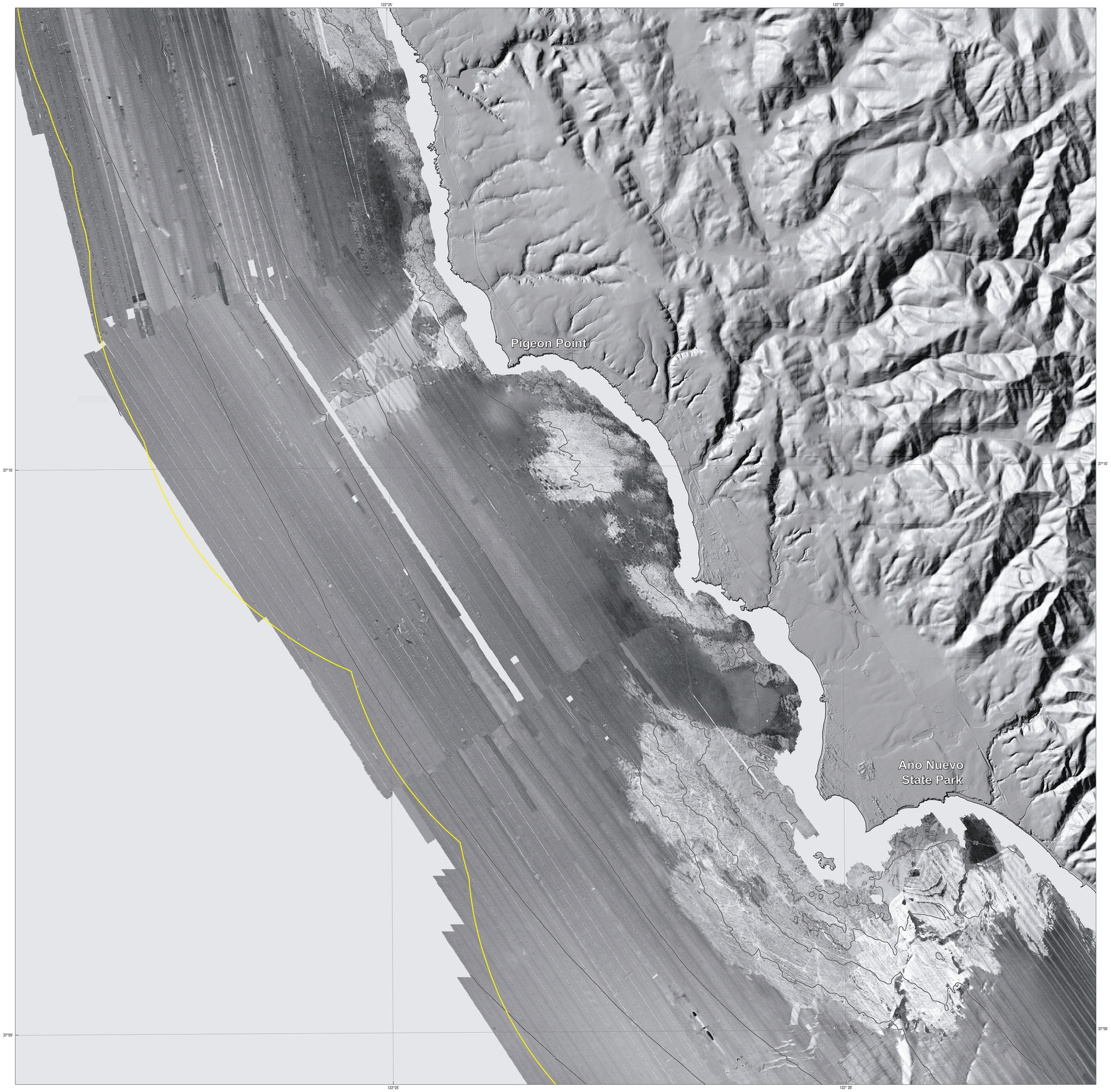
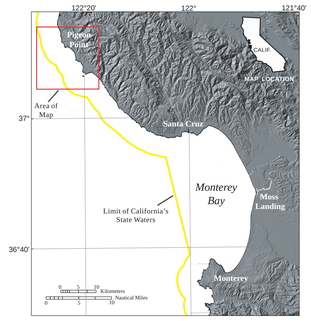
U.S. Department of the Interior
U.S. Geological Survey

