confining bed leakance (K'/b'); if uniform, K12 = 1 and only read one value
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Card 10 - Densities and viscosities

1-10	G10.0	DENF	Fresh-water density
11-20	G10.0	DENS	Salt-water density
21-30	G10.0	VF	Fresh-water viscosity
31-40	G10.0	VS	Salt-water viscosity

Card 11 - Recharge

1-10	G10.0	RECHG	Recharge (uniform value applied to each node)
------	-------	-------	--

^{1/} Read only if ALPHA = 0.0 and ILK = 1(card 4), indicating that leakage is included.

^{2/} Start new card for the beginning of each new row leaving blanks for missing blocks.

<u>Columns</u>	<u>Format</u>	<u>Name</u>	<u>Description</u>
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Data set 13 - Source/sink rates

1-4	I4	I	Column number of well
5-8	I4	J	Row number of well
9-18	G10.0	QT(I,J)	Volumetric rate of source/sink at block i,j (negative for a sink)
19-28	G10.0	WT1(I,J)	Elevation of top of well screen
29-38	G10.0	WB(I,J)	Elevation of bottom of well screen

Note: NF cards read; if NF = 0, this data set is omitted.

Card 12

1-4	I4	IDELT	Read 1 for constant time step; 0 for auto time step.
8-14	G10.0	ZMAX	Maximum change in interface elevation used to compute auto time step

Data set 14 - Constant salt water head nodes

1-4	I4	I	Column number of constant salt-water head node
5-8	I4	J	Row number of constant salt-water head node

Note: NHSC cards read; if NHSC = 0, this data set is omitted.

Data set 15 - Constant fresh water head nodes

1-4	I4	I	Column number of constant fresh-water head node
5-8	I4	J	Row number of constant fresh-water head node

Note: NHFC cards read; if NHFC = 0, this data set is omitted.

Output

To aid the user in detecting errors associated with data input, data read by the program is immediately printed out; thus, output appears in the following order:

Title of Problem
Finite Difference Data
Time Parameters
Multiplication Factors
Spacing in X-Direction
Spacing in Y-Direction
Initial Fresh-water Heads 1/
Initial Interface Elevation 1/
X-Hydraulic Conductivity 1/
Y-Hydraulic Conductivity 1/
Specific Storage 1/
Elevation of Aquifer Base 1/
Porosity 1/
Aquifer Thickness 1/ 2/
Multiplication Factors 1/ 3/
Confining Bed Head 1/ 3/

- 1/ Printed by rows with row number printed to left of data; if uniform, only one value is printed.
2/ For confined conditions
3/ For leakage and confined conditions

Confining Bed Leakance 1/ 2/

Densities and Viscosities

Recharge

Source/Sink Values and Locations

Constant Salt-water Head Locations

Constant Fresh-water Head Locations

Grid Block Numbers 3/

Initial Volume of Fresh Water and Salt Water
in Place

In addition, for every time step, the following is printed:

Iteration Information

Fresh- and Salt-water Balances

Time Step Information

Finally, for every ITP time step, the following is also printed:

Fresh-water Head

Interface Elevation

Salt-water Head 4/

Water Quality Map

1/ Printed by rows with row number printed to left of data; if
uniform, only one value is printed.

2/ For leakage and confined conditions

3/ If ID4 equals one

4/ If IPT equals one

Iteration information. The maximum difference error for each iteration is printed. This information gives an indication of the rate of convergence.

Fresh-water and Salt-water Balance information. The following rates and total volumes (for each time step) are given for both fresh and salt water:

Change in Storage

Source/Sink

Constant Head Nodes

Vertical Leakage

Recharge

Error, in percent

Totals

Equation Change in Storage

The rates and totals are indicated as being in the units ft^3/s and ft^3 , respectively. In actuality, these are printed in whatever consistent units were used for the input. The error, in percent, is based on a total net inflow volume. The total value is simply the difference between all inflows and outflows.

The mass balance summary includes two values of change in storage: the true change in storage and the change in storage expressed by the equations. These are given to help assess mass balance problems along the fresh-water tip or salt-water toe (Mercer and others, 1980). The equation change in storage should always balance with the net of the other inflow and

outflow terms. This indicates that the iterative method has successfully solved the algebraic equations. The mass balance error, however, is computed using the true or physical change in storage and may be significant even if the equations have been properly solved. This error reflects the effect of physically unrealistic interface conditions along the fresh-water tip or salt-water toe. A more complete discussion of this problem is given in Mercer and others (1980).

APPLICATIONS

To verify that the finite-difference approach is adequately approximating the partial differential equations, a comparison is made with an analytical solution. To test some of the assumptions that compose our mathematical model, a laboratory experiment is also simulated. In addition to verifying our approach, these applications serve as examples of how to set up problems and use the computer program.

Example 1

Consider a confined aquifer of uniform thickness, D (see figure 5). At time $t = 0$ there is a vertical interface, maintained by a gate at $x = 0$, separating salt water from fresh water. At $t = 0$ the gate is removed, and the interface begins to move owing to the density difference. After time $t = t_1$, the toe has moved a distance of $L(t_1)$. Keulegan (1954) gives an analytical solution for the motion of the interface, z_I^* , and for the location of the toe, $L(t)$:

$$z_I^*(x, t) = \frac{1}{2}D\{1+x/[(\Delta\rho K_f Dt)/(\phi\rho_f)]^{\frac{1}{2}}\}, \quad (52)$$

and

$$L(t) = (t\Delta\rho K_f D/\phi\rho_f)^{\frac{1}{2}}, \quad (53)$$

where $\Delta\rho = \rho_s - \rho_f$. The data for this problem are given in table 1 and the formatted model data are given in table 2.

The numerical solution was started with a linear interface ending at $L(t_0) = 20$ meters (following Shamir and Dagan, 1971), which was then allowed to move. This value of L corresponds to $t_0 = 12.28$ days. The numerical model used for this problem consisted of 20 finite-difference blocks, with a spacing of 5.0 meters each. Backward difference was used for the time derivative and a constant time step of one day was specified. The program was run for 20 days using both midpoint and upstream weighting. The results for $t = 32.28$ days are shown in figure 6. As may be seen, the results compare well, with upstream weighting showing slightly more smearing at the top and base of the aquifer.

Example 2

To test the vertical integration or Dupuit assumption, we consider a Hele-Shaw experiment performed by Bear and Dagan (1964). In these experiments, the interface began in a fixed position maintained by a constant fresh-water recharge at the left end (fig. 7). At $t = 0$ the recharge was abruptly increased to a new constant value. The length of the experimental apparatus was 400 cm and other pertinent data are given in table 3.

For this problem, backward difference is used for the time derivative and the time step was a constant 5 seconds. The spacing was 10 cm and midpoint weighting was used. The upstream boundary condition indicated by Bear and Dagan is one of constant flux ($18.8 \text{ cm}^2/\text{s}$) for $t > 0$. However, it was assumed that a constant head tank was probably used to produce this flux. In an attempt to simulate the experiment more precisely, the steady-state head at $x = 200$ cm for a flux of 18.8

cm²/s was computed by the model. This head value was used in transient simulations as the upstream boundary condition at $x = 200$ cm. Only 200 cm of the experimental apparatus was considered because the salt-water wedge is contained within this region during the entire experiment. At the downstream (right) end, the seepage face was approximated using a leakance and head that were computed to give the correct interface location at the initial and final flow conditions and assuming the downstream salt-water head was constant at 27 cm.

Using these boundary conditions and the formatted data in table 4, locations of the interface were computed for each 5-second time interval. Comparison with the results of Bear and Dagan are shown in figure 8. The line labeled $t = 0$ is the steady-state result that is used as initial conditions. The computed initial condition for the interface is in close agreement with the observed and thus it appears that the Dupuit approximation is valid for this interface shape. As the simulation progresses, however, the computed interface lags behind the observed interface. Shamir and Dagan (1971) also simulated this experiment, with computed results virtually identical to those presented in this paper.

The discrepancy between computed and observed could be the result of several factors: 1) error introduced from the Dupuit assumption; 2) error introduced in boundary condition approximations (that is, the way the leakance and head values are assigned); and 3) not knowing the exact experimental procedures.

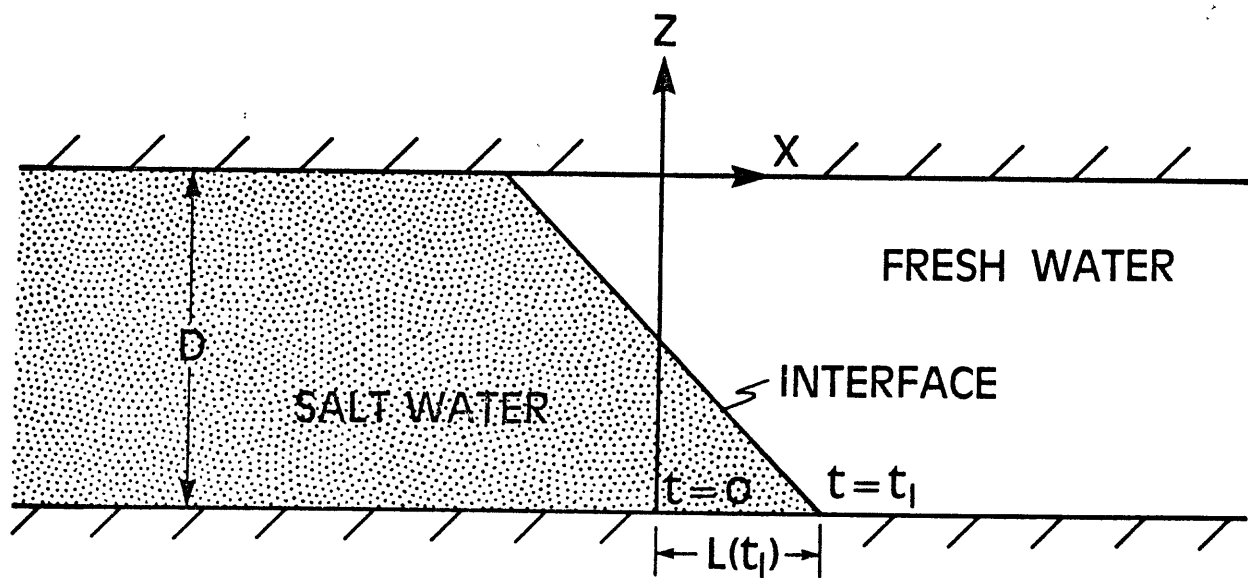


Figure 5. Diagram of linear interface in example 1.

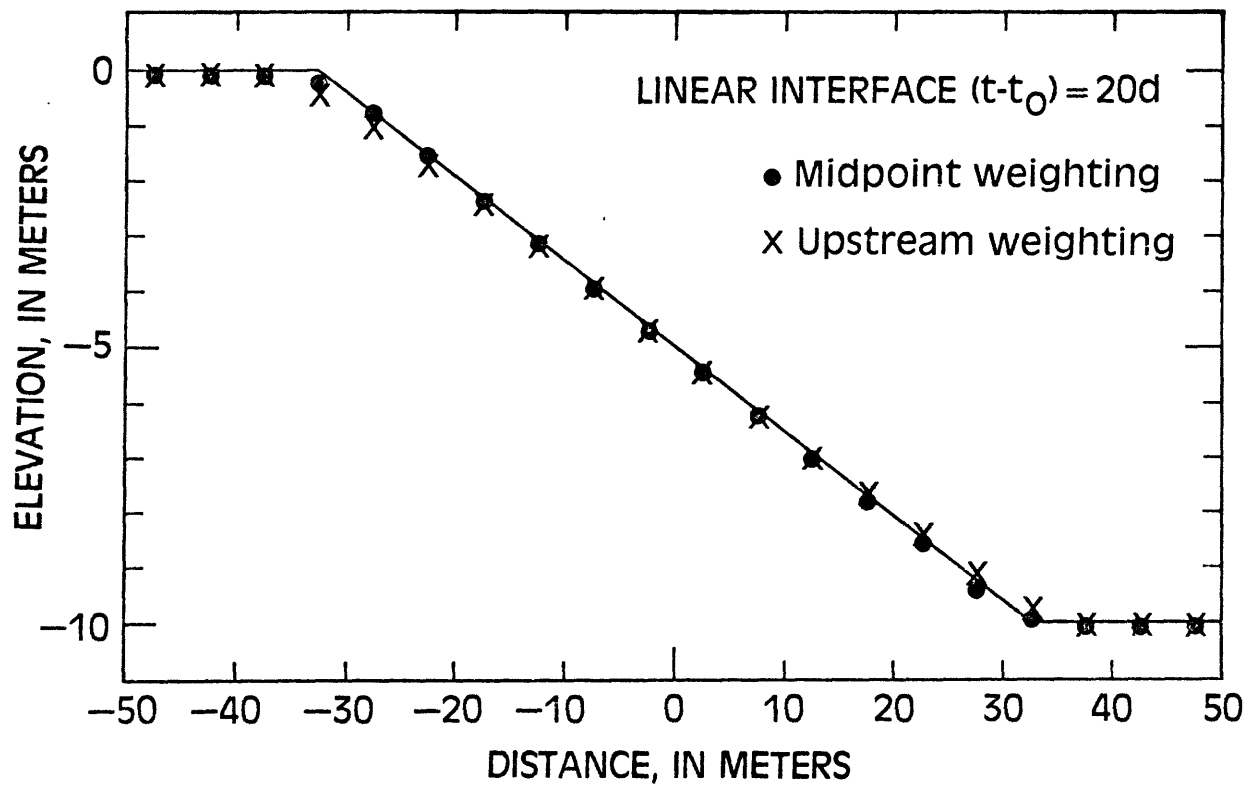


Figure 6. Computed results for midpoint and upstream weighting compared with Keulegan's analytical solution for example 1.

