

**AQMAN:  
LINEAR AND QUADRATIC PROGRAMMING  
MATRIX GENERATOR USING TWO-DIMENSIONAL  
GROUND-WATER FLOW SIMULATION FOR  
AQUIFER MANAGEMENT MODELING**

**By L. Jeff Lefkoff and Steven M. Gorelick**



**U. S. GEOLOGICAL SURVEY  
Water-Resources Investigations Report 87-4061**

**Menlo Park, California  
1987**

**DEPARTMENT OF THE INTERIOR**

**DONALD PAUL HODEL, Secretary**

**U. S. GEOLOGICAL SURVEY**

**Dallas L. Peck, Director**

---

**For additional information  
write to:**

**Regional Hydrologist, WR  
U.S. Geological Survey  
345 Middlefield Road  
Menlo Park, California 94025**

**Copies of this report can  
be purchased from:**

**Books and Open-File Report  
U.S. Geological Survey  
Box 25425, Federal Center  
Denver, Colorado 80225  
(Telephone: (303) 236-7476)**

## PREFACE

This report describes a computer model that combines ground-water flow simulation with mathematical optimization in order to develop and evaluate aquifer management strategies. The computer program is intended for general application and may have to be modified by the user for specific field problems. Although the program will produce reliable calculations for a wide variety of problems, the user is cautioned that in some cases the accuracy of management solutions can be significantly affected by user discretion during implementation.

The user is requested to kindly notify the originating office of any errors found in this report or in the computer program. Updates may occasionally be made to both the report and the computer program. Users who wish to be added to the mailing list to receive updates, if any, may send a request to the following address:

AQMAN  
U.S. Geological Survey  
345 Middlefield Road, MS-421  
Menlo Park, CA 94025

Copies of the computer program on tape are available at cost of processing from:

U.S. Geological Survey  
WATSTORE Program Office  
437 National Center  
Reston, VA 22092  
Telephone: (703) 648-5686

The use of computer and software brand names in this report is for identification purposes only and does not imply endorsement by the U. S. Geological Survey.

## CONTENTS

Abstract-----	7
Introduction-----	8
Ground-Water Management Modeling-----	10
Background-----	10
The response matrix method-----	10
General Problem Formulation for Linear and Quadratic Programs-----	13
Linear and quadratic objectives-----	13
Constraints and system linearity-----	14
Time parameters-----	15
Stress and response-----	16
Drawdowns-----	16
Gradients and velocities-----	16
Head, gradient, and velocity definitions-----	18
The MPS file and the solution-----	19
Problem Formulation with AQMAN-----	20
Objective function-----	20
Linear objective-----	20
Quadratic objective-----	20
Constraint set-----	23
Pumping and recharge constraints-----	23
Head constraints-----	24
Gradient and velocity constraints-----	26
Head and velocity definitions-----	30
Nonlinearities-----	34
Time parameters-----	34
The unit stress and scaling-----	36
Quadratic objective-----	37
The MPS file-----	37
User changes-----	37
MPS format conventions-----	37
Naming conventions-----	41
Size of the MPS file-----	42
Program Description-----	43
Main-----	43
Subroutine PRE-----	43
Subroutine CHKDAT-----	45
Subroutine GRADS-----	45
Subroutine MPSFMT-----	45
Subroutine QUAD-----	45
Subroutine READ1-----	46
Subroutine WRITE1-----	46
Data Files-----	47
Sample Problem-----	48
References-----	55
Appendix I, Definition of Variables-----	57
Appendix II, Date File Instructions-----	61
Appendix III, Quadratic Objective Subroutine FUNOBJ-----	67
Appendix IV, Data Files for Sample Problems-----	76
Appendix V, AQMAN Program List-----	94

## ILLUSTRATIONS

- Figure 1.** Managed and unmanaged potentiometric surfaces with several wells.
2. Lift, potentiometric surface, and seepage velocity induced by a pumping well.
  - 3a. MPS file written by AQMAN for the data shown in Table 1. There are three control locations, two decision wells, and one management period.
  - 3b. Head definition is substituted at control location 1.
  - 3c. Head constraint at location 1 is manually inserted.
  - 4a. MPS file written by AQMAN for the data shown in Table 1 with velocity control added at control pair 1.
  - 4b. Head definition is specified at velocity control pair 1 and 2.
  - 4c. Velocity constraint at control pair 1 is manually inserted.
  5. The vector sum  $V$  of velocity controls 1 and 2.
  6. Organization of the MPS file.
  7. Flow chart showing major computations performed by AQMAN.
  8. Finite-difference grid for the sample problem (after Trescott and others, 1976).
  9. The sample problem, re-formulated with a response matrix.
  10. The re-formulated sample problem with four head definitions added.

## LIST OF TABLES

- Table 1.** Sample computations of manageable drawdown, and response coefficients. The last two columns form the response matrix.

## CONVERSION FACTORS

For convenience of readers who prefer to use metric (International System) units, conversion factors for inch-pound units used in this report are listed below:

<u>Multiply inch-pound unit</u>	<u>By</u>	<u>To obtain metric unit</u>
foot (ft)	0.3048	meter (m)
cubic feet per second (ft <sup>3</sup> /s)	0.02832	cubic meter per second (m <sup>3</sup> /s)

## ABSTRACT

A FORTRAN-77 computer program code that helps solve a variety of aquifer management problems involving the control of ground-water hydraulics is presented. It is intended for use with any standard mathematical programming package that uses Mathematical Programming System input format. The computer program creates the input files to be used by the optimization program. These files contain all the hydrologic information and management objectives needed to solve the management problem.

Used in conjunction with a mathematical programming code, the computer program identifies the pumping or recharge strategy that achieves a user's management objective while maintaining ground-water hydraulic conditions within desired limits. The objective may be linear or quadratic, and may involve the minimization of pumping and recharge rates or of variable pumping costs. The problem may contain constraints on ground-water heads, gradients, and velocities for a complex, transient hydrologic system.

Linear superposition of solutions to the transient, two-dimensional ground-water flow equation is used by the computer program in conjunction with the response matrix optimization method. A unit stress is applied at each decision well and transient responses at all control locations are computed using a modified version of the U.S. Geological Survey two dimensional aquifer simulation model. The program also computes discounted cost coefficients for the objective function and accounts for transient aquifer conditions.

## INTRODUCTION

Numerical simulation models have become essential tools for hydrogeologists. Often models are utilized for evaluating different ground-water management strategies. Such strategies may be needed for aquifer management problems that involve:

- contaminant plume stabilization and removal
- coastal aquifer protection
- maximization of aquifer yields
- design of surface excavation dewatering systems
- development of policies for conjunctive use of surface and ground waters
- inspection of the impacts of water use regulation.

The difficulty with trying to use simulation models to study these problems is that potential strategies can be tested only on a trial and error basis. There is no guarantee that the best alternatives will be discovered. Simulation by itself is valuable for understanding system behavior and in some cases for predicting future responses, but it is far less valuable as a tool for discovering optimal aquifer management strategies. In order to effectively determine viable and efficient aquifer management plans, simulation can be combined with optimization procedures of operations research. Operations research is a general field of applied mathematics that is concerned with optimal decision making.

AQMAN is a FORTRAN-77 computer code that provides a link between ground-water simulation and two widely used techniques developed in operations research: linear programming and quadratic programming. These techniques provide a mathematical framework and efficient computational algorithms to determine the optimal allocation of scarce resources. Water, its cost of extraction, and the costs required to maintain its quality are the scarce resources of interest to the hydrologist. Combined simulation-management models can be used to identify pumping and recharge schedules that achieve some goal, such as minimizing ground-water production costs, while simultaneously protecting water quality and satisfying water demands. This procedure is known as **aquifer management modeling**.

Aquifer management modeling is concerned with the best selection of well locations and pumping and recharge rates that achieves certain goals with regard to aquifer yields, drawdowns, hydraulic heads, hydraulic gradients, and ground-water velocities. It also can involve recharge through streambeds, ground-water flow to streams and lakes, maintenance of surface-water levels, and other interactions between surface water and ground water. Aquifer management modeling is a multistaged procedure. First, a simulation model is developed for a particular field site. The hydrologic behavior of the site should be well understood. Second, a management problem is formulated. Third, the simulation model is used to generate a compact simulator called a response matrix. Fourth, a special data file is created that contains the response matrix and represents the management formulation in a format that is required for solution by any of a number of available optimization codes. Fifth, a standard linear or quadratic programming code reads the special file and determines the optimal solution. Sixth, the effect of the pumping and recharge schedules prescribed by the optimal solution is verified using the original simulation model. Seventh, the sensitivity of the solution to uncertainties is explored.

The AQMAN program performs stages three and four: generation of the response matrix and construction of the optimization data file. It is also useful in stage seven, sensitivity analysis.

Given a field area for which a simulation model has been developed and for which a management problem has been formulated, AQMAN can be used to evaluate alternative management strategies. It is applicable to problems for which two-dimensional confined aquifer simulation models are appropriate. AQMAN uses the code of Trescott and others (1976) to simulate the set of system responses to pumping or recharge, as well as other system stresses. It then converts this information into a response matrix and creates the optimization data file. From that point on an optimization code is employed to solve the linear or quadratic programming problem.

The use of AQMAN for aquifer management modelling requires a thorough understanding of aquifer simulation and the principle of linear superposition. Experience with the optimization methods of linear and quadratic programming is helpful, but not essential. The user should be familiar with aquifer flow simulation and should be able to use the code of Trescott and others (1976) for the problem of interest. AQMAN's programming logic is quite general for aquifer management modelling, so that with appropriate modifications other ground-water flow simulators may be linked with AQMAN. However, this may require several changes in both the flow simulator and in the AQMAN code. These changes should be performed only by experienced ground-water modellers. In its current form, AQMAN is fully linked only with the Trescott code.

Aquifer simulation must be performed for systems that show a linear drawdown response to pumping and are sufficiently described by the equation that governs two-dimensional ground-water flow:

$$\frac{\partial}{\partial x_i} \left[ T_{ij} \frac{\partial H}{\partial x_j} \right] = S \frac{\partial H}{\partial t} + W, \quad i, j = 1, 2 \quad (1)$$

- where H = hydraulic head [L],
- $T_{ij}$  = transmissivity tensor [ $L^2/T$ ],
- S = storage coefficient [ $L^0$ ],
- W = source (recharge) or sink (pumping) per unit area [ $L/T$ ],
- t = time [T],
- $x_i$   $x_j$  = spatial coordinates [L].

## GROUND-WATER MANAGEMENT MODELING

### Background

Ground-water management modeling is a relatively new discipline in hydrology. Over the past 25 years, two types of management models have been developed: lumped parameter and distributed parameter models. **Lumped parameter models** have been used to study economic and policy matters that involve ground-water resources. They do not explicitly consider the governing equations of ground-water flow, but rather conceptualize aquifers with simple water mass balances. Examples of lumped parameter models are those of Chaudhry and others (1974), Anderson and others (1983), and Khepar and Chaturvedi (1982). **Distributed parameter management models** join aquifer simulation with optimization methods and explicitly solve the partial differential equation that governs flow. Gorelick (1983) discusses and critically evaluates the methods and applications of these models. They have been used to manage well fields, to evaluate efficient conjunctive use of stream-aquifer systems, and to inspect the impacts of water-resource policies upon the hydrology and economics of ground-water use. AQMAN is a tool that helps solve distributed parameter aquifer management problems.

AQMAN links a distributed parameter ground-water simulation model with mathematical optimization methods using a technique known as the **response matrix approach** (see Gorelick, 1983). This approach was initially developed for optimizing profits from oil production, and was presented in the petroleum engineering literature by Lee and Aronofsky (1958). During the 1970's the technique was expanded and brought into the hydrologic literature, principally by Wattenbarger (1970), Maddock (1972), Rosenwald and Green (1974), and Schwarz (1976). Applications of the response matrix approach have been presented by Larson and others (1977) and by Heidari (1982) to determine "safe yield" of aquifers; by Willis (1983) to determine the optimal pumping scheme to meet agricultural water demands; by Danskin and Gorelick (1985) to evaluate the efficiency of a surface-water recharge program; and by Colarullo and others (1984), Atwood and Gorelick (1985), Gorelick and Wagner (1986), and Lefkoff and Gorelick (1985; 1986) to contain plumes of contaminated ground water and design aquifer restoration systems.

### The Response Matrix Method

The key idea behind the response matrix method is that because a ground-water system described by equation (1) is linear, the influence of each source or sink may be calculated separately and then superposed to compute the complete distribution of hydraulic heads over space and time under any pattern of pumping and recharge. The method fully accounts for the effects of initial conditions, which may vary over space, and the effects of boundary conditions, which may change over time.

A response matrix is an assemblage of coefficients, each of which relates pumping at one location to drawdown at another location. In order to see how a response matrix is developed using a simulation model, consider an example where head is to be controlled at a location P during two months by managing pumping at two wells, A and B. By use of a unit pumping rate, drawdown is calculated at the end of each month at location P.

Specifically,

- (1) Reference-head at P is computed by a transient simulation with no pumping.
- (2) A convenient unit pumping rate, 1.0 ft<sup>3</sup>/s, is selected.
- (3) A transient simulation is performed with only well A pumping at the unit rate during the first month and not pumping during the second month. Calculated head at P is subtracted from the reference head to obtain a drawdown for each month. For example, say that drawdown is 0.75 feet at the end of the first month and 0.20 feet at the end of the second month.
- (4) Step (3) is repeated for well B. Say that the calculated drawdown at P from the reference head is 0.40 feet at the end of the first month and 0.25 feet at the end of the second month.

Because the system is linear, total drawdown at P induced by managed pumping during each month equals the sum of the drawdowns due to the two wells:

$$s_1 = 0.75 Q_{A,1} + 0.40 Q_{B,1}$$

$$s_2 = 0.20 Q_{A,1} + 0.25 Q_{B,1} + 0.75 Q_{A,2} + 0.40 Q_{B,2}$$

where  $s$  = total drawdown [feet] from the reference head at location P at the end of month 1 or 2 due to managed pumping,

$Q$  = pumping rate [ft<sup>3</sup>/s] at well A or B during month 1 or 2.

These two equations can be expressed in matrix form:

$$\begin{bmatrix} s_1 \\ s_2 \end{bmatrix} = \begin{bmatrix} .75 & .40 & 0 & 0 \\ .20 & .25 & .75 & .40 \end{bmatrix} \begin{bmatrix} Q_{A,1} \\ Q_{B,1} \\ Q_{A,2} \\ Q_{B,2} \end{bmatrix}$$

vector of  
drawdowns

=

response matrix

x

vector of  
pumping rates

Response coefficients (0.75, 0.40, 0.20, 0.25) are stored in a matrix, thus the name **response matrix method**. Through matrix algebra, a large number of responses can conveniently be added over time and space. For any given set of initial and boundary conditions, total drawdown at a given location will be a linear function of pumping and recharge at all wells during all management periods.

The small example above demonstrates two general features of response matrices. First, the matrix contains zero elements in the upper triangular portion because pumping or recharge in some management period can never affect drawdowns in an earlier period. Second, matrix elements are repeated systematically. This is

because the response to a unit of pumping depends only on the time since pumping began. That is, the response to a unit pumping rate that begins today is the same as the response to a unit pumping rate that begins next month, except that the responses are lagged by one month. The matrix in the example above has the following general structure:

drawdown response in month 1 to unit pumping in month 1	zero response
drawdown response in month 2 to unit pumping in month 1	drawdown response in month 2 to unit pumping in month 2 (same as upper left)

When generating the response matrix, the number of computations performed in AQMAN is reduced by taking advantage of this matrix structure.

## GENERAL PROBLEM FORMULATION FOR LINEAR AND QUADRATIC PROGRAMS

The process of solving a linear or quadratic programming problem begins with the formulation of a management problem as a mathematical model. As with all models, the mathematical formulation extracts the essence of the real-world system and does not consider every detail. Problem formulation may reveal inadequacies in the data. It may also happen that the formulation process, which is often avoided during trial and error simulation, will lead directly to a highly simplified management model, or even to an apparent solution.

Problem formulation is certainly the most important and often the most difficult part of management modelling. A management model consists of an objective function (or goal) which to be minimized or maximized, and a series of linear constraints (or restrictions) that must be obeyed. Decision variables are the unknown quantities of concern that can be controlled in a managed system. For our purposes, these are pumping and recharge rates at specific locations.

### Linear and Quadratic Objectives

Linear programming is used for cases in which the objective function, whose value is  $F$ , is linear with respect to the decision variables. For example, one might maximize the sum of pumping rates,  $Q_{i,n}$  at five wells (index  $i$ ) during eight time periods (index  $n$ ):

$$\text{Maximize } F = \sum_{n=1}^8 \sum_{i=1}^5 Q_{i,n} \quad (2)$$

Quadratic programming is used for cases in which the objective is a quadratic function of the decision variables. For example, one might minimize the sum of squared differences between pumping rates and ideal target pumping rates,  $Q_{i,n}^*$ :

$$\text{Minimize } F = \sum_{n=1}^8 \sum_{i=1}^5 (Q_{i,n} - Q_{i,n}^*)^2 \quad (3)$$

Typical objective functions are:

- Minimize the cost of pumping
- Minimize total pumpage
- Maximize total pumpage
- Minimize the maximum pumping rate
- Maximize total recharge
- Minimize the maximum drawdown
- Maximize the minimum hydraulic head
- Minimize the sum of squared deviations from target heads, hydraulic gradients, velocities, drawdowns, or pumping rates
- Minimize the sum of the absolute value of deviations from target heads, hydraulic gradients, velocities, drawdowns, or pumping rates

Objectives may also involve fixed costs, such as well installation or capital investment in pumping capacity. Further, it is possible to formulate problems with multiple objectives. Aguado and Remson (1980) describe the fixed cost problem, and Cohon and Marks (1975) provide an excellent review of multi-objective analysis. AQMAN does not automatically generate fixed cost objectives nor multiple objective functions, but is nonetheless useful for solving such problems.

### Constraints and System Linearity

Constraints derive from the physical, economic, or social mechanisms operating in the managed system. Typical ground-water constraints might involve

- definition of drawdowns as a linear function of system stresses using a response matrix
- definition of hydraulic heads, velocities, and gradients as a function of system stresses
- limitations on local drawdowns, hydraulic gradients, velocities or heads
- restrictions on local hydraulic gradients or velocities to certain magnitudes and directions
- limitations on pumping rates at individual or groups of wells
- restrictions on changes in pumping rates, drawdowns, or hydraulic heads over time
- balances between total pumping and total recharge

Constraints may be represented by placing simple bounds on individual decision variables, by inequalities or equalities placed on groups of decision variables, or by restrictions on hydraulic conditions. In all cases, a specified limit appears on the right-hand side. For example, the pumping rate  $Q$  at well 2 during period 3 must not exceed 1.5 ft<sup>3</sup>/s:

$$Q_{2,3} \leq 1.5 \quad (4)$$

Total pumpage for three wells must supply at least 5.0 ft<sup>3</sup>/s during period 1:

$$Q_{1,1} + Q_{2,1} + Q_{3,1} \geq 5.0 \quad (5)$$

Pumping rates at well 1 must be the same for periods 3 and 4:

$$Q_{1,3} - Q_{1,4} = 0 \quad (6)$$

Hydraulic head  $H$  at location 3 must not exceed 50 feet during period 1:

$$H_{3,1} \leq 50 \quad (7)$$

During period 4, the hydraulic gradient between locations 1 and 2 must not be less than 5 percent ( $L$  is the distance between the two locations):

$$\frac{H_{1,4} - H_{2,4}}{L} \geq 0.05 \quad (8)$$

The seepage velocity  $V$  at location 2 must be at least 0.03 ft/s during period 5:

$$V_{2,5} \geq 0.03 \quad (9)$$

At location 3 during period 1, the x-component of the seepage velocity must be at least twice the y-component:

$$V_{3,1}^x - 2V_{3,1}^y \geq 0 \quad (10)$$

In both linear and quadratic programming problem formulations all constraints must be linear. This means that the ground-water system must respond linearly to management decisions. The hydraulics of a confined aquifer can be managed successfully using linear or quadratic programming, since ground-water flow is governed by equation (1), which contains a linear relation between head changes and well pumpages.

