

Velocity and Density Models Incorporating the Cascadia Subduction Zone for 3D Earthquake Ground Motion Simulations

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550 km



Earthquake Hazards Ground Motion Investigations

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Version 1.3

By W.J. Stephenson

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**U.S. Department of the Interior
U.S. Geological Survey**

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By W.J. Stephenson

Introduction

In support of earthquake hazards and ground motion studies in the Pacific Northwest, three-dimensional P- and S-wave velocity (3D V_p and V_s) and density (3D ρ) models incorporating the Cascadia subduction zone have been developed for the region encompassed from about 40.2°N to 50°N latitude, and from about -122°W to -129°W longitude (fig. 1). The model volume includes elevations from 0 km to 60 km (elevation is opposite of depth in model coordinates). Stephenson and Frankel (2003) presented preliminary ground motion simulations valid up to 0.1 Hz using an earlier version of these models. The version of the model volume described here includes more structural and geophysical detail, particularly in the Puget Lowland as required for scenario earthquake simulations in the development of the Seattle Urban Hazards Maps (Frankel and others, 2007). Olsen and others (in press) used the model volume discussed here to perform a Cascadia simulation up to 0.5 Hz using a Sumatra-Andaman Islands rupture history. As research from the EarthScope Program (<http://www.earthscope.org>) is published, a wealth of important detail can be added to these model volumes, particularly to depths of the upper-mantle. However, at the time of development for this model version, no EarthScope-specific results were incorporated. This report is intended to be a reference for colleagues and associates who have used or are planning to use this preliminary model in their research. To this end, it is intended that these models will be

considered a beginning template for a community velocity model of the Cascadia region as more data and results become available.

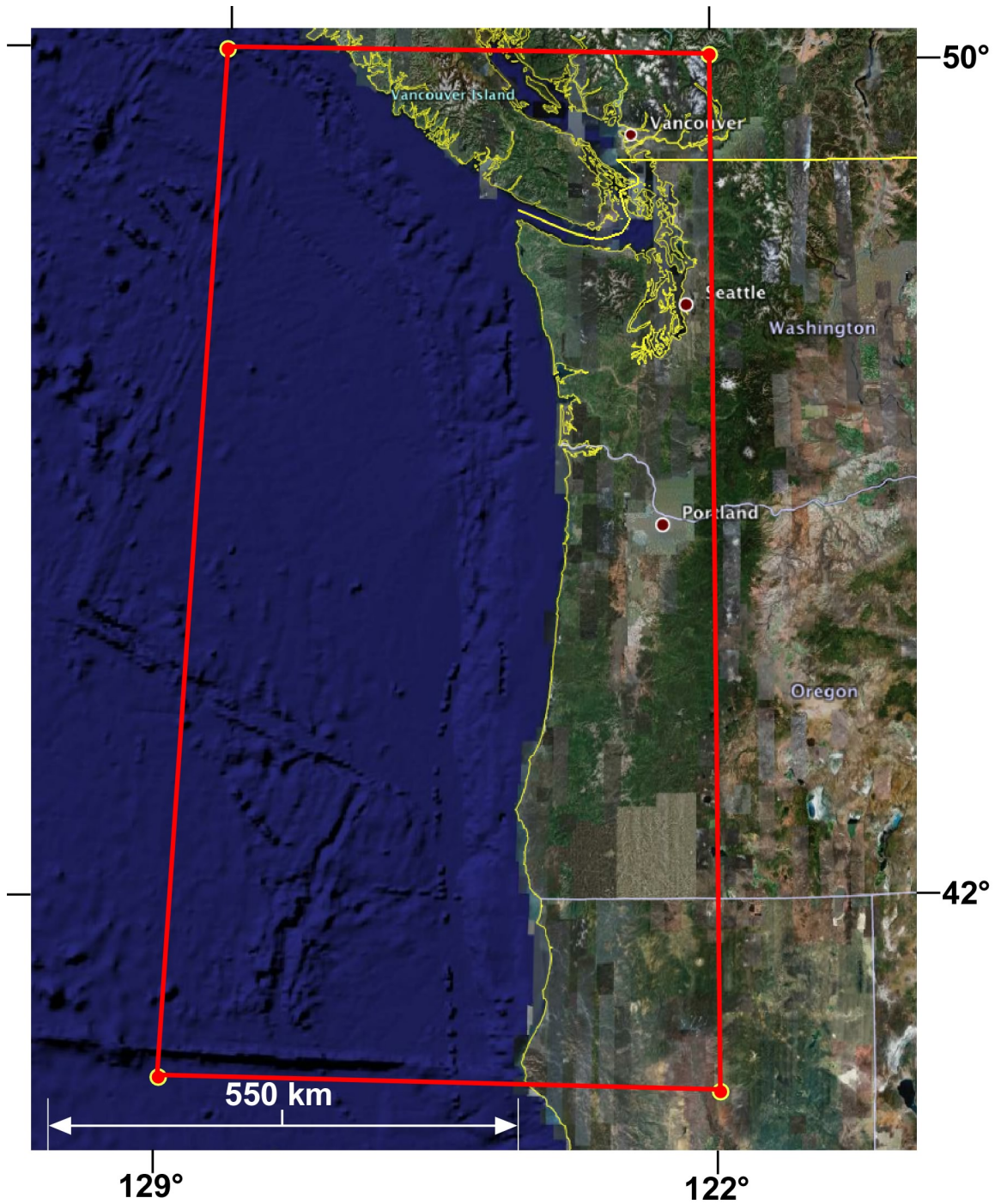


Figure 1. Region of velocity and density models described in this report. Base image is from GoogleEarth®, showing the urban centers of Portland, Oreg., Seattle, Wash., and Vancouver, British Columbia. Red polygon is approximate boundary of velocity and density property volumes that include the Cascadia subduction zone. Latitude and longitude coordinates at corners of red polygon are, clockwise from upper left, 50°N, -129°W; 50°N, -122°W; 40.2°N, -122°W; and 40.2°N, -129°W. Projection is geographic WGS 84.

