

Figure 2B. Digital still photograph no. B1 (see fig. 2A for location). Cobbles and gravel with scattered shells in area of rock outcrop (water depth, 10 m). Abiotic complexity is low, biotic complexity is present, and biocover is high. Biocover includes gorgonian (g), hydroid (h), and clam (cl). Distance between lasers (red dots) is 15 cm.

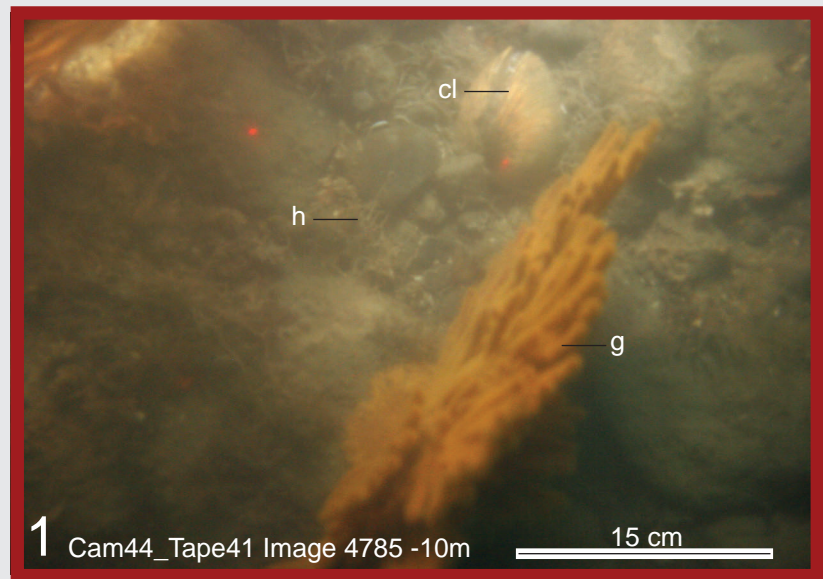


Figure 2C. Digital still photograph no. B2 (see fig. 2A for location). Rock patch in area of rock outcrop (water depth, 10 m). Abiotic complexity is moderate, biotic complexity is present, and biocover is high. Biocover includes hydroid (h) and gorgonian (g). Distance between lasers (red dots) is 15 cm.

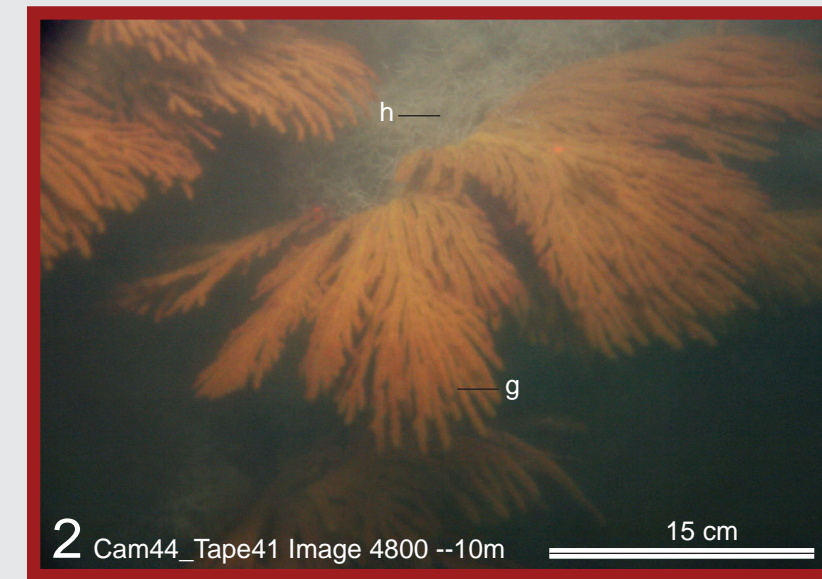


Figure 2D. Digital still photograph no. B3 (see fig. 2A for location). Cobbles and gravel in area of rock outcrop (water depth, 10 m). Abiotic complexity is moderate, biotic complexity is present, and biocover is high. Biocover includes sponge (spo) and gorgonian (g). Distance between lasers (red dots) is 15 cm.

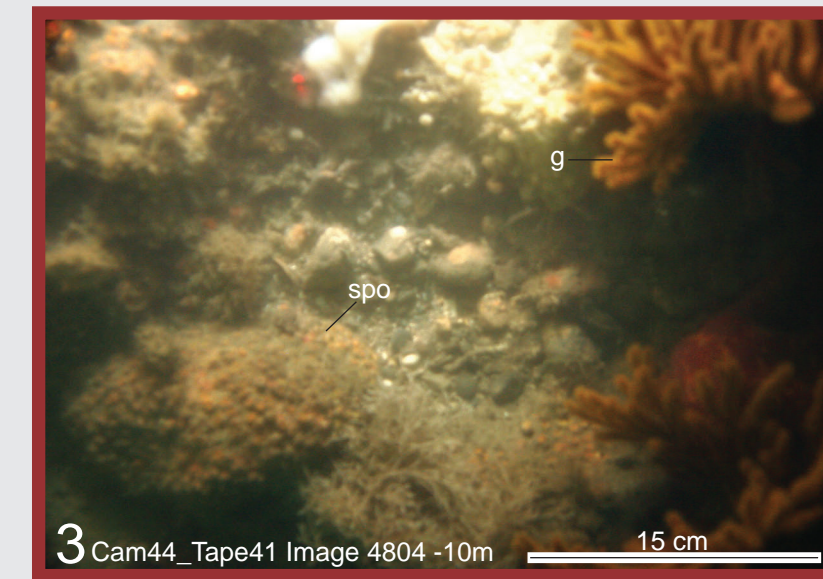


Figure 2E. Digital still photograph no. B4 (see fig. 2A for location). Gravel, cobbles, and boulders in area of rock outcrop (water depth, 10 m). Abiotic complexity is low, biotic complexity is present, and biocover is moderate. Biocover includes gorgonian (g) and sponge (spo). Distance between lasers (red dots) is 15 cm.