AQMAN is useful only for linear management problems. Nonlinear constraints cannot be imposed. For example, nonlinearities resulting from dewatering of unconfined aquifers cannot be rigorously handled by AQMAN. However, in some cases it may be possible to linearize such systems if drawdown is small compared to saturated thickness, or by solving sequential linear problems where the saturated thickness is given by the last iterate (Danskin and Gorelick, 1985). There is a certain art in formulating problems to avoid nonlinearities. For instance, the absolute value function, which is in fact nonlinear, has a linear equivalent that can be easily incorporated into linear programming problems. The problem and methods for deriving linear formulations is discussed in various operations research text books such as Dantzig (1963), Hillier and Lieberman (1974), and Wagner (1975).

Advanced techniques are now available to manage nonlinear systems (Gorelick and others, 1984). Nonlinear management modelling problems are not restricted to aquifer hydraulics. They involve the solution of governing equations which are not linear with respect to management decisions. For instance, a problem which calls for the management of solute concentrations when those concentrations are affected by pumping and recharge decisions is nonlinear.

### Time Parameters

Three time parameters are used in management modelling. The **planning horizon** is the total length of time over which a system is being managed. It consists of one or more **management periods** or **planning periods**, which define the time during which a particular decision variable is constant or a particular set of constraints applies. For instance, we may define a one-year planning horizon consisting of 12 one-month management periods. A separate decision variable would be defined for each well during each month, and a constraint that relates pumpage to drawdown would be formulated for each month. AQMAN requires that all management periods are equal in length. The third time parameter is the numerical time step used in the finite-difference simulation procedure.

## Stress and Response

### Drawdowns

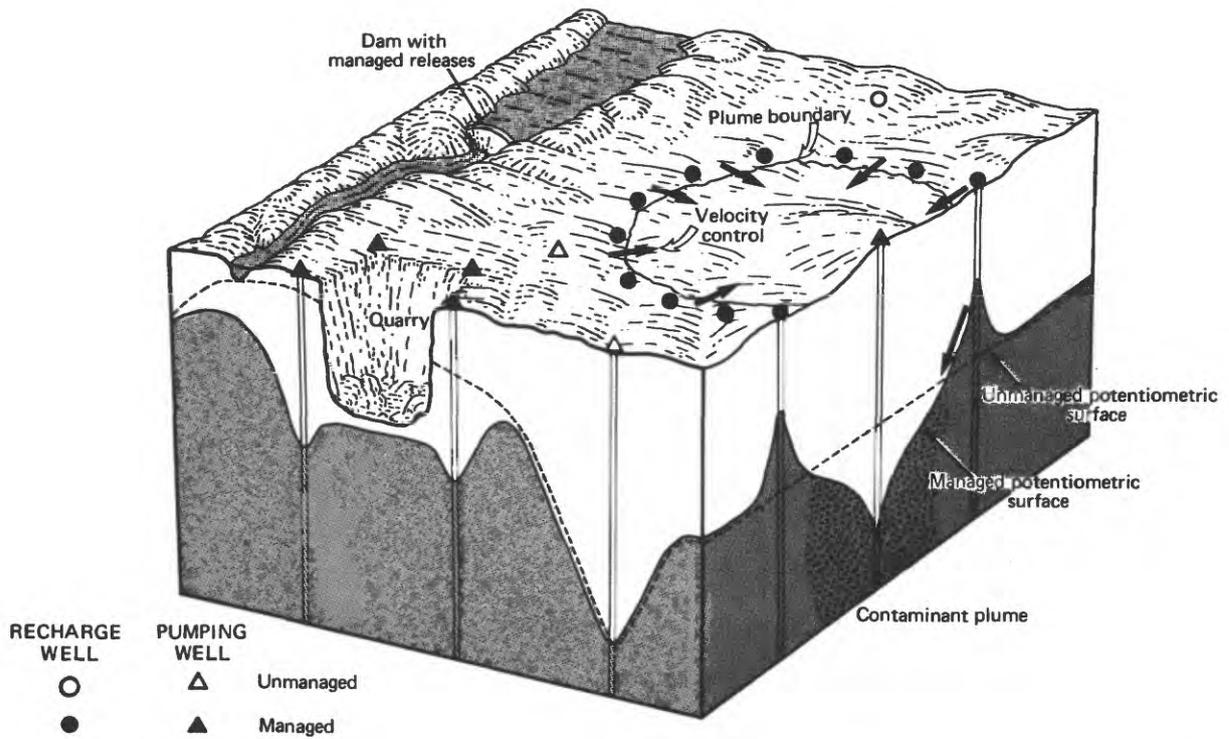
Use of the response matrix method for ground-water management modeling relies on the concept of linear response to system stress. A **stress** is an excitation that induces a change in aquifer heads. An **unmanaged stress** is one that cannot be controlled due to physical limitations or social demands. Examples might be boundary conditions and pre-determined pumpage or recharge rates given for **unmanaged wells**. **Managed stresses** are those described by the decision variables: pumpage and recharge at **managed wells**, where management decisions must be made. In this context, "well" refers to any source or sink. In addition to actual pumping or injection wells, the term includes stresses such as recharge from a lake or from a river where flow is controlled. In order to strictly maintain system linearity, the flux through a managed well can not be head-dependent. **Unstressed heads** or **unmanaged heads** are those that would occur if no managed stresses were applied to the system (Figure 1). **Manageable drawdown** is the difference between unmanaged head and any limit on head imposed by the user. For example, suppose that head at a location must always be greater than 88.0 feet, and that the unmanaged head there is 93.8 feet in the first management period, and 92.4 feet in the second period. Then the manageable drawdown in the two periods are +5.8 feet and +4.4 feet, respectively.

A **unit stress** is a convenient quantity of managed stress, such as  $0.1 \text{ ft}^3/\text{s}$  or  $1.0 \text{ ft}^3/\text{s}$ . For each separate managed well, AQMAN applies a unit stress at the well during the first management period and then applies no managed stresses during subsequent periods. The transient ground-water flow equation (1) is solved to obtain hydraulic head at every control location during every period. The **drawdown response** is the difference between this head and unmanaged head. Every response appears in the management formulation as a **response coefficient**. The coefficient measures the hydraulic relation between stress at a particular managed well and drawdown at a particular control location. Through the use of linear superposition, the product of the response coefficient and the actual managed stress gives the actual drawdown at the control location induced by pumping or recharge at the managed well. **Total drawdown** equals the sum of the individual drawdowns caused by each managed well, plus the drawdown caused by initial and boundary conditions and unmanaged pumping and recharge. Total drawdown must be contained within the limits imposed by the manageable drawdown.

### Gradients and velocities

A **control pair** is defined by two control locations across which a gradient or hydraulic ground-water velocity is being constrained. In order to define a gradient or a velocity, the **difference-in-drawdown** response is used in a manner similar to drawdown response. Each difference-in-drawdown response also appears in the management formulation as a response coefficient. The coefficient measures the hydraulic relation between stress at a decision well and the difference-in-drawdown within a control pair. The response coefficient multiplied by the managed pumping and recharge rates gives the difference in drawdown. The **total difference-in-drawdown** equals the sum of the influences due to managed stress, unmanaged stress, and initial and boundary conditions. This total difference is linearly proportional to the gradient and to the velocity at the control pair.

The total difference-in-drawdown must be contained within the limits imposed



**Figure 1. Managed and unmanaged potentiometric surfaces with several wells.**

by the **manageable gradient** or **manageable velocity** for the control pair. The manageable gradient is the difference between the gradient due to unmanaged heads and any limit on the gradient imposed by the user. The manageable velocity is the difference between the velocity under the unmanaged gradient and any limit on velocity imposed by the user. In both cases, the user's limit on gradient or velocity is multiplied by a factor that converts it to a head difference. For example, say that control pair 2 is defined by control location 4 and 7 (These are indicated below by the subscripts "2", "4", and "7"). Ignoring the time dimension for the sake of clarity,

$$G_2 = H_4 - H_7 - \bar{G}_2 (L_2) \quad (11)$$

$$V_2 = H_4 - H_7 - \bar{V}_2 \left[ \frac{\epsilon_2 L_2}{K_2} \right] \quad (12)$$

- where
- G = manageable gradient within the control pair [L],
  - V = manageable velocity within the control pair [L],
  - H = unmanaged head at a control location [L],
  - $\bar{G}$  = limit on gradient imposed by the user [ $L^{\circ}$ ],
  - $\bar{V}$  = limit on velocity imposed by the user [L/T],
  - L = distance between the two locations of the control pair [L],
  - $\epsilon$  = effective porosity within the control pair [ $L^{\circ}$ ],
  - K = hydraulic conductivity within the control pair [L/T].

The conversion factor L or ( $\epsilon L/K$ ) is read as input by AQMAN.

### Head, gradient, and velocity definitions

Ground-water management problems are usually formulated in terms of drawdown or difference-in-drawdown. AQMAN also allows for **head definition**, **gradient definition**, or **velocity definition** at any control location or control pair as a supplement to drawdown information. The use of definitions may serve two purposes. First, the management solution will directly contain the heads, gradients, or velocities that result in response to optimal pumping and recharge rates. This helps the user characterize the optimal management strategy. Second, the difference between two gradients or two velocities can be easily controlled. This is particularly useful in comparing the magnitude of the two vector components of the gradient or velocity at a pair of control locations.

Definitions can be specified for head at a single control location or for difference-in-head within a control pair. In the first case, AQMAN automatically introduces a new decision variable and sets it equal to the difference between unmanaged head and total drawdown. In the second case, the new decision variable

is set equal to the difference between: (1) the difference in unmanaged heads and (2) the total difference-in-drawdown. The user can then impose additional constraints on the new head, gradient, or velocity variables.

### The MPS File and the Solution

AQMAN creates a data file that defines the objective and all constraint functions and contains all of the response coefficients and manageable drawdowns, gradients, and velocities. The file is written in MPS (Mathematical Programming System) format, which is required by most standard linear and quadratic programming packages. The optimization package reads this MPS file as input, and computes a solution to the management problem.

A management solution consists of a set of values for the decision variables. A solution is either infeasible, optimal, or unbounded. An infeasible solution violates one or more of the constraints. A feasible solution is optimal if it produces the best (maximum or minimum) possible value of the objective function. An optimal solution is usually what we hope to find! A problem may have more than one optimal solution, where several management strategies satisfy the constraints and produce the same optimal value for the objective. A solution is unbounded if the optimal value of the objective function goes to positive or negative infinity without violating any of the constraints.

## PROBLEM FORMULATION WITH AQMAN

This section describes the general procedures required to utilize AQMAN, including manual changes to the MPS file. Detailed instructions for AQMAN input files are given in Appendix II.

### Objective Function

#### Linear objective

AQMAN is written to handle either a linear or a quadratic objective function. If the linear option is in effect, AQMAN assumes that the linear objective is to minimize or maximize total pumping:

$$\sum_{n=1}^N \sum_{i=1}^I C_{i,n} Q_{i,n} \quad (13)$$

where  $I$  = total number of managed wells,

$N$  = total number of management periods,

$Q_{i,n}$  = pumping rate at well  $i$  during period  $n$  [ $L^3/T$ ],

$C_{i,n}$  = cost coefficient for well  $i$  during period  $n$  [ $L^0$ ].

All cost coefficients are assumed to equal +1.0. These are automatically scaled by multiplying by the negative of the unit stress pumping or recharge rate. (See the sub-section below on "The Unit Stress and Scaling".) If no scaling is required and all unit stresses are either -1.0 (pumping) or +1.0 (recharge), cost coefficients will be +1.0 for pumping wells and -1.0 for recharge wells. These are written by AQMAN to the MPS file. Both pumping and recharge rates are non-negative by default in the MPS file.

If a linear objective other than (13) is desired, the user can make changes directly to the MPS file. For instance, say that the problem contains two decision wells, and management criteria specify that pumpage at the first well should be weighted twice as much as pumpage at the second well. Cost coefficients become weights, and the objective would be to optimize

$$\sum_{n=1}^N \left[ 2 Q_{1,n} + 1 Q_{2,n} \right] \quad (14)$$

The cost coefficient written by AQMAN to the MPS file for  $Q_1$  should be manually changed to twice its value for each management period  $n$ .

#### Quadratic objective

If the quadratic option is specified, AQMAN assumes that the objective is to minimize the present value of variable pumping costs. These are the costs associated with the energy required to operate pumps, and do not include capital (fixed) costs of well installation or pumping capacity. Variable pumping costs are a quadratic

function of pumping decisions. This is because costs vary with pumping rates and pumping lifts, and lifts depend on pumping rates:

$$P = \sum_{n=1}^N \sum_{i=1}^I C_{i,n} Z_{i,n} Q_{i,n} \quad (15)$$

where  $P$  = total variable pumping cost [\$],

$Z_{i,n}$  = total lift at well  $i$  during period  $n$  [L],

$C_{i,n}$  = unit cost of pumping per unit lift at well  $i$  during period  $n$  [ $\$/(\text{L}^3/\text{T})/\text{L}$ ].

The total lift is a function of pumping during period  $n$  and during all previous periods at all wells. It consists of two parts (Figure 2). One part,  $\bar{Z}$ , is the unmanaged lift, which is the distance from the land surface down to the transient potentiometric surface that would occur if there was no managed stress applied to the aquifer. The second part,  $\hat{Z}$ , is the managed lift, which is induced by pumping at all wells during the current period and during all previous periods. Both parts of  $Z$  are fully computed by AQMAN. That is,

$$Z_{i,n} = \bar{Z}_{i,n} + \hat{Z}_{i,n} \quad (16a)$$

and

$$\hat{Z}_{i,n} = \sum_{k=1}^n \sum_{j=1}^I r_{i,j,(n-k)} Q_{j,k} \quad (16b)$$

where  $r_{i,j,(n-k)}$  is the drawdown response at well  $i$  during period  $n$  induced by pumping a unit rate at well  $j$  during period  $k$ . If  $j$  is a recharge well, the response  $r$  will be negative.

Substitution of (16) into (15) gives

$$P = \sum_{n=1}^N \sum_{i=1}^I \left[ C_{i,n} \bar{Z}_{i,n} Q_{i,n} + \sum_{k=1}^n \sum_{j=1}^I C_{i,n} r_{i,j,(n-k)} Q_{j,k} Q_{i,n} \right] \quad (17)$$

$\uparrow$   
 cost due to  
 linear component

$\uparrow$   
 cost due to  
 quadratic component

The first set of terms is linear, while the second set is quadratic with respect to the decision variables  $Q$ .

When the user specifies that the objective is quadratic, AQMAN uses equation (17) as the function to be minimized. For the cost due to unmanaged lift, undiscounted unit cost coefficients  $C_{i,n}$  are read as input data and are scaled and discounted for each management period. The value of  $\bar{Z}_{i,n}$  during each period is computed, and the scaled product  $C_{i,n} \bar{Z}_{i,n}$  is written into the usual objective rows of the MPS file. For each management period, unit costs are discounted according to the

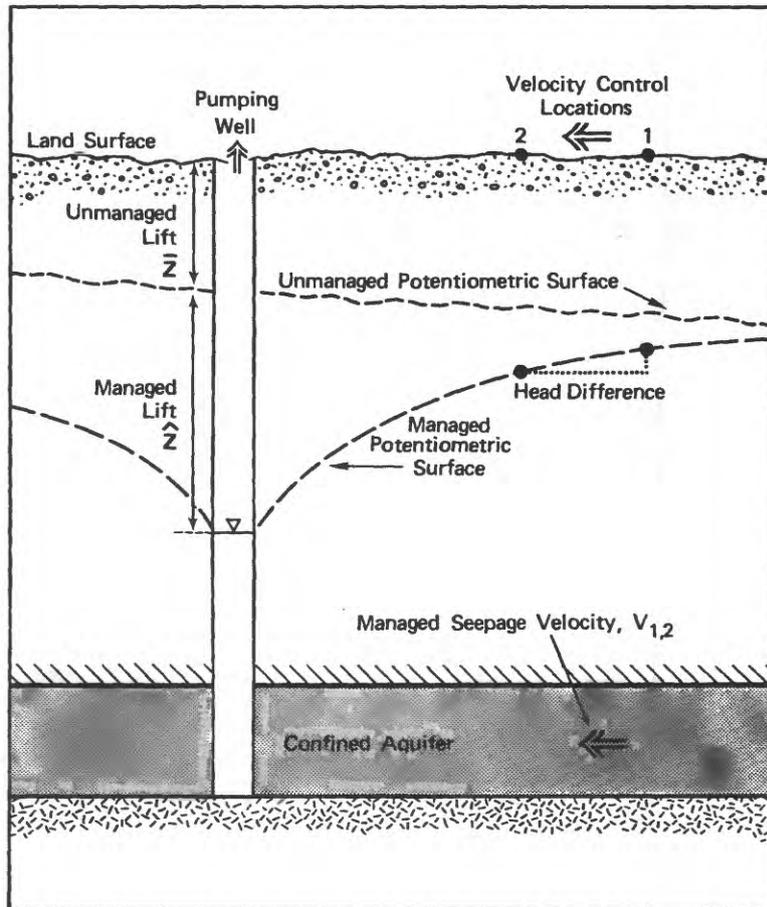


Figure 2. Lift, potentiometric surface, and seepage velocity induced by a pumping well.

number of whole months between the start of the planning horizon and the end of the period:

$$C_{i,n} = \frac{C'_{i,n}}{(1+r)^m} \quad (18)$$

where  $r$  = monthly discount rate [ $L^\circ$ ] = (annual discount rate/12.0),  
 $m$  = number of whole months between the start of the planning horizon and the end of period  $n$ .

Discounting adjusts future costs to the present, so that costs incurred at different times can be compared directly. Pumping costs are discounted monthly because the electricity required to operate pumps usually must be purchased on a monthly basis. Discounting is performed monthly regardless of the number of days in every management period, as specified by the user. Note that discounting monthly will decrease the present value of future costs slightly more than discounting annually. For instance, if the annual discount rate is 0.08, the first year of pumping cost will be discounted at an effective annual rate of 0.086988.

The quadratic portion of (17) is handled separately. The responses  $r_{i,j,(n-k)}$  are written to a new output file. When a quadratic programming code is employed, a special subroutine must be included that reads from this file, discounts unit cost coefficients, and computes the value of the objective function at each iteration of the optimization algorithm. Subroutine FUNOBJ, described in Appendix III, is supplied for this purpose.

### Constraint Set

#### Pumping and recharge constraints

Several types of constraints may be imposed directly on the decision variables. A bound constraint limits the value of an individual pumping or recharge decision. For instance,

$$Q_{4,1} \leq 3.0 \quad (19a)$$

$$Q_{2,2} \geq 1.2 \quad (19b)$$

$$Q_{3,1} = 0.74 \quad (19c)$$

This type of constraint must be manually entered into the MPS file (in the BOUNDS or COLUMNS section) by the user. See the section in this document that describes MPS format conventions.

