

DISCUSSION

This acoustic-backscatter map of the Offshore of Pacifica map area in northern California was generated from backscatter data collected by Fugro Pelagos and by California State University, Monterey Bay (CSUMB) (fig. 1). Mapping was completed in 2005, 2006, and 2007, using a combination of 400-kHz Reson 7125 and 244-kHz Reson 8101 multibeam echosounders. These mapping missions combined to collect acoustic-backscatter data from about the 10-m isobath to beyond the 3-nautical-mile limit of California's State Waters.


During all the mapping missions, an Applanix POS MV (Position and Orientation System for Marine Vessels) was used to accurately position the vessels during data collection, and it also accounted for vessel roll, pitch, yaw, heave, surge, sway, and heave rates. The accuracy of the positioning system was estimated as approximately ±5% or less. To account for tidal-cycle variations, CSUMed used NaoC 2060 GPS (CNAV) data, and Fugro Pelagius used Kongsberg GPS data (with real-time kinematic corrections), in combination with tide gauge information from NOAA's National Ocean Service (NOS). The tide gauge data were used to correct for vertical offsets between the vessel-mounted GPS and the NOS tide gauge. After the data were collected, the raw data were processed by either Soundings were corrected for vessel motion using the Applanix POS MV data, for variations in water-column sound velocity using the AM SVS8 data, and for variations in water height (tidal) using vertical-position data from the Kongsberg receivers. Data-acquired data were postprocessed using Geocorder version 2.0.0 software (Geacore Inc., San Francisco, CA) to correct for horizontal errors. All data were geographically corrected (including depth-based and angle-angle-range gain adjustments), and the position of each acoustic sample was geometrically corrected for slant range on a line-by-line basis. After the lines were corrected, they were projected onto a map grid. The map grid was created by projecting the geographic coordinates of the priority table whose values were based on the distance of each sample from the ship track, with the samples that were closest to and furthest from the ship track being given the lowest priority. An anti-aliasing algorithm (Bresenham's line-drawing algorithm) was used to generate the map grid images, imported into a geographic information system (GIS), and converted to GRID at 2-m resolution.

The acoustic-backscatter grids were combined in a GIS to create this map, on which brighter tones indicate higher backscatter intensities, and darker tones indicate lower backscatter intensity. The intensity represents a complex interaction between the acoustic pulse and the seafloor, as well as characteristics within the water column. The intensity of the backscatter is dependent on many factors, and seafloor type. Backscatter intensity depends on the acoustic source level, the frequency used to image the seafloor, the *grazing angle*, the composition and character of the seafloor, including grain size, water content, bulk density, and seafloor roughness, and some biological cover. Harder and rougher bottom types such as rocky outcrops or coarse sediment typically return stronger intensities (high backscatter, lighter tones), whereas softer bottom types such as fine sediment return weaker intensities (low backscatter, darker tones).


Bathymetric contours were generated at 10-m intervals from a merged 2-m-resolution bathymetric surface (see sheet 1 of this report). The most continuous contour segments were preserved; smaller segments and isolated island polygons were excluded from the final output. Contours were smoothed using a polynomial approximation with exponential kernel algorithm and a tolerance value of 60 m.


The onshore-area image was generated by applying an illumination having an azimuth of 300° and from 45° above the horizon to 1-m-resolution topographic-lidar data collected by Photoscience in 2005 for the U.S. Geological Survey and the County of San Mateo.

EXPLANATION

Backscatter Intensity
High

Low

Area of "no data"—Areas near shoreline not mapped owing to insufficient high-resolution
 seafloor mapping data; areas beyond 3-nautical-mile limit of California's State Waters were
 not mapped as part of California Seafloor Mapping Program

3-nautical-mile limit of California's State Waters


Bathymetric contour (in meters)—Derived from modified 2-m-resolution bathymetry grid
 Contour interval: 10 m