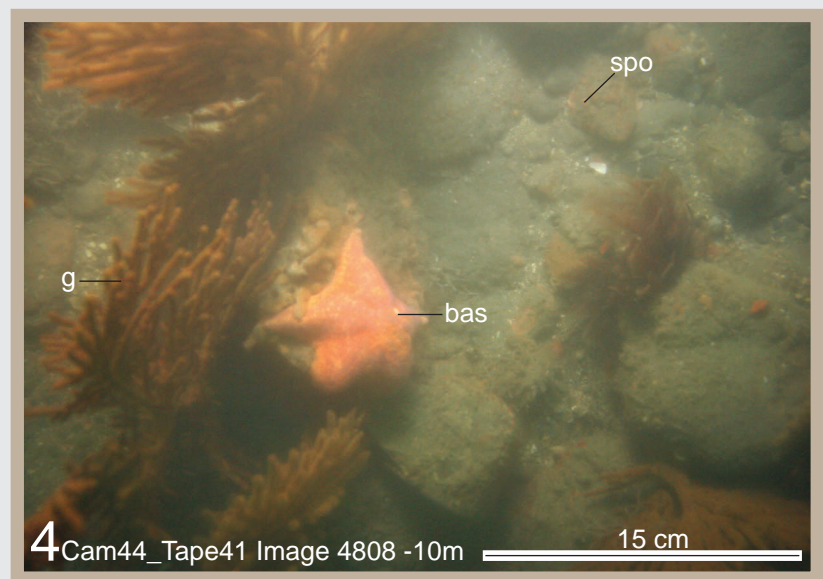


Figure 2F. Digital still photograph no. B5 (see fig. 2A for location). Cobbles and gravel with scattered shells in area of rock outcrop (water depth, 10 m). Abiotic complexity is low, biotic complexity is present, and biocover is high. Biocover includes scattered shells (ss) and sponge (spo). Distance between lasers (red dots) is 15 cm.

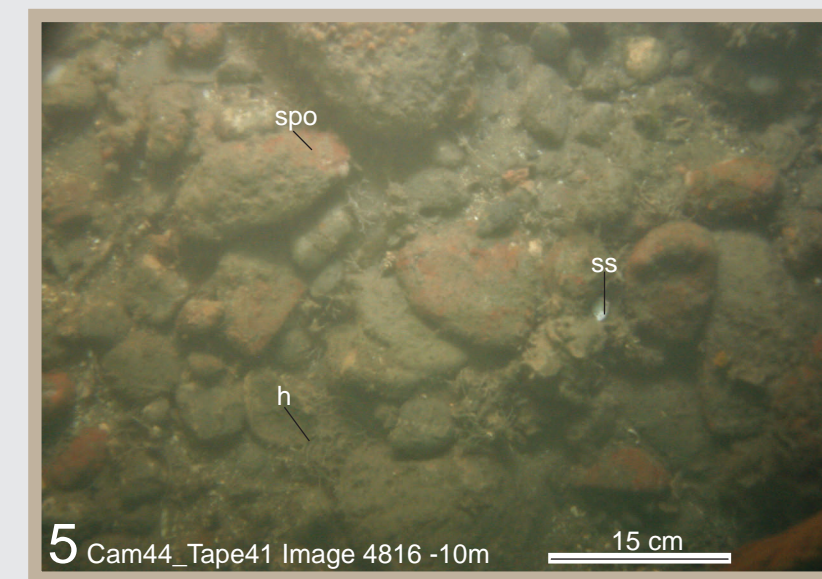


Figure 2G. Digital still photograph no. B6 (see fig. 2A for location). Gravel, cobbles, and boulders in area of rock outcrop (water depth, 10 m). Abiotic complexity is low, biotic complexity is present, and biocover is moderate. Biocover includes gorgonian (g) and sponge (spo). Distance between lasers (red dots) is 15 cm.

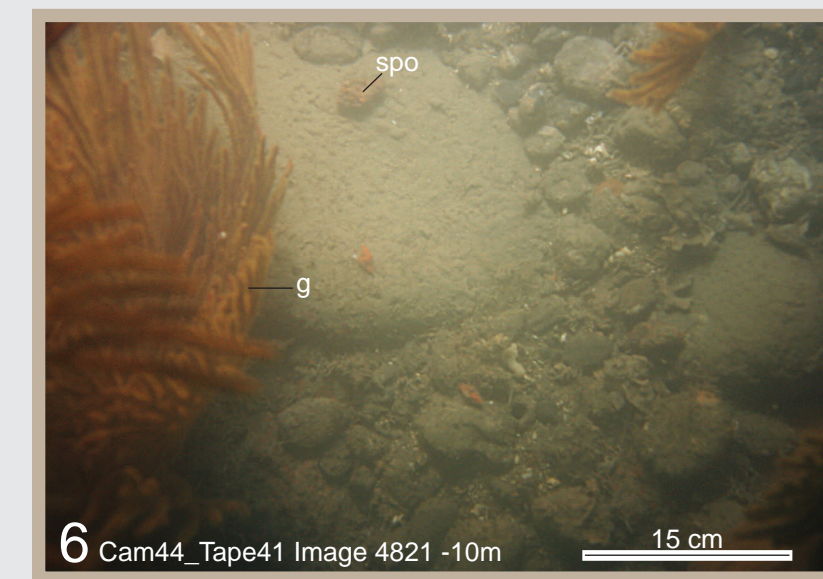


Figure 2H. Digital still photograph no. B7 (see fig. 2A for location). Sand, gravel, and cobbles with scattered shells in area of rock outcrop (water depth, 11 m). Abiotic complexity is low, biotic complexity is present, and biocover is moderate. Biocover includes scattered shells (ss) and sponge (spo). Distance between lasers (red dots) is 15 cm.

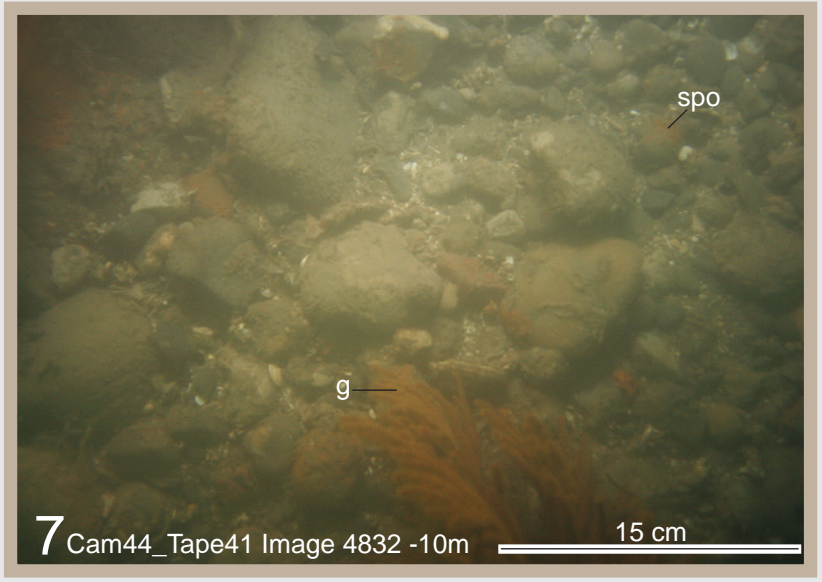


Figure 2I. Digital still photograph no. B8 (see fig. 2A for location). Sand, gravel, and cobbles with scattered shells in area of rock outcrop (water depth, 11 m). Abiotic complexity is low, biotic complexity is present, and biocover is moderate. Biocover includes scattered shells (ss) and sponge (spo). Distance between lasers (red dots) is 15 cm.