The Cascadia subduction zone stretches for over 1,000 km, from the Mendocino triple junction off the northern California coast northward to Vancouver Island, Canada (fig. 2). The primary reasons for developing these model volumes are (1) for simulating strong ground motions in the urbanized sedimentary basins of western Washington and Oregon and (2) for simulating Tsunami effects from a great (M 8–9) Cascadia subduction zone earthquake. As such, these are geophysical property models constrained by first-order geologic boundaries only. No effort has been made to represent detailed geologic terranes in the model volume unless they were deemed important for ground motion variability in urbanized regions. Thus, unique terranes within the continental crust, such as Siletz or Wrangellia, are not treated as unique units within the model; however, these units are essentially represented de facto through the use of passive- and active-source tomographic imaging results.

The velocity and density models were developed primarily with EarthVision® software on the Solaris operating system. Matlab® was also used as part of the development of the density model and for performing quality-control of the model volumes output in Institute of Electrical and Electronics Engineers, Incorporated (IEEE)

binary format from EarthVision[®]. While a wealth of published information for the Cascadia region has been incorporated in the development of these models, significant smoothing during extrapolation and interpolation in portions of the model were required to create the model interfaces and geophysical property volumes. Because there are many areas within the model where published data are sparse or of low resolution, there is significant uncertainty and therefore subjectivity involved in building model horizons and in populating the model volumes.

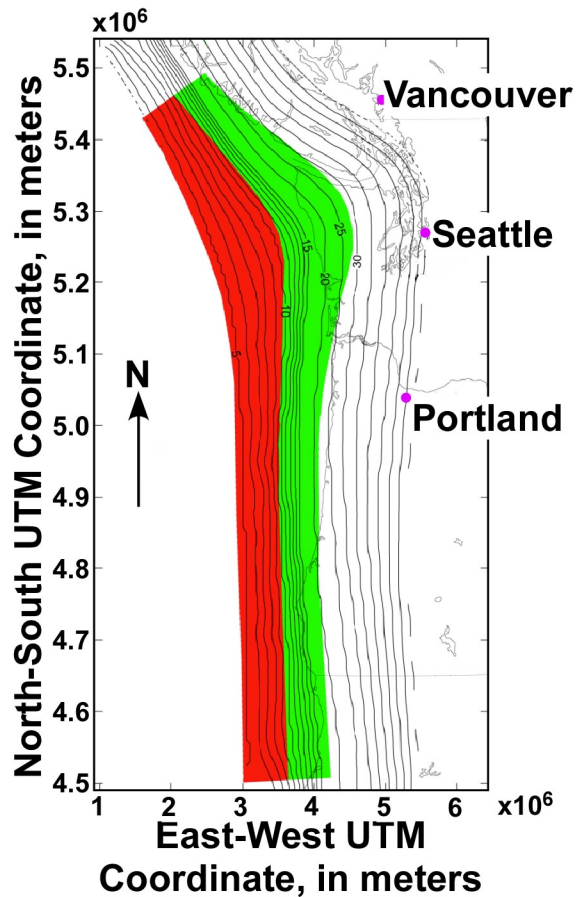


Figure 2. Contour map of Cascadia subduction slab showing estimated locked (red) and transitional (green) zones (Flück and others, 1997; McCrory and others, 2005). Contours in kilometers below sea-level. Figure is modified from Olsen and others (in press).

The model volume incorporates bathymetry (data of etopo5; Wessel and Smith, 1991) but does not incorporate topography. Topography was not included in the current version of the model volume because the initial objective in developing these models was for use in 3D finite-difference ground motion calculations with modeling codes that do not allow grid points for terrain. This omission of topography in the current model volume can be easily rectified in future versions using EarthVision®.

The Primary Geology-Based Model Units and Their Velocity-Density Properties

The backbone of the property volumes is the geologic model consisting of autonomous units representing simplified geologic volumes. For the purposes of this model, six units were defined. As shown in figure 3, these are (1) continental sedimentary basins, (2) continental crust, (3) continental mantle, (4) oceanic sediments, (5) oceanic crust, and (6) oceanic mantle. In addition to the Cascadia megathrust, the Seattle fault was incorporated into these models because of its use as a seismogenic source in the Seattle Urban Hazards Maps (Frankel and others, 2006). The modeling demands for the smaller-scale Seattle maps also drove the more detailed, complex overall appearance of the Puget Lowland region in the current velocity and density models. The Seattle fault delimits the southern edge of the Seattle basin and thrusts crystalline crust over basin sediments, creating a sharp lateral velocity-density contrast. Its surface trace was extracted from Blakely and others (2002) and projected to a depth of about 20 km assuming a 45° south dip. This dip angle is essentially a median value based on the range of dips published from seismic reflection surveys (Pratt and others, 1997; Johnson and others, 1999; ten Brink and others, 2002; Calvert and others, 2003). Additional crustal faults may be incorporated into the model as need and additional information arise.

Because much of the velocity information published in the literature is P-wave velocity (V_p), this property was first derived for each unit in the geologic model, then relationships between V_p and both S-wave velocity (V_s) and density (ρ) were used to derive these latter properties on a geologic unit-by-unit basis. First, V_p was defined for each unit based on available published results. Then V_p was converted to V_s using the empirical relation with depth of Brocher (2005), except for Quaternary and Tertiary sedimentary basin units. Property V_s for these units is defined in a later section, entitled “Continental Sedimentary Basins.”