Demand constraints and capacity constraints limit the sum of pumping or recharge. For instance, a minimum total demand may have to be met in period 3:

$$\sum_{i=1}^I Q_{i,3} \geq 10.5 \quad (20a)$$

There may be a limit on total pumping capacity during each period:

$$\sum_{i=1}^I Q_{i,n} \leq 22.1 \quad n = 1, \dots, N \quad (20b)$$

Balance constraints compare pumping flow rates with recharge flow rates. Perhaps a pumping and injection system must be designed so that the total recharge at wells k never exceeds total pumping at wells i:

$$\sum_{i=1}^I Q_{i,n} - \sum_{k=1}^K Q_{k,n} \geq 0.0 \quad n = 1, \dots, N \quad (21)$$

Where I and K are the total number of pumping and recharge wells, respectively.

For each demand, capacity, or balance constraint, the user must create a new row and enter its name into the ROWS section of the MPS file. (See the section below on "the MPS file" for a description of MPS format conventions.) In the COLUMNS section, a coefficient of +1.0 must be entered for each pumping decision that appears in these constraints. For balance constraints such as (21), recharge decisions are given a coefficient of -1.0. Values for the right-hand side of these constraints must be entered in the RHS section of the MPS file.

### Head constraints

Hydraulic constraints on aquifer heads, gradients, or velocities are more complicated, since these depend on complex hydrogeologic phenomena and require simulation to obtain the appropriate response coefficients. AQMAN does most of the work, calculating coefficients and transforming the user's constraints into MPS format.

Consider the following problem. Decisions are made during one management period at two pumping wells,  $Q_1$  and  $Q_2$ . Head H is constrained at three control locations, and only pumping is allowed:

$$H_1 \leq 70.0 \quad (22a)$$

$$H_2 \leq 90.0 \quad (22b)$$

$$H_3 \geq 50.0 \quad (22c)$$

$$Q_1, Q_2 \geq 0.0 \quad (22d)$$

The user provides AQMAN with the three control locations, the constraining values 70.0, 90.0, and 50.0 (feet), and the direction of the inequalities. As explained above, pumping constraints such as (22d) are entered directly into the MPS file. (Most optimization codes assume non-negativity for all decision variables unless stated otherwise in the MPS file.) AQMAN performs a series of calculations for the first three constraints:

(1) Compute the transient heads that would occur if there were no managed stresses on the system, that is  $Q_1=Q_2=0$ . These heads are shown in column 1 of Table 1.

CONTROL LOCATION	(1)	(2)	(3)	HEAD WITH UNIT STRESS APPLIED AT:		RESPONSE COEFFICIENT	
	UNMANAGED HEAD	USER'S CONSTRAINT ON HEAD	MANAGEABLE DRAWDOWN [(1) - (2)]	Well 1	Well 2	Well 1	Well 2
				(4a)	(4b)	[(1) - (4a)]	[(1) - (4b)]
1	80	$\leq 70$	+10	78	76	2	4
2	82	$\leq 90$	-8	79	75	3	7
3	75	$\geq 50$	+25	69	73	6	2

**Table 1. Sample computations of manageable drawdown, and response coefficients. The last two columns form the response matrix.**

- (2) Subtract the user's constraints from unmanaged heads to obtain manageable drawdowns. See column 3 of Table 1.
- (3) Compute the heads that occur in response to a unit rate of pumping at each well. In this example, the unit rate is 1.0 ft<sup>3</sup>/sec. Example values of computed heads are shown in Table 1, columns 4a and 4b.
- (4) Subtract these heads from unmanaged heads to obtain the drawdown responses. In this example, a unit rate of pumping at well 1 causes drawdowns of 2.0, 3.0, and 6.0 feet, while the same rate at well 2 induces drawdowns of 4.0, 7.0, and 2.0. These values appear in the last two columns of Table 1, and form the response matrix.

AQMAN transforms the first three constraints to:

$$2 Q_1 + 4 Q_2 \geq +10.0 \quad (23a)$$

$$3 Q_1 + 7 Q_2 \geq -8.0 \quad (23b)$$

$$6 Q_1 + 2 Q_2 \leq +25.0 \quad (23c)$$

The constraint on head at each control location is now expressed implicitly as a linear function of the pumping decisions. The non-negativity constraint will be assumed by the linear programming code:

$$Q_1 , Q_2 \geq 0.0 \quad (23d)$$

The MPS file shown in Figure 3a is written by AQMAN. Note that response coefficients appear in the COLUMNS section and manageable drawdowns appear in the RHS section.

### Gradient and velocity constraints

Another type of hydraulic constraint limits the gradient or the seepage velocity between two control locations. Using the above example, the user defines control pair 1 as control locations 1 and 2, and restricts seepage velocity  $V$  from location 2 to location 1 to be greater than or equal to 0.01 ft/sec (Figure 2).

$$V_1 \geq 0.01 \quad (24)$$

Velocity is related to the difference in head.

$$V_1 = \frac{K (H_1 - H_2)}{\epsilon L} \quad (25a)$$

For the sake of simplicity of presentation, assume that the hydraulic conductivity  $K$  and effective porosity  $\epsilon$  do not vary between the two locations. Head at each location is equal to the difference between unmanaged head  $H$  and drawdown  $s$ :

```

NAME          EXAMPLE
ROWS
G DR010001
G DR010002
L DR010003
N OBJ
COLUMNS
QP1001      OBJ          1.0
QP1001      DR010001     0.20000E+01   DR010002     0.30000E+01
QP1001      DR010003     0.60000E+01
QP1002      OBJ          1.0
QP1002      DR010001     0.40000E+01   DR010002     0.70000E+01
QP1002      DR010003     0.20000E+01
RHS
RHS         DR010001     0.10000E+02   DR010002    -0.80000E+01
RHS         DR010003     0.25000E+02
ENDATA

```

Figure 3a. MPS file written by AQMAN for the data shown in Table 1. There are three control locations, two decision wells, and one management period.

NAME	EXAMPLE				
ROWS					
E	DR010001				
G	DR010002				
L	DR010003				
N	OBJ				
COLUMNS					
QP1001	OBJ	1.0			
QP1001	DR010001	0.20000E+01	DR010002	0.30000E+01	
QP1001	DR010003	0.60000E+01			
QP1002	OBJ	1.0			
QP1002	DR010001	0.40000E+01	DR010002	0.70000E+01	
QP1002	DR010003	0.20000E+01			
H010001	DR010001	0.10000E+01			
RHS					
RHS	DR010001	0.80000E+02	DR010002	-0.80000E+01	
RHS	DR010003	0.25000E+02			
ENDATA					

Figure 3b. Head definition is substituted at control location 1.

```

NAME          EXAMPLE
ROWS
E DR010001
G DR010002
L DR010003
L H010001
N OBJ
COLUMNS
  QP1001      OBJ          1.0
  QP1001      DR010001    0.20000E+01  DR010002    0.30000E+01
  QP1001      DR010003    0.60000E+01
  QP1002      OBJ          1.0
  QP1002      DR010001    0.40000E+01  DR010002    0.70000E+01
  QP1002      DR010003    0.20000E+01
  H010001     DR010001    0.10000E+01
  H010001     H010001    0.10000E+01
RHS
  RHS         DR010001    0.80000E+02  DR010002   -0.80000E+01
  RHS         DR010003    0.25000E+02
  RHS         H010001    0.700000E+02
ENDATA

```

Figure 3c. Head constraint at location 1 is manually inserted.

$$H_1 = \bar{H}_1 - s_1 \quad (25b)$$

$$H_2 = \bar{H}_2 - s_2 \quad (25c)$$

Substitution of (25) into (24a) gives

$$s_1 - s_2 \leq \bar{H}_1 - \bar{H}_2 - 0.01 (\epsilon L/K) \quad (24b)$$

The user supplies three types of input data to AQMAN:

- (1) the location of the velocity-control pair,
- (2) the minimum (in other problems, maximum) velocity, e.g., 0.01 ft/sec,
- (3) the factor ( $\epsilon L/K$ ) that converts the minimum seepage velocity to a difference in head. For this example, we assume ( $\epsilon L/K$ ) equals 90.0 seconds.

AQMAN does the rest. Using the response information from Table 2 and the unmanaged heads from Table 1, the constraint (24b) is transformed for the optimization procedure:

$$\begin{array}{cccccc} s_1 & & s_2 & & \bar{H}_1 & \bar{H}_2 & (\epsilon L/K) \\ \downarrow & & \downarrow & & \downarrow & \downarrow & \downarrow \\ (2 Q_1 + 4 Q_2) - (3 Q_1 + 7 Q_2) & \leq & 80.0 & - & 82.0 & - & (0.01) (90.0) \end{array} \quad (24c)$$

$$- Q_1 - 3 Q_2 \leq -2.9 \quad (24d)$$

With the addition of the velocity constraint, AQMAN writes the expanded MPS file shown in Figure 4a to include inequality (24d).

Note that if the user wishes to control the hydraulic gradient rather than the velocity, the distance  $L$  should be substituted for the factor ( $\epsilon L/K$ ).

A ground-water management problem may involve a plume of contamination. If hydrodynamic dispersion is negligible and linear sorption can be assumed, movement of a contaminant front will be retarded relative to the bulk fluid flow (Freeze and Cherry, 1979). Under these conditions, AQMAN can be used to prescribe pumping and recharge rates that would control movement of the plume (Lefkoff and Gorelick, 1986). The user should incorporate a retardation factor  $R$  into the factor ( $\epsilon L/K$ ) that converts seepage velocity to a difference in head. The retarded seepage velocity would then be controlled. In the above example, equation (24b) would become

$$s_1 - s_2 \leq H_1 - H_2 - 0.01 \frac{\epsilon LR}{K} \quad (26)$$

where  $R$  = retardation factor [ $L^0$ ].

### Head and velocity definitions

A head definition can be used to obtain additional management information in the final solution. Again referring to the above example, the user now wishes to know the optimal head at location 1. The variable KDEFHD is set equal to 1, and

```

NAME          EXAMPLE
ROWS
L DIF01001
G DR010001
G DR010002
L DR010003
N OBJ
COLUMNS
QP1001      OBJ          1.0
QP1001      DIF01001     -0.10000E+01
QP1001      DR010001     0.20000E+01      DR010002      0.30000E+01
QP1001      DR010003     0.60000E+01
QP1002      OBJ          1.0
QP1002      DIF01001     -0.30000E+01
QP1002      DR010001     0.40000E+01      DR010002      0.70000E+01
QP1002      DR010003     0.20000E+01
RHS
RHS          DIF01001     -0.29000E+01
RHS          DR010001     0.10000E+02      DR010002     -0.80000E+01
RHS          DR010003     0.25000E+02
ENDATA

```

Figure 4a. MPS file written by AQMAN for the data shown in Table 1 with velocity control added at control pair 1.

NAME	EXAMPLE				
ROWS					
E	DIF01001				
E	DIF01002				
G	DR010001				
G	DR010002				
L	DR010003				
N	OBJ				
COLUMNS					
QP1001	OBJ	1.0			
QP1001	DIF01001	-0.10000E+01	DIF01002	0.30000E+01	
QP1001	DR010001	0.20000E+01	DR010002	0.30000E+01	
QP1001	DR010003	0.60000E+01			
QP1002	OBJ	1.0			
QP1002	DIF01001	-0.30000E+01	DIF01002	-0.50000E+01	
QP1002	DR010001	0.40000E+01	DR010002	0.70000E+01	
QP1002	DR010003	0.20000E+01			
G01001	DIF01001	0.10000E+01			
G01002	DIF01002	0.10000E+01			
RHS					
RHS	DIF01001	-0.20000E+01	DIF01001	-0.70000E+01	
RHS	DR010001	0.10000E+02	DR010002	-0.80000E+01	
RHS	DR010003	0.25000E+02			
ENDATA					

Figure 4b. Head definition is specified at velocity control pair 1 and 2.

```

NAME          EXAMPLE
ROWS
E  DIF01001
E  DIF01002
G  DR010001
G  DR010002
L  DR010003
G  G01001
G  G01002
N  OBJ
COLUMNS
QP1001      OBJ          1.0
QP1001      DIF01001    -0.10000E+01    DIF01002    0.30000E+01
QP1001      DR010001     0.20000E+01    DR010002     0.30000E+01
QP1001      DR010003     0.60000E+01
QP1002      OBJ          1.0
QP1002      DIF01001    -0.30000E+01    DIF01002    -0.50000E+01
QP1002      DR010001     0.40000E+01    DR010002     0.70000E+01
QP1002      DR010003     0.20000E+01
G01001      DIF01001     0.10000E+01    G01001       0.10000E+01
G01001      G01002         0.57700E+00
G01002      DIF01002     0.10000E+01    G01002      -0.10000E+01
RHS
RHS         DIF01001    -0.20000E+01    DIF01001    -0.70000E+01
RHS         DR010001     0.10000E+02    DR010002    -0.80000E+01
RHS         DR010003     0.25000E+02
RHS         G01001       0.90000E+00    G01002       0.00000E+00
ENDATA

```

Figure 4c. Velocity constraint at control pair 1 is manually inserted.

AQMAN will substitute

$$2Q_1 + 4Q_2 + H_1 = 80.0 \quad (27)$$

for inequality (23a). The right side of this equation is the unmanaged head shown in column 1 of Table 1. AQMAN now writes the MPS file shown in Figure 3b rather than 3a. A value of  $H_1$  will now appear in the management solution. In order to include the original constraint (22a), the user manually adds a row, a column entry, and a right-hand side into the MPS file. This is shown in Figure 3c. (See the section below on MPS formats.)

A velocity definition can be used to control the difference between two velocities. For example, the user defines control pair 2 as control locations 2 and 3, and restricts the vector sum of seepage velocities  $V_1$  and  $V_2$  to remain within  $30^\circ$  of the direction of  $V_1$  (Figure 5). That is

$$\tan 30^\circ \geq \frac{V_2}{V_1} \quad (28a)$$

$$0.577 V_1 - V_2 \geq 0 \quad (28b)$$

The user now supplies as input data to AQMAN only the locations of the two velocities control pairs, with KDEFGFR set equal to 1. The following equations replace (24b):

$$s_1 - s_2 + V_1 = \bar{H}_1 - \bar{H}_2 \quad (29a)$$

$$s_3 - s_2 + V_2 = \bar{H}_3 - \bar{H}_2 \quad (29b)$$

AQMAN now writes the MPS file shown in Figure 4b rather than 4a. In order to include the original constraint (24a) and the new constraint (28b), the user manually adds two rows, three column entries, and two right-hand sides into the MPS file. This is shown in Figure 4c.

### Nonlinearities

AQMAN uses the Trescott code to solve the ground-water flow equation (1), which contains a linear relation between heads and well pumpages. The user may introduce some nonlinearities into the simulated system by specifying unconfined conditions or head-dependent leakage or evapotranspiration (Trescott and others, 1976, pp. 2-8). In these cases, AQMAN will write a warning message, but otherwise will operate normally, as if the system behaved linearly. The user must judge whether the consequent error in the linear programming solution is acceptable. For instance, if an unconfined aquifer is thick and highly conductive, transmissivity will not be a strong function of head, and linear treatment of the system may provide an acceptable management solution.

### Time Parameters

The user must also select appropriate time parameters for the problem. Pumping periods in the Trescott code are synonymous with management periods in AQMAN, so

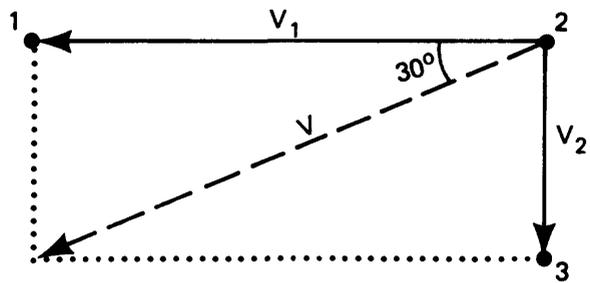


Figure 5. The vector sum  $V$  of velocity controls 1 and 2.

that management decisions are made for each pumping period specified. Hydraulic responses to applied stresses are written to the MPS file for the time corresponding to the end of each period. The response matrix formulation that AQMAN uses requires that **all pumping periods have the same length**. This assures that the time difference between implementation and effect of a decision is independent of pumping period. For instance, a decision for period 4 will cause an additional drawdown during period 6. The same decision in period 1 will cause the same additional drawdown during period 3. Transient responses are added over time. This fully utilizes the computational advantages of linear programming with response matrices.

For transient simulations, finite-difference computations are performed by time step within each pumping period. This is the numerical time step used in the finite-difference approximation, and should not be confused with the length of pumping periods. The numerical time step may have a variable length. Short time steps should be used while heads are rapidly recovering from the unit stress applied during the first period. Longer time steps may be used for later pumping periods in order to save computer time. The length of the initial time step within each period is read as the variable TIMINC. Subsequent time steps within a period are increased by a multiplying factor, CDELT. Time steps are automatically adjusted so that the end of each pumping period corresponds to the end of a time step.

### The Unit Stress and Scaling

The value of the unit stress is read by AQMAN as the variable UNITQ. Its sign indicates whether the stress is a (-) sink (pumping) or a (+) source (recharge). AQMAN input follows the convention used in the Trescott code: negative for pumping, positive for recharge. AQMAN converts signs so that pumping and recharge rates are positive in the MPS file.

Many optimization codes automatically constrain decision variables to non-negative values. This is useful if each well is restricted to either pumping or recharge. In the input files for AQMAN, the user should specify a uniform positive unit stress at recharge wells and an equal negative stress at pumping wells. The management solution obtained with the optimization code will contain positive rates for both recharge and pumping.

Rather than place a restriction on the decision wells, the user may want to let the optimization code determine whether each well should pump or recharge. To accomplish this, assign a positive unit stress for all wells in AQMAN. Before executing the optimization code, override the automatic non-negativity constraints. (This is usually done in a specification file that gives general instructions to the optimization code.) The management solution will contain negative values that represent pumping rates, and positive values that indicate recharge rates.

Usually, all unit stresses are equal. A uniform, convenient unit stress, such as 1.0 ft<sup>3</sup>/s, simplifies interpretation of the optimization results. However, in some cases this may cause a scaling problem, where the range in magnitude of the response coefficients is large. If the coefficients vary over several orders of magnitude, the optimization code may not be able to compute an optimal solution. If this occurs, the user will have to scale the formulation by specifying a different unit stress (UNITQ in the AQMAN input file) at certain decision wells. After re-executing AQMAN, the objective function coefficients in the new MPS file will be

automatically adjusted to consistent units. Finally, the management solution computed by the optimization code must be scaled back to the original units.

For example, consider a problem containing two decision wells. The objective is to minimize the sum of the pumping rates. AQMAN is used with a uniform unit stress of  $-1.0 \text{ ft}^3/\text{s}$  to create an MPS file. The file is used by a linear programming package, which reports an error message that relates to poor scaling. Examination of the MPS file reveals that well A has a very large effect on drawdowns, while well B has a very small effect. AQMAN is used to create a new MPS file, this time applying a unit stress of  $-0.001 \text{ ft}^3/\text{s}$  at well A and  $-1.0 \text{ ft}^3/\text{s}$  at well B. This means that every unit of pumping at well A represents only 1/1000 of each unit at well B. After re-executing AQMAN, the coefficient for well A in the objective row of the new MPS file will be changed to 0.001, while the coefficient for B will be left at 1.0. Say that the optimal solution to the scaled problem specifies pumping rates of 240 units at well A and 3.4 units at well B. This translates to  $0.24 \text{ ft}^3/\text{s}$  and  $3.4 \text{ ft}^3/\text{s}$ , respectively.