Open-File Report 2015–1232
Sheet 3 of 10
Pamphlet accompanies map





DISCUSSION

This acoustic-backscatter map of the Offshore of Pigeon Point map area in central California was generated from acoustic-backscatter data collected by California State University, Monterey Bay (CSUMB), by Fugro Pelagos, and by the U.S. Geological Survey (USGS) (fig. 1). Mapping was completed between 2006 and 2009, using a combination of 400-kHz Reson 7125 and 244-kHz Reson 8101 multibeam echosounders, as well as a 234-kHz SWATHplus bathymetric sidescan-sonar system. These mapping missions combined to collect acoustic-backscatter data from about the 10-m isobath to beyond the 3-nautical-mile limit of California's State Waters.

During the CSUMB and Fugro Pelagos multibeam mapping missions, an Applanix POS MV (Position and Orientation System for Marine Vessels) was used to accurately position the vessels during data collection, and it also accounted for vessel motion such as heave, pitch, and roll (position accuracy, ±2 m; pitch, roll, and heading accuracy, ±0.02°; heave accuracy, ±5%, or 5 cm). To account for tidal-cycle fluctuations, Fugro Pelagos used StarFix HP and XP real-time kinematic (RTK) GPS receivers, and CSUMB used a NavCom 2050 receiver; in addition, sound-velocity profiles were collected with an Applied Microsystems (AM) SVPlus sound velocimeter. Soundings were corrected for vessel motion using the Applanix POS MV data, for variations in water-column sound velocity using the AM SVPlus data, and for variations in water height (tides) using vertical-position data from the RTK receivers. The multibeam backscatter data were postprocessed using Geocoder, within which the backscatter intensities were radiometrically corrected (including despeckling and angle-varying gain adjustments), and the position of each acoustic sample was geometrically corrected for slant range on a line-by-line basis. After the lines were corrected, they were mosaicked into 1- or 2-m-resolution images. Overlap between parallel lines was resolved using a priority table whose values were based on the distance of each sample from the ship track, with the samples that were closest to and furthest from the ship track being given the lowest priority. An anti-aliasing algorithm was also applied. The mosaics were then exported as georeferenced TIFF images, imported into a geographic information system (GIS), and converted to GRIDs at 2-m resolution.

During the USGS mapping mission, GPS data with real-time-kinematic corrections were combined with measurements of vessel motion (heave, pitch, and roll) in a CodaOctopus F180 attitude-and-position system to produce a high-precision vessel-attitude packet. This packet was transmitted to the acquisition software in real time and combined with instantaneous sound-velocity measurements at the transducer head before each ping. The returned samples were projected to the seafloor using a ray-tracing algorithm that works with previously measured sound-velocity profiles. Statistical filters were applied to discriminate seafloor returns (soundings and backscatter intensity) from unintended targets in the water column (Ritchie and others, 2010). The backscatter data were postprocessed using USGS software (D.P. Finlayson, written commun., 2011) that normalizes for time-varying signal loss and beam-directivity differences. Thus, the raw 16-bit backscatter data were gain-normalized to enhance the backscatter of the SWATHplus system. The resulting normalized-amplitude values were rescaled to 16-bit and gridded into GeoJPEGs using GRID Processor Software, then imported into a GIS and converted to GRIDs.

The acoustic-backscatter imagery from each different mapping system and processing method were merged into their own individual grids. These individual grids, which cover different areas, were displayed in a GIS to create this map, on which brighter tones indicate higher backscatter intensity, and darker tones indicate lower backscatter intensity. The intensity represents a complex interaction between the acoustic pulse and the seafloor, as well as characteristics within the shallow subsurface, providing an indication of seafloor texture and composition. Backscatter intensity depends on the acoustic source level; the frequency used to image the seafloor; the grazing angle; the composition and character of the seafloor, including grain size, water content, bulk density, and seafloor roughness; and some biological cover. Harder and rougher bottom types such as rocky outcrops or coarse sediment typically return stronger intensities (high backscatter, lighter tones), whereas softer bottom types such as fine sediment return weaker intensities (low backscatter, darker tones). Note that the differences in backscatter intensity that are apparent in some areas of the map are due to the different frequencies of the mapping systems, as well as to different processing techniques. Parallel lines of higher backscatter intensity throughout the map area are data-collection and -processing artifacts.