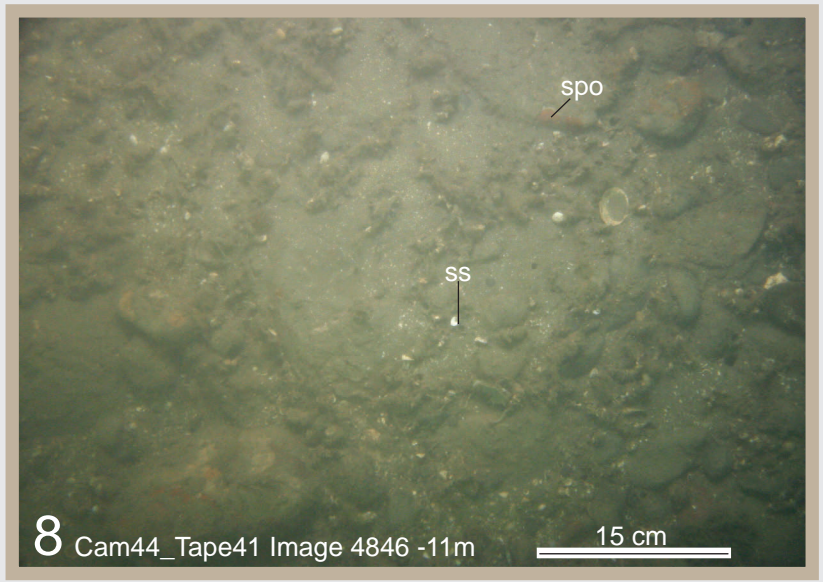


Figure 2J. Digital still photograph no. B9 (see fig. 2A for location). Boulders, cobbles, and gravel with scattered shells in area of rock outcrop (water depth, 11 m). Abiotic complexity is low, biotic complexity is present, and biocover is low. Biocover includes drift wood (dw), gorgonian (g), and sponge (spo). Distance between lasers (red dots) is 15 cm.

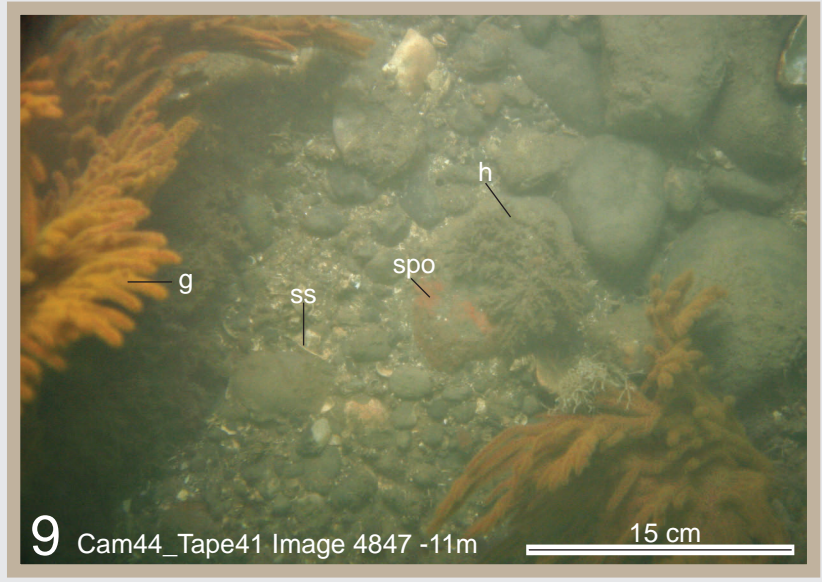


Figure 2K. Digital still photograph no. B10 (see fig. 2A for location). Sand with degraded ripples in confound, crossing pattern (water depth, 11 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes drift wood (dw). Distance between lasers (red dots) is 15 cm.

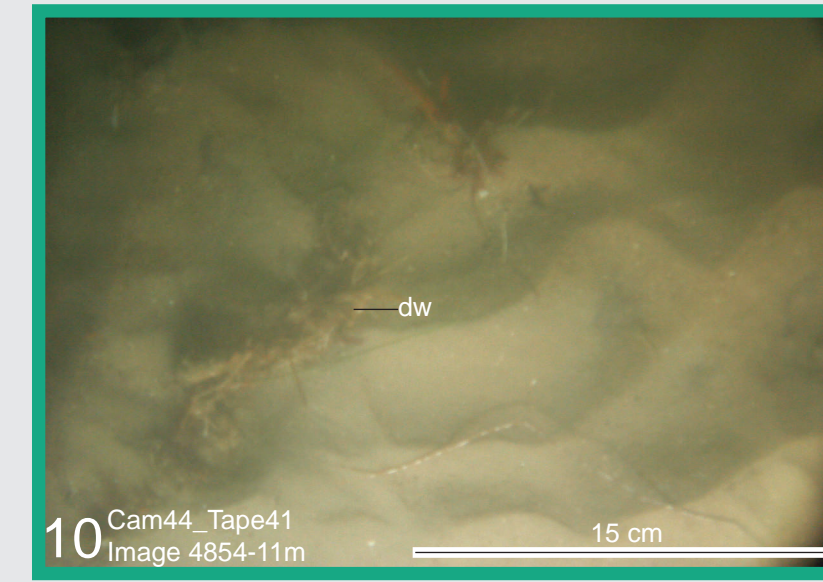


Figure 2L. Digital still photograph no. B11 (see fig. 2A for location). Sand with degraded ripples in confound, crossing pattern (water depth, 11 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes drift wood (dw). Distance between lasers (red dots) is 15 cm.