Table 1. Data for example 1 (linear interface).

D	$= 10 \text{ m}$	K_f	$= 39.024 \text{ m/d}$
ρ_f	$= 1.0 \text{ g/cm}^3$	ϕ	$= 0.3$
ρ_s	$= 1.025 \text{ g/cm}^3$		

Initial conditions: $L(t_o) = 20 \text{ m}$

$t_o = 12.28 \text{ d}$

Table 2. Formated data for example 1.

TEST USING KEULEGAN'S ANALYTICAL SOLUTION (FINITE DIFFERENCE)											
CARD 1.....	20	1	20	7	20	0	0	0	150		
CARD 2.....											
CARD 3.....		86400.			1.0			1.0			
CARD 4.....		1.0	1	0	1	1					
CARD 5.....	1	1	0	0	1	1	1	1	1	1	
CARD 6.....		1.0			1.0		1.0		1.0		1.0
CARD 7.....		1.0			1.0						
DATA SET 1.....		5.0									
DATA SET 2.....		5.0									
DATA SET 3.....		.06250		.06250		.06250		.06250		.06250	
		.07493		.08665		.10085		.11257		.12500	
		.12500		.12500		.12500		.12500		.12500	
		0.000		0.000		0.000		0.000		0.000	
		-3.125		-4.375		-5.625		-6.875		-8.125	
		-10.000		-10.000		-10.000		-10.000		-10.000	
DATA SET 4.....											
		.06250		.06250		.06250		.06250		.06250	
		.07493		.08665		.10085		.11257		.12500	
		.12500		.12500		.12500		.12500		.12500	
		0.000		0.000		0.000		0.000		0.000	
		-3.125		-4.375		-5.625		-6.875		-8.125	
		-10.000		-10.000		-10.000		-10.000		-10.000	
DATA SET 5.....		.00045167		.00045167		.00045167		.00045167		.00045167	
DATA SET 6.....		.00045167		.00045167		.00045167		.00045167		.00045167	
DATA SET 7.....		.0001		.0001		.0001		.0001		.0001	
DATA SET 8.....		-10.0		-10.0		-10.0		-10.0		-10.0	
DATA SET 9.....		0.3		0.3		0.3		0.3		0.3	
CARD 10.....		1.0		1.0		1.0		1.0		1.0	
CARD 11.....		0.0		0.0		0.0		0.0		0.0	
CARD 12.....	1										

Figure 7. Diagram of Hele-Shaw experiment of Bear and Dagan (1964).

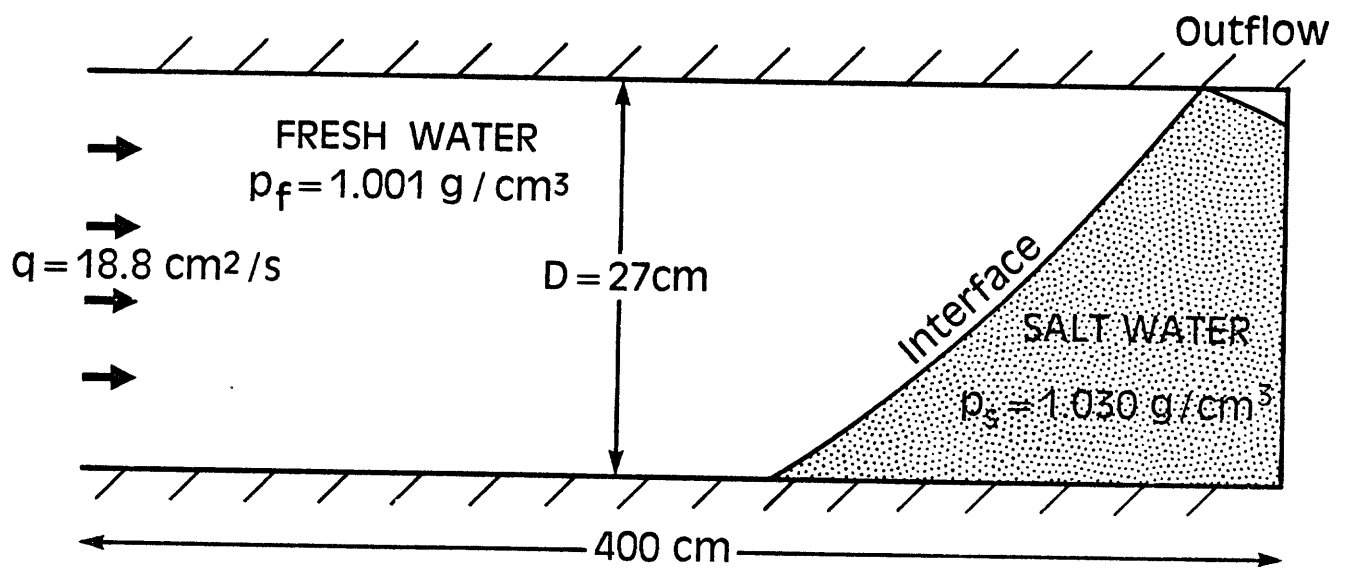


Table 3. Data for example 2 (Hele-Shaw experiment).

K_f	=	69 cm/s	ρ_f	=	1.001 g/cm ³
ϕ	=	1.0	ρ_s	=	1.030 g/cm ³
D	=	27 cm			
For $t < 0$, $q_{fb} = 3.9 \text{ cm}^2/\text{s}$					
For $t \geq 0$, $q_{fb} = 18.8 \text{ cm}^2/\text{s}$					
$h_f(x,0)$ and $z(x,0)$, computed steady state for $q_{fb} = 3.9 \text{ cm}^2/\text{s}$.					

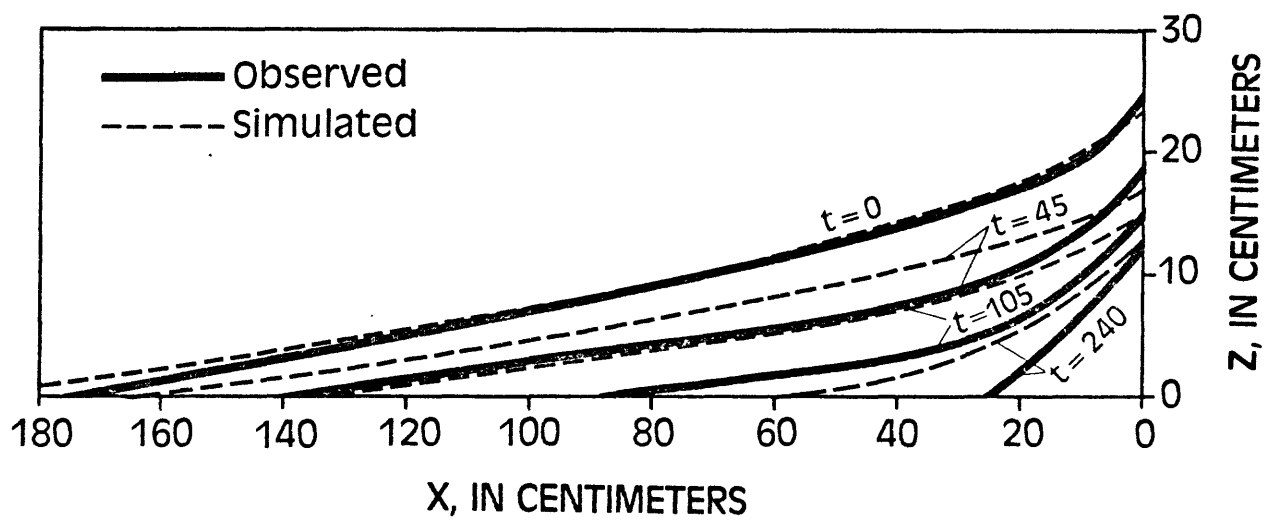


Figure 8. Computed results compared to Hele-Shaw data in example 2.

NOTATION

Parameter	Coded Name	Description
b	TH	aquifer thickness
h_f	HF	fresh-water head
h_s	HS	salt-water head
h'	BH	head in overlying aquifer
K'/b'	BL	leakance
K_{fx}	XK	x-hydraulic conductivity
K_{fy}	YK	y-hydraulic conductivity
-	QT	total discharge
R	RECHG	recharge
S_f	S	specific storage
WB	WB	well bottom
WT1	WT1	well top
z_b	ZB	elevation of aquifer base
z_I	ZI	interface elevation
α	ALPHA	confined/water-table indicator
β	WT	upstream/mid-point weighting indicator
μ_f	VF	fresh-water viscosity
μ_s	VS	salt-water viscosity
ρ_f	DENF	fresh-water density
ρ_s	DENS	salt-water density
w	WØ	relaxation parameter
ϕ	PØR	porosity

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Program listing and sample output

C	MAIN PROGRAM	A	10
C	*****	A	20
C		A	30
C	PURPOSE: TO SIMULATE A FRESH WATER-SALT WATER INTERFACE OVER AN	A	40
C	AREAL DOMAIN USING FINITE-DIFFERENCE TECHNIQUES	A	50
C	THERE MAY BE PARTS OF THIS PROGRAM THAT ARE NOT THOROUGHLY	A	60
C	DEBUGGED; THE AUTHORS AND THE GEOLOGICAL SURVEY WILL TAKE CREDIT	A	70
C	FOR ANY SUCCESSFUL RUNS OF THE MODEL, BUT THE USER ASSUMES FULL	A	80
C	RESPONSIBILITY FOR ALL RUNS THAT BOMB!	A	90
C	-----	A	100
C		A	110
C	COMMON /LGE/ AF(4342),RF(1088),AS(4352),RS(1088),CI11(1088),CI12(1	A	120
C	1088),CI21(1088),CI22(1088)	A	130
C		A	140
C	COMMON /INPUT/ S(34,32),XK(34,32),YK(34,32),HF(34,32),HS(34,32),DX	A	150
C	1(34),DY(32),ZB(34,32),ZI(34,32),QF(34,32),QT(34,32),POR(34,32),TH(A	160
C	234,32),NP(34,32)	A	170
C	COMMON /CONTROL/ TIME,DELT,DENS,DENF,VS,VF,WT,ZMAX,ALPHA,WO,NK,NX,N	A	180
C	1Y,NXX,NYY,NB,NBB,NT,NBW,MBE,IPT,NIT,PCHG	A	190
C	COMMON /WORK/ AX(35,32),BX(35,32),AY(34,33),BY(34,33),TX(35,32),TY	A	200
C	1(34,33),F(34,32),B(34,32),C(34,32),D(34,32),FT(34,32),ST(34,32),BH	A	210
C	2(34,32),BL(34,32),NHS(34,32),NHF(34,32),DOF(34,32),DOS(34,32),WT1(A	220
C	334,32),WB(34,32)	A	230
C	DIMENSION DELHF(1088),DELHS(1088),ERR(150),NFE(41),RFT(40),RS	A	240
C	1T(40)	A	250
C	-----	A	260
C		A	270
C	READ AND WRITE PROBLEM DATA -	A	280
C	CALL GDATA(IDELI,1IP,NFE)	A	290
C	*****	A	300
C		A	310
C	CALCULATE TRANSMISSIBILITY TERMS -	A	320
C	CALL TCALC(DY,DX,POR,XK,YK,TY,IX,NY,NX,NYY,NXX)	A	330
C	*****	A	340
C		A	350
C	COMPUTE THE REST OF THE SPACE COEFFICIENT AND	A	360
C	TIME COEFFICIENTS -	A	370
C	CALL COEF(1,1DELT,DZMX)	A	380
C	*****	A	390
C	DO 20 K=1,NB	A	400
C	DELHF(K)=0.	A	410
C	20 DELHS(K)=0.	A	420
C		A	430
C	CALCULATE INITIAL MASS IN PLACE	A	440
C	CALL BAL(0,DELHF,DELHS)	A	450
C	*****	A	460
C		A	470
C		A	480
C	BEGIN TIME LOOP	A	490
C	DO 190 LI=1,NI	A	500
C		A	510
C	FOR INCREASING TIME STEP -	A	520
C	IF (IDELT.EQ.1) GO TO 40	A	530
C	IF (DZMX.LT.0.EQ) GO TO 40	A	540
C	IF (DZMX.EQ.0.EQ) GO TO 30	A	550