Bathymetric contours were generated at 10-m intervals from a modified 2-m-resolution bathymetric surface (see sheets 1 and 2 of this report). The merged surface was smoothed using the Focal Mean tool in ArcGIS and a circular neighborhood that has a radius of between 20 and 30 m (depending on the location). The contours were generated from this smoothed surface using the Spatial Analyst Contour tool in ArcGIS. The most continuous contour segments were preserved; smaller segments and isolated island polygons were excluded from the final output. The contours were then clipped to the boundary of the map area.

The onshore-area image was generated by applying an illumination having an azimuth of 300° and from 45° above the horizon to 2-m-resolution topographic-lidar data from California Coastal Conservancy (available from National Oceanic and Atmospheric Administration [NOAA] Coastal Service Center's Digital Coast at http://www.csc.noaa.gov/digitalcoast/data/coastallidar/) and to 10-m-resolution topographic-lidar data from the U.S. Geological Survey's National Elevation Dataset (available at http://ned.usgs.gov/).

REFERENCE CITED

Ritchie, A.C., Finlayson, D.P., and Logan, J.B., 2010, Swath bathymetry surveys of the Monterey Bay area from Point Año Nuevo to Moss Landing, San Mateo, Santa Cruz, and Monterey Counties, California: U.S. Geological Survey Data Series 514, available at http://pubs.usgs.gov/ds/514/.

EXPLANATION

Backscatter intensity

High

Low

Area of "no data"—Areas near shoreline not mapped owing to insufficient high-resolution seafloor mapping data; areas beyond 3-nautical-mile limit of California's State Waters were not mapped as part of California Seafloor Mapping Program

3-nautical-mile limit of California's State Waters

Bathymetric contour (in meters)—Derived from modified 2-m-resolution bathymetry grid. Contour interval: 10 m

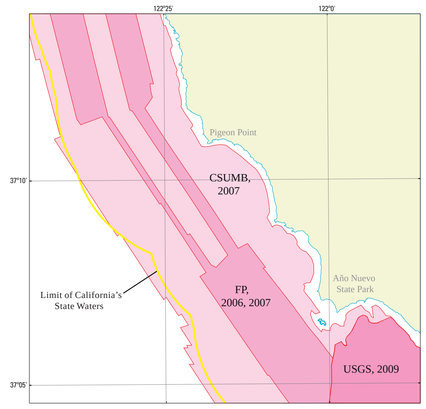


Figure 1. Map showing areas of multibeam-echosounder and bathymetric-sidescan surveys (pink shading) and onshore topographic-lidar surveys (yellow shading). Also shown are data-collecting agencies (CSUMB, California State University, Monterey Bay, Seafloor Mapping Lab; FP, Fugro Pelagos; USGS, U.S. Geological Survey) and dates of surveys if known. Yellow line shows limit of California's State Waters.

Onshore elevation data from California Coastal Conservancy (available from National Oceanic and Atmospheric Administration [NOAA] Coastal Service Center's Digital Coast at http://www.csc.noaa.gov/digitalcoast/data/coastallidar/) and from U.S. Geological Survey's National Elevation Dataset (available at http://ned.usgs.gov/). California's State Waters limit from NOAA Office of Coast Survey

Universal Transverse Mercator projection, Zone 10N

NOT INTENDED FOR NAVIGATIONAL USE

APPROXIMATE MEAN DECLINATION, 2015

SCALE 1:24 000

1 MILE
1000 0 1000 2000 3000 4000 5000 6000 7000 FEET
1 KILOMETER

BATHYMETRIC CONTOUR INTERVAL 10 METERS

ONE MILE = 0.869 NAUTICAL MILES

MAP LOCATION

Acoustic-backscatter data collected by Fugro Pelagos in 2006–2007, by California State University, Monterey Bay, Seafloor Mapping Lab in 2007 (data available at http://seafloor.otterlabs.org/index.html), and by U.S. Geological Survey in 2009 (data available at http://pubs.usgs.gov/ds/514/). Bathymetric contours by Mercedes D. Erdey, 2014

GIS database and digital cartography by Nadine E. Golden, 2013

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Acoustic Backscatter, Offshore of Pigeon Point Map Area, California

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2015

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