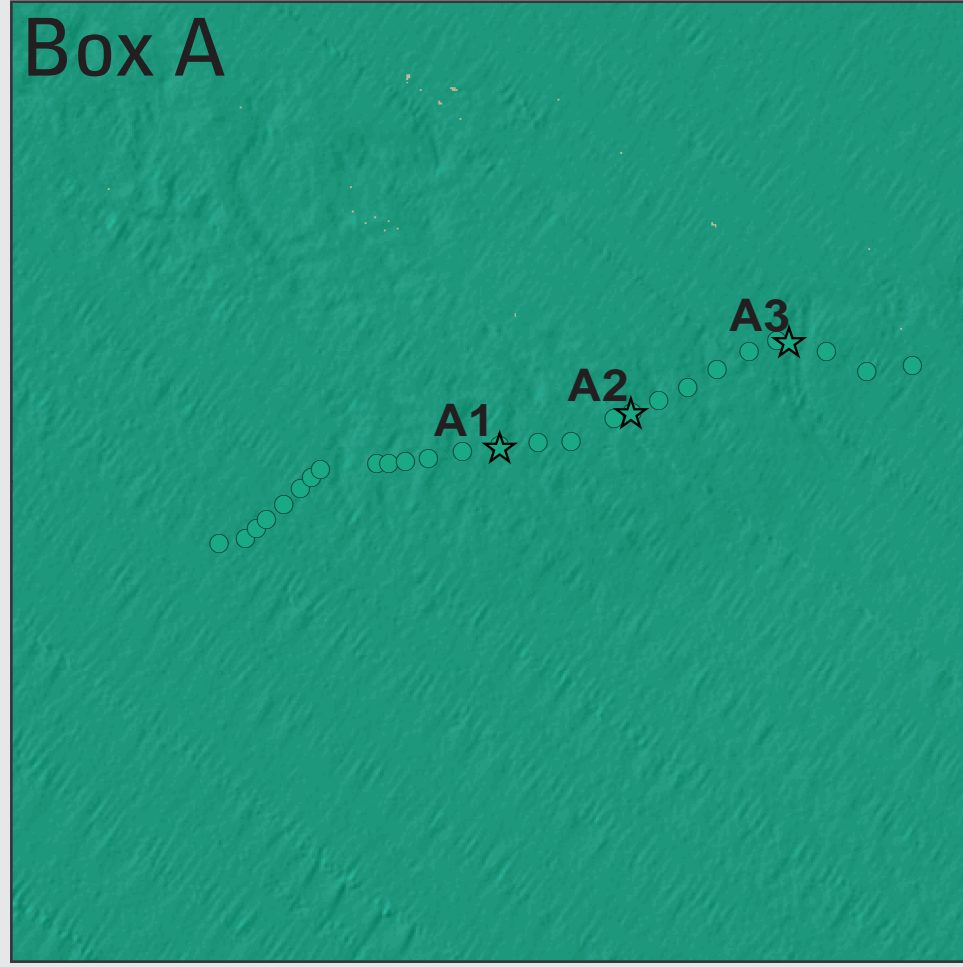


Figure 1A. Detailed view of seafloor character mapped 1.5 km offshore of Pitas Point, approximately 8 km northwest of Ventura River mouth (see Box A, on map, for location), showing locations of periodic real-time video observations (dots) and digital still photographs (stars; see figs. 1B through 1D, from camera line CAM45, cruise S-1C-08-SC).

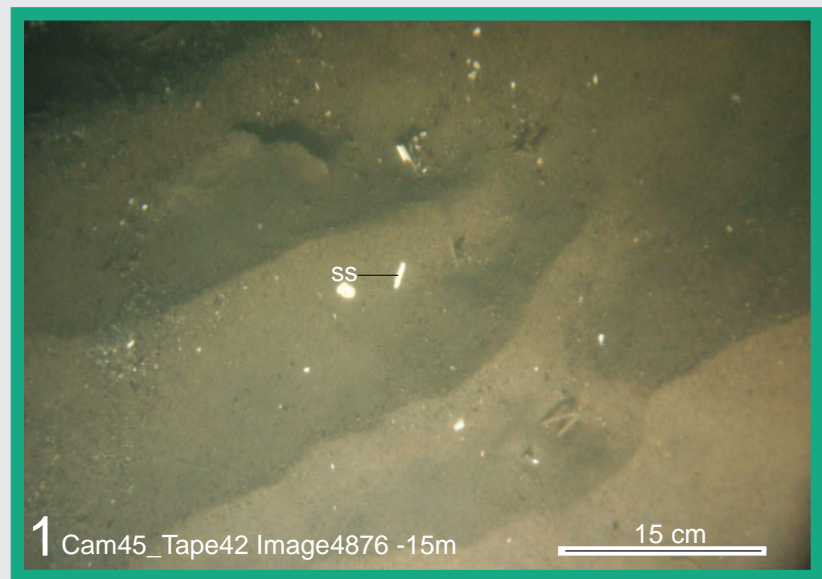


Figure 1B. Digital still photograph no. A1 (see fig. 1A for location). Fine to coarse sand with degraded wave ripples (water depth, 15 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes scattered shells (ss). Distance between lasers (red dots) are just out of view in this image but are visible in previous video frame) is 15 cm.



Figure 1C. Digital still photograph no. A2 (see fig. 1A for location). Fine to coarse sand with degraded wave ripples (water depth, 14 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes scattered shells (ss). Distance between lasers (red dots) are just out of view in this image but are visible in previous video frame) is 15 cm.

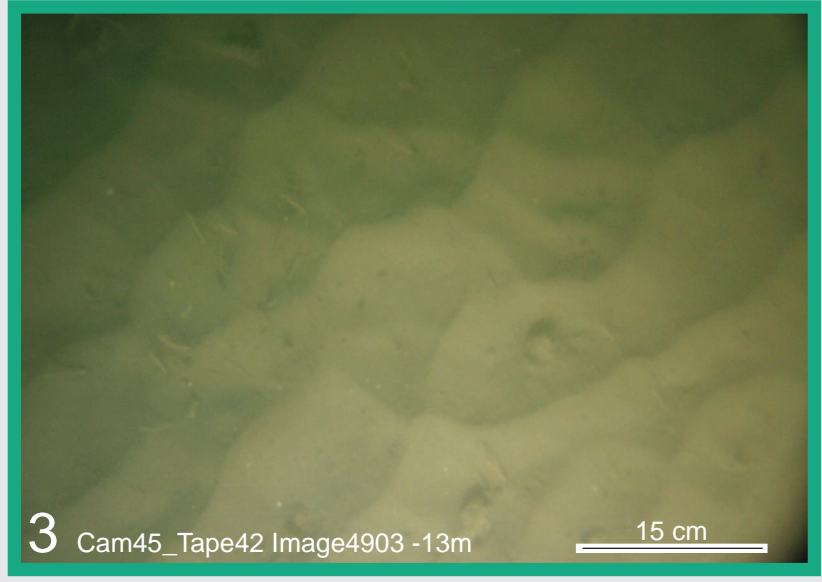


Figure 1D. Digital still photograph no. A3 (see fig. 1A for location). Fine sand with degraded sinusoidal wave ripples (water depth, 13 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Distance between lasers (red dots) are just out of view in this image but are visible in previous video frame) is 15 cm.