FAC=ZMAX/DZMX	A 560
IF (FAC.GT.1.2) FAC=1.2	A 570
DELT=DELT1*FAC	A 580
GO TO 40	A 590
30 FAC=1.2	A 600
DELT=DELT1*FAC	A 610
40 CONTINUE	A 620
C	A 630
C INITIALIZE BOUNDARY ARRAYS -	A 640
DO 50 I=1,NX	A 650
AY(I,1)=0.E0	A 660
AY(I,NYY)=0.E0	A 670
BY(I,1)=0.E0	A 680
50 BY(I,NYY)=0.E0	A 690
C	A 700
DO 60 J=1,NY	A 710
AX(1,J)=0.E0	A 720
BX(1,J)=0.E0	A 730
AX(NXX,J)=0.E0	A 740
60 BX(NXX,J)=0.E0	A 750
C	A 760
C COMPUTE FINAL SPACE COEFFICIENTS -	A 770
DO 70 J=1,NY	A 780
DO 70 I=2,NX	A 790
ALS=WT	A 800
ALD=WT	A 810
IF (HF(I-1,J).GT.HF(I,J)) ALD=1.E0-WT	A 820
IF (HS(I-1,J).GT.HS(I,J)) ALS=1.E0-WT	A 830
AX(I,J)=(ALD*FT(I,J)+(1.E0-ALD)*FT(I-1,J))*TX(I,J)	A 840
70 BX(I,J)=(ALS*ST(I,J)+(1.E0-ALS)*ST(I-1,J))*TX(I,J)	A 850
C	A 860
DO 80 I=1,NX	A 870
DO 80 J=2,NY	A 880
ALS=WT	A 890
ALD=WT	A 900
IF (HF(I,J-1).GT.HF(I,J)) ALD=1.E0-WT	A 910
IF (HS(I,J-1).GT.HS(I,J)) ALS=1.E0-WT	A 920
AY(I,J)=(ALD*FT(I,J)+(1.E0-ALD)*FT(I,J-1))*TY(I,J)	A 930
80 BY(I,J)=(ALS*ST(I,J)+(1.E0-ALS)*ST(I,J-1))*TY(I,J)	A 940
C	A 950
C FORM FINAL MATRIX EQUATION -	A 960
CALL FORMER(AF,AS,RF,RS)	A 970
C *****	A 980
C FACTOR MATRICES FOR EACH ROW	A 990
DO 90 J=1,NY	A1000
N=NFE(J+1)-NFE(J)	A1010
IF (N.LE.1) GO TO 90	A1020
ID=4*NFE(J)-3	A1030
K=NFE(J)-1	A1040
C	A1050
C FACTOR ROW J	A1060
CALL BSBAND(AF(ID),AS(ID),RFT,RS1,C111,C112,C121,C122,N,K,1)	A1070
90 CONTINUE	A1080
C *****	A1090
C BEGIN ITERATIONS	A1100

DO 160 KK=1,NIT	A1110
ERR(KK)=0.	A1120
ERMAX=0.	A1130
DO 150 J=1,NY	A1140
K=NFE(J)-1	A1150
N=NFE(J+1)-NFE(J)	A1160
IF (N.EQ.0) GO TO 150	A1170
ID=4*NFE(J)-3	A1180
C UPDATE RIGHT HAND SIDE	A1190
L=0	A1200
DO 120 I=1,NX	A1210
IF (POR(I,J).LE.0.) GO TO 120	A1220
L=L+1	A1230
KL=K+L	A1240
RFT(L)=RF(KL)	A1250
RST(L)=RS(KL)	A1260
IF (J.EQ.1) GO TO 100	A1270
NJM=NP(I,J-1)	A1280
IF (NJM.EQ.0) GO TO 100	A1290
RFT(L)=RFT(L)-AY(I,J)*DELHF(NJM)	A1300
RST(L)=RST(L)-BY(I,J)*DELHS(NJM)	A1310
100 IF (J.EQ.NY) GO TO 110	A1320
NJP=NP(I,J+1)	A1330
IF (NJP.EQ.0) GO TO 110	A1340
RFT(L)=RFT(L)-AY(I,J+1)*DELHF(NJP)	A1350
RST(L)=RST(L)-BY(I,J+1)*DELHS(NJP)	A1360
110 IF (MPF(I,J).EQ.1) RFT(L)=0.	A1370
IF (VHS(I,J).EQ.1) RST(L)=0.	A1380
120 CONTINUE	A1390
C	A1400
C COMPUTE SOLUTION FOR ROW J	A1410
CALL BSBAND(AF(ID),AS(ID),RFT,RST,C111,C112,C121,C122,N,K,2)	A1420
C *****	A1430
C OVER-RELAX AND FIND MAXIMUM CHANGE	A1440
KL=K	A1450
DO 140 L=1,N	A1460
KL=KL+1	A1470
ERF1=RFT(L)-DELHF(KL)	A1480
ERF=ABS(ERF1)	A1490
ERS1=RST(L)-DELHS(KL)	A1500
ERS=ABS(ERS1)	A1510
DELHF(KL)=WD*RFT(L)+(1.-WD)*DELHF(KL)	A1520
DELHS(KL)=WD*RST(L)+(1.-WD)*DELHS(KL)	A1530
IF (ERF.LT.ERMAX) GO TO 130	A1540
ERMAX=ERF	A1550
ERR(KK)=ERF1	A1560
130 IF (ERS.LT.ERMAX) GO TO 140	A1570
ERMAX=ERS	A1580
ERR(KK)=ERS1	A1590
140 CONTINUE	A1600
150 CONTINUE	A1610
IF (ERMAX.LI.1.E-6) GO TO 170	A1620
160 CONTINUE	A1630
PRINT 200	A1640
PRINT 210, (ERR(K),K=1,NIT)	A1650

STOP	A1660
170 CONTINUE	A1670
PRINT 210, (ERR(K),K=1,KK)	A1680
K=0	A1690
DO 180 J=1,NY	A1700
DO 180 I=1,NX	A1710
IF (POR(I,J).LE.G.) GO TO 180	A1720
K=K+1	A1730
HF(I,J)=HF(I,J)+DELHF(K)	A1740
HS(I,J)=HS(I,J)+DELHS(K)	A1750
180 CONTINUE	A1760
LL=LI+1	A1770
C	A1780
C** UPDATE SPACE COEFFICIENTS	A1790
CALL COEF(LL,IDELT,DZMX)	A1800
C *****	A1810
C	A1820
C** CALCULATE BALANCE -	A1830
CALL BAL(1,DELHF,DELHS)	A1840
C *****	A1850
TIME=TIME+DELT	A1860
C	A1870
C** PRINT RESULTS -	A1880
CALL PDATA(LI,ITP)	A1890
C *****	A1900
190 CONTINUE	A1910
C	A1920
C END TIME LOOP	A1930
STOP	A1940
C	A1950
200 FORMAT (46H ITERATIONS EXCEEDED, PROGRAM ABORTED*****)	A1960
210 FORMAT (39H MAXIMUM HEAD CHANGE FOR EACH ITERATION,/, (2X,10G12.5))	A1970
END	A1980-
SUBROUTINE GDATA(IDELT,ITP,NFE)	B 10
C *****	B 20
C	B 30
C CALLED FROM MAIN	B 40
C PURPOSE: TO READ AND WRITE PROBLEM DATA	B 50
C -----	B 60
DIMENSION TITLE(20), NFE(1)	B 70
C	B 80
COMMON /INPUT/ S(34,32),XK(34,32),YK(34,32),HF(34,32),HS(34,32),DX	B 90
1(34),DY(32),ZB(34,32),ZI(34,32),QF(34,32),QT(34,32),POR(34,32),TH(B 100
234,32),NP(34,32)	B 110
COMMON /CONTROL/ TIME,DELT,DENS,DENF,VS,VF,WT,ZMAX,ALPHA,W0,NK,NX,N	B 120
1Y,NXX,NYY,NB,NBB,N1,MBW,MBE,IPT,NIT,RECHG	B 130
COMMON /WORK/ AX(35,32),HX(35,32),AY(34,33),BY(34,33),TX(35,32),TY	B 140
1(34,33),F(34,32),B(34,32),C(34,32),D(34,32),FT(34,32),ST(34,32),BH	B 150
2(34,32),BL(34,32),NHS(34,32),NHF(34,32),DQF(34,32),DQS(34,32),WT1(B 160
334,32),WB(34,32)	B 170
C -----	B 180
C	B 190
C READ AND WRITE UNITS -	B 200
NR=7	B 210
NW=6	B 220

C		B	230
C	INITIALIZE SIMULATION TIME -	B	240
	TIME=0.E0	B	250
C		B	260
C	READ AND WRITE PROBLEM TITLE -	B	270
	READ (NR,740) TITLE	B	280
	WRITE (NW,290)	B	290
	WRITE (NW,300) TITLE	B	300
C		B	310
C	FINITE-DIFFERENCE DATA -	B	320
	READ (NR,750) NX,NY,NB,MBE,NT,NF,NHSC,NHFC,NIT	B	330
C	NX - NUMBER OF COLUMNS (X-DIRECTION)	B	340
C	NY - NUMBER OF ROWS (Y-DIRECTION)	B	350
C	NB - NUMBER OF NON-ZERO BLOCKS	B	360
C	MBE - NOT USED	B	370
C	NT - MAXIMUM NUMBER OF TIME STEPS	B	380
C	NF - NUMBER OF SOURCES	B	390
C	NHSC - NUMBER OF CONSTANT SALT WATER HEAD NODES	B	400
C	NHFC - NUMBER OF CONSTANT FRESH WATER HEAD NODES	B	410
C	NIT - NUMBER OF LAGGING ITERATIONS	B	420
	IF (NX.NE.0) GO TO 10	B	430
	WRITE (NW,310)	B	440
	STOP	B	450
10	IF (NY.NE.0) GO TO 20	B	460
	WRITE (NW,320)	B	470
	STOP	B	480
20	IF (NB.NE.0) GO TO 30	B	490
	WRITE (NW,330)	B	500
	STOP	B	510
30	CONTINUE	B	520
	WRITE (NW,340)	B	530
	WRITE (NW,350) NX,NY,NB,MBE,NT,NF,NHSC,NHFC,NIT	B	540
C		B	550
	NXX=NX+1	B	560
	NYN=NY+1	B	570
C		B	580
C	TIME PARAMETERS -	B	590
	READ (NR,760) DELT,WT,W0	B	600
C	DELT - INITIAL TIME STEP IN SECONDS	B	610
C	WT - WEIGHTING FACTOR (1. FOR UPSIDEAM; .5 FOR MIDPOINT)	B	620
C	W0 - OVER-RELAXATION FACTOR (1.0-1.8)	B	630
	WRITE (NW,360) DELT,WT,W0	B	640
C		B	650
	READ (NR,370) ALPHA,IPT,ILK,ITP,ID4	B	660
C	ALPHA - 1.0 FOR WATER-TABLE CONDITIONS;	B	670
C	0.0 FOR CONFINED CONDITIONS.	B	680
C	IPT - READ 1 TO PRINT SALT WATER HEADS	B	690
C	ILK - READ 1 IF LEAKAGE IS DESIRED (CONFINED CASE)	B	700
C	ITP - NUMBER OF TIME STEPS BETWEEN PRINTING OUTPUT	B	710
C	ID4 - READ 1 TO PRINT MATRIX INFORMATION	B	720
	IF (ITP.EQ.0) ITP=1	B	730
	IF (ALPHA.EQ.1.0) WRITE (NW,380) ALPHA	B	740
	IF (ALPHA.EQ.0.0) WRITE (NW,390) ALPHA	B	750
C		B	760
C	DATA CODES -	B	770