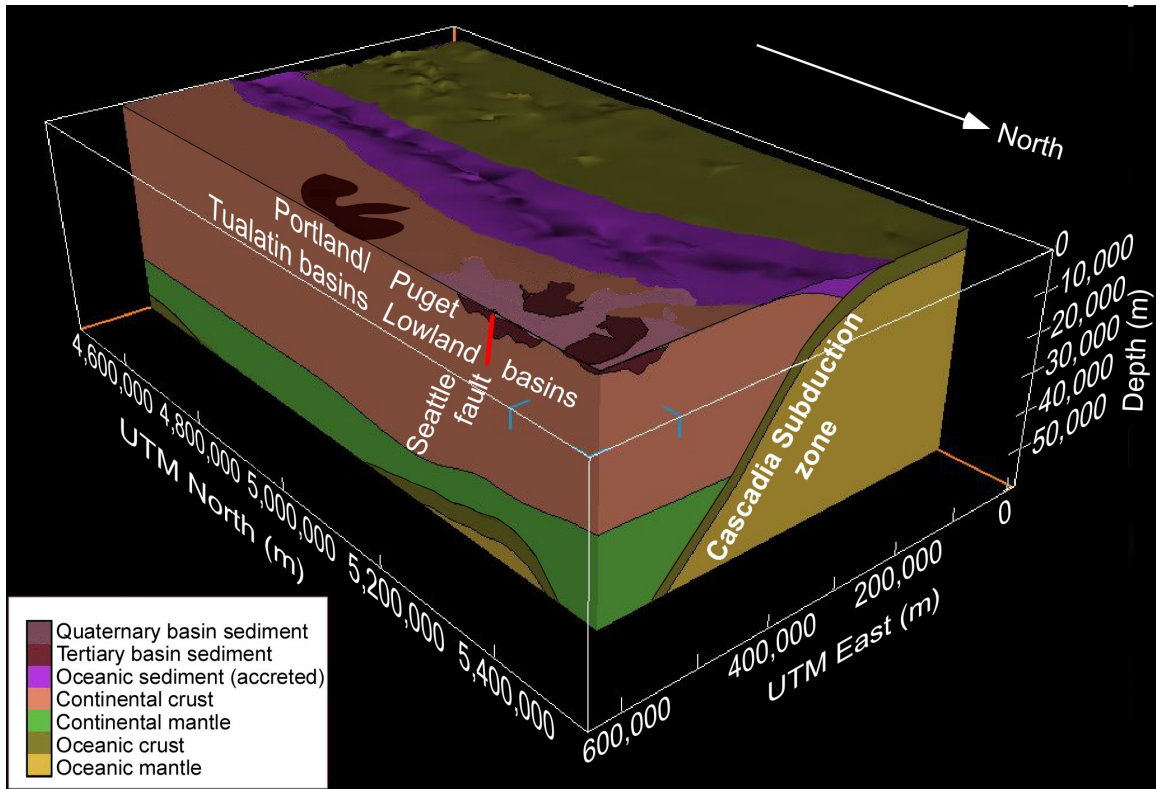


Figure 3. Model volume sliced through urbanized sedimentary basins overlying Cascadia subduction zone (for example, the Seattle and Tacoma basins) of the Puget Lowland, western Washington. Cascadia velocity and density models cover 40.2° to 50° N. latitude, -121° to -129° W. longitude, and 0- to -60-km elevation. Bathymetry is

included while topography above mean sea level (0 m) is excluded. Model projected into Universal Transverse Mercator Zone 10 North (UTM) coordinates for display. Sliced view shows the seven basic geology-based model units and their relationships at depth. Cascadia subduction fault surface is inferred along top of oceanic crust model unit. Seattle fault is shown by red line within the Puget Lowland basins; fault dip within model volume is 45° south.

As noted earlier, rho values for all model units were calculated directly from the empirical relationship with Vp derived by Brocher (2005), which is approximately the deterministic form of the Nafe-Drake law. This empirical equation is:

$$\rho = 1.6612 \cdot V_p - 0.4721 \cdot V_p^2 + 0.0671 \cdot V_p^3 - 0.0043 \cdot V_p^4 + 0.000106 \cdot V_p^5$$

where Vp is in km/s and rho is in g/cm³. After this calculation, the minimum and maximum nonwater densities were then constrained to be 2.0 g/cm³ and 3.5 g/cm³, respectively. Ocean water was set to 1.028 g/cm³.

Continental Sedimentary Basins

Sedimentary basin deposits are further subdivided into Quaternary and Tertiary geologic units. The thickness of Quaternary deposits through the southern Puget Lowland was compiled by Jones (1996) and Johnson and others (1999), and was originally used by Frankel and Stephenson (2000) then later by Pitarka and others (2004) for 3D ground motion modeling of the Seattle basin. For the Quaternary thickness through eastern Juan de Fuca Strait, the data of Mosher and Johnson (2000) were incorporated to create the Quaternary-Tertiary interface throughout the Puget Lowland.

Quaternary V_p varied one-dimensionally with a range of 1,500, 1,905, and 1,980 m/s at 0, 200, and 1,000 m depth, respectively. These values were derived from land surface measurements and high-resolution marine seismic surveys (for example, Williams and others, 1999; Calvert and others, 2003). The Quaternary unit V_s is derived from V_{s30} and V_{p30} measurements at the surface to constrain V_p/V_s to approximately 2.5, while V_p/V_s at 1 km was constrained to approximately 2.2. The minimum V_s in the Quaternary unit, and also in all nonwater regions of the model volume, was constrained to 600 m/s. For water regions, V_s was set to 0.