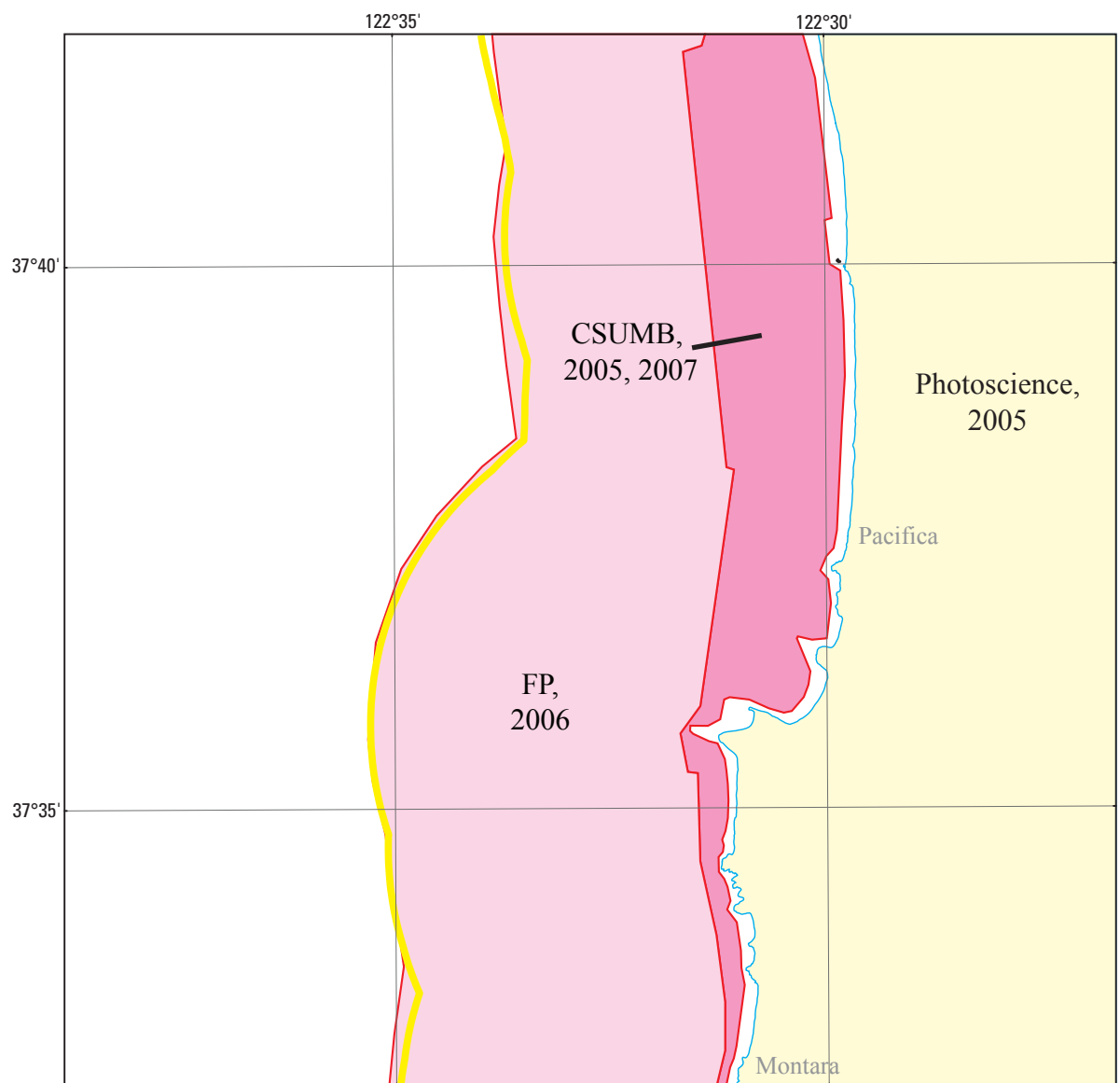


Figure 1. Map showing areas of multibeam-echosounder surveys (pink shading) and onshore topographic-lidar surveys (yellow shading). Also shown are data-collecting agencies (CSUMB, California State University, Monterey Bay, Seafloor Mapping Lab; FP, Fugro Pelagos) and dates of surveys if known. Yellow line shows limit of California's State Waters.



The map was printed on an electronic paper directly from digital files. Dimensional calibration may vary between electronic plates.
Between X and Y directions on the same plate, and paper may change size due to atmospheric conditions; therefore, scale or proportions may not be true as points of this map.

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Acoustic Backscatter, Offshore of Pacifica Map Area, California

By
Carrie K. Bretz,¹ Rikk G. Kvitek,¹ Peter Dartnell,² Mercedes D. Erdey,² and Eleyne L. Phillips²
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²U.S. Geological Survey

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