	READ (NR,750) K1,K2,K3,K4,K5,K6,K7,K8,K9,K10	B 780
C	K1 - READ 1 IF X-SPACING IS UNIFORM	B 790
C	K2 - READ 1 IF Y-SPACING IS UNIFORM	B 800
C	K3 - READ 1 IF INITIAL FRESH WATER HEAD IS UNIFORM	B 810
C	K4 - READ 1 IF INITIAL INTERFACE ELEVATION IS UNIFORM	B 820
C	K5 - READ 1 IF X-HYDRAULIC CONDUCTIVITY IS UNIFORM	B 830
C	K6 - READ 1 IF Y-HYDRAULIC CONDUCTIVITY IS UNIFORM	B 840
C	K7 - READ 1 IF SPECIFIC STORAGE IS UNIFORM	B 850
C	K8 - READ 1 IF ELEVATION OF AQUIFER BASE IS UNIFORM	B 860
C	K9 - READ 1 IF POROSITY IS UNIFORM	B 870
C	K10 - READ 1 IF AQUIFER THICKNESS IS UNIFORM	B 880
	WRITE (NW,400)	B 890
	IF (K1.EQ.1) WRITE (NW,410)	B 900
	IF (K2.EQ.1) WRITE (NW,420)	B 910
	IF (K3.EQ.1) WRITE (NW,430)	B 920
	IF (K4.EQ.1) WRITE (NW,440)	B 930
	IF (K5.EQ.1) WRITE (NW,450)	B 940
	IF (K6.EQ.1) WRITE (NW,460)	B 950
	IF (K7.EQ.1) WRITE (NW,470)	B 960
	IF (K8.EQ.1) WRITE (NW,480)	B 970
	IF (K9.EQ.1) WRITE (NW,490)	B 980
	IF (K10.EQ.1.AND.ALPHA.EQ.0.) WRITE (NW,500)	B 990
C		B1000
C	MULTIPLICATION FACTORS -	B1010
	READ (NR,760) F1,F2,F3,F4,F5,F6,F7,F8	B1020
	READ (NR,760) F9,F10	B1030
	IF (F1.EQ.0.) F1=1.0	B1040
	IF (F2.EQ.0.) F2=1.0	B1050
	IF (F3.EQ.0.) F3=1.0	B1060
	IF (F4.EQ.0.) F4=1.0	B1070
	IF (F5.EQ.0.) F5=1.0	B1080
	IF (F6.EQ.0.) F6=1.0	B1090
	IF (F7.EQ.0.) F7=1.0	B1100
	IF (F8.EQ.0.) F8=1.0	B1110
	IF (F9.EQ.0.) F9=1.0	B1120
	IF (F10.EQ.0.) F10=1.0	B1130
C	F1 - MULTIPLICATION FACTOR FOR X-SPACING	B1140
C	F2 - MULTIPLICATION FACTOR FOR Y-SPACING	B1150
C	F3 - MULTIPLICATION FACTOR FOR INITIAL FRESH WATER HEAD	B1160
C	F4 - MULTIPLICATION FACTOR FOR INITIAL INTERFACE ELEVATION	B1170
C	F5 - MULTIPLICATION FACTOR FOR X-HYDRAULIC CONDUCTIVITY	B1180
C	F6 - MULTIPLICATION FACTOR FOR Y-HYDRAULIC CONDUCTIVITY	B1190
C	F7 - MULTIPLICATION FACTOR FOR SPECIFIC STORAGE	B1200
C	F8 - MULTIPLICATION FACTOR FOR ELEVATION OF AQUIFER BASE	B1210
C	F9 - MULTIPLICATION FACTOR FOR POROSITY	B1220
C	F10 - MULTIPLICATION FACTOR FOR AQUIFER THICKNESS	B1230
	WRITE (NW,510) F1,F2,F3,F4,F5,F6,F7,F8,F9,F10	B1240
C		B1250
C	SPACING -	B1260
	IF (K1.EQ.1) GO TO 40	B1270
	READ (NR,760) (DX(I),I=1,NX)	B1280
	GO TO 60	B1290
40	READ (NR,760) DX1	B1300
	DO 50 I=1,NX	B1310
50	DX(I)=DX1	B1320

60	DO 70 I=1,NX	81330
70	DX(I)=DX(I)*F1	81340
	WRITE (NW,520)	81350
	WRITE (NW,530) (DX(I),I=1,NX)	81360
C		81370
	IF (K2.EQ.1) GO TO 80	81380
	READ (NR,760) (DY(J),J=1,NY)	81390
	GO TO 100	81400
80	READ (NR,760) DY1	81410
	DO 90 J=1,NY	81420
90	DY(J)=DY1	81430
100	DO 110 J=1,NY	81440
110	DY(J)=DY(J)*F2	81450
	WRITE (NW,540)	81460
	WRITE (NW,530) (DY(J),J=1,NY)	81470
C		81480
C	INITIAL FRESH WATER HEADS -	81490
	WRITE (NW,550)	81500
	CALL READ(HF,K3,NY,NX,F3)	81510
C	*****	81520
C		81530
C	INITIAL INTERFACE ELEVATION -	81540
	WRITE (NW,560)	81550
	CALL READ(Z1,K4,NY,NX,F4)	81560
C	*****	81570
C		81580
C	X-HYDRAULIC CONDUCTIVITY -	81590
	WRITE (NW,570)	81600
	CALL READ(XK,K5,NY,NX,F5)	81610
C	*****	81620
C		81630
C	Y-HYDRAULIC CONDUCTIVITY -	81640
	WRITE (NW,580)	81650
	CALL READ(YK,K6,NY,NX,F6)	81660
C	*****	81670
C		81680
C	SPECIFIC STORAGE -	81690
	WRITE (NW,590)	81700
	CALL READ(S,K7,NY,NX,F7)	81710
C	*****	81720
C		81730
C	ELEVATION OF AQUIFER BASE -	81740
	WRITE (NW,600)	81750
	CALL READ(ZB,K8,NY,NX,F8)	81760
C	*****	81770
C		81780
C	POROSITY -	81790
	WRITE (NW,610)	81800
	CALL READ(POR,K9,NY,NX,F9)	81810
C	*****	81820
C	NOTE: POROSITY IS USED TO KEY IN ON ZERO BLOCKS	81830
	DO 120 I=1,NX	81840
	DO 120 J=1,NY	81850
	BH(I,J)=0.	81860
120	BL(I,J)=0.	81870

C		81880
C	AQUIFER THICKNESS -	81890
	IF (ALPHA.EQ.1.0) GO TO 130	81900
	WRITE (NW,620)	81910
	CALL READ (TH,K10,NY,NX,F10)	81920
C	*****	81930
C		81940
C	LEAKAGE -	81950
	IF (ILK.EQ.0) GO TO 130	81960
	READ (NR,750) K11,K12	81970
C	K11 - READ 1 IF CONFINING BED HEAD IS UNIFORM	81980
C	K12 - READ 1 IF CONFINING BED LEAKANCE (K/B) IS UNIFORM	81990
C		82000
	READ (NR,760) F11,F12	82010
	IF (F11.EQ.0.) F11=1.0	82020
	IF (F12.EQ.0.) F12=1.0	82030
C	F11 - MULTIPLICATION FACTOR FOR CONFINING BED HEAD	82040
C	F12 - MULTIPLICATION FACTOR FOR CONFINING BED LEAKANCE	82050
C	CONFINING BED HEAD -	82060
	WRITE (NW,630)	82070
	CALL READ (BH,K11,NY,NX,F11)	82080
C	*****	82090
C		82100
C	CONFINING BED LEAKANCE -	82110
	WRITE (NW,640)	82120
	CALL READ (BL,K12,NY,NX,F12)	82130
C	*****	82140
130	CONTINUE	82150
C		82160
C	DENSITIES AND VISCOSITIES -	82170
	READ (NR,760) DENF,DENS,VF,VS	82180
C	DENF - FRESH WATER DENSITY	82190
C	DENS - SALT WATER DENSITY	82200
C	VF - FRESH WATER VISCOSITY	82210
C	VS - SALT WATER VISCOSITY	82220
	WRITE (NW,650) DENF,DENS,VF,VS	82230
C		82240
C	RECHARGE -	82250
	WRITE (NW,660)	82260
	READ (NR,760) RECHG	82270
	PRINT 770, RECHG	82280
	DO 140 J=1,NY	82290
	DO 140 I=1,NX	82300
	WT1(I,J)=0.0	82310
	WB(I,J)=0.0	82320
	DQS(I,J)=0.	82330
	DQF(I,J)=0.	82340
	QT(I,J)=0.E0	82350
140	QF(I,J)=0.E0	82360
C		82370
C	CUBIC FEET PER SECOND	82380
C	SOURCE/SINK (NEGATIVE IMPLIES OUT) -	82390
	IF (NF.EQ.0) GO TO 160	82400
	WRITE (NW,670)	82410
	WRITE (NW,680)	82420

	DO 150 K=1,NF	82430
	READ (NR,780) I,J,QT(I,J),WT1(I,J),WB(I,J)	82440
150	PRINT 790, I,J,QT(I,J),WT1(I,J),WB(I,J)	82450
C	WT1 - ELEVATION OF TOP OF WELL SCREEN	82460
C	WB - ELEVATION OF BOTTOM OF WELL SCREEN	82470
160	CONTINUE	82480
	READ (NR,800) IDELT,ZMAX	82490
	PRINT 810, IDELT,ZMAX	82500
C	IDELT - READ 1 FOR CONSTANT TIME STEP;	82510
C	0 FOR AUTO TIME STEP (BASED ON A MAXIMUM CHANGE IN	82520
C	INTERFACE ELEVATION OF ZMAX)	82530
C		82540
C	CONSTANT SALT WATER HEAD NODES -	82550
	DO 170 I=1,NX	82560
	DO 170 J=1,NY	82570
170	NHS(I,J)=0	82580
	IF (NHSC.EQ.0) GO TO 190	82590
	WRITE (NW,690)	82600
	DO 180 K=1,NHSC	82610
	READ (NR,750) I,J	82620
	WRITE (NW,700) I,J	82630
180	NHS(I,J)=1	82640
190	CONTINUE	82650
C		82660
C	CONSTANT FRESH WATER HEAD NODES -	82670
	DO 200 I=1,NX	82680
	DO 200 J=1,NY	82690
200	NHF(I,J)=0	82700
	IF (NHFC.EQ.0) GO TO 220	82710
	WRITE (NW,710)	82720
	DO 210 K=1,NHFC	82730
	READ (NR,750) I,J	82740
	WRITE (NW,700) I,J	82750
210	NHF(I,J)=1	82760
220	CONTINUE	82770
C		82780
C	NUMBER GRID BLOCKS -	82790
C	NP(I,J) - SEQUENCE NUMBERING OF BLOCKS I,J	82800
	IBN=0	82810
	NFE(1)=1	82820
	DO 250 J=1,NY	82830
	DO 240 I=1,NX	82840
	IF (POR(I,J).EQ.0.) GO TO 230	82850
	IBN=IBN+1	82860
	NP(I,J)=IBN	82870
	GO TO 240	82880
230	NP(I,J)=0	82890
240	CONTINUE	82900
	NFE(J+1)=IBN+1	82910
250	CONTINUE	82920
	NB=IBN	82930
	IF (ID4.NE.1) GO TO 270	82940
	WRITE (NW,720)	82950
	DO 260 J=1,NY	82960
260	WRITE (NW,730) (NP(I,J),I=1,NX)	82970

