



Based from Sorbus, Inc., proprietary to MACTEC Engineering and Consulting, Inc.
One-half foot pixel resolution, January 2006
Universal Transverse Mercator projection, Zone 15
Horizontal coordinate information referenced to the
North American Datum of 1983 (NAD 83)

EXPLANATION
Difference between light detection and ranging (LIDAR) surface and surface developed from high water marks, in feet, >, greater than

- 0 to 10
- > 10 to 20
- > 20 to 30
- > 30 to 40
- > 40 to 50
- > 50

0 0.5 1 MILE
0 0.5 1 KILOMETER

Estimated Maximum Water Depth Upstream From the Lower Reservoir of the Upper Reservoir Embankment Failure Flood, December 14, 2005
By
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2006