### Quadratic Objective

If the objective function is the minimization of variable pumping costs, set the variable CASE equal to 'QUAD' in the AQMAN input file. Another output file, the quadratic response file, will be created. This file will be used by a subroutine in the quadratic programming package that evaluates the value and gradient of the quadratic objective for a given set of decisions. This subroutine must be supplied by the user. Two suggested versions, named Subroutine FUNOBJ, can be found in Appendix III.

A quadratic objective function will have both linear and quadratic terms, as in (17). Coefficients for the linear terms are written by AQMAN into the objective row of the MPS file. During execution with the optimization package, coefficients for the quadratic terms will be computed by FUNOBJ using input data read from the quadratic response file and from an additional input file. This additional file is constructed by the user, and contains information on well locations, unit pumping costs, and the discount rate. Instructions for preparing this file appear in Appendix III. Appendix III also describes how to specify pumping wells for AQMAN when the objective is quadratic.

### The MPS File

#### User changes

Before using an optimization package, the user may want to make changes in the MPS file written by AQMAN. The most common changes will involve the addition of pumping and recharge constraints or changes in linear objective function coefficients. Examples are presented in (14), (19), and (20). Before editing the MPS file, the user should be familiar with MPS formats and the naming conventions used by AQMAN.

#### MPS format conventions

This section presents a basic description of the MPS format. More complete discussions can be found elsewhere (IBM Document No. H20-0476-2; Murtagh and Saunders, 1983).

Figure 6 shows the organization of the MPS file. The first line of the file must say "NAME" and the last line must say "ENDATA". The rest of the file is organized into sections. Each section is introduced by a line that contains one of the following words, starting in the first column: "ROWS", "COLUMNS", "RHS", "RANGES", "BOUNDS". The sections consist of data lines that either identify constraints or specify the numerical values that appear in the management problem. AQMAN writes all lines that are not optional.

The ROWS section names and defines the type of each constraint and names the objective function. Each line contains:

- (1) A row name, in columns 5 through 12. The row names identify each constraint and the objective.
- (2) A key to indicate the type of the row, in either column 2 or 3. There are four types of rows:

<u>key</u>	<u>row type</u>
G	greater than or equal to, $\geq$
L	less than or equal to, $\leq$
E	equality, =
N	unconstrained. (used for objective)

The key N is required for the objective row. It is also useful for providing head and velocity information at uncontrolled locations.

The COLUMNS section names the decision variables, and specifies the response coefficients and cost coefficients. Each coefficient links a decision variable (column) to either a constraint (row) or to the objective (row). Each line contains:

- (1) A column name, in columns 5 through 12. The column names are the decision variables.
- (2) A numerical response coefficient, in columns 25 through 36. The name of the row in which the coefficient appears for the decision variable named on this line is entered in columns 15 through 22.
- (3) Optionally, another response coefficient and row name, respectively in columns 50 through 61 and columns 40 through 47. AQMAN uses this option in order to minimize the length of the file.

The RHS section specifies the values for the right-hand side of each constraint row. Each line contains:

- (1) A right-hand side data set name, in columns 5 through 12. Usually, there is only one set of right-hand sides, in which case this name would be the same for all lines.
- (2) The numerical value of a right-hand side, in columns 25 through 36, and the

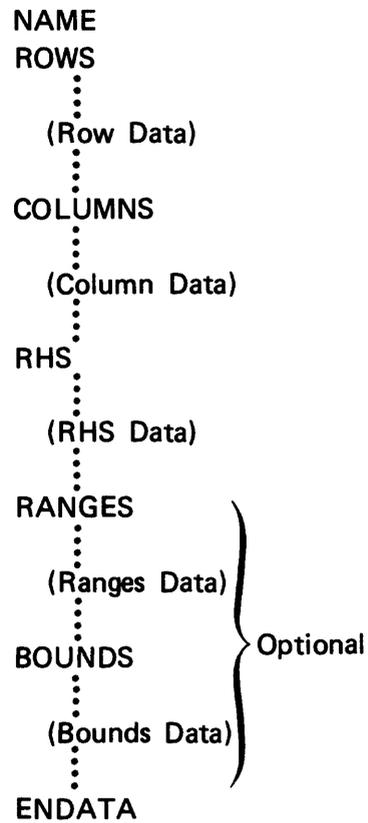


Figure 6. Organization of the MPS file.

name of its corresponding row, in columns 15 through 22.

- (3) Optionally, the numerical value of another right-hand side and its corresponding row, respectively in columns 50 through 61 and columns 40 through 47. AQMAN uses this option in order to minimize the length of the file.

The RANGES section can be used during sensitivity analysis to allow the right-hand side of a constraint to range between upper and lower limits. This section is not required by most optimization packages, and is not written by AQMAN. If ranges for the constraints are desired, the user must manually enter the entire section.

A range for a constraint is defined by its RANGE value  $r$ , its RHS value  $c$ , and its row type. The sign of  $r$  should be positive. There are two possibilities:

Row type	Upper limit	Lower limit
G	$c + r$	$c$
L	$c$	$c - r$

Each line in the RANGES section contains:

- (1) The range data set name, in columns 5 through 12. Usually, there is only one set of ranges, in which case this name would be the same for all lines.
- (2) The numerical value of a range, in columns 25 through 36, and the name of the row in which it appears, in columns 15 through 22.
- (3) Optionally, the numerical value of another range and its corresponding row, respectively in columns 50 through 61 and columns 40 through 47.

The BOUNDS section is used to specify upper and/or lower limits directly on the value of individual decision variables. This section is not required by most optimization packages, and is not written by AQMAN. If bounds on the decision variables are desired, the user must manually enter the entire section. (Many optimization packages automatically restrict decision variables to non-negative values.)

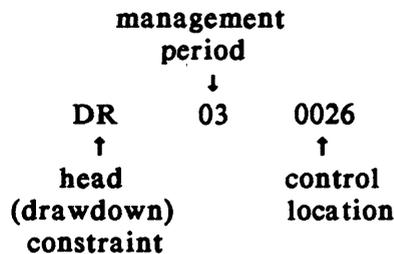
Each line in the BOUNDS section contains: (1) The type of bound, in columns 2 through 3. Six types of bounds are possible:

<u>bound type</u>	<u>explanation</u>
LO	lower bound
UP	upper bound
FX	fixed value
FR	free (-infinity to +infinity)
MI	lower bound = -infinity
PL	upper bound = +infinity

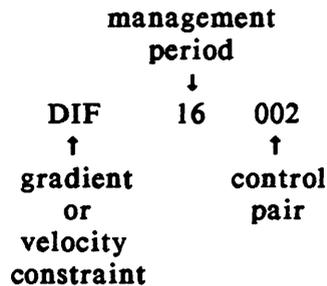
- (2) The BOUNDS data set name, in columns 5 through 12. Usually, there is only one set of bounds, in which case this name would be the same for all lines.
- (3) The numerical value of a bound, in columns 25 through 36, and the name of the decision variable (COLUMN name) to which it applies, in columns 15 through 22.

Naming conventions

There are three different types of rows named by AQMAN. The row for the objective function is simply named "OBJ". Row names that correspond to constraints on head begin with the letters "DR", followed by a 6-digit number. The last four digits identify the control location, and the first two digits refer to the management period. For example, DR030026 indicates:

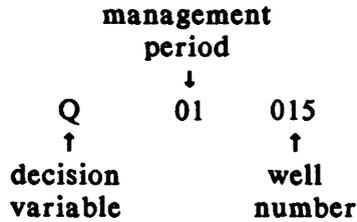


Row names for constraints on a gradient or a velocity begin with the letters "DIF", followed by a 5-digit number. The last three digits identify the control pair, and the first two digits identify the management period. For example, DIF16002 indicates:



Appendix IV shows a sample MPS file written by AQMAN using these names. Note that these naming conventions for the rows restrict the number of control locations to less than 10,000, the number of control pairs to less than 1000, and the number of management periods to less than 100.

Column names begin with the letter "Q", followed by a 5-digit number. The last three digits identify the decision well, and the first two digits denote the management period. For example,



The naming convention for columns restricts the number of decision wells to less than 1000, and the number of management periods to less than 100.

Column names for head definitions are identical to the corresponding row name, except that "DR" is replaced by "H" and "DIF" is replaced by "G". For example, if head definition is specified for location 119 during period 2, the row name would be DR020119 and the column name would be H020119.

Size of the MPS file

The MPS file written by AQMAN may be quite large. The approximate number of lines in the file is given by:

$$7 + MN + M'N + D'N + I \left[ N + \frac{M'N(N+1)}{2} \right] \tag{25}$$

where I = number of decision wells,

N = number of management periods,

M = number of control locations plus control pairs,

M' = M/2, rounded up to the nearest whole number,

D = number of head, gradient, and velocity definitions,

D' = D/2, rounded up to the nearest whole number.

The first term accounts for the seven required identification lines. The second, third, and fourth terms are the number of lines in the ROWS section, the RHS section, and the COLUMNS section, respectively.

For example, say that AQMAN is given a problem that contains 12 decision wells, 20 locations where head is controlled, 41 control pairs where velocity is controlled, and 4 management periods. The MPS file will contain approximately the following number of lines:

$$7 + (61)(4) + (31)(4) + (12) [4 + (31)(4)(5)/2] = 4143$$

## PROGRAM DESCRIPTION

AQMAN consists of several subroutines combined with a modified version of the U.S. Geological Survey's two-dimensional, finite-difference aquifer model (Trescott and others, 1976). AQMAN uses the Trescott code as a subroutine (named TRES) to obtain hydraulic responses to management alternatives. The Trescott code has been modified for compatibility with the AQMAN subroutines. AQMAN subroutines read and write data, perform simple calculations, and make repeated calls of Subroutine TRES to obtain results of aquifer simulation. The functions performed by each subroutine are described below. Program variables appear in capital letters and are defined in Appendix I.

### Main

The main program makes several calls of Subroutine PRE, and performs simple calculations after each call. This is shown in Figure 7. Subroutine PRE is called once to read input files and to calculate transient, unmanaged heads, given initial and boundary conditions and any pre-determined pumping or recharge at unmanaged wells. Input data are checked for consistency, and unmanaged (unstressed) heads are stored in the HDUS vector and are written to unit 17. The user's desired limit on head, CONHD, at each control location is read from unit 14. These values are subtracted from the unstressed heads to obtain a vector of manageable drawdowns, MNGDRD, which will be written in the RHS section of MPS file.

If the objective function is quadratic, Subroutine QUAD is called to compute the cost coefficients for the linear part of the objective. If there are any gradients or velocities to be controlled, Subroutine GRADS is called to identify locations and to compute values for constraints on these controls.

Next, four tasks are performed for each managed well. First, Subroutine PRE is called to obtain hydraulic responses at all control locations to a unit stress applied at the well. Second, the head responses are converted to drawdown responses, DRDRES, by subtracting from unmanaged head at each control location. Third, if there are gradients or velocities to be managed, Subroutine GRADS is called to compute RDIF, which is the difference in drawdown response within a control pair. Fourth, Subroutine MPSFMT is called to write the response coefficients that correspond to this managed well into the COLUMNS section of the MPS file, unit 18. During the initial call of MPSFMT, the ROWS section of the MPS file is written.

Subroutine MPSFMT is called a final time to write the RHS section of the MPS file. Program execution then terminates.

### Subroutine PRE

PRE controls simulations by calling the Trescott code as Subroutine TRES. Before each call, PRE assigns values to the vector of pumpages (variable QWELL), which is passed to TRES through the "AQMAN1" common block. PRE also initializes the pumping period counter (variable KPER) to 1. In addition, during the first call of PRE, data describing the management problem are read from unit 14. These include information on the type of problem and objective, the managed wells, the control locations, and time parameters.

After control returns to PRE from Subroutine TRES, the head vector (variable

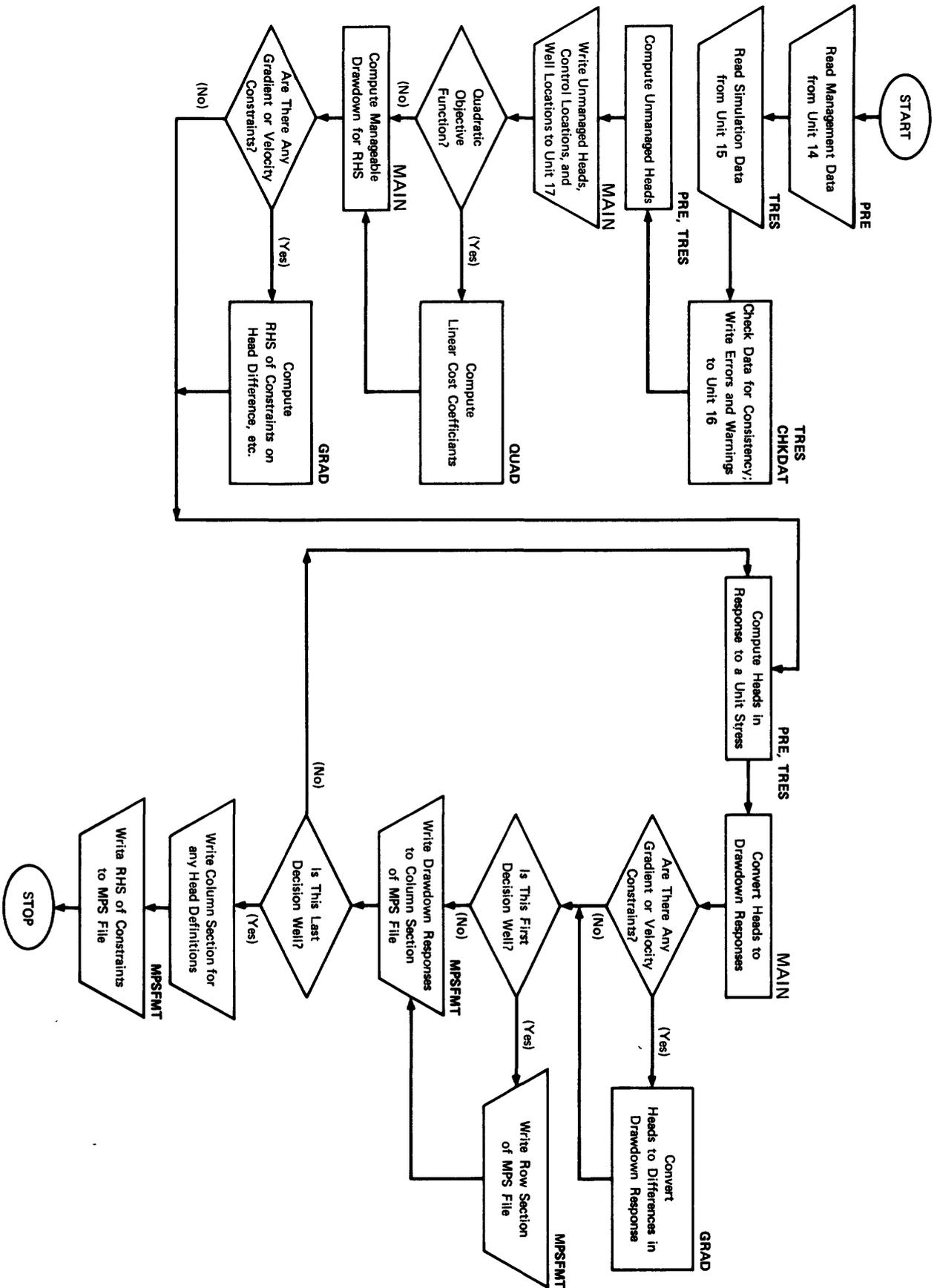


Figure 7. Flow chart showing major computations performed by AQMAN.

HD) is equated to the XHEAD vector. XHEAD contains solved heads at all control locations, and is stored by Subroutine WRITE1 in the "AQMAN1" common block after all Trescott computations. The HD vector is a subroutine argument that passes the computed heads to the Main program.

### Subroutine CHKDAT

This subroutine checks input data for internal consistency. First, all control locations where KEYWL is not equal to zero are checked. The number of non-zero KEYWLs must equal NW, which is read from the usual Trescott data set on unit 15. NW is the number of well locations where head at the well, rather than average head for the finite-difference cell, is desired. Two conditions must hold for each location where KEYWL is not zero: (1) a well must exist (as specified by ILOCW and JLOCW) at that control location, and (2) the radius of the well (XRAD) must be positive, so that hydraulic head at the well radius will be computed correctly. If an error in the input data is found here, CHKDAT writes an error message to unit 16 and stops program execution.

CHKDAT also checks for nonlinearities introduced by unconfined conditions, evapotranspiration, or leakage. If any exist, a warning message is written to unit 16.

### Subroutine GRADS

This subroutine is called if gradients or velocities are to be controlled. It reads information from unit 13 on each gradient or velocity control pair. These data are checked for consistency with input from unit 14. The locations specified as control pairs in unit 13 must also have been identified as "primary" control locations in unit 14. If not, GRADS writes an error message to unit 16 and stops execution.

GRADS computes the manageable drawdown for each control pair. This is the difference between the unstressed heads at the two control points, minus the product of GFACT and GCON. GCON is the user's desired limit on gradient or velocity, and GFACT is the factor that converts a gradient or a velocity into a head difference. (See equations 11, 12, and 24.) The difference in drawdown response (RDIF) between the two points of each control pair is also computed.

### Subroutine MPSFMT

This subroutine writes all output in MPS format to the MPS file, unit 18. A row name for each constraint during every management period is written into the ROWS section. For each managed well, drawdown responses at control locations are converted to MPS input format, and are written in the COLUMNS section of the MPS file. For each constraint, the right-hand side values are written into the RHS section in MPS format. If the problem has a quadratic objective function, MPSFMT writes to unit 19 the drawdown responses at all pumping managed wells. These are identified as control locations at which KEYWL=1 and KEYGRD=1. Unit 19 is read by the optimization code in order to compute the value and gradient of the quadratic objective function for a given set of decisions (see Appendix III).

### Subroutine QUAD

This subroutine is called only if the objective function is quadratic, indicated when the input variable CASE equals "QUAD". It reads from unit 13 the land

surface elevation at each managed well, the annual discount rate, and the undiscounted unit pumping costs for each managed well during each period. For each management period, unit costs are discounted according to equation (18).

At each managed pumping well, QUAD computes pumping lifts under unstressed conditions. These are multiplied by the discounted unit pumping cost to obtain the cost coefficient for the linear part of the quadratic objective function. This will be written in the OBJ rows of the COLUMNS section in the MPS file by Subroutine MPSFMT. No cost coefficients are computed for recharge wells or for unmanaged wells.

#### Subroutine READ1

At the start of each management (pumping) period, this subroutine retrieves input data stored in common blocks and prepares them for transfer to Subroutine TRES. These data include information on the management period, well locations, well radii, and well pumpages.

#### Subroutine WRITE1

At the end of each management period, this subroutine enters the computed head at every control location into a vector XHEAD, which is then stored in the "AQMAN1" common block. Each of these heads is an average value for a cell in the finite-difference grid.