The base of the Tertiary sediments within the Puget Lowland is inferred to be at the 4,500-m/s velocity contour, based on oil-industry borehole data (Brocher and Ruebel, 1998). This contour surface was extracted from the Seismic Hazards Investigations in the Puget Sound (SHIPS) and earthquake data 3D P-wave tomography of Ramachandran and others (2004, 2006), which incorporate the same or similar data from many previous tomography studies in the lowland (for example, Stanley and others, 1999; Brocher and others, 2001; Van Wagoner and others, 2002). The Willamette Valley basin deposits (Portland area) are derived from well data intersecting crystalline rocks under (generally) Tertiary deposits (Yeats and others, 1996; Gannett and others, 1998). Quaternary deposits are generally less than 30 m in thickness and are currently not included in the model region for these basin deposits. Future consideration of simulations requiring grid spacing less than 100 m should include a thin Quaternary layer. Additionally, recent gravity modeling has suggested that a significant thickness of lower-density sediment may exist in the Tualatin basin west of Portland below what is interpreted in this model as the base of basin sediments (about 12-km depth versus about 0.5-km depth in current model; McPhee and others, 2007).

The V_p of the Tertiary subunit in the Puget Lowland basins is defined by tomography results from SHIPS and local earthquake data as calculated by Ramachandran and others (2004, 2006). The V_p within the Willamette Valley basin deposits assumes a similar velocity-depth structure to that of the Puget Lowland. A constant V_p/V_s conversion factor of 2 was imposed on the Tertiary subunit to obtain V_s . ρ was derived from V_p using the empirical relationship of Brocher (2005).

Continental Crust

Topography is not included in this current model. The surface of the continental crust below Mean Sea Level was controlled by the smoothed continental shoreline as well as numerous published active and passive source results along the continental margin (for example, Trehu and others, 1994; Clowes and others, 1997; Flueh and others, 1998; Fuis, 1998; Gulick and others 1998; Fleming and Trehu, 1999; Parsons and others, 1999; Stanley and Villasenor, 2000; Bostock and others, 2002; and Ramachandran and others, 2004). This unit's V_p is derived from the above-mentioned studies and, most prominently, from the 3D tomography model of Ramachandran and others (2004, 2006) through the Puget Lowland. Properties V_s and ρ were derived from V_p using the empirical relationship of Brocher (2005).

Continental Mantle

The top of continental mantle is derived from data of Chulick and Mooney (2002). These data were edited and smoothed to create the surface of this unit. The tomography of Stanley and others (1999) from the Puget Lowland area was used to constrain upper mantle V_p , extrapolating a generalized V_p -depth structure throughout the

unit. Rho and Vs were derived from Vp using the empirical relationship of Brocher (2005).

Oceanic Sediments

The oceanic sediment unit represents accreted and sedimentary deposits overlying the top of the continental crustal unit and underlying the eastern portion of the bathymetric surface. Parameter Vp is derived from results of Parsons and others (1999) and numerous active-source marine seismic surveys (for example,). Parameter Vp varies primarily as a function of depth. Parameters Vs and rho were derived from Vp using the empirical relationship of Brocher (2005). Preliminary ground motion studies suggest this unit will be subject to more intense shaking during a Cascadia megathrust event than other units of similar distance from the fault rupture (Olsen and other, in press).

Oceanic Crust

The top of the oceanic crustal unit is defined in the subsurface based on the results of Flück and others (1997) and McCrory and others (2005). These data are merged with bathymetric data west of the oceanic sediment terminus to create the oceanic crust surface. The top of oceanic crust in the subsurface is also defined to be the top of the Cascadia megathrust (subducting slab). Based on available marine seismic-reflection profiling (for example, Fuis, 1998) and studies worldwide (for example, Turcotte and Shubert, 1982), the thickness of the oceanic crust was set to 5 km. This thickness is most likely on the low end of realistic values. Average values derived from marine seismic surveys were extrapolated to obtain Vp (for example, Trehu and others, 1994; Flueh and others, 1998; Fuis, 1998; Gulick and others 1998; Fleming and Trehu, 1999; and Ramachandran and others, 2004, 2006) and extrapolated smoothly to 60 km depth. Rho

and V_s were derived from V_p using the empirical relationship of Brocher (2005). As the oceanic crust subducts into the mantle, the crust at depth is less dense and slower than the surrounding mantle to the bottom of the model at 60 km depth.

Oceanic Mantle

The ocean mantle is the only unit in the model underlying oceanic crust. The top surface is derived by down-projecting the top of the oceanic crust 5 km and smoothing the resulting surface. This unit has the poorest-resolved V_p , V_s , and ρ parameters because of limited published results. Parameter V_p was set to vary from 7,900 m/s to 8,300 m/s between about 10 km and 60 km depth, respectively. Parameters V_s and ρ were derived from V_p using the empirical relationship of Brocher (2005).

Discussion and Summary

The first two sets of incremental property slices discussed here are from the V_s model volume because of this property's importance for earthquake ground motion characterization. In figure 4, east-west slices spaced every 200 km through the model reveal the subducting slab and areas of the model with higher apparent resolution in western Washington due in large part to P-wave tomography results using SHIPS data (for example, Brocher and others, 2001; Ramachandran and others, 2004, 2006). Elevation slices from the V_s property volume from -4 to -44 km, every 10 km, are shown in figure 5. Velocities for V_s range from 600 m/s to 4,830 m/s. The -4 km elevation slice shows the oceanic sediment as the arc-shaped light-blue-colored band of approximately 2,000 m/s. Small light-blue patches in the northeast quadrant of this slice are low-velocity sediments within basins of the Puget Lowland. Subducting oceanic crust is

clearly visible in the depth slices -14 km to -44 km. At elevations below -14 km, oceanic mantle Vs is consistently higher than continental units at the same elevation.

