

**DISCUSSION**

This acoustic-backscatter map of the Offshore of San Francisco map area in northern California was generated from backscatter data collected by California State University, Monterey Bay (CSUMB) and by Fugro Pelagos in 2004, 2005, 2007, and 2008; a small offshore portion near the southern boundary of the map area was mapped by Fugro Pelagos in 2006. Both used a combination of 400-kHz Reson 7125 and 244-kHz Reson 8101 multibeam echosounders. These mapping missions combined to collect acoustic-backscatter data from about the 10-m isobath to beyond the 3-nautical-mile limit of California's State Waters.

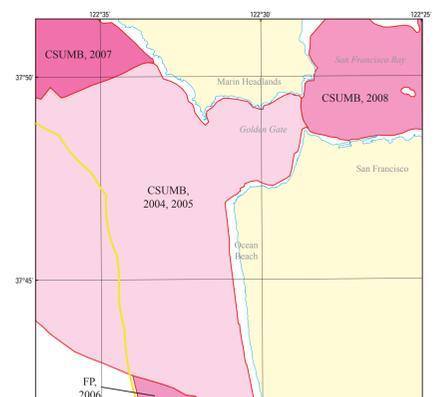
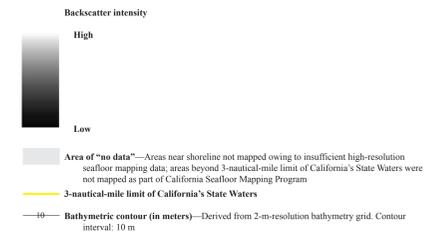
During all the mapping missions, an Applanix POS MV (Position and Orientation System for Marine Vessels) was used to accurately position the vessels during data collection, and it also accounted for vessel motion such as heave, pitch, and roll (position accuracy, ±2 m; pitch, roll, and heading accuracy, ±0.02°; heave accuracy, ±5%, or 5 cm). To account for tidal-cycle fluctuations, CSUMB used NavCom 2050 GPS receiver (CNAV) data, and Fugro Pelagos used KGPS data (GPS data with real-time kinematic corrections), in addition, sound-velocity profiles were collected with an Applied Microsystems (AM) SV Plus sound velocimeter. Soundings were corrected for vessel motion using the Applanix POS MV data, for variations in water-column sound velocity using the AM SV Plus data, and for variations in water height (tides) using vertical-position data from the KGPS receivers. Backscatter data were postprocessed using Geocoder version 3.2 (Fugro Pelagos modified test release 16). Within Geocoder, the backscatter intensities were radiometrically corrected (including despeckling and angle-varying gain adjustments), and the position of each acoustic sample was geometrically corrected for slant range on a line-by-line basis. After the lines were corrected, they were mosaicked into a 1-m-resolution image. Overlap between parallel lines was resolved using a priority table whose values were based on the distance of each sample from the ship track, with the samples that were closest to and furthest from the ship track being given the lowest priority. An anti-aliasing algorithm was also applied. The mosaics were then exported as georeferenced TIFF images, imported into a geographic information system (GIS), and converted to GRIDS at 2-m resolution.

The acoustic-backscatter grids were combined in a GIS to create this map, on which brighter tones indicate higher backscatter intensity, and darker tones indicate lower backscatter intensity. The intensity represents a complex interaction between the acoustic pulse and the seafloor, as well as characteristics within the shallow subsurface, providing an indication of seafloor texture and sediment type. Backscatter intensity depends on the acoustic source level, the frequency used to image the seafloor, the grazing angle, the composition and character of the seafloor, including grain size, water content, bulk density, and seafloor roughness, and some biological cover. Harder and rougher bottom types such as rocky outcrops or coarse sediment typically return stronger intensities (high backscatter, lighter tones), whereas softer bottom types such as fine sediment return weaker intensities (low backscatter, darker tones).

Bathymetric contours were generated at 10-m intervals from a merged 2-m-resolution bathymetric surface (see sheet 1 of this report). The most continuous contour segments were preserved; smaller segments and isolated island polygons were excluded from the final output. Contours were smoothed using a polynomial approximation with exponential kernel algorithm and a tolerance value of 60 m.

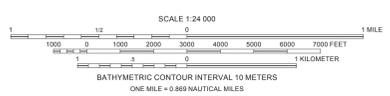
The onshore-area image was generated by applying an illumination having an azimuth of 300° and from 45° above the horizon to topographic-lidar data collected by Earth Eye in 2010 for San Francisco State University and the U.S. Geological Survey.

**EXPLANATION**



**Figure 1.** Map showing areas of multibeam-echosounder surveys (pink shading) and onshore topographic-lidar surveys (yellow shading). Also shown are data-collecting agencies (CSUMB, California State University, Monterey Bay; Seafloor Mapping Lab, FP, Fugro Pelagos) and dates of surveys if known.

Onshore elevation data collected by Earth Eye in 2010 for San Francisco State University and the U.S. Geological Survey, California's State Waters limit from NOAA Office of Coast Survey, Universal Transverse Mercator projection, Zone 10N  
**NOT INTENDED FOR NAVIGATIONAL USE**



Acoustic-backscatter data collected by California State University, Monterey Bay, Seafloor Mapping Lab in 2004-2008 and by Fugro Pelagos in 2006. 2004-2005 backscatter data reprocessed by Mercedes D. Erley in 2012. Bathymetric contours by Mercedes D. Erley, 2008. GIS database and digital cartography by Nadine E. Golden. Manuscript approved for publication April 7, 2015.

**Acoustic Backscatter, Offshore of San Francisco Map Area, California**

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