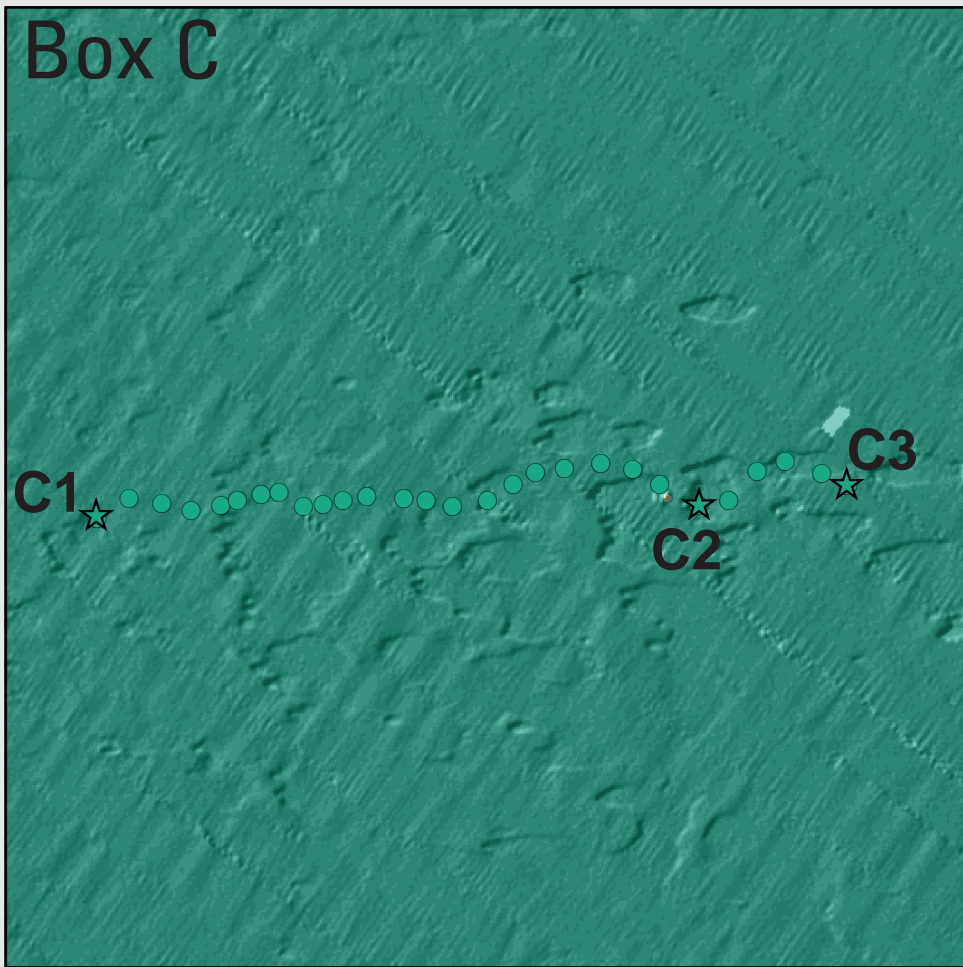


Figure 3A. Detailed view of seafloor character mapped southwest of Ventura, approximately 3 km offshore of Ventura River mouth (see Box C, on map, for location), showing locations of periodic real-time video observations (dots) and digital still photographs (stars; see figs. 3B through 3D, from camera line CAM43, cruise S-1C-08-SC).

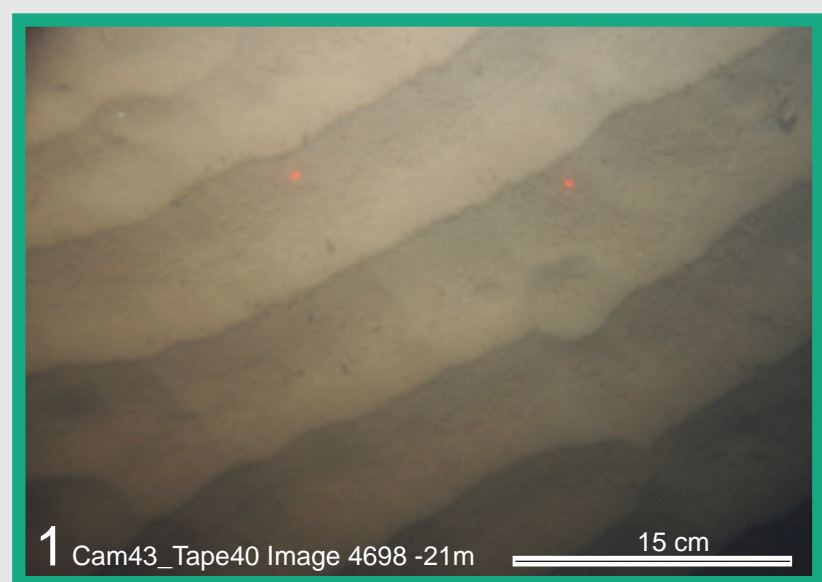


Figure 3B. Digital still photograph no. C1 (see fig. 3A for location). Fine sand with symmetrical and sharp crested wave ripples (water depth, 21 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Distance between lasers (red dots) is 15 cm.

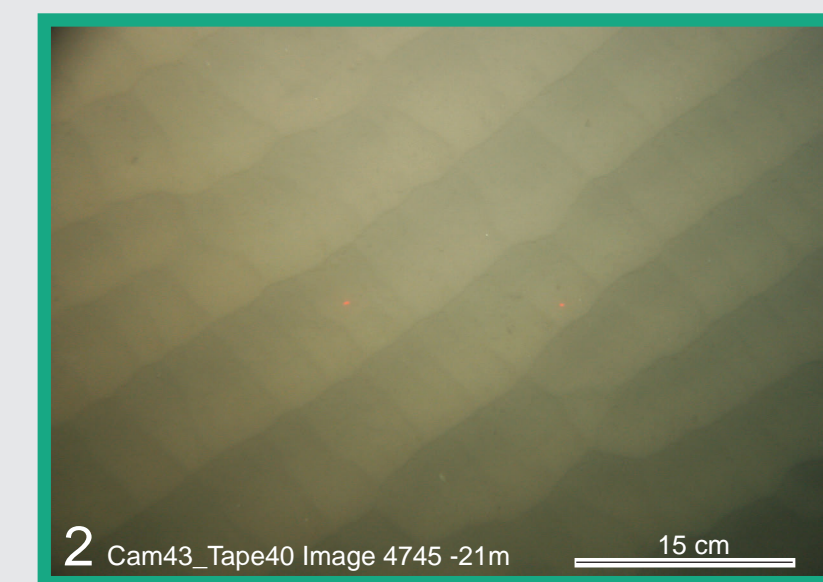


Figure 3C. Digital still photograph no. C2 (see fig. 3A for location). Fine sand with asymmetrical and sharp crested wave ripples (water depth, 20 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes crab (cl). Distance between lasers (red dots) is 15 cm.

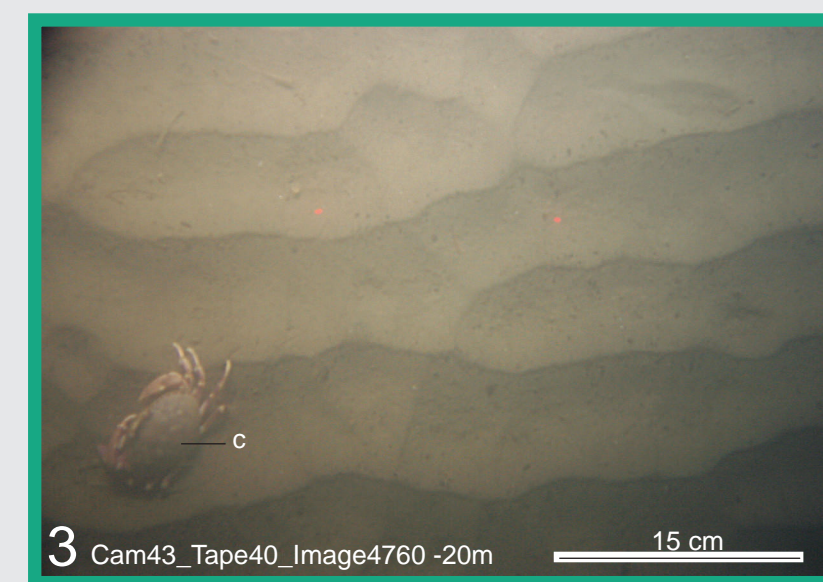


Figure 3D. Digital still photograph no. C3 (see fig. 3A for location). Fine sand with asymmetrical and sharp crested wave ripples (water depth, 21 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes crab (cl). Distance between lasers (red dots) is 15 cm.