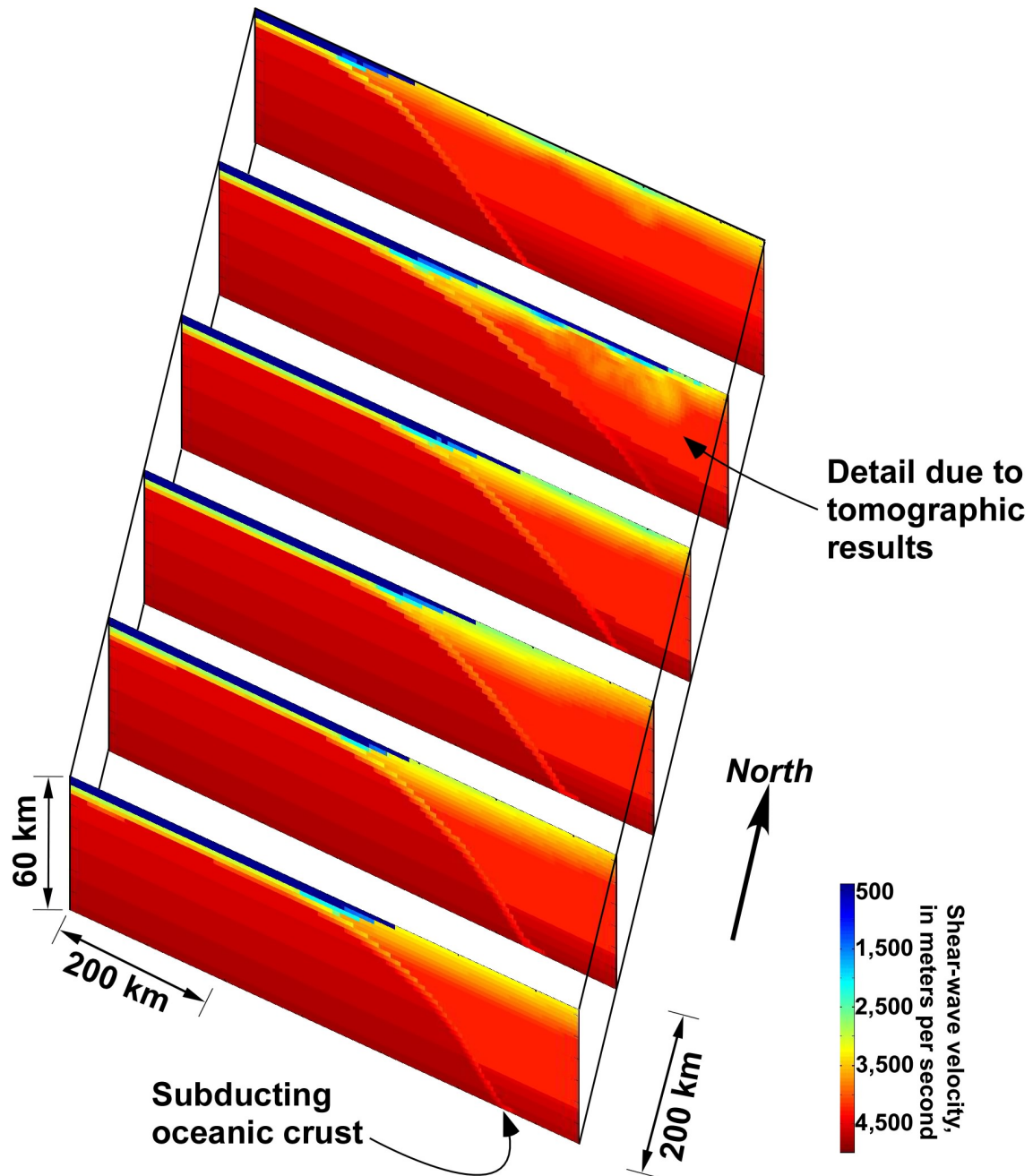


Figure 4. East-west slices through Vs model every 200 km. Velocities are scaled from 400 to 5,000 m/s. Water velocity is set to 0 m/s.