If pumping or recharge occurs in the cell, head at the well may be significantly different than the average cell value. The Trescott code uses the Thiem equation to compute head at the well radius (Trescott and others, 1976, pp.8-10). Subroutine WRITE1 tests each element of the XHEAD vector for whether the variable KEYWL equals zero. If not, head at the well radius is indicated, and this head is entered into XHEAD, replacing the average head previously stored. This does not affect future finite-difference calculations, as the average head in every cell is used at the start of the next management period.

## Data Files

The purpose of each input and output file used by AQMAN is summarized below.

<u>File Unit Number</u>	<u>Type</u>	<u>Description</u>
13	Input	Management data for gradient/velocity controls and quadratic objective.
14	Input	Management data for all wells, control locations, and time periods.
15	Input	Hydrogeologic data for aquifer simulation (The usual Trescott data set).
16	Output	Error and warning messages.
17	Output	Unmanaged heads, user-defined limit stresses.
18	Output	The MPS file.

## SAMPLE PROBLEM

In this section a simple example of the use of AQMAN is presented. The hypothetical aquifer to be managed is shown in Figure 8, and is similar to the sample problem of Trescott and others (1976). Modifications include the addition of a third pumping well and the relocation of the four recharge wells. The aquifer is confined, and the constant head boundary occurs at an undersea outcrop offshore.

Suppose that the following management criteria are specified. The objective is to maximize net water supply during two one-month management periods from the two wells located at cells (4,11) and (6,6). The third pumping well, located at cell (3,7), must pump at a fixed rate of 0.005 ft<sup>3</sup>/s and 0.10 ft<sup>3</sup>/s during the first and second months, respectively. At least a 1.0 percent southward gradient is to be maintained in order to prevent intrusion of salt water from the sea. Heads in the stippled area to the northeast must remain above 80.0 feet. Pumping at cell (6,6) must not pull head below the top of the aquifer, which has an elevation of 50.0 feet. The recharge wells must not raise heads above the height of the land surface, 250.0 feet. Finally, all recharge water must be supplied by the pumping wells, so total recharge can never exceed total pumpage.

The first step in formulating this problem mathematically is to identify the decision variables. These are pumping or recharge at six wells during two management periods. Denote these as  $Q_{i,n}$ , where  $i$  is the well index and  $n$  is the period index. Let  $i$  equal 1 to 6 for cells (4,11), (6,6), (7,8), (7,9), (7,10), and (7,11). Let  $n$  equal 1 to 2 for the first and second month. Restrict all decision variables to non-negative values; wells 1 and 2 can only pump, and wells 3 through 6 can only recharge.

The next step is to identify locations where head must be controlled. Denote head values as  $H_{k,n}$ , where  $k$  is the location index. To maintain southward gradients along the coast, heads must be controlled at four pairs of cells along the coast, as shown in Figure 8. In addition to these eight locations, head is controlled in the stippled area, at well 2, and at all four recharge wells. Let  $k$  equal 1 to 17 for cells (3,11), (3,12), (4,11), (4,12), (6,6), (7,8), (7,9), (7,10), (7,11), (8,8), (8,9), (8,10), (8,11), (9,8), (9,9), (9,10), and (9,11). Let  $L$  denote the distance (28.5 feet) between nodes in row 8 and nodes in row 9.

The user's linear programming formulation can now be stated:

$$\begin{aligned} \text{Maximize } & Q_{1,1} + Q_{1,2} + Q_{2,1} + Q_{2,2} - Q_{3,1} - Q_{3,2} - Q_{4,1} \\ & - Q_{4,2} - Q_{5,1} - Q_{5,2} - Q_{6,1} - Q_{6,2} \end{aligned} \quad (31)$$

Subject to the constraints:

$$H_{1,n} \geq 80.0 \quad (32)$$

$$H_{2,n} \geq 80.0 \quad (33)$$

$$H_{3,n} \geq 80.0 \quad (34)$$

$$H_{4,n} \geq 80.0 \quad (35)$$

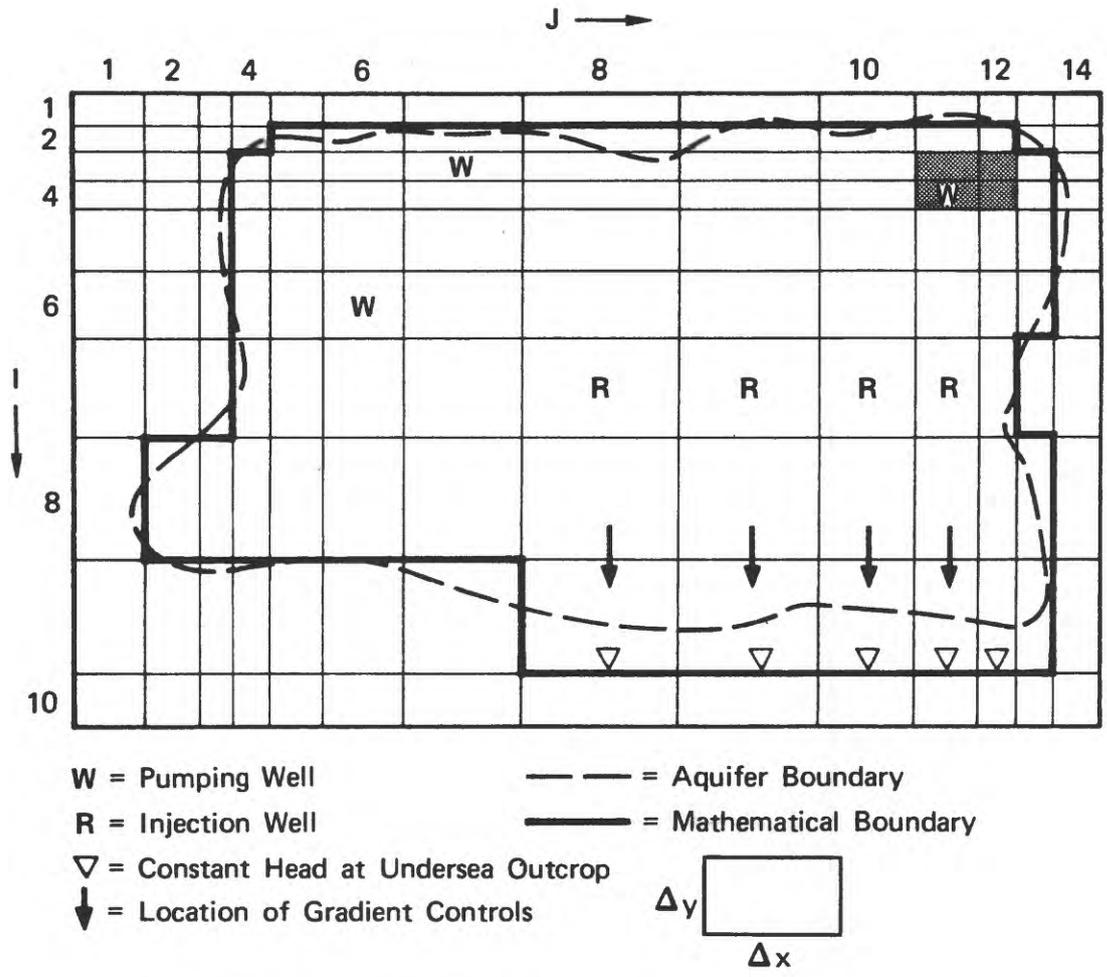


Figure 8. Finite-difference grid for the sample problem (after Trescott and others, 1976).

$$H_{5,n} \geq 50.0 \quad (36)$$

$$H_{6,n} \leq 250.0 \quad (37)$$

$$H_{7,n} \leq 250.0 \quad (38)$$

$$H_{8,n} \leq 250.0 \quad (39)$$

$$H_{9,n} \leq 250.0 \quad (40)$$

$$(H_{10,n} - H_{14,n})/L \geq 0.01 \quad (41)$$

$$(H_{11,n} - H_{15,n})/L \geq 0.01 \quad (42)$$

$$(H_{12,n} - H_{16,n})/L \geq 0.01 \quad (43)$$

$$(H_{13,n} - H_{17,n})/L \geq 0.01 \quad (44)$$

$$Q_{1,n} + Q_{2,n} - Q_{3,n} - Q_{4,n} - Q_{5,n} - Q_{6,n} \geq 0.0 \quad (45)$$

$$Q_{i,n} \geq 0.0, \quad \text{for } i = 1, \dots, 6 \quad (46)$$

All constraints must hold for  $n$  equals 1 and 2. Inequalities (32) through (40) are head constraints, (41) through (44) are gradient constraints, (45) is a balance constraint, and (46) is a non-negativity constraint.

At this point, AQMAN can be utilized to generate the response matrix needed for the problem and to create the MPS file required by standard optimization codes. Three input files, shown in Appendix IV, are needed to use AQMAN. Unit 15 is the original data set shown as Figure 33 in Trescott and others (1976). "Group IV" data will be ignored by AQMAN. In order to simulate a strictly linear system, unconfined conditions, leakage, and evapotranspiration have been omitted. (If these were not omitted, AQMAN would write warning messages to unit 16 but otherwise would operate normally). The value of NW has been changed to 6, since head at a well radius is managed at 6 locations. In order to demonstrate a transient problem, the number of pumping periods has been increased to two and a uniform storativity of 0.001 has been entered for all active nodes.

Unit 14 is the first of two data sets containing management information. (See Appendix II for a description of unit 14 formats.) The second line states that there are 7 wells, 17 control locations, 2 pumping periods, and 4 gradient control pairs. The fifth line specifies that one of the wells is an unmanaged well, operating at a pre-determined rate. This well is identified in the sixth line, with KEYQ equal to 1. The next two lines specify that this well must pump 0.005 ft<sup>3</sup>/s during the first period and 0.01 ft<sup>3</sup>/s during the second period. The two pumping decision wells are identified on lines 9 and 10. A unit stress of -1.0 ft<sup>3</sup>/s will be applied at each pumping well in order to obtain responses at control locations. Lines 11 through 14 indicate that a unit stress of +1.0 ft<sup>3</sup>/s will be applied at the four recharge wells. The 17 control locations are identified in lines 15 through 31. At the six control locations that require head of the well radius, KEYWL equals 1. Eight control locations involve only gradient control, so KEYGRD equals 1 at each of these. The next 17 lines specify the minimum or maximum head allowed at each of the control

locations during the first period; these are followed by the same restrictions for the second period. Within each set of 17 lines, the first 9 lines specify the right-hand side and the direction of the inequalities for constraints (32) through (40). The remaining 8 lines correspond to control locations 10 through 17. Since heads are not controlled at these locations (gradient controls only), the values specified in these 8 lines are ignored. However, these "dummy" lines must be entered into the file.

Unit 13 contains information for the gradient constraints, (41) through (44). (See Appendix II for a description of unit 13 formats.) The first 4 lines define the gradient control pairs, using control locations that have already been defined in unit 14. The next 4 lines specify the minimum gradients allowed at each of the control pairs during the first period; these are followed by the same restrictions for the second period. Within each set of 4 lines, the variable GCON specifies the right-hand side of the constraints. The variable GFACT equals the distance between the two nodes of each control pair. It converts GCON to a difference in head, as in equation (11).

AQMAN was run with these three input files. Before examining the output, it is instructive to see how AQMAN internally re-formulates the problem before it constructs the MPS file. The re-formulated problem is shown in matrix form in Figure 9. Heads and gradients are converted to drawdown responses, and the user's limits on heads and gradients are converted to manageable drawdowns.

The output from AQMAN is also shown in Appendix IV. Unit 16 contains no messages.

Unit 17 provides intermediate results of the simulation. Unstressed heads may be useful in interpreting the hydrologic significance of the final management solution. The user's desired limits on head are provided as a check against input data.

Unit 18 is the MPS file. Before using it in an optimization model for this problem, several modifications are necessary in order to incorporate the balance constraint (45). These changes are all indicated with bold type in the modified MPS file, also shown in Appendix IV. One change is needed in the ROWS section. The two constraints on pumping and recharge balance must be named and identified as "greater than or equal to". In this case, the user chooses the names BAL1 and BAL2. In the COLUMNS section, for all 12 decision variables, a coefficient of +1.0 (pumping) or -1.0 (recharge) is added for the constraints on pumping and recharge balance. Finally, the right-hand sides of the two balance constraints are added to the RHS section.

The modified MPS file was used as input for an optimization code, MINOS (Murtaugh and Saunders, 1983). The results are shown in Appendix IV. The optimal solution is to pump wells 1 and 2 at rates of 0.415 and 0.972 ft<sup>3</sup>/s during the first period, at rates of 0.408 and 1.166 ft<sup>3</sup>/s during the second period, and to recharge well 3 at a rate of 0.308 ft<sup>3</sup>/s during the second period. This solution satisfies all the constraints and yields a net water supply of 2.65 ft<sup>3</sup>/s.



On a PRIME 850 mini-computer, AQMAN used 76 CPU seconds for this problem. MINOS used 16 CPU seconds.

It is also instructive to see the effect of head definitions on the internally re-formulated problem. For example, the user wants the optimal head at locations 1 and 2 during both periods to appear directly in the solution, and KDEFHD is set equal to 1. The re-formulated problem is shown in Figure 10. Extra unity values have been added to the response matrix, inequalities are changed to equalities, and the value of the right-hand side is now unmanaged heads. The user will have to manually add constraints (32) and (33) to the MPS file.



## REFERENCES

- Aguado, E., and Remson, I., 1980, Ground-water management with fixed charges: Journal of Water Resources Planning and Management Division, American Society of Civil Engineering, v. 106, no. WR2, p. 375-382.
- Anderson, T., Burt, O.R., and Fractor, D.T., 1983, Privatizing groundwater basins: a model and its application: in Water Rights, Scarce Resource Allocation, Bureaucracy, and the Environment, by T.L. Anderson (editor), Pacific Institute for Policy Research, San Francisco, 348 p.
- Atwood, D.F., and Gorelick, S.M., 1985, Hydraulic gradient control for ground water contaminant removal: Journal of Hydrology, v. 76, p. 85-106.
- Chaudry, M.T., Labadie, J.W., Hall, W.A., and Albertson, M.L., 1974, Optimal conjunctive use model for the Indus basin: Journal of Hydraulics Division, American Society of Civil Engineering, v. 100, no. HY5, p. 667- 687.
- Cohon, J.L., and Marks, D.H., 1975, A review and evaluation of multi-objective programming techniques: Water Resources Research, v. 11, no. 2, p. 208- 220.
- Colarullo, S.J., Heidari, M., and Maddock III, T., 1984, Identification of an optimal groundwater strategy in a contaminated aquifer: Water Resources Bulletin, v. 20, no. 5, p. 747-760.
- Danskin, W.R., and Gorelick, S.M., 1985, A policy evaluation tool: management of a multiaquifer system using controlled stream recharge: Water Resources Research, v. 21, no. 11, p. 1731-1747.
- Dantzig, G.B., 1963, Linear Programming and Extensions: Princeton University Press, Princeton, 627 p.
- Freeze, R.A., and Cherry, J.A., 1979, Groundwater: Prentice-Hall, Englewood Cliffs, 604 p.
- Gorelick, S.M., 1983, A review of distributed parameter groundwater management modeling methods: Water Resources Research, v. 19, no. 2, p. 305-319.
- Gorelick, S.M., Voss, C.I., Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1984, Aquifer reclamation design: the use of contaminant transport simulation combined with non-linear programming: Water Resources Research, v. 20, no. 4, p. 415-427.
- Gorelick, S.M., and Wagner, B.J., 1986, Evaluating strategies for ground water contaminant plume stabilization and removal, Selected Papers in the Hydrologic Sciences: U.S. Geological Survey Water-Supply Paper 2290, pp. 81-89.
- Heidari, M., 1982, Application of linear system's theory and linear programming to groundwater management in Kansas: Water Resources Bulletin, v. 18, no. 6, p. 1003-1012.
- Hillier, F.S., and Lieberman, G.J., 1974, Introduction to Operations Research: Holden-Day, San Francisco, 829 p.

- IBM, Mathematical programming system/360, Version 2, Linear and separable programming--User's Manual: Document No. H20-0476-2, IBM Corporation, New York.
- Khepar, S.D., and Chaturvedi, M.C., 1982, Optimum cropping pattern and ground water management: Water Resources Bulletin, v. 18, no. 4, p. 655-660.
- Larson, S.P., Maddock III, T., and Papadopoulos, S., 1977, Optimization techniques applied to groundwater development: Memoirs of the International Association of Hydrogeology, v. 13, p. E57-E67.
- Lee, A.S., and Aronofsky, J.S., 1958, A linear programming model for scheduling crude oil production: Journal of Petroleum Technology, v. 213, p. 51-54.
- Lefkoff, L.J., and Gorelick, S.M., 1985, Rapid removal of a groundwater contaminant plume: Proceedings of the Symposium on Groundwater Contamination and Reclamation, American Water Resources Association, p. 125-131.
- Lefkoff, L.J., and Gorelick, S.M., 1986, Design and cost analysis of rapid aquifer restoration systems using flow simulation and quadratic programming: Ground Water, v. 24, no. 6, p. 777-790.
- Maddock III, T., 1972, Algebraic technological function from a simulation model: Water Resources Research, v. 8, no. 1, p. 129-134.
- Murtagh, B.A., and Saunders, M.A., 1983, MINOS 5.0 User's Guide: Technical Report SOL 83-20, Department of Operations Research, Stanford University, Stanford, 118 p.
- Rosenwald, G.W., and Green, D.W., 1974, A method for determining the optimal location of wells in a reservoir using mixed-integer programming: Society of Petroleum Engineering Journal, v. 14, p. 44-54.
- Schwarz, J., 1976, Linear models for groundwater management: Journal of Hydrology, v. 28, p. 377-392.
- Trescott, P.C., Pinder, G.F., and Larson, S.P., 1976, Finite-difference model for aquifer simulation in two dimensions with results of numerical experiments: U.S. Geological Survey Techniques of Water Resources Investigations, Book 7, Chap. C1, 116 p.
- Wagner, 1975, Principles of Operations Research: Prentice-Hall, Englewood Cliffs, 1039 p.
- Wattenbarger, R.A., 1970, Maximizing seasonal withdrawals from gas storage reservoirs: Journal of Petroleum Technology, p. 994-998.
- Willis, R., 1983, A unified approach to regional groundwater management: in Groundwater Hydraulics, Water Resource Monograph Series, by J.S. Rosenzhein and G.D. Bennett (edited), American Geophysical Union, Washington, 416 p.