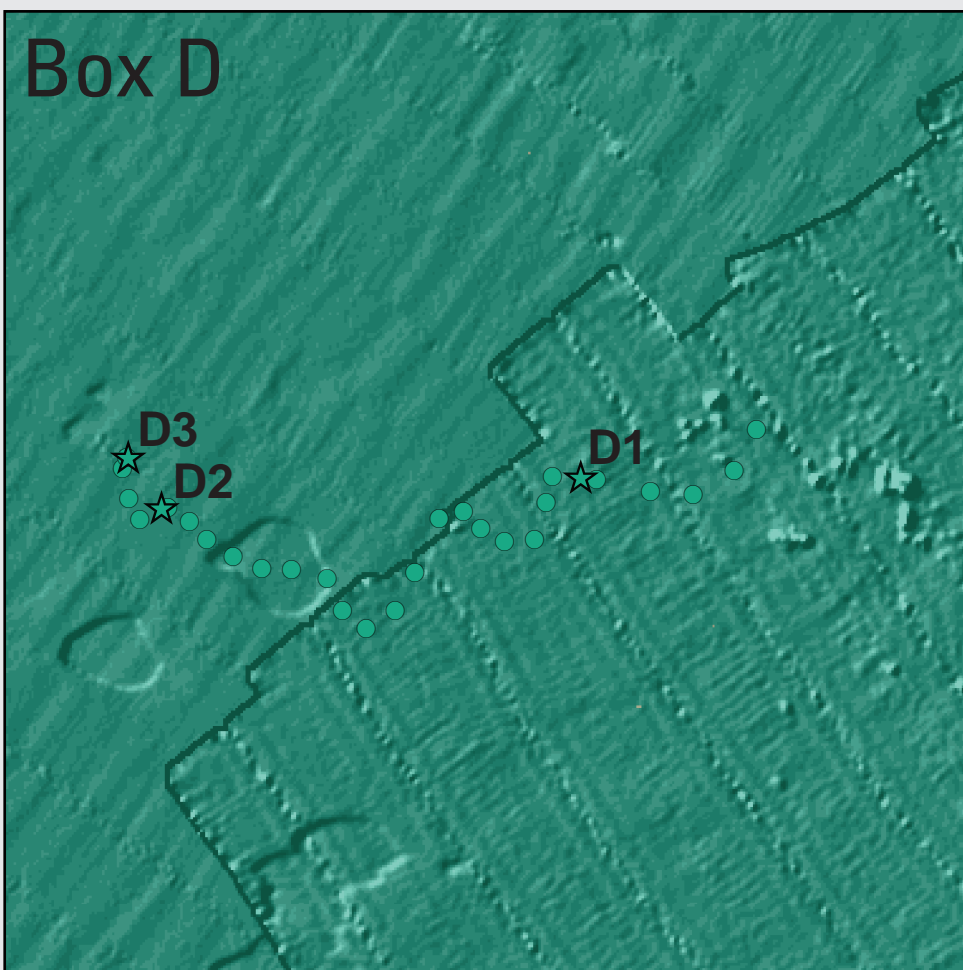


Figure 4A. Detailed view of seafloor character mapped southwest of Ventura, approximately 4.5 km offshore of Ventura River mouth (see Box D, on map, for location), showing locations of periodic real-time video observations (dots) and digital still photographs (stars; see figs. 4B through 4E, from camera line CAM70, cruise S-W1-08-SC).

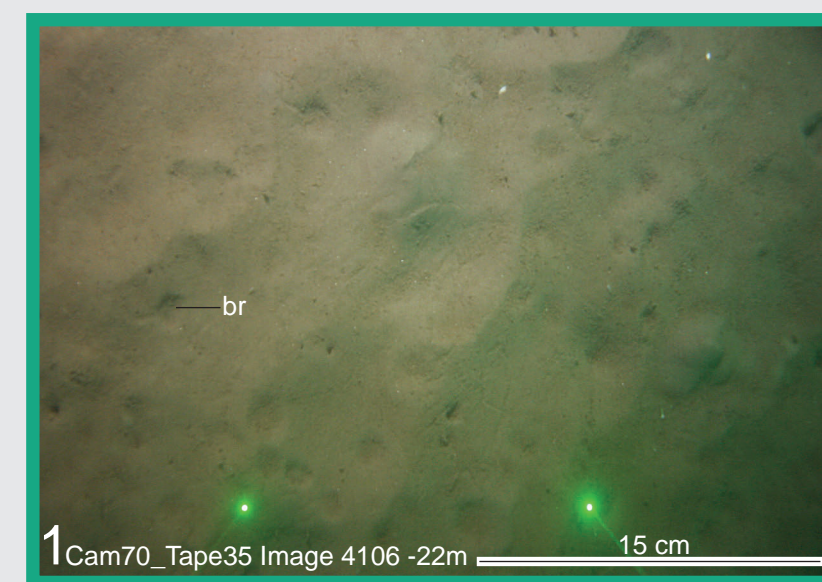


Figure 4B. Digital still photograph no. D1 (see fig. 4A for location). Mud and sand deposited with degraded ripple pattern (water depth, 22 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes burrows (br). Distance between lasers (green dots) is 15 cm.

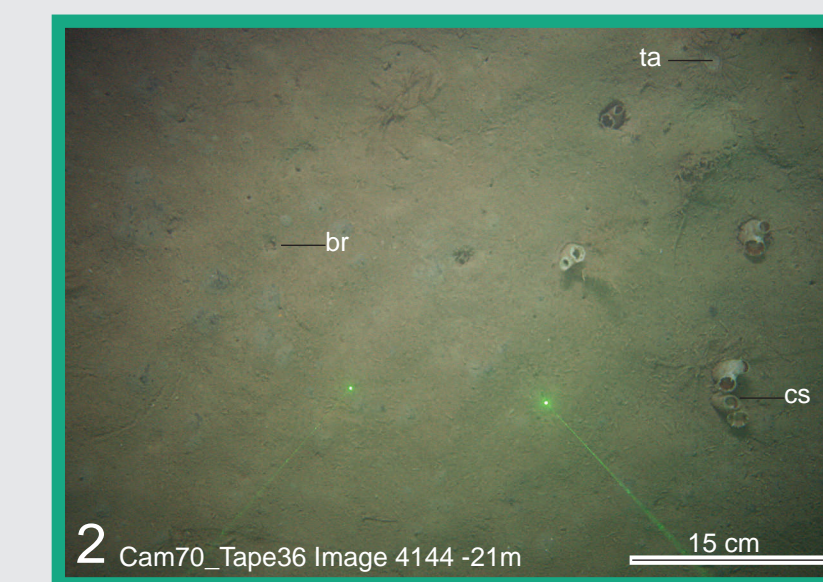


Figure 4C. Digital still photograph no. D2 (see fig. 4A for location). Mud and sand deposited with degraded ripple pattern (water depth, 21 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes burrows (br), clam siphon (cl), and tube anemone (ta). Distance between lasers (green dots) is 15 cm.