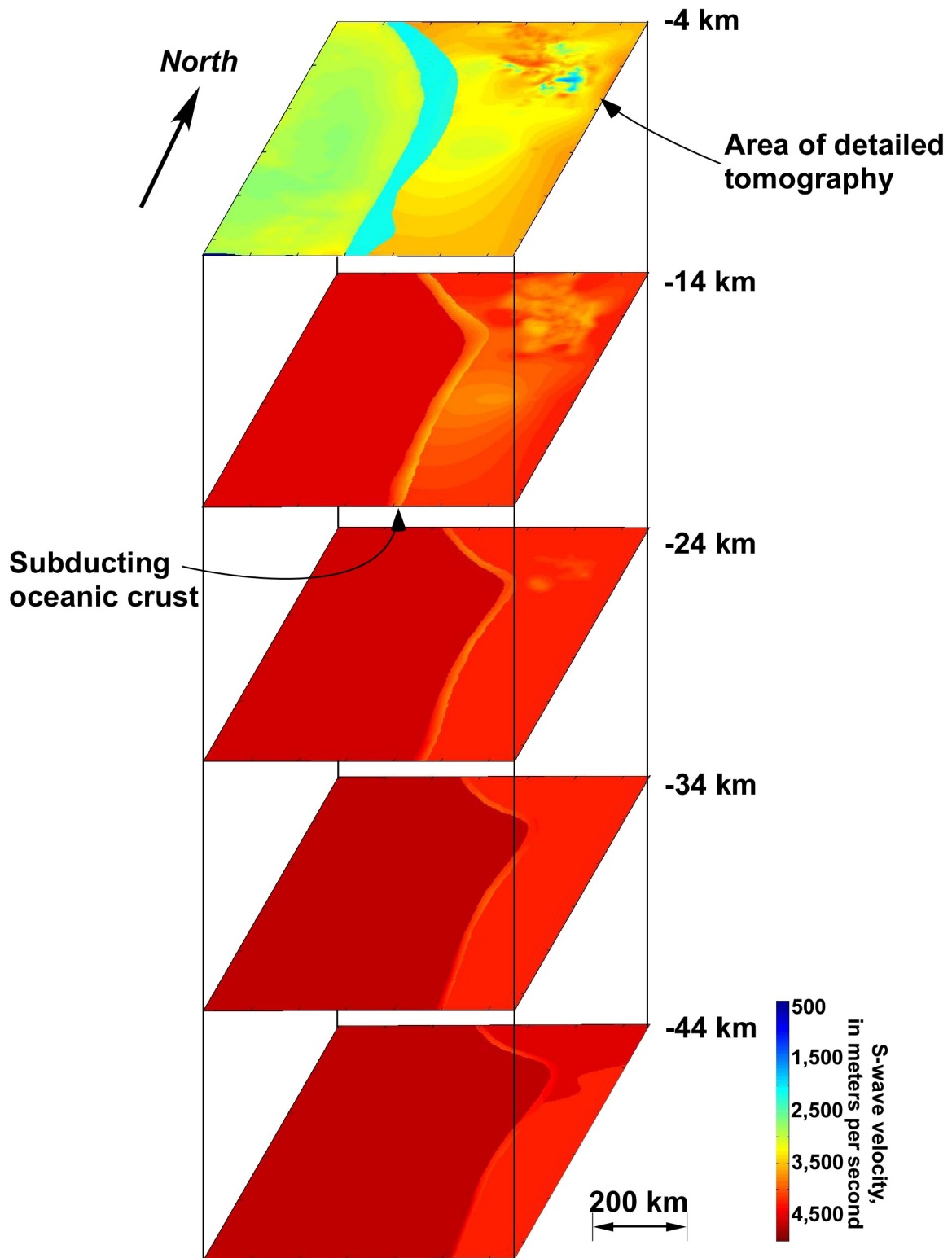


Figure 5. Vs model slices at 10-km elevation intervals, beginning at -4 km elevation.

Velocity scale is same as in figure 4.

Property V_p slices, corresponding in elevation to the V_s slices in figure 5, are shown in figure 6. Velocities range from 1,290 m/s to 8,470 m/s in the V_p model. The V_p/V_s elevation slices, shown in figure 7, reveal that nominal ratios in the deeper crust and mantle range between 1.71 and 1.76. The mean V_p/V_s between -15 km and -60 km elevation is approximately 1.733, consistent with a Poisson solid value of 1.732 g/cm³ for non-ocean-water regions. Property V_p/V_s varies most markedly at elevations above -2 km, where the ratio goes as high as 2.5 in urban sedimentary basins in the upper few hundred meters. Property ρ elevation slices, again corresponding to those displayed for V_s in figure 5, are shown in figure 8. These values for rock units range from 2.0 g/cm³ in Quaternary basin sediments up to 3.46 g/cm³ for ocean mantle at great depth.

The model volume in the immediate vicinity of Seattle, including most of the Puget Lowland, has been validated with ground motion simulations of the 2001 Nisqually earthquake as well as other weak-motion events (Frankel and others, 2006, 2007). The V_s , V_p , and ρ model volumes were implemented in these ground motion simulations, and these results were incorporated into the U.S. Geological Survey Urban Hazards Maps for Seattle. The Seattle urban hazard model volume was a subset of the greater Cascadia velocity-density model volume. These finite difference simulations with these velocity-density models have been qualitatively accurate at matching waveform data to 1 Hz.