610	FORMAT (//////,11X,8HPOROSITY/11X,8(1H-)/)	B3530
620	FORMAT (//////,11X,17HAQUIFER THICKNESS/11X,17(1H-)/)	B3540
630	FORMAT (//////,11X,18HCONFINING BED HEAD/11X,18(1H-)/)	B3550
640	FORMAT (//////,11X,22HCONFINING BED LEAKANCE/11X,22(1H-)/)	B3560
650	FORMAT (//////,11X,19HFRESH WATER DENSITY,G12.4/11X,18HSALT WATER D	B3570
	ENSITY,G13.4/11X,21HFRESH WATER VISCOSITY,G10.4/11X,20HSALT WATER	B3580
	2VISCOSITY,G11.4/)	B3590
660	FORMAT (//////,11X,8HRECHARGE/11X,8(1H-)/)	B3600
670	FORMAT (//////,11X,11HSOURCE/SINK/11X,11(1H-)/)	B3610
680	FORMAT (/ ,13X,13HI J QT,9X,3HWT1,10X,2HWB/)	B3620
690	FORMAT (//////,11X,30HCONSTANT SALT WATER HEAD NODES/11X,30(1H-)/)	B3630
700	FORMAT (11X,2HI=I4,4H, J={4})	B3640
710	FORMAT (//////,11X,31HCONSTANT FRESH WATER HEAD NODES/11X,31(1H-)/)	B3650
720	FORMAT (///11X,12HGRID NUMBERS/11X,12(1H-))	B3660
730	FORMAT (11X,16I5)	B3670
740	FORMAT (20A3)	B3680
750	FORMAT (16I4)	B3690
760	FORMAT (8G10.4)	B3700
770	FORMAT (//10X,12HRECHARGE = ,G10.4)	B3710
780	FORMAT (2I4,3G10.4)	B3720
790	FORMAT (11X,2I4,3(2X,G10.3))	B3730
800	FORMAT (14,G10.4)	B3740
810	FORMAT (//11X,7HIDELI= ,I4,2X,6HZMAX= ,G10.4)	B3750
	END	B3760-
	SUBROUTINE READ(DUM,KODE,NY,NX,FAC)	C 10
	*****	C 20
C		C 30
C	CALLED FROM GDATA	C 40
C	PURPOSE: TO READ TWO-DIMENSIONAL ARRAYS	C 50
C	-----	C 60
	DIMENSION DUM(34,32)	C 70
C	-----	C 80
	NR=7	C 90
	NW=6	C 100
	IF (KODE.EQ.1) GO TO 20	C 110
	DO 10 J=1,NY	C 120
10	READ (NR,110) (DUM(I,J),I=1,NX)	C 130
	GO TO 40	C 140
20	READ (NR,110) DUM1	C 150
	DO 30 J=1,NY	C 160
	DO 30 I=1,NX	C 170
30	DUM(I,J)=DUM1	C 180
40	DO 50 J=1,NY	C 190
	DO 50 I=1,NX	C 200
50	DUM(I,J)=DUM(I,J)*FAC	C 210
	IF (KODE.EQ.1) GO TO 70	C 220
	DO 60 J=1,NY	C 230
60	WRITE (NW,90) J,(DUM(I,J),I=1,NX)	C 240
	GO TO 80	C 250
70	WRITE (NW,100) DUM(1,1)	C 260
80	CONTINUE	C 270
	RETURN	C 280
C		C 290
C		C 300
	90 FORMAT (/7X,I2,2X,8(G12.5,2X),/, (11X,8(G12.5,2X)))	C 310

C		82980
C		82990
C	COMPUTE INITIAL SALT WATER HEAD -	83000
	270 DO 280 J=1,NY	83010
	DO 280 I=1,NX	83020
	IF (POR(I,J).LE.0.) GO TO 280	83030
	HS(I,J)=DENF/DENS*HF(I,J)+(DENS-DENF)/DENS*Z1(I,J)	83040
	280 CONTINUE	83050
C		83060
	RETURN	83070
C		83080
	290 FORMAT (1H1,///25X,36HSALT WATER-FRESH WATER FLOW ANALYSIS//)	83090
	300 FORMAT (11X,70(1H*)//11X,20A3//11X,70(1H*)//)	83100
	310 FORMAT (//5X,59H***** FATAL ERROR -- ZERO COLUMNS *****)	83110
	320 FORMAT (//5X,56H***** FATAL ERROR -- ZERO ROWS *****)	83120
	330 FORMAT (//5X,47H***** FATAL ERROR -- ZERO NON-ZERO BLOCKS *****)	83130
	340 FORMAT (/11X,22HFINITE DIFFERENCE DATA/11X,22(1H-)/)	83140
	350 FORMAT (1H,10X,11HNUMBER OF -,2X,7HCOLUMNS,123/21X,1H-,2X,4HROWS,	83150
	1126/21X,1H-,2X,15HNON-ZERO BLOCKS,115/21X,1H-,2X,9HNOT USED,121/2	83160
	21X,1H-,2X,18HMAXIMUM TIME STEPS,112/21X,1H-,2X,15HSOURCES,	83170
	3115/21X,1H-,2X,21HCONSTANT HEADS (SALT),19/21X,1H-,2X,22HCONSTANT	83180
	4HEADS (FRESH),18/21X,1H-,2X,18HLAGGING ITERATIONS,112//)	83190
	360 FORMAT (///,11X,15HTIME PARAMETERS/11X,15(1H-)//11X,28HINITIAL TIM	83200
	1E STEP IN SECONDS,622.6//11X,19HWEIGHTING PARAMETER,631.2/11X,22H0	83210
	2VER-RELAXATION FACTOR,628.2//)	83220
	370 FORMAT (610.0,4I4)	83230
	380 FORMAT (//,11X,6HALPHA=,F4.1,1X,22HWATER-TABLE CONDITIONS)	83240
	390 FORMAT (//,11X,6HALPHA=,F4.1,1X,21HCONFINED CONDITIONS -/22X,56HMO	83250
	1ST READ AQUIFER THICKNESS AND NONZERO SPECIFIC STORAGE)	83260
	400 FORMAT (/////11X,26HTHE FOLLOWING ARE UNIFORM:)	83270
	410 FORMAT (40X,9HX-SPACING)	83280
	420 FORMAT (40X,9HY-SPACING)	83290
	430 FORMAT (40X,25HINITIAL FRESH WATER HEADS)	83300
	440 FORMAT (40X,27HINITIAL INTERFACE ELEVATION)	83310
	450 FORMAT (40X,24HX-HYDRAULIC CONDUCTIVITY)	83320
	460 FORMAT (40X,24HY-HYDRAULIC CONDUCTIVITY)	83330
	470 FORMAT (40X,16HSPECIFIC STORAGE)	83340
	480 FORMAT (40X,25HELEVATION OF AQUIFER BASE)	83350
	490 FORMAT (40X,8HPOROSITY)	83360
	500 FORMAT (40X,17HAQUIFER THICKNESS)	83370
	510 FORMAT (/////11X,26HMULTIPLICATION FACTORS FOR/11X,26(1H-)//11X,9	83380
	1HX-SPACING,627.3/11X,9HY-SPACING,627.3/11X,24HINITIAL FRESH WATER	83390
	2HEAD,612.3/11X,27HINITIAL INTERFACE ELEVATION,69.3/11X,24HX-HYDRAU	83400
	3LIC CONDUCTIVITY,612.3/11X,24HY-HYDRAULIC CONDUCTIVITY,612.3/11X,1	83410
	46HSPECIFIC STORAGE,620.3/11X,25HELEVATION OF AQUIFER BASE,611.3/11	83420
	5X,8HPOROSITY,623.3/11X,17HAQUIFER THICKNESS,619.3//)	83430
	520 FORMAT (/////11X,22HSPACING IN X-DIRECTION/11X,22(1H-)/)	83440
	530 FORMAT (/11X,8(G12.5,2X))	83450
	540 FORMAT (/////11X,22HSPACING IN Y-DIRECTION/11X,22(1H-)/)	83460
	550 FORMAT (/////11X,25HINITIAL FRESH WATER HEADS/11X,25(1H-)/)	83470
	560 FORMAT (/////11X,27HINITIAL INTERFACE ELEVATION/11X,27(1H-)/)	83480
	570 FORMAT (/////11X,24HX-HYDRAULIC CONDUCTIVITY/11X,24(1H-)/)	83490
	580 FORMAT (/////11X,24HY-HYDRAULIC CONDUCTIVITY/11X,24(1H-)/)	83500
	590 FORMAT (/////11X,16HSPECIFIC STORAGE/11X,16(1H-)/)	83510
	600 FORMAT (/////11X,25HELEVATION OF AQUIFER BASE/11X,25(1H-)/)	83520

100	FORMAT (/11X,612.5)	C 320
110	FORMAT (8G10.0)	C 330
	END	C 340-
	SUBROUTINE TICALC(DY,DX,POR,XK,YK,TY,TX,NY,NX,NYY,NXX)	D 10
	*****	D 20
C		D 30
C	CALLED FROM MAIN	D 40
C	PURPOSE: TO COMPUTE TRANSMISSIVITY TERMS -	D 50
C	-----	D 60
	DIMENSION DY(1), DX(1), XK(34,32), YK(34,32), TY(34,33), TX(35,32)	D 70
	1, POR(34,32)	D 80
C	-----	D 90
C		D 100
C	COMPUTE TRANSMISSIVITY TERMS IN THE X-DIRECTION -	D 110
	DO 10 J=1,NY	D 120
C	IF ONLY ONE COLUMN, SKIP CALCULATIONS -	D 130
	IF (NX.EQ.1) GO TO 20	D 140
	DO 10 I=2,NX	D 150
	TX(I,J)=0.	D 160
	IF (POR(1,J).LE.0..OR.POR(I-1,J).LE.0.) GO TO 10	D 170
	TXC=DY(J)/DX(I-1)	D 180
	TXD=DY(J)/DX(I)	D 190
	TXA=TXC*XK(I-1,J)	D 200
	TXB=TXD*XK(I,J)	D 210
	TTT=TXA+TXB	D 220
C	PERMEABILITY TERM -	D 230
	TX(I,J)=2.0*TXA*TXB/TTT	D 240
	10 CONTINUE	D 250
	20 CONTINUE	D 260
C		D 270
C	COMPUTE TRANSMISSIVITY TERMS IN THE Y-DIRECTION -	D 280
	DO 30 I=1,NX	D 290
	IF (NY.EQ.1) GO TO 40	D 300
	DO 30 J=2,NY	D 310
	TY(I,J)=0.	D 320
	IF (POR(I,J).LE.0..OR.POR(I,J-1).LE.0.) GO TO 30	D 330
	TYC=DX(1)/DY(J-1)	D 340
	TYD=DX(1)/DY(J)	D 350
	TYA=TYC*YK(I,J-1)	D 360
	TYB=TYD*YK(I,J)	D 370
	TTT=TYA+TYB	D 380
	TY(I,J)=2.0*TYA*TYB/TTT	D 390
	30 CONTINUE	D 400
	40 CONTINUE	D 410
C		D 420
C	SET TRANSMISSIVITY OF BOUNDARY BLOCKS (REGULAR RECTANGULAR MESH)	D 430
C	TO ZERO (NO-FLOW) -	D 440
	DO 50 I=1,NX	D 450
	TY(I,1)=0.E0	D 460
	TY(I,NYY)=0.E0	D 470
	50 CONTINUE	D 480
C		D 490
	DO 60 J=1,NY	D 500
	TX(1,J)=0.E0	D 510
	TX(NXX,J)=0.E0	D 520

60	CONTINUE	D 530
	RETURN	D 540
	END	D 550-
	SUBROUTINE COEF(L,DELTA,DZMX)	E 10
	*****	E 20
C		E 30
C		E 40
C	CALLED FROM MAIN	E 50
C	PURPOSE: TO COMPUTE THE REST OF THE SPACE COEFFICIENTS	E 60
C	(OTHER THAN THOSE COMPUTED IN TCAIC)	E 70
C	AND TIME COEFFICIENTS	E 80
	-----	E 90
	COMMON /INPUT/ S(34,32),XK(34,32),YK(34,32),HF(34,32),HS(34,32),DX	E 100
	1(34),DY(32),ZB(34,32),Z1(34,32),OF(34,32),OT(34,32),POR(34,32),TH(E 110
	234,32),NP(34,32)	E 120
	COMMON /CONTROL/ TIME,DELTA,DENS,DENF,VS,VF,WT,ZMAX,ALPHA,WD,NK,NX,N	E 130
	1Y,NXX,NYY,NB,NBB,NT,MBA,MBAE,IPT,NIT,RECHG	E 140
	COMMON /WORK/ AX(35,32),BX(35,32),AY(34,33),BY(34,33),TX(35,32),TY	E 150
	1(34,33),F(34,32),R(34,32),C(34,32),O(34,32),FT(34,32),ST(34,32),BH	E 160
	2(34,32),BL(34,32),NHS(34,32),NHF(34,32),DNF(34,32),DQS(34,32),WT1(E 170
	334,32),WB(34,32)	E 180
	-----	E 190
	RAF=DENF/(DENF-DENS)	E 200
	RAS=DENS/(DENF-DENS)	E 210
	DZMX=-1.0	E 220
	IF (L.NE.1) GO TO 20	E 230
C		E 240
C	INITIALIZE SPACE COEFFICIENTS -	E 250
	DO 10 I=1,NX	E 260
	DO 10 J=1,NY	E 270
	FT(I,J)=0.00	E 280
	ST(I,J)=0.00	E 290
C	FT - COEFFICIENT FOR FRESH WATER	E 300
C	ST - COEFFICIENT FOR SALT WATER	E 310
10	CONTINUE	E 320
20	CONTINUE	E 330
	DO 50 I=1,NX	E 340
	DO 50 J=1,NY	E 350
	IF (POR(I,J).EQ.0.0) GO TO 50	E 360
	K=NP(I,J)	E 370
	NHF=HF(I,J)	E 380
	NHS=HS(I,J)	E 390
	ZIE=RAF*NHF-RAS*NHS	E 400
	IF (ZIE.LT.ZB(I,J)) ZIE=ZB(I,J)	E 410
	FTH=NHF-ZIE	E 420
	IF (FTH.LE.0.) FTH=0.	E 430
	STH=ZIE-ZB(I,J)	E 440
	IF (ALPHA.EQ.1.0) GO TO 30	E 450
	TOP=ZB(I,J)+TH(1,J)	E 460
	FTH=TOP-ZIE	E 470
	IF (FTH.LT.0.) FTH=0.	E 480
	STH=FTH(1,J)-FTH	E 490
30	CONTINUE	E 500
C		E 510
C	COMPUTE TIME COEFFICIENTS -	E 520
C		