## APPENDIX I -- DEFINITION OF VARIABLES

- ANNDIS** = the annual discount rate, used only with quadratic objective function. Read by Subroutine QUAD from unit 13.
- CASE** = the type of objective function in a linear management problem. Must equal either "LINEAR" or "QUAD". Read by PRE from unit 14.
- CDELTA** = multiplying factor for time steps. Read by subroutine PRE from unit 14. The Trescott variable CDLT is set equal to CDELTA.
- CONHD(JN)** = user-defined limit on head at each control location JN. Read by Main from unit 14. JN goes from 1 to (NCNTR x NNPER). The CONHD vector is ordered by control location numbers within each sequential management period.
- CONTYP(JN)** = user-defined type of head constraint at control location JN. Read by Main from unit 14. Must equal either "L" for "less than or equal to", "G" for "greater than or equal to", or "E" for "equal to". Because constraints are re-formulated in terms of drawdowns, these inequalities are reversed in the MPS file. The vector CONTYP is ordered as is CONHD.
- COSTC(IQ,N)** = pumping cost per unit pumping rate per unit lift for well IQ during period N. Read as undiscounted unit cost from unit 13 by subroutine QUAD. Subroutine QUAD and MPSFMT apply a discount factor and a scaling factor to each unit pumping cost. IQ includes only quadratic (usually, pumping) managed wells.
- COSTF** = unit pumping cost like COSTC, but constant for all wells and all periods. If KEYCOS equals 0, pumping costs are constant and read by subroutine QUAD from unit 13 as COSTF. Subroutine QUAD then applies a discount factor and enters COSTF into the COSTC matrix.
- DRDRES(JN)** = drawdown response at each control location during each period. For each decision well, AQMAN's Main calls subroutine PRE to obtain heads HD, computes  $DRDRES(JN) = HDSS(JN) - HD(JN)$ , and passes DRDRES to subroutine MPSFMT, which writes it into the column section of the MPS file.
- FIXQ(I,N)** = pre-determined pumping rate given for unmanaged well I during pumping period N. Read from unit 14 by subroutine PRE.
- GCON(KN)** = user-defined limit on either the gradient or the seepage velocity between the two locations of control pair KN during each period. Read from unit 13 by Subroutine GRADS. KN goes from 1 to (NGRAD x NPER). GCON is ordered by control pairs within each sequential pumping period. The convention adopted is  $GCON = \text{Head}(1) - \text{Head}(2)$ .
- GFACT(KN)** = user-defined factor by which GCON is multiplied. Read from unit 13 by Subroutine GRADS. GFACT converts GCON to a difference in head. If simply the difference in head is managed,  $GFACT=1.0$ . If gradient is managed,  $GFACT = (\text{the distance between the two locations})$ . If velocity is managed,  $GFACT = (\text{the distance between the two locations}) \times (\text{effective aquifer porosity}) / (\text{hydraulic conductivity between the two locations})$ . See equations

(11) and (12). KN goes from 1 to (NGRAD x NPER). GFACT is ordered as is GCON.

GRADE(KN) = manageable gradient or manageable velocity for control pair KN. Subroutine GRADS computes  $GRADE = HDUS(1) - HDUS(2) - (GCON \times GFACT)$ . GRADE(KN) is written in the RHS section of the MPS file for the row corresponding to constraint KN. The vector GRADE is ordered as is GCON.

GRATYP(KN) = user-defined type of gradient or velocity constraint for control pair KN. Must be either "L" for "less than or equal to", "G" for "greater than or equal to", or "E" for "equal to". Because constraints are re-formulated in terms of drawdowns, these inequalities are reversed in the MPS file. The GRATYP vector is ordered as is GCON.

HD(JN) = heads computed by subroutine TRES. JN goes from 1 to (NCNTR x NPER). HD is ordered by control locations within pumping periods.

HDUS(JN) = unstressed, transient heads computed on first call of subroutine PRE. HDUS contains the heads that would occur over time if no managed wells were stressed.

ILOCC(J), JLOCC (J) = row (y-axis) and column (x-axis) location of control node J. Read by subroutine PRE from unit 14. J goes from 1 to NCNTR.

ILOGG1(K), JLOGG1(K) = row (y-axis) location and column (x-axis) location of the first node of control pair K. Read by subroutine GRADS from unit 13. Every ILOGG1 must correspond to some entry in the ILOCC vector, and every JLOGG1 must correspond to some entry in the JLOCC vector. K goes from 1 to NGRAD.

ILOGG2(K), JLOGG2(K) = row (y-axis) location and column (x-axis) location of the second node of control pair K. Read by subroutine GRADS from unit 13. Every ILOGG2 must correspond to some entry in the ILOCC vector, and every JLOGG2 must correspond to some entry in the JLOCC vector. K goes from 1 to NGRAD.

ILOCW(I), JLOCW (I) = row (y-axis) and column (x-axis) location of each managed or unmanaged well I. Read by subroutine PRE from unit 14. I goes from to NWLS.

KCALL, KCALLP = counter for number of times AQMAN's main has called subroutine PRE.

KDEFHD (J) = toggle (0 if no, 1 if yes) to indicate whether head definition is desired at control location J. Read by subroutine PRE from until 14. J goes from 1 to NCNTR. If KDEFHD (J) = 0, total drawdown from unmanaged conditions is constrained. If KDEFHD(J) = 1, a new decision variable is introduced and defined as unmanaged head minus total drawdown; the user may manually enter constraints on the new variable into the MPS file.

KDEFGR(K) = toggle (0 if no, 1 if yes) to indicate whether gradient or velocity definition is desired at control pair K. Read by subroutine PRE from unit 14. K goes from 1 to NGRAD. If KDEFGR(K) = 0, total difference-in-drawdown

from unmanaged conditions is constrained. If  $KDEFGR(K) = 1$ , a new decision variable is introduced and defined as the unmanaged difference in head minus total difference-in-drawdown; the user may manually enter constraints on the new variable into the MPS file.

**KEYCOS** = toggle (0 if yes, 1 if no) to indicate whether undiscounted pumping cost **COSTC** is constant for all wells over all periods. Read from unit 13 by subroutine **QUAD**. Used only with a quadratic objective function. If **KEYCOS=0**, a single cost factor **COSTF** is read, discounted on a monthly basis, and entered into the **COSTC** matrix. If **KEYCOS=1**, variable **COSTC** is read and discounted.

**KEYGRD(J)** = toggle (0 if no, 1 if yes) to indicate whether primary control location **J** is only to be used for gradient or velocity control. Read from unit 14 by subroutine **PRE**. **J** goes from 1 to **NCNTR**. If **KEYGRD(J) = 0**, either (a) the head or (b) both the head and the gradient or velocity is controlled at location **J**, so that a drawdown response at **J** will be written in the MPS file by Subroutine **MPSFMT**. If **KEYGRD(J) = 1**, only the gradient or velocity is controlled at **J**, so that no drawdown response will be written in the MPS file; only a difference in drawdown response for the control pair to which control location **J** belongs will be written.

**KEYQ(I)** = toggle (0 if no, 1 if yes) to denote whether well **I** is a fixed, unmanaged well. Read by **PRE** from unit 14. **I** goes from 1 to **NWLS**. If there is a quadratic objective function, enter **KEYQ=2** for non-quadratic (recharge) managed wells, and **KEYQ=0** for quadratic (pumping) managed wells. When reading input data on the wells, all quadratic wells must be listed before any non-quadratic wells.

**KEYWL(J)** = toggle (0 if no, 1 if yes) to indicate whether control node **J** also contains a well, so that head at the well radius is needed. Read by Subroutine **PRE** from unit 14. **J** goes from 1 to **NCNTR**. The number of non-zero **KEYWLs** must equal the value of **NW** read by subroutine **TRES** from unit 15. For each non-zero value of **KEYWL**, **XRAD** at that node must be positive. For each zero value of **KEYWL**, **XRAD** must be zero.

**KPER** = pumping period counter. **KPER** is increased by 1 in subroutine **TRES** at line \$2-730, after the new pumping period begins but before the **SOLVE** subroutines are called. **KPER** counts from 1 to **NNPER**.

**MNGDRD(JN)** = manageable drawdown at each control location during each period. Computed as  $MNGDRD(JN) = HDUS(JN) - CONHD(JN)$ . **MNGDRD** is written by subroutine **MPSFMT** into the RHS section of the MPS file.

**NNAME** = the alphanumeric name given to the MPS data set. Read by subroutine **PRE** from unit 14. May contain up to 64 characters.

**NCNTR** = number of control locations. Read by Subroutine **PRE** from unit 14. Current maximum value (for storage of **ILOCC**, **JLOCC**, **KEYWL**) is 500.

**NGRAD** = number of gradient control pairs. Read by Subroutine **PRE** from unit 14. Each gradient pair consists of two control locations that have each been previously read as one of the **NCNTR** primary control nodes.

**NKEYQ** = the number of fixed (unmanaged) wells. Read by Subroutine PRE from unit 14.

**NNPER** = number of pumping periods. Read by Subroutine PRE from unit 14. The Trescott variable NPER is set equal to NNPER. The current maximum value of NNPER (for storage of TIMINC) is 50.

**NWLS** = total number of wells (managed plus unmanaged). Read by subroutine PRE from unit 14. NWLS is read instead of the Trescott variable NWEL. Current maximum value (for storage of XRAD, ILOCW, JLOCW) is 200.

**QWELL(IN)** = pumpage and recharge rates. IN goes from 1 to (NWEL x NNPER). QWELL is used instead of the Trescott variable WELL. The current maximum value for (NWEL x NNPER) is 500. QWELL is ordered by well numbers within pumping periods.

**RDIF(KN)** = the difference in drawdown response between the two locations of a control pair. KN goes from 1 to (NGRAD x NNPER). RDIF(KN) is written in the column section of the MPS file for the constraint corresponding to control pair KN.

**SURF(IQ)** = the elevation of the land surface at each quadratic (pumping) managed well. Read from unit 13 by subroutine QUAD. IQ goes from 1 to (number of quadratic decision wells). SURF is used to compute unmanaged lift required at these decision wells.

**TIMINC(N)** = number of hours in initial time step for each pumping period. Read by subroutine PRE from unit 14. N goes from 1 to NNPER. TIMINC is read instead of the Trescott variable DELT.

**TIMPER** = number of days in each pumping period. Read by subroutine PRE from unit 14. TIMPER is read instead of the Trescott variable TMAX.

**UNITQ(I)** = unit pumpage or recharge stress. Read by subroutine PRE from unit 14. UNITQ is negative for pumping, positive for recharge. If a problem requires scaling, the UNITQ vector can vary accordingly (eg., -1.0, 0.1, -0.001). All cost coefficients in the objective function will be automatically scaled (multiplied) by UNITQ at the appropriate well. The user must be careful to re-scale the final optimization results.

**XHEAD(JN)** = computed head at control locations. JN goes from 1 to (NCNTR x NNPER). XHEAD is ordered by locations within pumping periods.

**XRAD(I)** = well radius. Read by subroutine PRE from unit 14. I goes from 1 to NWLS. XRAD is read instead of the Trescott variable RADIUS. Non-zero values must be entered for any well that is also a control location, and zero values entered for any well that is not a control location.

## APPENDIX II--DATA FILE INSTRUCTIONS

Two input files are always required for AQMAN. A third is needed if the problem involves gradients or velocities or if a quadratic objective function is desired. English or metric units can be used, as long as all input data are consistent.

1. Logical unit 15 contains the usual Trescott data set. "Group IV" data may be included, but will be ignored by AQMAN. "Group IV" contains the pumping period parameters and the well locations, pumpages, and radii (Trescott and others, 1976, pp. 49-55).
2. Logical unit 14 contains input read by subroutine PRE and Main:

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
1	1	1-4	A4	CASE	The type of objective function in a linear problem. LINE for linear function, QUAD for quadratic.
		7-70	16A4	NNAME	Any title the user wishes to print on the first line of the MPS file.
2	1	1-10	I10	NWLS	Total number of wells (managed plus unmanaged) in the system. NWLS must be constant for all pumping periods.
		11-20	I10	NCNTR	Number of control locations, constant for all pumping periods. HD and XHEAD will contain the computed head at these nodal locations.
		21-30	I10	NNPER	Number of pumping periods to be simulated.
		31-40	G10.0	CDELTA	Multiplying factor for DELT, constant for all pumping periods. Used instead of the Trescott variable CDLT.
3	1	1-80	8G10.0	TIMPER	Number of days in each time period.

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
4	1+	1-80	8G10.0	TIMINC(N)	Number of hours in initial time step for each period. TIMINC is a vector containing NPER elements; if NPER exceeds 8, more than one line will be needed. See discussion of time parameters in text.
5	1	1-10	I10	NKEYQ	Number of fixed (unmanaged) wells. Cannot be greater than NWLS.
6	NWLS	1-10	I10	ILOCW(I)	Row (y-axis) location of well I. ILOCW is a vector containing NWLS elements.
		11-20	I10	JLOCW(I)	Column (x-axis) location of well I. JLOCW is a vector containing NWLS elements.
		21-40	G10.0	XRAD(I)	Radius [L] of well I. XRAD is a vector containing NWLS elements.
		31-40	I10	KEYQ(I)	Switch (0=no, 1=yes) to indicate whether I is an unmanaged well. For all cases, if KEYQ(I)=1 pumpage at well I is not a decision variable, and no drawdown response is computed for it. For a quadratic objective, KEYQ(I)=2 if I is a nonquadratic, managed well, and KEYQ(I)=0 if I is a quadratic, managed well.
		41-50	F10.0	UNITQ(I)	The unit pumping [ $L^3/T$ ] rate used at well I obtain drawdown responses. A negative value indicates a pumping well; a positive value indicates a recharge well. **Use care if UNITQ is not constant for all decision wells. See discussion on scaling in text.

Note--If a KEYQ=1 is read for well I, the reading of the above five variables is interrupted, and FIXQ is read for each period at well I. NNPER lines are required at each interruption.

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
6	NNPER	1-10	G10.0	FIXQ(I,N)	Pumpage or recharge [ $L^3/T$ ] at the unmanaged well I during period N. There must be NNPER values for FIXQ following a KEYQ=1.
7	NCNTR	1-10	I10	ILOCC(J)	Row (y-axis) location of control node J. ILOCC is a vector containing NCNTR elements.
		11-20	I10	JLOCC(J)	Column (x-axis) location of control node J. JLOCC is a vector containing NCNTR elements.
		21-30	I10	KEYWL(J)	Switch to indicate whether control location J also contains a well. If KEYWL(J) does not equal zero, a well exists at J, and XRAD is used to compute head at the well, rather than a cell-averaged head.

Note--The number of non-zero KEYWLs must equal the value of NW read by the TRESMOTT code from unit 15. For each non-zero value of KEYWL, XRAD at that node must be positive.

31-40	I10	KEYGRD(J)	Switch to indicate whether control location J is to be used only for gradient or velocity control. If KEYGRD(J)=0, J will be used for head control and may be used for gradient or velocity control. If KEYGRD(J)=1, J will not be used for head control: no constraint row and no response coefficient for J will be written in the MPS file.
-------	-----	-----------	--

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
		41-50	I10	KDEFHD(J)	Switch to indicate whether head definition is desired at location J. If KDEFHD(J)=0, total drawdown is constrained. If KDEFHD(J)=1, head is defined and any constraint must be manually added to the MPS file.
8	NNPER x NCNTR	1-10	G10.0	CONHD(JN)	Desired upper or lower limit [L] on average cell head or head at a well radius at each control location during each pumping period. The first NCNTR lines are for period 1, the second NCNTR lines are for period 2, etc. Read dummy values for locations where head is not constrained.
		15	A1	CONTYP(JN)	Type of constraint on head at each control location. Must be either "L" for $\leq$ , "G" for $\geq$ , or "E" for =
3. Logical unit 13 is used only if NGRAD is positive or CASE equals "QUAD". It contains input read by subroutines QUAD and GRADS. If the problem is not quadratic, omit the lines containing ANNDIS, COSTF, KEYCOS, COSTC, and SURF.					
1	1	1-10	G10.3	ANNDIS	Annual discount rate [ $L^{\circ}$ ], applied to pumping costs in each period on a monthly basis.
		11-20	G10.0	COSTF	Undiscounted pumping cost [\$], constant for all wells in all periods. Used only if KEYCOS =0
		21-30	I10	KEYCOS	Switch to indicate whether pumping costs are constant (0) or variable (1). If KEYCOS=0, COSTC=COSTF. If KEYCOS=1, variable COSTC is read.
2	NNPER+	1-80	8G10.0	COSTC(IQ,N)	Undiscounted pumping cost [\$] at quadratic managed well IQ during pumping period N. If IQ exceeds 8, more than one line will be needed for each period.

Note--Omit if KEYCOS=0

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
3	1+	1-80	8G10.0	SURF(IQ,N)	Land surface elevation [L] at quadratic managed well. IQ goes from 1 to the number of managed wells included in the quadratic objective (usually, pumping wells). A new line is needed for every 8 entries.
4	NGRAD	1-10	I10	ILOGG1(K)	Row (y-axis) location of the first node of control pair K. Must correspond to some ILOCC, i.e., must already be specified as a head control location.
		11-20	I10	JLOGG1(K)	Column (x-axis) location of the first node of control pair K. Must correspond to some JLOCC, i.e., must already be specified as a head control location.
		21-30	I10	ILOGG2(K)	Row (y-axis) location of the second node of control pair K. Must correspond to some ILOCC, i.e., must already be specified as a head control location.
		31-40	I10	JLOGG2(K)	Column (x-axis) location of the second node of control pair K. Must correspond to some JLOCC, i.e., must already be specified as head control location.
		41-50	I10	KDEFGR(K)	Switch to indicate whether head definition is desired at control pair K. If KDEFGR(K) = 0 total difference-in-drawdown is constrained. If KDEFGR(K) = 1, difference in head is defined and any constraint must be manually added to the MPS file.
5	NNPER x NGRAD	1-15	G15.6	GFACT(KN)	Factor by which GCON is multiplied. Used to control velocities or gradients rather than head differences.

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
	16-30		G15.6	GCON(KN)	Constraint on gradient [L/L] or or velocity [L/T] between the two locations of a control pair. Direction defined as (value at 1) (value at 2).
	35	A1		GRATYP(KN)	The type of gradient or velocity constraint at a control pair. Must be either "L" for $\leq$ , "G" for $\geq$ , or "E" for $=$ .

Three output files must always be open for program execution. Unit 16 will contain error and warning messages. Unit 17 will contain the user-defined limits on head and the unmanaged heads for all control locations, and pumping or recharge rates at all wells. Unit 18 is the MPS file, to be used as input for a mathematical programming package.

A fourth output file is needed for quadratic problems. AQMAN writes to unit 19 the drawdown responses at all pumping (quadratic) managed wells. (These are recognized as control locations at which KEYWL=1 and KEYGRD=1). Unit 19 will be used by the optimization model to compute the value and gradient of the quadratic objective function for a given set of decisions. See Appendix III.

### APPENDIX III -- QUADRATIC OBJECTIVE: SUBROUTINE FUNOBJ

In order to execute an optimization code that solves a quadratic objective, the user must supply to the code a subroutine that evaluates the value and the gradient of the quadratic objective function for a given set of decisions. The quadratic portion of the objective is given by:

$$F = \sum_{j=1}^J \sum_{n=1}^N \sum_{i=1}^I \sum_{k=1}^n C_{j,n} Q_{j,n} Q_{i,k} \beta_{i,j,(n-k)} \quad (A1)$$

Where  $J$  = number of pumping managed wells,

$I$  = number of managed (pumping + recharge) wells,

$N$  = number of management periods,

$C$  = unit cost of pumping per unit pumping rate per unit lift [ $\$L^{-4} T$ ],

$Q$  = pumping or recharge rate at managed wells [ $L^3/T$ ],

$\beta$  = response coefficient between the head at well  $j$  and pumping or recharge at well  $i$  separated by  $(n-k)$  management periods [ $L^0$ ]

The gradient is the partial derivative with respect to each of the decision variables  $Q$ :

$$\frac{\partial F}{\partial Q_{w,p}} = \sum_{j=1}^J \sum_{n=k}^N C_{j,n} Q_{j,n} \beta_{i,j,(n-k)} \left[ \begin{array}{l} \text{for} \\ i=w \\ k=p \end{array} \right]$$

$$+ \sum_{i=1}^I \sum_{k=1}^n C_{j,n} Q_{i,k} \beta_{i,j,(n-k)} \left[ \begin{array}{l} \text{for} \\ j=w \\ n=p \end{array} \right] \quad \begin{array}{l} w = 1, \dots, I \\ p = 1, \dots, N \end{array} \quad (A2)$$

This appendix contains two versions of a subroutine that calculates (A1) and (A2). The subroutine, FUNOBJ, was written for use by the mathematical programming package MINOS (Murtagh and Saunders, 1983), but should be easily adaptable to other optimization codes. The two versions differ only in the amount of computer CPU time and storage required. The first version operates faster, and is recommended for most problems. This version reads all input data once, and needs CPU core storage space at least as large as the input files. The second version of FUNOBJ should only be used for very large problems. It reads input data repeatedly, requiring less storage but much more input/output time. The definition of a "large" problem depends on the computer facilities available; if the CPU can easily store all input files, the first version of FUNOBJ should be used. For example, if the input file that requires the most storage needs 0.5 megabyte of core and the problem is to be run on an 8.0 megabyte machine, the problem is not large and the fast FUNOBJ should be used.