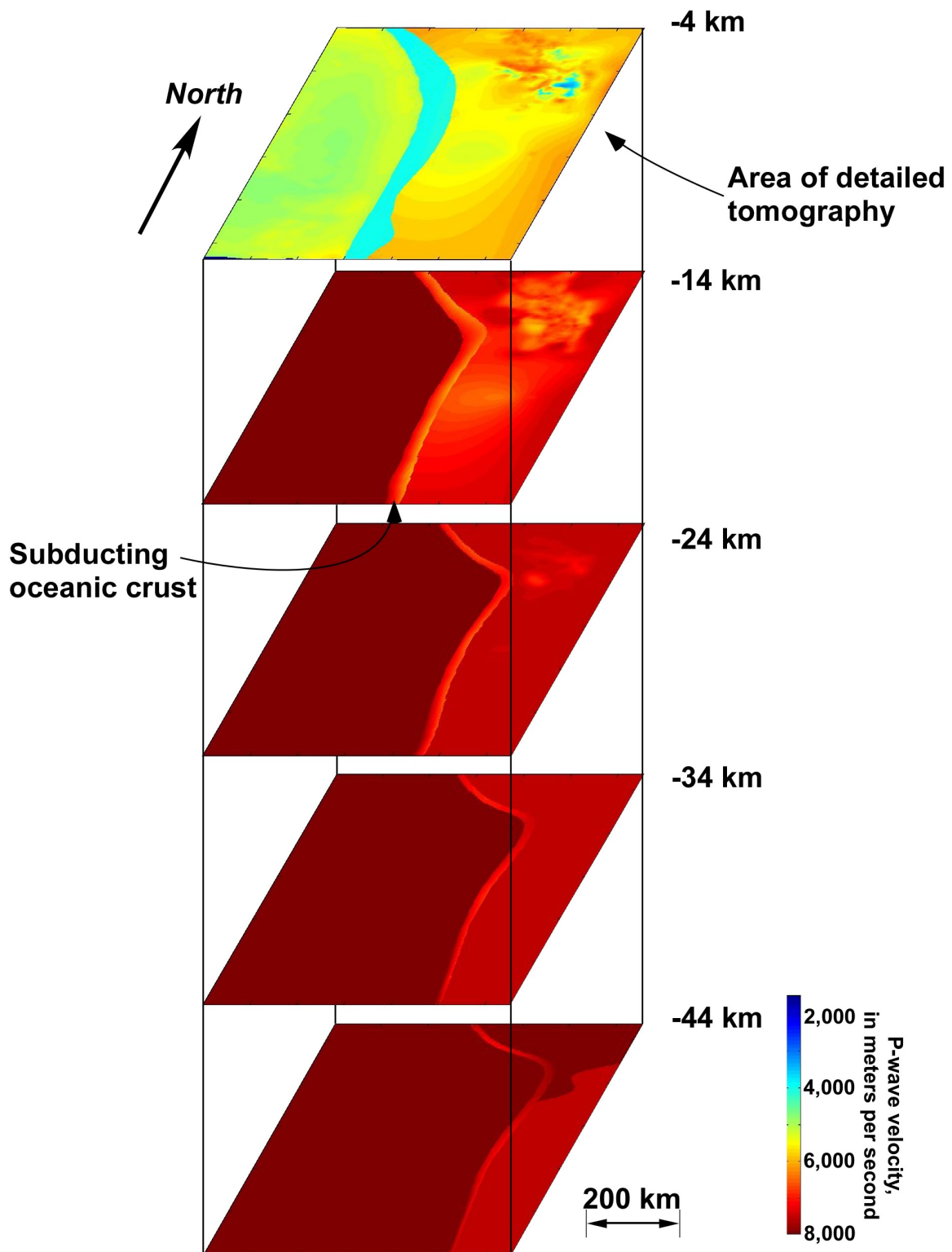


Figure 6. V_p model slices at 10-km elevation intervals, beginning at -4 km elevation (same elevations as slices shown in figure 5).