	AREA=DX(1)*DY(J)	E 530
C	FRESH WATER EQUATION	E 540
C	FRESH WATER DERIVATIVE -	E 550
	F(I,J)=AREA*(S(I,J)*FTH-POR(I,J)*RAF+ALPHA*POR(I,J))	E 560
C	SALT WATER DERIVATIVE -	E 570
	B(I,J)=AREA*POR(I,J)*RAS	E 580
C		E 590
C	SALT WATER EQUATION -	E 600
C	FRESH WATER DERIVATIVE -	E 610
	C(I,J)=AREA*POR(I,J)*RAF	E 620
C	SALT WATER DERIVATIVE -	E 630
	D(I,J)=AREA*(DENS/DENF*S(I,J)*STH-POR(I,J)*RAS)	E 640
C		E 650
C	COMPUTE SPACE COEFFICIENTS -	E 660
	FT(I,J)=FTH	E 670
	ST(I,J)=STH*VF/VS*DENS/DENF	E 680
	IF (L.EQ.1) GO TO 40	E 690
	IF (IDELT.EQ.1) GO TO 40	E 700
C		E 710
C	COMPUTE TIME STEP INCREASING FACTOR -	E 720
	DZI=ZI(I,J)-ZIE	E 730
	IF (DZI.LI.0.EQ) DZI=-DZI	E 740
	IF (DZI.GT.DZMX) DZMX=DZI	E 750
40	CONTINUE	E 760
50	CONTINUE	E 770
	RETURN	E 780
	END	E 790-
	SUBROUTINE FORMED(AF,AS,RF,RS)	F 10
	*****	F 20
C		F 30
C		F 40
C	CALLED FROM MAIN	F 50
C	PURPOSE: FORM FINAL MATRIX EQUATIONS	F 60
C	-----	F 70
	DIMENSION AF(1), AS(1), RF(1), RS(1)	F 80
	COMMON /INPUT/ S(34,32), XK(34,32), YK(34,32), HF(34,32), HS(34,32), DX	F 90
	1(34), DY(32), ZH(34,32), ZI(34,32), QF(34,32), QT(34,32), POR(34,32), TH(F 100
	234,32), NP(34,32)	F 110
	COMMON /CONTROL/ TIME, DELT, DENS, DENF, VS, VF, WT, ZMAX, ALPHA, WO, NK, NX, N	F 120
	1Y, NXX, NYY, NB, NBB, NT, MBW, MBE, IPT, NIT, RECHG	F 130
	COMMON /WORK/ AX(35,32), BX(35,32), AY(34,33), BY(34,33), TX(35,32), TY	F 140
	1(34,33), F(34,32), B(34,32), C(34,32), D(34,32), FT(34,32), ST(34,32), BH	F 150
	2(34,32), BL(34,32), NHS(34,32), NHF(34,32), DQF(34,32), DQS(34,32), WT1(F 160
	334,32), Wb(34,32)	F 170
C	-----	F 180
	RAF=DENF/(DENF-DENS)	F 190
	RAS=DENS/(DENF-DENS)	F 200
	DO 10 K=1,NB	F 210
	RF(K)=0.	F 220
	RS(K)=0.	F 230
	DO 10 L=1,4	F 240
	N=4*(K-1)	F 250
	AF(N+L)=0.	F 260
10	AS(N+L)=0.	F 270
	K1=0	F 280
	K=-3	

DO 60 J=1,NY	F 290
DO 60 I=1,NX	F 300
IF (POR(I,J).EQ.0.) GO TO 60	F 310
K1=K1+1	F 320
K=K+4	F 330
AREA=DX(I)*DY(J)	F 340
C FRESH WATER EQUATION	F 350
C DIAGONAL	F 360
DIAP=-AX(I,J)-AX(I+1,J)-AY(I,J)-AY(I,J+1)-BL(I,J)*AREA	F 370
RHSF=-DIAP*HF(I,J)-BL(I,J)*BH(I,J)*AREA-RECHG*AREA	F 380
DIAP=DIAP-F(I,J)/DELT	F 390
C OFF DIAGONAL	F 400
AF(K+2)=AX(I+1,J)	F 410
C COMPLETE RIGHT HAND SIDE	F 420
IF (I.GT.1) RHSF=RHSF-AX(I,J)*HF(I-1,J)	F 430
IF (I.LT.NX) RHSF=RHSF-AX(I+1,J)*HF(I+1,J)	F 440
IF (J.GT.1) RHSF=RHSF-AY(I,J)*HF(I,J-1)	F 450
IF (J.LT.NY) RHSF=RHSF-AY(I,J+1)*HF(I,J+1)	F 460
C SALT WATER EQUATION	F 470
C DIAGONAL	F 480
DIAS=-BX(I,J)-BX(I+1,J)-BY(I,J)-BY(I,J+1)	F 490
RHSS=-DIAS*HS(I,J)	F 500
DIAS=DIAS-D(I,J)/DELT	F 510
C OFF DIAGONAL	F 520
AS(K+3)=BX(I+1,J)	F 530
C COMPLETE RIGHT HAND SIDE	F 540
IF (I.GT.1) RHSS=RHSS-BX(I,J)*HS(I-1,J)	F 550
IF (I.LT.NX) RHSS=RHSS-BX(I+1,J)*HS(I+1,J)	F 560
IF (J.GT.1) RHSS=RHSS-BY(I,J)*HS(I,J-1)	F 570
IF (J.LT.NY) RHSS=RHSS-BY(I,J+1)*HS(I,J+1)	F 580
C WELL TERMS	F 590
FDQB=1.0	F 600
DQDF=0.	F 610
DQDS=0.	F 620
IF (QT(I,J).EQ.0.) GO TO 30	F 630
IF (ZI(I,J).LT.WB(1,J)) GO TO 20	F 640
FDQB=0.	F 650
WTOP=WT1(I,J)	F 660
IF (ALPHA.EQ.1.) WTOP=HF(I,J)	F 670
IF (ZI(I,J).GT.WTOP) GO TO 20	F 680
WTH=WTOP-WB(1,J)	F 690
IF (WTH.LE.0.) GO TO 30	F 700
WETH=WTOP-RAF*HF(I,J)+RAS*HS(1,J)	F 710
FDQB=WETH/WTH	F 720
DQDF=(WTH*(ALPHA-RAF)-ALPHA*WETH)/(WTH*WTH)*QT(I,J)	F 730
DQDS=RAS/WTH*QT(I,J)	F 740
20 RHSF=RHSF-QT(1,J)*FDQB	F 750
RHSS=RHSS-RT(1,J)*(1.-FDQB)	F 760
DIAP=DIAP+DQDF	F 770
DIAS=DIAS-DQDS	F 780
QF(I,J)=QT(I,J)*FDQB	F 790
DQF(I,J)=DQDF	F 800
DQS(I,J)=DQDS	F 810
30 CONTINUE	F 820
C CONSTANT HEAD CONDITIONS	F 830

C	FRESH WATER	F 840
	IF (NHF(I,J).NE.1) GO TO 40	F 850
	RHSF=0.	F 860
	DIAF=DIAF*1.E16	F 870
C	SALT WATER	F 880
	40 IF (NHS(1,J).NE.1) GO TO 50	F 890
	RHSS=0.	F 900
	DIAS=DIAS*1.E16	F 910
	50 CONTINUE	F 920
C	COMPLETE LOADING	F 930
	AF(K+1)=DNDS-B(1,J)/DELT	F 940
	AS(K)=-DDDF-C(I,J)/DELT	F 950
	AF(K)=DIAF	F 960
	AS(K+1)=DIAS	F 970
	RF(K1)=RHSF	F 980
	RS(K1)=RHSS	F 990
	60 CONTINUE	F1000
	RETURN	F1010
	END	F1020-
	SUBROUTINE BSBAND(A1,A2,B1,B2,C111,C112,C121,C122,NEQ,NT,INTRY)	G 10
	*****	G 20
C		G 30
C	CALLER FROM MAIN	G 40
C	PURPOSE: FACTOR BLOCK SYMMETRIC MATRIX	G 50
C	FORWARD AND BACK SUBSTITUTE	G 60
C	-----	G 70
	DIMENSION A1(1), A2(1), B1(1), B2(1), C111(1), C112(1), C121(1), C	G 80
	1122(1)	G 90
C	-----	G 100
	NR=NEQ-1	G 110
	NI=NEQ	G 120
	IF (NEQ.EQ.1) GO TO 50	G 130
	IF (INTRY.EQ.2) GO TO 20	G 140
	I1=-3	G 150
	DO 10 I=1,NR	G 160
	I1=I1+4	G 170
	I2=I1+1	G 180
	I3=I1+2	G 190
	I4=I1+3	G 200
	L1=I1+4	G 210
	L2=L1+1	G 220
	IT=NT+I	G 230
	L=I+1	G 240
	D1=A1(I1)*A2(I2)-A1(I2)*A2(I1)	G 250
	C1=1./D1	G 260
	P11=A2(I2)*C1	G 270
	P12=-A1(I2)*C1	G 280
	P21=-A2(I1)*C1	G 290
	P22=A1(I1)*C1	G 300
	IF (L.GT.NEQ) GO TO 10	G 310
	C11=A1(I3)*P11+A1(I4)*P21	G 320
	C12=A1(I3)*P12+A1(I4)*P22	G 330
	C21=A2(I3)*P11+A2(I4)*P21	G 340
	C22=A2(I3)*P12+A2(I4)*P22	G 350
	C111(IT)=C11	G 360

CI12(I1)=C12	G 370
CI21(I1)=C21	G 380
CI22(I1)=C22	G 390
A1(L1)=A1(L1)+(-C11*A1(I3)-C12*A2(I3))	G 400
A1(L2)=A1(L2)+(-C11*A1(I4)-C12*A2(I4))	G 410
A2(L1)=A2(L1)+(-C21*A1(I3)-C22*A2(I3))	G 420
A2(L2)=A2(L2)+(-C21*A1(I4)-C22*A2(I4))	G 430
D11=P11*A1(I3)+P12*A2(I3)	G 440
D12=P11*A1(I4)+P12*A2(I4)	G 450
D21=P21*A1(I3)+P22*A2(I3)	G 460
D22=P21*A1(I4)+P22*A2(I4)	G 470
A1(I3)=D11	G 480
A1(I4)=D12	G 490
A2(I3)=D21	G 500
A2(I4)=D22	G 510
10 CONTINUE	G 520
RETURN	G 530
C	G 540
C*** FORWARD SUBSTITUTION	G 550
C	G 560
20 CONTINUE	G 570
I1=-3	G 580
DO 40 I=1,NR	G 590
I1=I1+4	G 600
I2=I1+1	G 610
IT=NT+1	G 620
L=I+1	G 630
D1=A1(I1)*A2(I2)-A1(I2)*A2(I1)	G 640
C1=1./D1	G 650
P11=A2(I2)*C1	G 660
P12=-A1(I2)*C1	G 670
P21=-A2(I1)*C1	G 680
P22=A1(I1)*C1	G 690
IF (L.GT.NEQ) GO TO 30	G 700
B1(L)=B1(L)-CI11(I1)*B1(I)-CI12(I1)*B2(I)	G 710
B2(L)=B2(L)-CI21(I1)*B1(I)-CI22(I1)*B2(I)	G 720
30 BB1=P11*B1(I)+P12*B2(I)	G 730
BB2=P21*B1(I)+P22*B2(I)	G 740
B1(I)=BB1	G 750
B2(I)=BB2	G 760
40 CONTINUE	G 770
C	G 780
C*** BACKWARD SUBSTITUTION	G 790
C	G 800
50 N1=4*NR+1	G 810
N2=N1+1	G 820
DN=A1(N1)*A2(N2)-A1(N2)*A2(N1)	G 830
CN=1./DN	G 840
B2N=(A1(N1)*B2(N1)-A2(N1)*B1(N1))*CN	G 850
B1N=(A2(N2)*B1(N1)-A1(N2)*B2(N1))*CN	G 860
B1(N1)=B1N	G 870
B2(N1)=B2N	G 880
IF (NEQ.EQ.1) RETURN	G 890
K3=N2+1	G 900
DO 60 I=1,NR	G 910