In addition to the MPS file, two other input files are needed to execute a quadratic programming code. One of these is the quadratic response file, which is written by AQMAN as unit 19. It contains the drawdown response at "response wells" to a unit stress applied at all managed wells. "Response wells" consist of all pumping managed wells plus all recharge managed wells where head is controlled. Usually, head is controlled at all recharge wells to remain below some level, such as the land surface. In this case, all managed wells are response wells. There may be some exceptional problems in which head is not controlled at all recharge decision wells. If this is specified in the input files for AQMAN (units 14 and 13), the number of response wells written to unit 19 will be less than the number of decision wells.

During execution of the optimization code combined with Subroutine FUNOBJ, the quadratic response file will require more storage than any other input file. (The MPS file will be larger, but most optimization codes store it in a compact form.) The size of the quadratic response file determines whether the fast version of FUNOBJ can be used. The number of lines in the file equals the number of decision wells times the number of response wells times the number of management periods. The variable RBETA in FUNOBJ must be dimensioned large enough to store these numbers. For instance, say that a problem contains 50 managed wells and 25 periods, and that all of the managed wells are response wells. The file will contain 62,500 lines, and RBETA should be dimensioned 50 by 50 by 25. Since RBETA is double precision, this would reserve 0.5 megabytes of core. If the computer has a core memory of 8.0 megabytes, the fast FUNOBJ can be used.

In order for the data in the MPS file and the quadratic response file to be properly organized for the optimization code and for FUNOBJ, two precautions must be taken before execution of AQMAN. (1) Pumping wells, which all appear in the quadratic terms of the pumping cost objective, must be included as control locations (part of NCNTR) in order to obtain the well heads needed to compute induced lifts and cost coefficients. At each of these wells, if head-control is not desired, enter KEYGRD=1. This will prevent the writing of a constraint row for these wells to the MPS file. Remember that for each managed well at control locations, XRAD must be positive and KEYWL set equal to 1. (2) When entering well information into unit 14, all quadratic managed wells (usually, pumping wells) must be listed before non-quadratic managed wells (usually, recharge wells). This is needed for proper ordering of the responses written to unit 19. For non-quadratic managed wells, enter KEYQ=2. For quadratic managed wells, enter KEYQ=0. As always, enter KEYQ=1 for unmanaged wells.

The other input file needed by FUNOBJ is created by the user. It is unit number 12. Definitions and format instructions are given below. A listing of the two versions of Subroutine FUNOBJ follows.

<u>Data Set</u>	<u>Number of Lines</u>	<u>Columns</u>	<u>Format</u>	<u>Variable</u>	<u>Definition</u>
1	1	1-10	I10	NDWLS	The number of decision wells.
		11-20	I10	NRES	The number of response wells. This is all pumping managed wells (quadratics) plus all recharge managed wells where head is controlled. Usually, NRES equals NDWLS.
		21-30	I10	NPWLS	The number of pumping managed wells, where quadratic pumping costs are being minimized.
***Note--NPWLS cannot be greater than NRES, and NRES cannot be greater than NDWLS.					
2	1	31-40	I10	NPER	The number of management (pumping) periods.
		1-80	G10.2	TIMPER	Number of days in each management period. TIMPER is used here for discounting future costs.
		1-10	G10.3	ANNDIS	Annual discount rate [ $L^{\circ}$ ], applied to pumping costs in each period.
3	1	11-20	G10.3	COSTF	Undiscounted pumping cost [\$], constant for all wells in all periods. Used only if KEYCOS = 0.
		21-30	I10	KEYCOS	Switch to indicate whether pumping costs are constant (0) or spatially variable (1). If KEYCOS=0, COSTC=COSTF. If KEYCOS=1, variable COSTC is read.
		4	NNPER +	1-80	8G10.2
** Note--Omit if KEYCOS=0					
5	NPWLS	1-10	G10.2	UNITQ(IP)	The unit pumping rate [ $-L^3/T$ ] applied by AQMAN at each well IP. Used to scale cost coefficients in the quadratic objective.

C---Subroutine FUNOBJ for MINOS with quadratic objective function.	FUNa 10
C---Calculates value and gradient of the objective function.	FUNa 20
C---This version requires more storage, but runs must faster.	FUNa 30
SUBROUTINE FUNOBJ(MODE,NN,X,F,G,NSTATE,NPROB,Z,NWCORE)	FUNa 40
IMPLICIT REAL*8 (A-H,O-Z)	FUNa 50
DIMENSION X(NN),G(NN),Z(NWCORE)	FUNa 60
C*** Check dimensions!! Be sure that RBETA(I,K,N), COSTC(I,N), and	FUNa 70
C*** Q(I,N) are large enough for the problem:	FUNa 80
C    I=number of decision (managed) wells, NDWLS	FUNa 90
C    K=number of response wells, NRES	FUNa 100
C    N=number of management periods, NPER	FUNa 110
COMMON /QUADAQ/ RBETA(30,30,4),COSTC(30,4),Q(30,4),UNITQ(30)	FUNa 120
C---Read data only if first call by MINOS.	FUNa 130
IF(NSTATE.NE.1) GO TO 170	FUNa 140
C---Read number of decision (managed) wells, response (observation)	FUNa 150
C----wells, pumping (quadratic) wells, and pumping periods.	FUNa 160
C**** NOTE *** In ordering decision vector, all response wells must	FUNa 170
C        be first decision wells, and all pumping wells must be	FUNa 180
C        first response wells.	FUNa 190
READ(12,10)NDWLS,NRES,NPWLS,NPER	FUNa 200
10 FORMAT(4I10)	FUNa 210
C---Read length (in days) of pumping periods	FUNa 220
READ(12,20)TIMPER	FUNa 230
20 FORMAT(G10.2)	FUNa 240
C--Read annual discount rate, constant pumping cost, and key to	FUNa 250
C----indicate whether costs are constant (0) or variable (1):	FUNa 260
READ(12,25)ANNDIS,COSTF,KEYCOS	FUNa 270
25 FORMAT(2G10.3,I10)	FUNa 280
DISMON=ANNDIS/12.0	FUNa 290
NDAYS=0	FUNa 300
DO 140 N=1,NPER	FUNa 310
NDAYS=NDAYS+TIMPER	FUNa 320
NMONTH=NDAYS/30	FUNa 330
DISFAC=1./((1.+DISMON)**NMONTH)	FUNa 340
IF(KEYCOS.EQ.0) GO TO 120	FUNa 350
C--Read variable pumping costs into cost vector and discount according	FUNa 360
C----to time period lengths by months:	FUNa 370
READ(12,30)(COSTC(I,N),I=1,NPWLS)	FUNa 380
30 FORMAT(8G10.2)	FUNa 390
DO 110 I=1,NPWLS	FUNa 400
110 COSTC(I,N)=DISFAC*COSTC(I,N)	FUNa 410
GO TO 140	FUNa 420
C--Put constant pumping costs into costs vector and discount by time	FUNa 430
C---period:	FUNa 440
120 DO 130 I=1,NPWLS	FUNa 450
130 COSTC(I,N)=COSTF*DISFAC	FUNa 460
140 CONTINUE	FUNa 470
C--Read unit pumping rates used to obtain responses. Be sure that each	FUNa 480
C---unit rate corresponds to correct pumping well! Remember: NEGATIVE	FUNa 490
C---for pumping.	FUNa 500
DO 145 I=1,NPWLS	FUNa 510
145 READ(12,20)UNITQ(I)	FUNa 520
C--Scale cost coefficients according to unit pumping rates.	FUNa 530
	FUNa 540

DO 150 N=1,NPER	FUNa 550
DO 150 I=1,NPWLS	FUNa 560
150 COSTC(I,N)=COSTC(I,N)*(-UNITQ(I))	FUNa 570
C--Read matrix of responses between well I and well L for separated by	FUNa 580
C----(NPER-1) pumping periods.	FUNa 590
DO 160 I=1,NDWLS	FUNa 600
DO 160 N=1,NPER	FUNa 610
DO 160 L=1,NRES	FUNa 620
READ(19,50)RBETA(I,L,N)	FUNa 630
50 FORMAT(20X,F15.7)	FUNa 640
160 CONTINUE	FUNa 650
C--Convert pumpage vector into two dimensional matrix:	FUNa 660
170 DO 180 I=1,NDWLS	FUNa 670
DO 180 N=1,NPER	FUNa 680
KPUMP=N+(I-1)*NPER	FUNa 690
Q(I,N)=X(KPUMP)	FUNa 700
180 CONTINUE	FUNa 710
C--Compute value of objective function.	FUNa 720
F=0.0	FUNa 730
DO 200 L=1,NPWLS	FUNa 740
DO 200 N=1,NPER	FUNa 750
FTEMP=0.0	FUNa 760
DO 190 I=1,NDWLS	FUNa 770
DO 190 K=1,N	FUNa 780
KT=N-K+1	FUNa 790
FTEMP=FTEMP+(Q(I,K)*RBETA(I,L,KT))	FUNa 800
190 CONTINUE	FUNa 810
F=F+(FTEMP*COSTC(L,N)*Q(L,N))	FUNa 820
200 CONTINUE	FUNa 830
C-Compute value of gradient at each decision (managed) well during each	FUNa 840
C---management period.	FUNa 850
DO 230 IWL=1,NDWLS	FUNa 860
DO 230 IPER=1,NPER	FUNa 870
KG=IPER+(IWL-1)*NPER	FUNa 880
G(KG)=0.0	FUNa 890
DO 225 I=1,NDWLS	FUNa 900
DO 225 K=1,NPER	FUNa 910
IF(I.NE.IWL .OR. K.NE.IPER)GO TO 225	FUNa 920
DO 220 L=1,NPWLS	FUNa 930
DO 220 N=K,NPER	FUNa 940
KT=N-K+1	FUNa 950
G(KG)=G(KG)+(COSTC(L,N)*Q(L,N)*RBETA(IWL,L,KT))	FUNa 960
220 CONTINUE	FUNa 970
GO TO 230	FUNa 980
225 CONTINUE	FUNa 990
230 CONTINUE	FUNa1000
DO 300 LWL=1,NPWLS	FUNa1010
DO 300 IPER=1,NPER	FUNa1020
G2=0.0	FUNa1030
DO 280 L=1,NPWLS	FUNa1040
DO 270 N=1,NPER	FUNa1050
IF(L.NE.LWL .OR. N.NE.IPER)GO TO 270	FUNa1060
DO 260 I=1,NDWLS	FUNa1070
DO 260 K=1,N	FUNa1080

	KT=N-K+1	FUNa1090
	G2=G2+(COSTC(L,N)*Q(I,K)*RBETA(I,LWL,KT))	FUNa1100
260	CONTINUE	FUNa1110
	KG=IPER+(LWL-1)*NPER	FUNa1120
	G(KG)=G(KG)+G2	FUNa1130
	GO TO 300	FUNa1140
270	CONTINUE	FUNa1150
280	CONTINUE	FUNa1160
300	CONTINUE	FUNa1170
	RETURN	FUNa1180
	END	FUNa1190

220	CONTINUE	FUNb1080
	GO TO 230	FUNb1090
225	CONTINUE	FUNb1100
230	CONTINUE	FUNb1110
	DO 300 LWL=1,NPWLS	FUNb1120
	REWIND 19	FUNb1130
	IF(LWL.EQ.1)GO TO 240	FUNb1140
	LSKIP=LWL-1	FUNb1150
	DO 235 ISKIP=1,LSKIP	FUNb1160
235	READ(19,50)DUMMY	FUNb1170
240	DO 250 I=1,NDWLS	FUNb1180
	DO 250 N=1,NPER	FUNb1190
	IF(I.EQ.1 .AND. N.EQ.1)GO TO 250	FUNb1200
	NSKIP=NRES-1	FUNb1210
	DO 245 ISKIP=1,NSKIP	FUNb1220
245	READ(19,50)DUMMY	FUNb1230
250	READ(19,50)RBETA(I,N)	FUNb1240
	DO 300 IPER=1,NPER	FUNb1250
	G2=0.0	FUNb1260
	DO 280 L=1,NPWLS	FUNb1270
	DO 270 N=1,NPER	FUNb1280
	IF(L.NE.LWL .OR. N.NE.IPER)GO TO 270	FUNb1290
	DO 260 I=1,NDWLS	FUNb1300
	DO 260 K=1,N	FUNb1310
	KT=N-K+1	FUNb1320
	G2=G2+(COSTC(L,N)*Q(I,K)*RBETA(I,KT))	FUNb1330
260	CONTINUE	FUNb1340
	KG=IPER+(LWL-1)*NPER	FUNb1350
	G(KG)=G(KG)+G2	FUNb1360
	GO TO 300	FUNb1370
270	CONTINUE	FUNb1380
280	CONTINUE	FUNb1390
300	CONTINUE	FUNb1400
	RETURN	FUNb1410
	END	FUNb1420



C---Subroutine FUNOBJ for MINOS with quadratic objective function.	FUNb 10
C---Calculates value and gradient of the objective function.	FUNb 20
C---This version requires less storage, but runs much slower.	FUNb 30
SUBROUTINE FUNOBJ(MODE,NN,X,F,G,NSTATE,NPROB,Z,NWCORE)	FUNb 40
IMPLICIT REAL*8 (A-H,O-Z)	FUNb 50
DIMENSION X(NN),G(NN),Z(NWCORE)	FUNb 60
C*** Check dimensions!! Be sure that RBETA(I,N), COSTC(I,N), and	FUNb 70
C*** Q(I,N) are large enough for the problem:	FUNb 80
C    I=number of decision (managed) wells, NDWLS	FUNb 90
C    N=number of management periods, NPER	FUNb 100
COMMON /QUADAQ/ RBETA(200,50),COSTC(200,50),Q(200,50),UNITQ(200)	FUNb 110
C---Read data only if first call by MINOS.	FUNb 120
IF(NSTATE.NE.1) GO TO 155	FUNb 130
C---Read number of decision (managed) wells, response (observation)	FUNb 140
C---wells, pumping (quadratic) wells, and pumping periods.	FUNb 150
C*** NOTE *** In ordering decision vector, all response wells must	FUNb 160
C    be first decision wells, and all pumping wells must be	FUNb 170
C    first response wells.	FUNb 180
READ(12,10)NDWLS,NRES,NPWLS,NPER	FUNb 190
10 FORMAT(4I10)	FUNb 200
C---Read length (in days) of pumping periods	FUNb 210
READ(12,20)TIMPER	FUNb 220
20 FORMAT(8G10.2)	FUNb 230
C--Read annual discount rate, constant pumping cost, and key to	FUNb 240
C----indicate whether costs are constant (0) or variable (1):	FUNb 250
READ(12,25)ANNDIS,COSTF,KEYCOS	FUNb 260
25 FORMAT(2G10.3,I10)	FUNb 270
DISMON=ANNDIS/12.0	FUNb 280
NDAYS=0	FUNb 290
DO 130 N=1,NPER	FUNb 300
NDAYS=NDAYS+TIMPER	FUNb 310
NMONTH=NDAYS/30	FUNb 320
DISFAC=1./((1.+DISMON)**NMONTH)	FUNb 330
IF(KEYCOS.EQ.0) GO TO 110	FUNb 340
C--Read variable pumping costs into cost vector and discount according	FUNb 350
C----to time period lengths by months:	FUNb 360
READ(12,30)(COSTC(I,N),I=1,NPWLS)	FUNb 370
30 FORMAT(8G10.2)	FUNb 380
DO 100 I=1,NPWLS	FUNb 390
100 COSTC(I,N)=DISFAC*COSTC(I,N)	FUNb 400
GO TO 130	FUNb 410
C--Put constant pumping costs into costs vector and discount by time	FUNb 420
C---period:	FUNb 430
110 DO 120 I=1,NPWLS	FUNb 440
120 COSTC(I,N)=COSTF*DISFAC	FUNb 450
130 CONTINUE	FUNb 460
C--Read unit pumping rates used to obtain responses. Be sure that each	FUNb 470
C---unit rate corresponds to correct pumping well! Remember: NEGATIVE	FUNb 480
C---for pumping.	FUNb 490
DO 140 I=1,NPWLS	FUNb 500
140 READ(12,20)UNITQ(I)	FUNb 510
C--Scale cost coefficients according to unit pumping rates.	FUNb 520
	FUNb 530

DO 150 N=1,NPER	FUNb 540
DO 150 I=1,NPWLS	FUNb 550
150 COSTC(I,N)=COSTC(I,N)*(-UNITQ(I))	FUNb 560
C--Convert pumpage vector into two dimensional matrix:	FUNb 570
155 DO 160 I=1,NDWLS	FUNb 580
DO 160 N=1,NPER	FUNb 590
KPUMP=N+(I-1)*NPER	FUNb 600
Q(I,N)=X(KPUMP)	FUNb 610
160 CONTINUE	FUNb 620
C--Compute value of objective function.	FUNb 630
F=0.0	FUNb 640
DO 200 L=1,NPWLS	FUNb 650
REWIND 19	FUNb 660
IF(L.EQ.1)GO TO 163	FUNb 670
LSKIP=L-1	FUNb 680
DO 162 ISKIP=1,LSKIP	FUNb 690
162 READ(19,50)DUMMY	FUNb 700
163 DO 170 I=1,NDWLS	FUNb 710
DO 170 N=1,NPER	FUNb 720
IF(N.EQ.1 .AND. I.EQ.1)GO TO 170	FUNb 730
NSKIP=NRES-1	FUNb 740
DO 165 ISKIP=1,NSKIP	FUNb 750
165 READ(19,50)DUMMY	FUNb 760
170 READ(19,50)RBETA(I,N)	FUNb 770
50 FORMAT(20X,F15.7)	FUNb 780
FTEMP2=0.0	FUNb 790
DO 190 N=1,NPER	FUNb 800
FTEMP1=0.0	FUNb 810
DO 180 I=1,NDWLS	FUNb 820
DO 180 K=1,N	FUNb 830
KRES=N-K+1	FUNb 840
FTEMP1=FTEMP1+Q(I,K)*RBETA(I,KRES)	FUNb 850
180 CONTINUE	FUNb 860
FTEMP2=FTEMP2+(COSTC(L,N)*Q(L,N)*FTEMP1)	FUNb 870
190 CONTINUE	FUNb 880
F=F+FTEMP2	FUNb 890
200 CONTINUE	FUNb 900
C-Compute value of gradient at each decision (managed) well during each	FUNb 910
C---decision period.	FUNb 920
REWIND 19	FUNb 930
DO 230 IWL=1,NDWLS	FUNb 940
DO 210 N=1,NPER	FUNb 950
DO 210 I=1,NRES	FUNb 960
210 READ(19,50)RBETA(L,N)	FUNb 970
DO 230 IPER=1,NPER	FUNb 980
KG=IPER+(IWL-1)*NPER	FUNb 990
G(KG)=0.0	FUNb1000
DO 225 I=1,NDWLS	FUNb1010
DO 225 K=1,NPER	FUNb1020
IF(I.NE.IWL .OR. K.NE.IPER)GO TO 225	FUNb1030
DO 220 L=1,NPWLS	FUNb1040
DO 220 N=K,NPER	FUNb1050
KT=N-K+1	FUNb1060
G(KG)=G(KG)+(COSTC(L,N)*Q(L,N)*RBETA(L,KT))	FUNb1070

4	11	-10
6	6	-10

UNIT 14. input file

1234567890123456789012345678901234567890123456789012345678901234567890

LINE	SAMPLE	PROBLEM			
	7	17	2	1.5	4
	30.0				
	24.0	24.0			
	1				
	3	7	0.50	1	
	-0.005				
	-0.010				
	4	11	0.50		-1.0
	6	6	0.50		-1.0
	7	8	0.25		1.0
	7	9	0.25		1.0
	7	10	0.25		1.0
	7	11	0.25		1.0
	3	11			
	3	12			
	4	11	1		
	4	12			
	6	6	1		
	7	8	1		
	7	9	1		
	7	10	1		
	7	11	1		
	8	8		1	
	8	9		1	
	8	10		1	
	8	11		1	
	9	8		1	
	9	9		1	
	9	10		1	
	9	11		1	
	80.0	G			
	80.0	G			
	80.0	G			
	80.0	G			
	50.0	G			
	250.0	L			
	250.0	L			
	250.0	L			
	250.0	L			
	0				
	0				
	0				
	0				
	0				
	0				
	0				
	0				
	0				
	80.0	G			

80.0 G  
80.0 G  
80.0 G  
50.0 G  
250.0 L  
250.0 L  
250.0 L  
250.0 L  
0  
0  
0  
0  
0  
0  
0  
0

UNIT 13. input file

1234567890123456789012345678901234567890123456789012345678901234567890

8	8	9	8
8	9	9	9
8	10	9	10
8	11	9	11
28.5		0.01	G

UNIT 16. ouput

\*\*\*\*\*WARNING\*\*\* THE UNITQ VECTOR AS READ FROM UNIT 14 IS NOT UNIFORM,  
SO DIFFERENT UNIT STRESSES WILL BE APPLIED AT SOME WELLS.  
THE OBJECTIVE FUNCTION COEFFICIENTS IN THE MPS FILE WILL BE SCALED ACCORDINGLY.