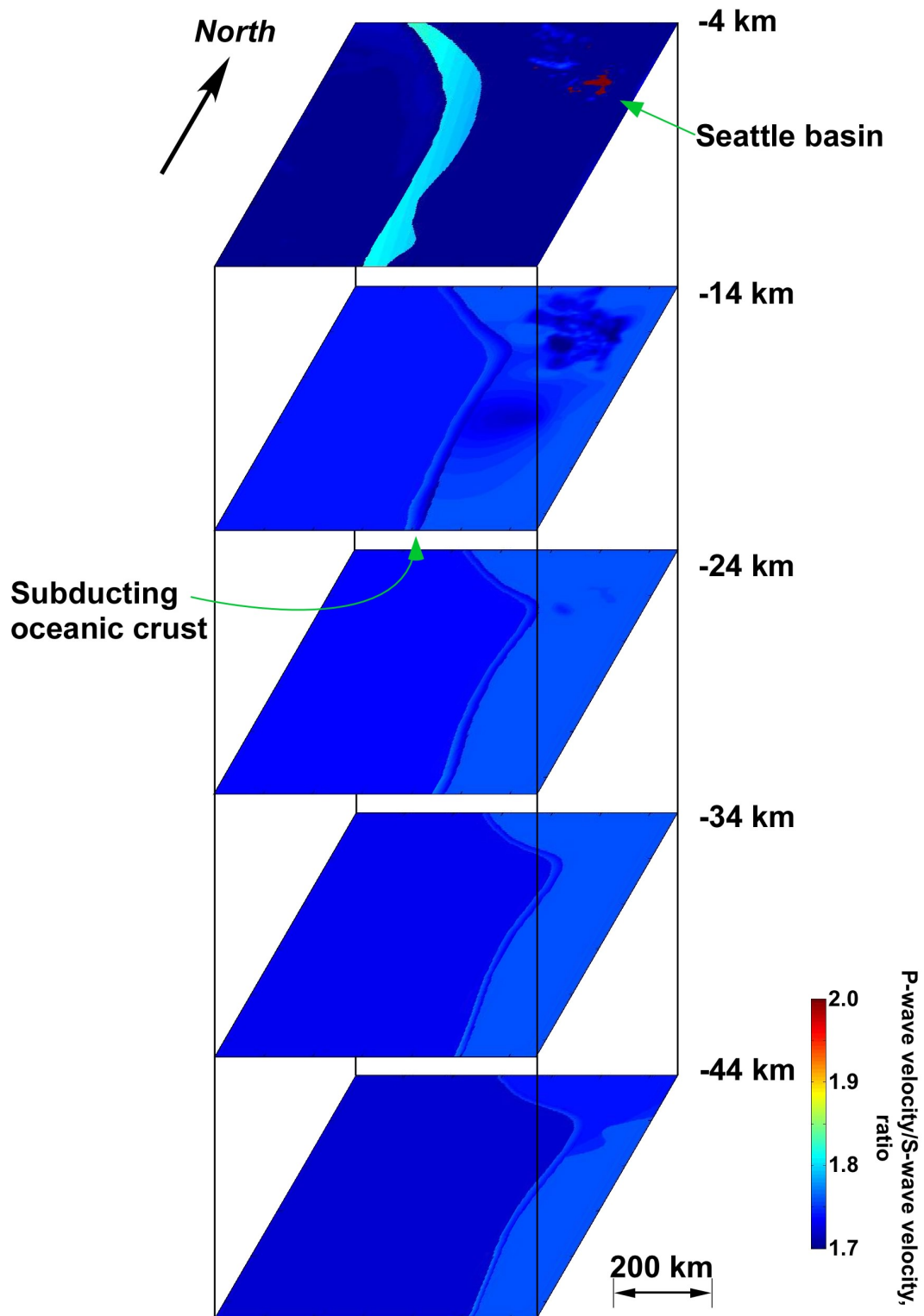


Figure 7. V_p/V_s model slices at 10-km elevation intervals, beginning at -4 km elevation (same elevations as slices shown in figure 5).

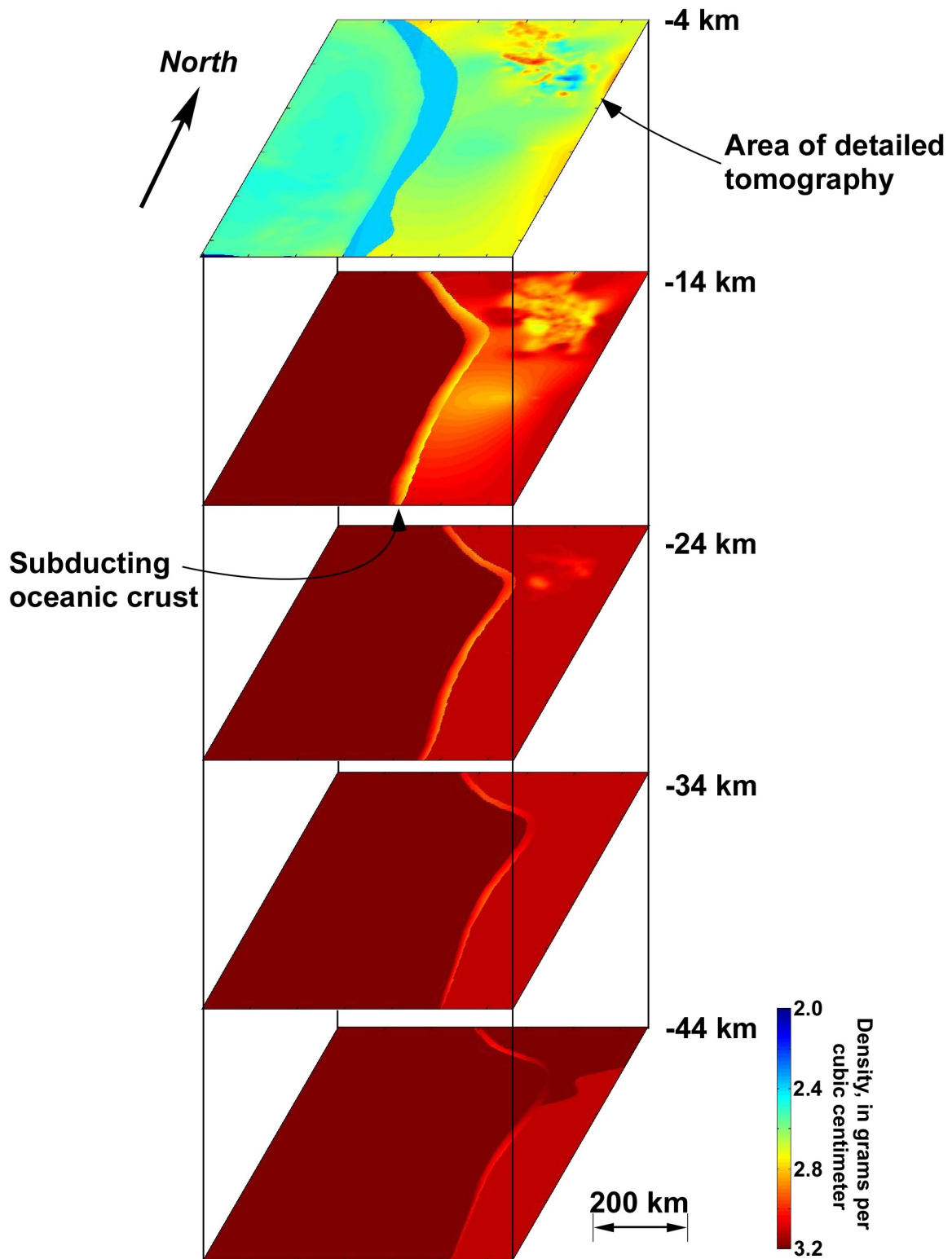


Figure 8. Rho model slices at 10-km elevation intervals, beginning at -4 km elevation (same elevations as slices in figure 5).

The 3D velocity and density property models described in this paper were developed in FY2005 and FY2006 for use in strong ground motion simulations of Seattle fault, Cascadia megathrust, and other earthquake events of interest. These models were derived primarily using published geophysical data in addition to borehole and other geological constraints. The model volume as developed in EarthVision® is designed to be flexible and can be modified to add further complexity as new published information becomes available or as scientific focus is redirected to new challenges in the Cascadia region. This flexibility allows model grid, or node, spacing to be customized from the EarthVision® model for a user's specific purpose. At present, the model can be obtained from the author (wstephens@usgs.gov) in raw IEEE binary format.

Acknowledgments

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