	K3=K3-4	G 920
	K4=K3+1	G 930
	K=NEQ-I	G 940
	L=K+1	G 950
	B2(K)=B2(K)-A2(K3)*B1(L)-A2(K4)*B2(L)	G 960
	B1(K)=B1(K)-A1(K3)*B1(L)-A1(K4)*B2(L)	G 970
60	CONTINUE	G 980
	RETURN	G 990
	END	G1000-
	SUBROUTINE PDATA(L,ITP)	H 10
	*****	H 20
C		H 30
C		H 40
C	CALLED FROM MAIN	H 50
C	PURPOSE: TO PRINT COMPUTED OUTPUT	H 60
C	-----	H 70
	DIMENSION MAF(34,32)	H 80
	COMMON /INPUT/ S(34,32),XK(34,32),YK(34,32),HF(34,32),HS(34,32),DX	H 90
	1(34),DY(32),ZB(34,32),ZI(34,32),WF(34,32),WT(34,32),POR(34,32),TH(H 100
	234,32),NP(34,32)	H 110
	COMMON /CONTROL/ TIME,DELT,DENS,DENF,VS,VF,WT,ZMAX,ALPHA,W0,NK,NX,N	H 120
	1Y,NXX,NYY,NB,NBB,NT,MBW,MBE,IPT,NIT,RECHG	H 130
	COMMON /WORK/ AX(35,32),BX(35,32),AY(34,33),BY(34,33),TX(35,32),TY	H 140
	1(34,33),F(34,32),B(34,32),C(34,32),D(34,32),FT(34,32),ST(34,32),BH	H 150
	2(34,32),BL(34,32),NHS(34,32),NHF(34,32),DOF(34,32),DQS(34,32),WT1(H 160
	334,32),WB(34,32)	H 170
C	-----	H 180
C		H 190
	TMN=TIME/60.	H 200
	THR=TMN/60.	H 210
	TDA=THR/24.	H 220
	TYR=TDA/365.	H 230
	PRINT 90, L, TIME, TMN, THR, TDA, TYR	H 240
C		H 250
C	COMPUTE INTERFACE ELEVATION -	H 260
	RAF=DENF/(DENF-DENS)	H 270
	RAS=DENS/(DENF-DENS)	H 280
	DO 10 I=1,NX	H 290
	DO 10 J=1,NY	H 300
	IF (POR(I,J).EQ.0.) GO TO 10	H 310
	ZI(I,J)=RAF*HF(I,J)-RAS*HS(I,J)	H 320
10	CONTINUE	H 330
	IF (MOD(L,ITP).NE.0) GO TO 80	H 340
	PRINT 100	H 350
	DO 20 J=1,NY	H 360
20	PRINT 110, J, (HF(1,J),I=1,NX)	H 370
	PRINT 120	H 380
	DO 30 J=1,NY	H 390
30	PRINT 110, J, (ZI(1,J),I=1,NX)	H 400
	IF (IPT.NE.1) GO TO 50	H 410
	PRINT 130	H 420
	DO 40 J=1,NY	H 430
40	PRINT 110, J, (HS(1,J),I=1,NX)	H 440
50	CONTINUE	H 450
	DO 60 I=1,NX	H 460
	DO 60 J=1,NY	

MAP(I,J)=0	H 470
ZIT=ZI(1,J)	H 480
ZBT=ZB(I,J)	H 490
IF (ZII.GT.ZBT) MAP(I,J)=1	H 500
IF (ABS(ZIT-ZBT).LE.0.01) MAP(I,J)=0	H 510
TOP=ZBT+TH(I,J)	H 520
IF (ALPHA.EQ.1) TOP=HF(1,J)	H 530
IF (ZII.GT.TOP) MAP(I,J)=2	H 540
IF (ABS(ZII-TOP).LE.0.01) MAP(I,J)=2	H 550
IF (POR(I,J).EQ.0.) MAP(I,J)=9	H 560
60 CONTINUE	H 570
PRINT 140	H 580
DO 70 J=1,NY	H 590
70 PRINT 150, (MAP(I,J),I=1,NX)	H 600
80 CONTINUE	H 610
RETURN	H 620
C	H 630
90 FORMAT (///11X,11HSTEP NUMBER,I4,10X,26HSIMULATION TIME IN SECONDS	H 640
1,E10.3/11X,15(1H*),26X,10HIN MINUTES,E10.3/52X,10HIN HOURS ,E10.3	H 650
2/52X,10HIN DAYS ,E10.3/52X,10HIN YEARS ,E10.3//)	H 660
100 FORMAT (11X,16HFRESH WATER HEAD/11X,16(1H-)//)	H 670
110 FORMAT (/7X,12,2X,8(G12.5,2X),/, (11X,8(G12.5,2X)))	H 680
120 FORMAT (//11X,15HINTERFACE LEVEL/11X,15(1H-)//)	H 690
130 FORMAT (//11X,15HSALT WATER HEAD/11X,15(1H-)//)	H 700
140 FORMAT (//11X,42HWATER QUALITY MAP: 0=FRESH, 1=MIX, 2=SALT/11X,17	H 710
1(1H-)//)	H 720
150 FORMAT (11X,40I2)	H 730
END	H 740-
SUBROUTINE BAL(ICX,DELHF,DELHS)	I 10
*****	I 20
C	I 30
C CALLED FROM MAIN	I 40
C PURPOSE: TO COMPUTE MASS BALANCE	I 50
C -----	I 60
C DIMENSION DELHF(1), DELHS(1)	I 70
C	I 80
COMMON /INPUT/ S(34,32),XK(34,32),YK(34,32),HF(34,32),HS(34,32),DX	I 90
1(34),DY(32),ZB(34,32),ZI(34,32),QF(34,32),QT(34,32),POR(34,32),TH(I 100
234,32),NF(34,32)	I 110
COMMON /CONTROL/ TIME,DELT,DENS,DENF,VS,VF,WT,ZMAX,ALPHA,WD,NK,NX,N	I 120
1Y,NXX,NYY,NB,NBS,N1,MBW,MBE,IPT,N11,RECHG	I 130
COMMON /WORK/ AX(35,32),BX(35,32),AY(34,33),BY(34,33),TX(35,32),TY	I 140
1(34,33),F(34,32),B(34,32),C(34,32),D(34,32),FT(34,32),ST(34,32),BH	I 150
2(34,32),BL(34,32),NHS(34,32),NHF(34,32),DQF(34,32),DQS(34,32),WT1(I 160
334,32),WB(34,32)	I 170
C -----	I 180
C	I 190
C COMPUTE TOTAL MASS IN THE SYSTEM AND CHANGE IN MASS	I 200
TMFW=0.	I 210
TMSW=0.	I 220
DMFW=0.	I 230
DMSN=0.	I 240
DMFWE=0.	I 250
DMSWE=0.	I 260
DO 10 I=1,NX	I 270

DO 10 J=1,NY	I 280
IF (POR(I,J).LE.0.) GO TO 10	I 290
AREA=DX(I)*DY(J)	I 300
FTH=FT(I,J)	I 310
STH=ST(I,J)*VS/VF*DENF/DENS	I 320
TMFW=TMFW+FTH*POR(I,J)*AREA	I 330
TMSW=TMSW+STH*POR(I,J)*AREA	I 340
IF (ICX.EQ.0) GO TO 10	I 350
K=NP(I,J)	I 360
C SUM TOTAL CHANGE FROM EQUATION VIEWPOINT	I 370
DMFWE=DMFWE+F(I,J)*DELHF(K)+B(I,J)*DELHS(K)	I 380
DMSWE=DMSWE+C(I,J)*DELHF(K)+D(I,J)*DELHS(K)	I 390
C SUM THE STORAGE PART OF THE TRUE MASS CHANGE	I 400
DMFW=DMFW+S(I,J)*FTH*DELHF(K)*AREA	I 410
DMSW=DMSW+S(I,J)*DENS/DENF*STH*DELHS(K)*AREA	I 420
10 CONTINUE	I 430
IF (ICX.EQ.0) GO TO 50	I 440
CHF=0.	I 450
CHS=0.	I 460
RQ=0.	I 470
QFI=0.	I 480
QST=0.	I 490
QLK=0.	I 500
C BEGIN LOOP TO CALCULATE RATES OF OTHER COMPONENTS	I 510
DO 40 I=1,NX	I 520
DO 40 J=1,NY	I 530
IF (POR(I,J).LE.0.) GO TO 40	I 540
K=NP(I,J)	I 550
AREA=DX(I)*DY(J)	I 560
C CONSTANT HEAD FLUX--FRESH WATER	I 570
IF (NHFI(I,J).NE.1) GO TO 20	I 580
X=HF(I,J)	I 590
CHF=CHF+B(I,J)/DELT*DELHS(K)+AY(I,J+1)*X+AY(I,J)*X+AX(I+1,J)*X+AX(I,J)*X	I 600
IF (J.GT.1) CHF=CHF-AY(I,J)*HF(I,J-1)	I 610
IF (J.LT.NY) CHF=CHF-AY(I,J+1)*HF(I,J+1)	I 620
IF (I.GT.1) CHF=CHF-AX(I,J)*HF(I-1,J)	I 630
IF (I.LT.NX) CHF=CHF-AX(I+1,J)*HF(I+1,J)	I 640
C CONSTANT HEAD FLUX--SALT WATER	I 650
20 IF (NHS(I,J).NE.1) GO TO 30	I 660
X=HS(I,J)	I 670
CHS=CHS+C(I,J)/DELT*DELHF(K)+BY(I,J)*X+BY(I,J+1)*X+BX(I,J)*X+BX(I,J+1)*X	I 680
IF (J.GT.1) CHS=CHS-BY(I,J)*HS(I,J-1)	I 690
IF (J.LT.NY) CHS=CHS-BY(I,J+1)*HS(I,J+1)	I 700
IF (I.GT.1) CHS=CHS-BX(I,J)*HS(I-1,J)	I 710
IF (I.LT.NX) CHS=CHS-BX(I+1,J)*HS(I+1,J)	I 720
30 IF (NHFI(I,J).NE.1) RQ=RQ+RECHG*AREA	I 730
C SOURCE-SINK TERMS	I 740
DELQ=QFI(I,J)*DELHF(K)+DQS(I,J)*DELHS(K)	I 750
QFI=QFI+QF(I,J)+DELQ	I 760
QST=QST+QF(I,J)-QF(I,J)-DELQ	I 770
C LEAKAGE TERM	I 780
IF (NHFI(I,J).NE.1) QLK=QLK+BL(I,J)*(BH(I,J)-HF(I,J))*AREA	I 790
40 CONTINUE	I 800
	I 810
	I 820