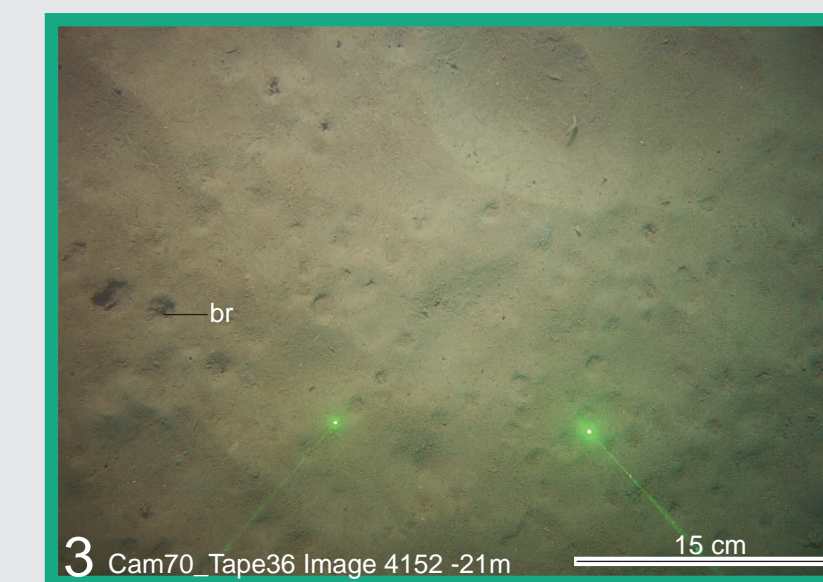
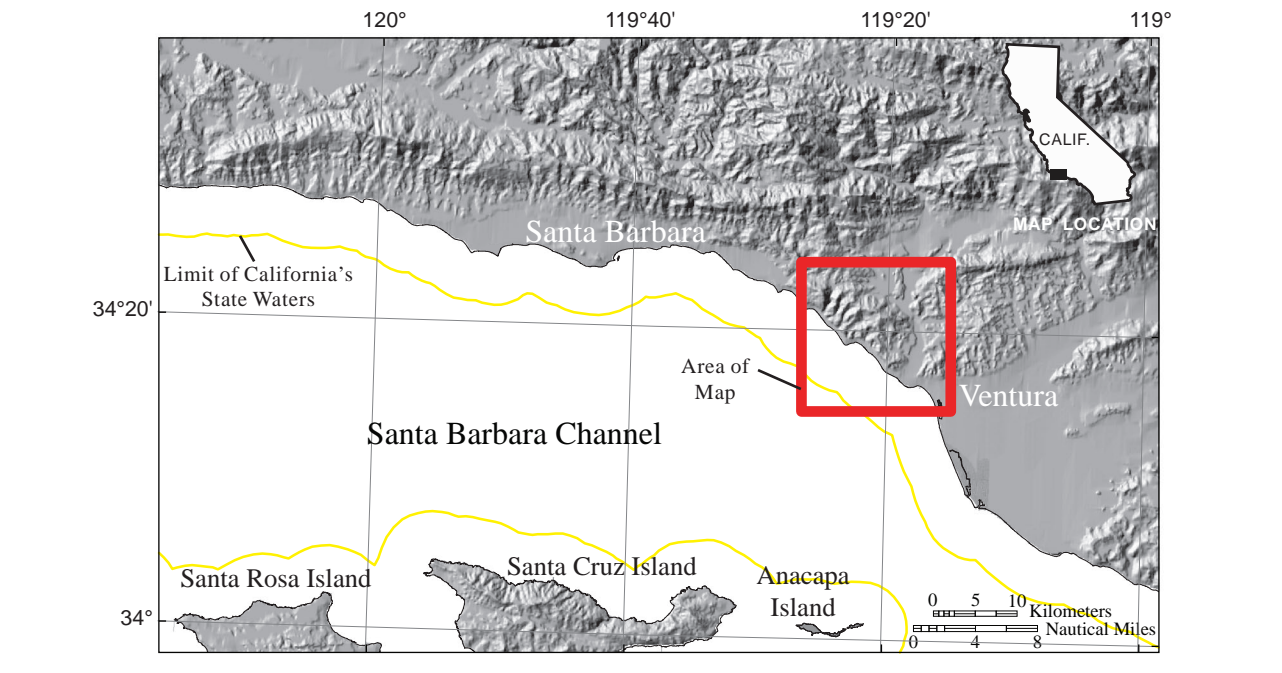


Figure 4D. Digital still photograph no. D3 (see fig. 4A for location). Relatively flat mud and sand deposited with degraded ripple pattern (water depth, 21 m). Abiotic complexity is low, biotic complexity is absent, and biocover is low. Biocover includes burrows (br). Distance between lasers (green dots) is 15 cm.



DISCUSSION

Between 2006 and 2010, the seafloor in the Offshore of Ventura map area in southern California was mapped by California State University, Monterey Bay (CSUMB), and the U.S. Geological Survey (USGS), using both multibeam echosounders and bathymetric sidescan-sonar units (see sheets 1, 2, 3). These mapping missions combined to collect bathymetry and acoustic-backscatter data from about the 10-m isobath to not beyond the 3-nautical-mile limit of California's State Waters. In order to characterize the bathymetry and acoustic-backscatter data into geologically and biologically useful information, the USGS ground-truth-surveyed the data by towing camera sleds (fig. 5) over specific locations throughout the map area.

The ground-truth surveys occurred on two separate cruises over a two-year period. The camera sleds were towed 1 to 2 m over the seafloor, at speeds of between 1 and 2 nautical miles/hour. During the 2007 ground-truth cruise, a smaller USGS camera sled was used that housed two video cameras; one was forward looking, and the other was downward looking. The video was relayed in real time to the research vessel, where USGS and National Oceanic and Atmospheric Administration (NOAA) scientists recorded both the geologic and biologic character of the seafloor once every minute, using programmable keyboards. During the 2008 ground-truth cruise, a larger camera sled was used that housed two video cameras (one forward looking, the other downward looking), a high-definition video camera, and an 8-megapixel digital still camera, which captured a digital still photograph once every 30 seconds. The location and direction of the camera-sled tracklines were chosen in order to visually inspect areas thought to represent the full range of bottom hardness and rugosity in the map area.

