http://128.128.205.110/?f=7f

whoi mvco

# USGS Pivot Arm Controller - Modtronix SBC65EC Web Server

- Introduction
- Analog Inputs
- Port Values
- LCD Display
- PWM Values
- Expansion Board
- Example 1
- System Configuration
- Serial Configuration
- Contact
- USGS Pivot Control
- USGS Pivot Status

Trip is armed
A0 Arm Current 2 = 0.03 Amp
A1 Tachometer 0 = -0.67 rpm
Trip C5 = 0

Reset B2 = 0

Act +12 B3 = 0

IG20 +12 C0 = 1

Port F = 127 = 0x7f = 0 1 1 1 1 1 1 1