C	VOLUME TOTALS	I 830
	TCHF=CHF*DELT	I 840
	TCHS=CHS*DELT	I 850
	TRQ=RQ*DELT	I 860
	TQF=QFT*DELT	I 870
	TQS=QST*DELT	I 880
	TQLK=QLK*DELT	I 890
	DELMF=-TMFW+TMFW1-DMFW	I 900
	DELS=-TMSW+TMSW1-DMSW	I 910
	TMFW1=TMFW	I 920
	TMSW1=TMSW	I 930
C	STORAGE CHANGE RATES	I 940
	X=1./DELT	I 950
	DELMFR=DELMF*X	I 960
	DELSR=DELS*X	I 970
	DELMFE=-DMFE*X	I 980
	DELMSE=-DMSW*X	I 990
C	PERCENT ERROR	I1000
	SUMP=0.	I1010
	SUMN=0.	I1020
	IF (TQLK.GT.0.) SUMP=SUMP+TQLK	I1030
	IF (TQLK.LE.0.) SUMN=SUMN+TQLK	I1040
	IF (TCHF.GT.0.) SUMP=SUMP+TCHF	I1050
	IF (TCHF.LE.0.) SUMN=SUMN+TCHF	I1060
	IF (TRQ.GT.0.) SUMP=SUMP+TRQ	I1070
	IF (TRQ.LE.0.) SUMN=SUMN+TRQ	I1080
	IF (DELMF.GT.0.) SUMP=SUMP+DELMF	I1090
	IF (DELMF.LE.0.) SUMN=SUMN+DELMF	I1100
	IF (TQF.GT.0.) SUMP=SUMP+TQF	I1110
	IF (TQF.LE.0.) SUMN=SUMN+TQF	I1120
	RES1=SUMN+SUMP	I1130
	PCEFM=RES1*100.	I1140
	IF (SUMP.GT.0.) PCEFM=PCEFM/SUMP	I1150
	SUMP=0.	I1160
	SUMN=0.	I1170
	IF (TCHS.GT.0.) SUMP=SUMP+TCHS	I1180
	IF (TCHS.LE.0.) SUMN=SUMN+TCHS	I1190
	IF (DELS.GT.0.) SUMP=SUMP+DELS	I1200
	IF (DELS.LE.0.) SUMN=SUMN+DELS	I1210
	IF (TQS.GT.0.) SUMP=SUMP+TQS	I1220
	IF (TQS.LE.0.) SUMN=SUMN+TQS	I1230
	RES3=SUMN+SUMP	I1240
	PCESM=RES3*100.	I1250
	IF (SUMP.GT.0.) PCESM=PCESM/SUMP	I1260
	PRINT 60, DELMFR,DELMF,DELSR,DELS,QFT,TQF,QST,TQS,CHF,TCHF,CHS,T	I1270
	1CHS,QLK,TQLK,RQ,TRQ,PCEFM,PCESM	I1280
	RES2=RES1*X	I1290
	RES4=RES3*X	I1300
	PRINT 70, RES2,RES1,RES4,RES3	I1310
	PRINT 80, DELMFE,DELMSE	I1320
	RETURN	I1330
50	TMFW1=TMFW	I1340
	TMSW1=TMSW	I1350
	PRINT 90, TMFW,TMSW	I1360
	RETURN	I1370

C

60	FORMAT (//46X,13HFRESH BALANCE,33X,12HSALT BALANCE/46X,13(1H-),33X	I1380
	1,12(1H-)/41X,10HRATE (CFS),5X,10HTOTAL (CF),19X,10HRATE (CFS),5X,1	I1390
	20HTOTAL (CF)//11X,17HCHANGE IN STORAGE,13X,G12.5,2X,G12.5,18X,G12.	I1400
	35,2X,G12.5/11X,11HSOURCE/SINK,19X,G12.5,2X,G12.5,18X,G12.5,2X,G12.	I1410
	45/11X,19HCONSTANT HEAD NODES,11X,G12.5,2X,G12.5,18X,G12.5,2X,G12.5	I1420
	5/11X,16HVERTICAL LEAKAGE,14X,G12.5,2X,G12.5/11X,8HRECHARGE,22X,G12	I1430
	6.5,2X,G12.5/11X,14HPER CENT ERROR,30X,G12.5,32X,G12.5/)	I1440
70	FORMAT (11X,6HTOTALS,24X,G12.5,2X,G12.5,18X,G12.5,2X,G12.5)	I1450
80	FORMAT (11X,21HCHANGE IN STORAGE,9X,G12.5,32X,G12.5/)	I1460
90	FORMAT (//11X,20HINITIAL FRESH VOLUME,G12.5,1X,10HCUBIC FEET/11X,2	I1470
	10HINITIAL SALT VOLUME,G12.5,1X,10HCUBIC FEET/)	I1480
	END	I1490
		I1500-

EOF..

SALT WATER-FRESH WATER FLOW ANALYSIS

HELE SHAW EXPERIMENTS TRANSIENT

FINITE DIFFERENCE DATA

NUMBER OF	COLUMNS	20
- ROWS		1
- NON-ZERO BLOCKS		20
- NOT USED		2
- MAXIMUM TIME STEPS		3
- SOURCES		0
- CONSTANT HEADS (SALT)		1
- CONSTANT HEADS (FRESH)		1
- LAGGING ITERATIONS		150

TIME PARAMETERS

INITIAL TIME STEP IN SECONDS	5.0000000
WEIGHTING PARAMETER	0.50
OVER-RELAXATION FACTOR	1.0

ALPHAS 0.0 CONFINED CONDITIONS -
MUST READ AQUIFER THICKNESS AND NONZERO SPECIFIC STORAGE

THE FOLLOWING ARE UNIFORM:

X-SPACING
Y-SPACING
X-HYDRAULIC CONDUCTIVITY
Y-HYDRAULIC CONDUCTIVITY
SPECIFIC STORAGE

ELEVATION OF AQUIFER BASE
POROSITY
AQUIFER THICKNESS

MULTIPLICATION FACTORS FOR

X-SPACING 1.00
Y-SPACING 1.00
INITIAL FRESH WATER HEAD 1.00
INITIAL INTERFACE ELEVATION 1.00
X-HYDRAULIC CONDUCTIVITY 1.00
Y-HYDRAULIC CONDUCTIVITY 1.00
SPECIFIC STORAGE 1.00
ELEVATION OF AQUIFER BASE 1.00
POROSITY 1.00
AQUIFER THICKNESS 1.00

SPACING IN X-DIRECTION

10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000
10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000
10.000	10.000	10.000	10.000	10.000	10.000	10.000	10.000

SPACING IN Y-DIRECTION

1.0000

INITIAL FRESH WATER HEADS

1	20.496	27.790	27.769	27.748	27.727	27.704	27.681	27.658
	27.633	27.607	27.561	27.552	27.523	27.491	27.458	27.421
	27.361	27.337	27.263	27.222				

INITIAL INTERFACE ELEVATION

1	0.0000	0.0000	0.43040	1.1592	1.9027	2.6693	3.4617	4.2820
	5.1334	6.0200	6.9471	7.9200	8.9471	10.038	11.204	12.463
	13.841	15.381	17.161	19.346				

X-HYDRAULIC CONDUCTIVITY

69.000

Y-HYDRAULIC CONDUCTIVITY

69.000

SPECIFIC STORAGE

0.10000E-05

ELEVATION OF AQUIFER BASE

0.0000

POROSITY

1.0000

AQUIFER THICKNESS

27.000

CONFINING BED HEAD

27.136

CONFINING BED LEAKANCE

0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
0.0000	0.0000	0.0000	4.6067	0.0000	0.0000	0.0000

FRESH WATER DENSITY 1.001
SALT WATER DENSITY 1.030
FRESH WATER VISCOSITY 1.000
SALT WATER VISCOSITY 1.000

RECHARGE

RECHARGE = 0.000

IDELT= 1 ZMAX= 0.000

CONSTANT SALT WATER HEAD NODES

I= 20, J= 1

CONSTANT FRESH WATER HEAD NODES

I= 1, J= 1

INITIAL FRESH VOLUME 3916.9 CUBIC FEET
INITIAL SALT VOLUME 1463.1 CUBIC FEET

MAXIMUM HEAD CHANGE FOR EACH ITERATION
1.5979 0.0000

	FRESH BALANCE		SALT BALANCE	
	RATE (CFS)	TOTAL (CF)	RATE (CFS)	TOTAL (CF)
CHANGE IN STORAGE	-14.227	-71.135	14.226	71.131
SOURCE/SINK	0.0000	0.0000	0.0000	0.0000
CONSTANT HEAD NODES	20.131	100.66	-14.372	-71.062
VERTICAL LEAKAGE	-5.7580	-28.790		
RECHARGE	0.0000	0.0000		
PER CENT ERROR		0.72647		-1.0280
TOTALS	0.14625	0.73124	-0.14625	-0.73124
EGW CHANGE IN STORAGE	-14.373		14.372	

STEP NUMBER 1 SIMULATION TIME IN SECONDS 0.500E+01

IN MINUTES 0.833E-01
IN HOURS 0.139E-02
IN DAYS 0.579E-04
IN YEARS 0.159E-06

FRESH WATER HEAD

1	29.496	29.500	29.200	29.171	29.062	20.952	20.041	20.730
	20.010	20.504	20.390	20.270	20.157	20.030	27.917	27.794
	27.667	27.536	27.001	27.261				

INTERFACE LEVEL

1	0.37253E-00	-0.73127E-01	0.25950	0.93055	1.6730	2.0329	3.2171	4.0203
	0.0697	5.7040	6.6506	7.6162	0.6200	9.6920	10.030	12.051
	13.371	14.009	16.374	10.002				

SALT WATER HEAD

1	20.666	20.550	20.463	20.376	20.291	20.205	20.120	20.034
	27.949	27.064	27.770	27.693	27.607	27.522	27.436	27.350
	27.264	27.170	27.090	27.000				

WATER QUALITY MAP: 0=FRESH, 1=MIX, 2=SALT

0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1
MAXIMUM HEAD CHANGE FOR EACH ITERATION
-1.5975 0.0000

FRESH BALANCE		SALT BALANCE	
RATE (CF3)	TOTAL (CF)	RATE (CF3)	TOTAL (CF)

CHANGE IN STORAGE	-12.912	-64.562	12.912	64.562
SOURCE/SINK	0.0000	0.0000	0.0000	0.0000
CONSTANT HEAD NODES	20.046	100.23	-13.003	-65.014
VERTICAL LEAKAGE	-7.0437	-35.219		
RECHARGE	0.0000	0.0000		
PER CENT ERROR	0.0000	0.45025		-0.69901

TOTALS	0.90259E-01	0.45130	-0.90260E-01	-0.45130
EON CHANGE IN STORAGE	-13.003		13.003	

STEP NUMBER 2 SIMULATION TIME IN SECONDS 0.100E+02
 ***** IN MINUTES 0.167E+00
 IN HOURS 0.278E-02
 IN DAYS 0.116E-03
 IN YEARS 0.317E-06

FRESH WATER HEAD

1	29.496	29.300	29.201	29.173	29.064	20.955	20.845	20.734
	20.623	20.510	20.397	20.202	20.165	20.040	27.920	27.806
	27.601	27.553	27.421	27.269				

INTERFACE LEVEL

1	0.37253E-08	-0.11026	0.11012	0.72966	1.4494	2.2003	2.9763	3.7709
	4.6105	5.4747	6.3759	7.3100	8.3099	9.3564	10.467	11.651
	12.919	14.273	15.690	17.039				

SALT WATER HEAD

1	20.066	20.550	20.460	20.372	20.287	20.202	20.117	20.032
	27.947	27.862	27.777	27.691	27.606	27.521	27.436	27.351
	27.265	27.179	27.091	27.000				

WATER QUALITY MAP: 0=FRESH, 1=MIX, 2=SALT

0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1
 MAXIMUM HEAD CHANGE FOR EACH ITERATION
 -0.09953E-02 0.0000

FRESH BALANCE		SALT BALANCE	
RATE (CFS)	TOTAL (CF)	RATE (CFS)	TOTAL (CF)
CHANGE IN STORAGE	-11.927	-59.633	59.633
SOURCE/SINK	0.0000	0.0000	0.0000
CONSTANT HEAD NODES	19.976	99.870	-59.843
VERTICAL LEAKAGE	-0.0071	-40.035	
RECHARGE	0.0000	0.0000	

PER CENT ERROR 0.21027
 TOTALS 0.42002E-01 0.21001
 EOM CHANGE IN STORAGE -11.969 -0.42002E-01 -0.21001
 11.969

STEP NUMBER 3 SIMULATION TIME IN SECONDS 0.150E+02
 ***** IN MINUTES 0.250E+00
 IN HOURS 0.417E-02
 IN DAYS 0.174E-03
 IN YEARS 0.476E-06

FRESH WATER HEAD

1	29.496	29.309	29.202	29.174	29.066	20.957	20.040	20.730
	20.627	20.515	20.402	20.200	20.173	20.056	27.937	27.016
	27.693	27.567	27.439	27.310				

INTERFACE LEVEL

1	0.57253E-00	-0.13926	0.44071E-02	0.53412	1.2306	1.9715	2.7393	3.5333
	4.3556	5.2093	6.0903	7.0274	8.0010	9.0201	10.113	11.264
	12.405	13.771	15.090	16.310				

SALT WATER HEAD

1	26.666	20.557	20.457	20.360	20.202	20.190	20.113	20.020
	27.944	27.859	27.774	27.690	27.605	27.520	27.435	27.350
	27.265	27.179	27.091	27.000				

WATER QUALITY MAP: 0=FRESH, 1=MIX, 2=SALT

0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1