In the context of marine-fisheries management, benthic-habitat complexity can be divided into abiotic (geologic) and biotic (biologic) components. Benthic-habitat complexity refers to the visual classification of local abiotic and biotic vertical relief and structure that may provide potential refuge for both juvenile and adult forms of various species. Only abiotic attributes (primary and secondary substrate composition) were used in the prediction of the seafloor-character map on sheet 5. Classifications of primary and secondary substrate are based on the Wentworth scale of sediment grain-size categories, except that the granule and pebble sizes have been grouped together into a class called "gravel," and the clay and silt sizes have been grouped into a class called "mud." Primary and secondary substrate constitute greater than 50 and 20 percent of the seafloor during an observation, respectively.

This sheet contains a smaller, simplified depth-zone symbology has been removed version of the seafloor-character map (sheet 5), in which the camera-sled tracklines used in ground-truth the sonar data are indicated by aligned colored stars, each dot representing the location of a recorded observation. Primary- and secondary-substrate compositions are shown by different colored stars. The map also shows the locations of the detailed views of seafloor character along some of the tracklines (Boxes A through D) that are highlighted on this sheet (figs. 1A through 4A, respectively). Also shown are locations of samples (triangles) from USSEABED (Red and others, 2000) and by Barnard and others (2009) that were used to supplement the ground-truth surveys. The seafloor-character map shows that this area is mostly covered with sediment, except for two small outcroppings of rock in the nearshore region.

Each detailed view (figs. 1A through 4A) shows the locations of camera-sled tracklines (aligned colored stars), as well as the photographs (colored stars) taken along the tracklines. These photographs, which are representative of the seafloor, are displayed with a description of the observed seafloor characteristics recorded by USGS and NOAA scientists (figs. 1B through 1D, 2B through 2D, 3B through 3D, 4B through 4D). Only primary and secondary substrate are reported, although individual photographs may show more substrate types. Organisms, when present, are labeled on the photographs.

Ground-truth surveys in the Offshore of Ventura map area include approximately 6,811 trackline kilometers of video and 308 still photographs, in addition to 213 seafloor observations of abiotic and biotic attributes. A visual estimate of slope also was recorded.

GLOSSARY

Rugosity—A GIS-derived characterization of seafloor roughness, calculated as the ratio of the three-dimensional surface area of seafloor to the two-dimensional planar base area, for each cell in the bathymetry grid.

Backscatter intensity—The amplitude of the reflected sonar signal (see sheet 3) used to infer the hardness of the bottom, determined after sonar-data processing has removed (as much as possible) the effects of water depth, angle of reflection, and bottom roughness.

Biocomplexity—The assessment of the presence or absence of biological structures that have the potential of providing shelter for fauna, determined by estimating the scale, the amount, and the morphology of biological relief (as described by Towse and others, 2000).

Biocover—The visual estimate of the proportion of biologic cover by encrusting organisms: high, greater than 50 percent; moderate, between 50 percent and 10 percent; low, less than 10 percent.

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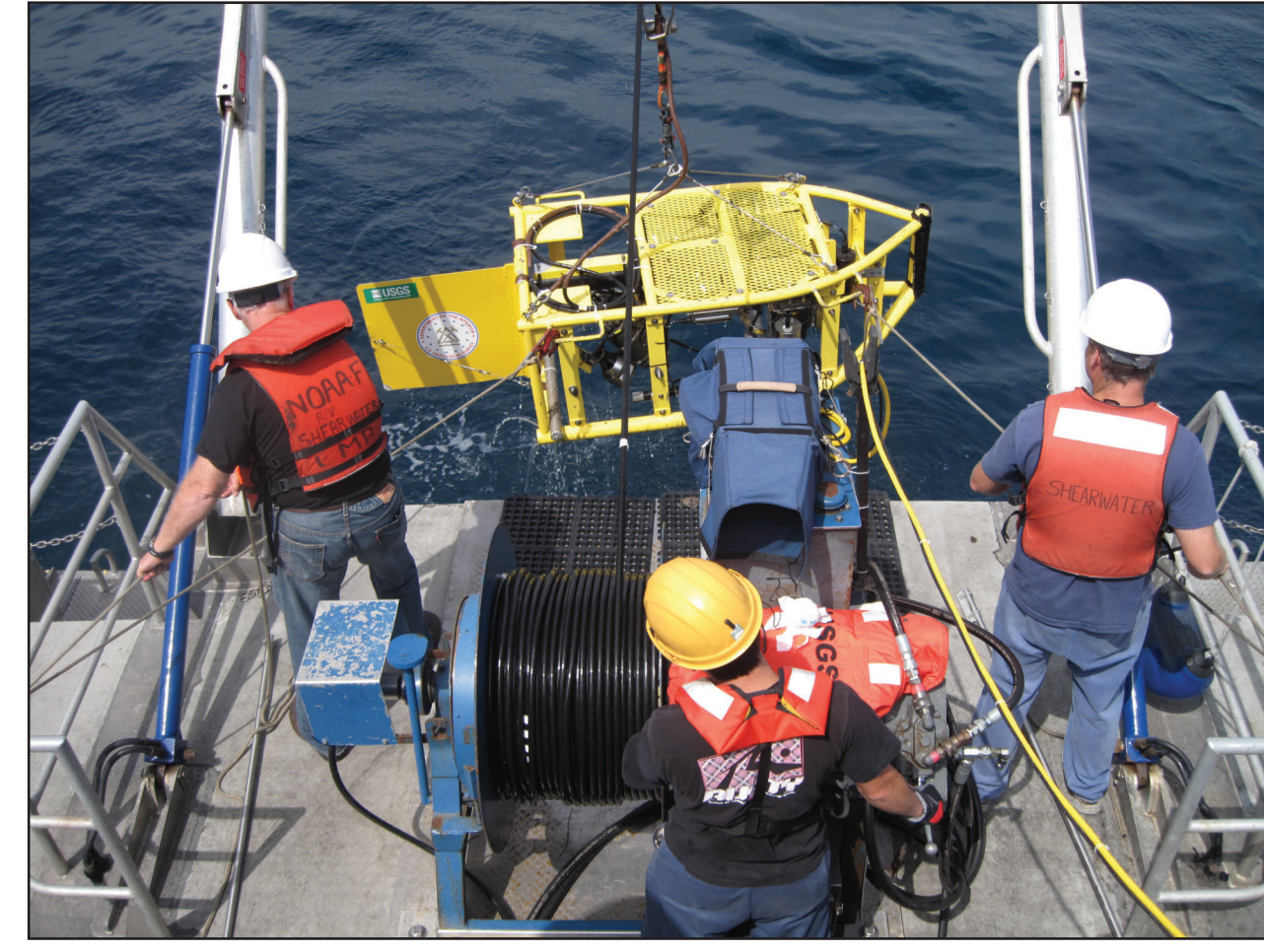


Figure 5. USGS-designed camera sled being launched off research vessel for ground-truth studies. Components onboard sled include four digital video cameras, one 8-megapixel digital SLR camera, lasers for scale, and various strobe and video lights, as well as telemetry instrumentation that records depth, altitude, and compass heading.



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U.S. Geological Survey, National Oceanic and Atmospheric Administration, National Marine Fisheries Service

Ground-Truth Studies, Offshore of Ventura Map Area, California

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