UNIT 17. output

CONTROL LOCATIONS AND UNSTRESSED HEADS					
Period	Location #	I-Loc.	J-Loc.	Unmanaged Head	KEYWL
1	1	3	11	236.546565	0
2	1	3	12	236.446269	0
3	1	4	11	239.695702	1
4	1	4	12	235.842201	0
5	1	6	6	235.880777	1
6	1	7	8	242.667764	1
7	1	7	9	231.336352	1
8	1	7	10	228.216894	1
9	1	7	11	226.083924	1
10	1	8	8	222.510705	0
11	1	8	9	218.438309	0
12	1	8	10	215.595586	0

13	1	13	8	11	211.735532	0
14	1	14	9	8	200.000000	0
15	1	15	9	9	200.000000	0
16	1	16	9	10	200.000000	0
17	1	17	9	11	200.000000	0
18	2	1	3	11	253.715131	0
19	2	2	3	12	253.448525	0
20	2	3	4	11	262.752494	1
21	2	4	4	12	252.467227	0
22	2	5	6	6	252.636217	1
23	2	6	7	8	269.255351	1
24	2	7	7	9	247.825653	1
25	2	8	7	10	241.450164	1
26	2	9	7	11	237.517420	1
27	2	10	8	8	234.059561	0
28	2	11	8	9	226.531944	0
29	2	12	8	10	221.799685	0
30	2	13	8	11	216.178031	0
31	2	14	9	8	200.000000	0
32	2	15	9	9	200.000000	0
33	2	16	9	10	200.000000	0
34	2	17	9	11	200.000000	0

USER IMPOSED LIMITS ON HEAD AT CONTROL LOCATIONS

Period	Loc. #	I-Location	J-Location	Limit	Type	KEYGRD	KDEFHD
1	1	3	11	80.0	G	0	0
1	2	3	12	80.0	G	0	0
1	3	4	11	80.0	G	0	0
1	4	4	12	80.0	G	0	0
1	5	6	6	50.0	G	0	0
1	6	7	8	250.	L	0	0
1	7	7	9	250.	L	0	0
1	8	7	10	250.	L	0	0
1	9	7	11	250.	L	0	0
1	10	8	8	0.000		1	0
1	11	8	9	0.000		1	0
1	12	8	10	0.000		1	0
1	13	8	11	0.000		1	0
1	14	9	8	0.000		1	0
1	15	9	9	0.000		1	0
1	16	9	10	0.000		1	0
1	17	9	11	0.000		1	0
2	1	3	11	80.0	G	0	0
2	2	3	12	80.0	G	0	0
2	3	4	11	80.0	G	0	0
2	4	4	12	80.0	G	0	0
2	5	6	6	50.0	G	0	0
2	6	7	8	250.	L	0	0
2	7	7	9	250.	L	0	0
2	8	7	10	250.	L	0	0
2	9	7	11	250.	L	0	0
2	10	8	8	0.000		1	0
2	11	8	9	0.000		1	0

2	12	8	10	0.000	1	0
2	13	8	11	0.000	1	0
2	14	9	8	0.000	1	0
2	15	9	9	0.000	1	0
2	16	9	10	0.000	1	0
2	17	9	11	0.000	1	0

WELL LOCATIONS AND TYPE

Period	Loc. #	I-Loc.	J-Loc.	KEYQ	Fixed or Unit Rate
1	1	3	7	1	-.5000E-02
1	2	4	11	0	-1.000
1	3	6	6	0	-1.000
1	4	7	8	0	1.000
1	5	7	9	0	1.000
1	6	7	10	0	1.000
1	7	7	11	0	1.000
2	1	3	7	1	-.1000E-01
2	2	4	11	0	-1.000
2	3	6	6	0	-1.000
2	4	7	8	0	1.000
2	5	7	9	0	1.000
2	6	7	10	0	1.000
2	7	7	11	0	1.000

CONTROL PAIR LOCATIONS AND DEFINITIONS

Pair #	1st I-Loc.	1st J-Loc.	2nd I-Loc.	2nd J-Loc.	KDEFGR
1	8	8	9	8	0
2	8	9	9	9	0
3	8	10	9	10	0
4	8	11	9	11	0

USER IMPOSED LIMITS ON HEAD DIFFERENCE AT CONTROL PAIRS

Period	Pair #	Conversion Factor	Difference Limit	Type
1	1	28.5000	0.100000E-01	G
1	2	28.5000	0.100000E-01	G
1	3	28.5000	0.100000E-01	G
1	4	28.5000	0.100000E-01	G
2	1	28.5000	0.100000E-01	G
2	2	28.5000	0.100000E-01	G
2	3	28.5000	0.100000E-01	G
2	4	28.5000	0.100000E-01	G

UNIT 18. output -- The MPS file

NAME            SAMPLE PROBLEM

ROWS

L DIF01001  
 L DIF01002  
 L DIF01003  
 L DIF01004  
 L DIF02001  
 L DIF02002  
 L DIF02003  
 L DIF02004  
 L DR010001  
 L DR010002  
 L DR010003  
 L DR010004  
 L DR010005  
 G DR010006  
 G DR010007  
 G DR010008  
 G DR010009  
 L DR020001  
 L DR020002  
 L DR020003  
 L DR020004  
 L DR020005  
 G DR020006  
 G DR020007  
 G DR020008  
 G DR020009  
 N OBJ

COLUMNS

Q01001	OBJ	1.0000		
Q01001	DIF01001	0.81642E+01	DIF01002	0.13411E+02
Q01001	DIF01003	0.17481E+02	DIF01004	0.15720E+02
Q01001	DIF02001	0.77105E+01	DIF02002	0.81007E+01
Q01001	DIF02003	0.79189E+01	DIF02004	0.62541E+01
Q01001	DR010001	0.17992E+03	DR010002	0.15956E+03
Q01001	DR010003	0.99542E+01	DR010004	0.15561E+03
Q01001	DR010005	0.43191E+03	DR010006	0.66832E+01
Q01001	DR010007	0.14001E+02	DR010008	0.26553E+02
Q01001	DR010009	0.40146E+02		
Q01001	DR020001	0.28949E+02	DR020002	0.29659E+02
Q01001	DR020003	0.13823E+02	DR020004	0.28879E+02
Q01001	DR020005	0.28078E+02	DR020006	0.11768E+02
Q01001	DR020007	0.11951E+02	DR020008	0.14197E+02
Q01001	DR020009	0.15493E+02		
Q02001	OBJ	1.0000		
Q02001	DIF02001	0.81642E+01	DIF02002	0.13411E+02
Q02001	DIF02003	0.17481E+02	DIF02004	0.15720E+02
Q02001	DR020001	0.17992E+03	DR020002	0.15956E+03
Q02001	DR020003	0.99542E+01	DR020004	0.15561E+03
Q02001	DR020005	0.43191E+03	DR020006	0.66832E+01

Q02001	DR020007	0.14001E+02	DR020008	0.26553E+02
Q02001	DR020009	0.40146E+02		
Q01002	OBJ	1.0000		
Q01002	DIF01001	0.19372E+02	DIF01002	0.86257E+01
Q01002	DIF01003	0.45041E+01	DIF01004	0.26437E+01
Q01002	DIF02001	0.14814E+02	DIF02002	0.85608E+01
Q01002	DIF02003	0.55619E+01	DIF02004	0.36689E+01
Q01002	DR010001	0.67215E+01	DR010002	0.60359E+01
Q01002	DR010003	0.62028E+02	DR010004	0.59800E+01
Q01002	DR010005	0.66834E+01	DR010006	0.38717E+03
Q01002	DR010007	0.27418E+02	DR010008	0.13228E+02
Q01002	DR010009	0.76126E+01		
Q01002	DR020001	0.11981E+02	DR020002	0.11428E+02
Q01002	DR020003	0.37489E+02	DR020004	0.11225E+02
Q01002	DR020005	0.11769E+02	DR020006	0.39594E+02
Q01002	DR020007	0.20561E+02	DR020008	0.13456E+02
Q01002	DR020009	0.98090E+01		
Q02002	OBJ	1.0000		
Q02002	DIF02001	0.19372E+02	DIF02002	0.86257E+01
Q02002	DIF02003	0.45041E+01	DIF02004	0.26437E+01
Q02002	DR020001	0.67215E+01	DR020002	0.60359E+01
Q02002	DR020003	0.62028E+02	DR020004	0.59800E+01
Q02002	DR020005	0.66834E+01	DR020006	0.38717E+03
Q02002	DR020007	0.27418E+02	DR020008	0.13228E+02
Q02002	DR020009	0.76126E+01		
Q01003	OBJ	-1.0000		
Q01003	DIF01001	-0.31994E+02	DIF01002	-0.17166E+02
Q01003	DIF01003	-0.95931E+01	DIF01004	-0.57806E+01
Q01003	DIF02001	-0.91502E+01	DIF02002	-0.63330E+01
Q01003	DIF02003	-0.47126E+01	DIF02004	-0.33140E+01
Q01003	DR010001	-0.14011E+02	DR010002	-0.12973E+02
Q01003	DR010003	-0.28951E+02	DR010004	-0.12909E+02
Q01003	DR010005	-0.14001E+02	DR010006	-0.27417E+02
Q01003	DR010007	-0.21074E+03	DR010008	-0.28579E+02
Q01003	DR010009	-0.16479E+02		
Q01003	DR020001	-0.12223E+02	DR020002	-0.11970E+02
Q01003	DR020003	-0.20667E+02	DR020004	-0.11720E+02
Q01003	DR020005	-0.11950E+02	DR020006	-0.20561E+02
Q01003	DR020007	-0.13104E+02	DR020008	-0.10295E+02
Q01003	DR020009	-0.85876E+01		
Q02003	OBJ	-1.0000		
Q02003	DIF02001	-0.31994E+02	DIF02002	-0.17166E+02
Q02003	DIF02003	-0.95931E+01	DIF02004	-0.57806E+01
Q02003	DR020001	-0.14011E+02	DR020002	-0.12973E+02
Q02003	DR020003	-0.28951E+02	DR020004	-0.12909E+02
Q02003	DR020005	-0.14001E+02	DR020006	-0.27417E+02
Q02003	DR020007	-0.21074E+03	DR020008	-0.28579E+02
Q02003	DR020009	-0.16479E+02		
Q01004	OBJ	-1.0000		
Q01004	DIF01001	-0.17407E+02	DIF01002	-0.28650E+02
Q01004	DIF01003	-0.18668E+02	DIF01004	-0.11718E+02
Q01004	DIF02001	-0.69626E+01	DIF02002	-0.57777E+01
Q01004	DIF02003	-0.48619E+01	DIF02004	-0.36042E+01
Q01004	DR010001	-0.26331E+02	DR010002	-0.25115E+02

Q01004	DR010003	-0.15836E+02	DR010004	-0.25183E+02
Q01004	DR010005	-0.26553E+02	DR010006	-0.13228E+02
Q01004	DR010007	-0.28579E+02	DR010008	-0.20992E+03
Q01004	DR010009	-0.35396E+02		
Q01004	DR020001	-0.14571E+02	DR020002	-0.14561E+02
Q01004	DR020003	-0.14342E+02	DR020004	-0.14227E+02
Q01004	DR020005	-0.14201E+02	DR020006	-0.13455E+02
Q01004	DR020007	-0.10295E+02	DR020008	-0.96834E+01
Q01004	DR020009	-0.91080E+01		
Q02004	OBJ	-1.0000		
Q02004	DIF02001	-0.17407E+02	DIF02002	-0.28650E+02
Q02004	DIF02003	-0.18668E+02	DIF02004	-0.11718E+02
Q02004	DR020001	-0.26331E+02	DR020002	-0.25115E+02
Q02004	DR020003	-0.15836E+02	DR020004	-0.25183E+02
Q02004	DR020005	-0.26553E+02	DR020006	-0.13228E+02
Q02004	DR020007	-0.28579E+02	DR020008	-0.20992E+03
Q02004	DR020009	-0.35396E+02		
Q01005	OBJ	-1.0000		
Q01005	DIF01001	-0.10410E+02	DIF01002	-0.19316E+02
Q01005	DIF01003	-0.28980E+02	DIF01004	-0.20445E+02
Q01005	DIF02001	-0.56896E+01	DIF02002	-0.53342E+01
Q01005	DIF02003	-0.48657E+01	DIF02004	-0.37299E+01
Q01005	DR010001	-0.39102E+02	DR010002	-0.39148E+02
Q01005	DR010003	-0.96869E+01	DR010004	-0.39893E+02
Q01005	DR010005	-0.40147E+02	DR010006	-0.76122E+01
Q01005	DR010007	-0.16480E+02	DR010008	-0.35396E+02
Q01005	DR010009	-0.21464E+03		
Q01005	DR020001	-0.15928E+02	DR020002	-0.16135E+02
Q01005	DR020003	-0.10893E+02	DR020004	-0.15749E+02
Q01005	DR020005	-0.15498E+02	DR020006	-0.98091E+01
Q01005	DR020007	-0.85883E+01	DR020008	-0.91081E+01
Q01005	DR020009	-0.92744E+01		
Q02005	OBJ	-1.0000		
Q02005	DIF02001	-0.10410E+02	DIF02002	-0.19316E+02
Q02005	DIF02003	-0.28980E+02	DIF02004	-0.20445E+02
Q02005	DR020001	-0.39102E+02	DR020002	-0.39148E+02
Q02005	DR020003	-0.96869E+01	DR020004	-0.39893E+02
Q02005	DR020005	-0.40147E+02	DR020006	-0.76122E+01
Q02005	DR020007	-0.16480E+02	DR020008	-0.35396E+02
Q02005	DR020009	-0.21464E+03		
Q01006	OBJ	-1.0000		
Q01006	DIF01001	-0.77557E+01	DIF01002	-0.14700E+02
Q01006	DIF01003	-0.24083E+02	DIF01004	-0.26166E+02
Q01006	DIF02001	-0.50783E+01	DIF02002	-0.50368E+01
Q01006	DIF02003	-0.47606E+01	DIF02004	-0.37032E+01
Q01006	DR010001	-0.45348E+02	DR010002	-0.47645E+02
Q01006	DR010003	-0.73425E+01	DR010004	-0.49326E+02
Q01006	DR010005	-0.47098E+02	DR010006	-0.55942E+01
Q01006	DR010007	-0.12294E+02	DR010008	-0.25909E+02
Q01006	DR010009	-0.51208E+02		
Q01006	DR020001	-0.16210E+02	DR020002	-0.16521E+02
Q01006	DR020003	-0.93659E+01	DR020004	-0.16119E+02
Q01006	DR020005	-0.15761E+02	DR020006	-0.82578E+01
Q01006	DR020007	-0.77416E+01	DR020008	-0.86745E+01

Q01006	DR020009	-0.91486E+01		
Q02006	OBJ	-1.0000		
Q02006	DIF02001	-0.77557E+01	DIF02002	-0.14700E+02
Q02006	DIF02003	-0.24083E+02	DIF02004	-0.26166E+02
Q02006	DR020001	-0.45348E+02	DR020002	-0.47645E+02
Q02006	DR020003	-0.73425E+01	DR020004	-0.49326E+02
Q02006	DR020005	-0.47098E+02	DR020006	-0.55942E+01
Q02006	DR020007	-0.12294E+02	DR020008	-0.25909E+02
Q02006	DR020009	-0.51208E+02		
RHS				
RHS	DIF01001	0.22226E+02	DIF01002	0.18153E+02
RHS	DIF01003	0.15311E+02	DIF01004	0.11451E+02
RHS	DIF02001	0.33775E+02	DIF02002	0.26247E+02
RHS	DIF02003	0.21515E+02	DIF02004	0.15893E+02
RHS	DR010001	0.15655E+03	DR010002	0.15645E+03
RHS	DR010003	0.15970E+03	DR010004	0.15584E+03
RHS	DR010005	0.18588E+03	DR010006	-0.73322E+01
RHS	DR010007	-0.18664E+02	DR010008	-0.21783E+02
RHS	DR010009	-0.23916E+02		
RHS	DR020001	0.17372E+03	DR020002	0.17345E+03
RHS	DR020003	0.18275E+03	DR020004	0.17247E+03
RHS	DR020005	0.20264E+03	DR020006	0.19255E+02
RHS	DR020007	-0.21743E+01	DR020008	-0.85498E+01
RHS	DR020009	-0.12483E+02		
ENDATA				

The Modified MPS file

The MPS file above printed by AQMAN is modified for the sample problem to include a constraint that balances total pumping and injection (equation 45). Changes were performed by manually editing the file, and are indicated below in bold type.

NAME                   SAMPLE PROBLEM

ROWS

L DIF01001  
 L DIF01002  
 L DIF01003  
 L DIF01004  
 L DIF02001  
 L DIF02002  
 L DIF02003  
 L DIF02004  
 L DR010001  
 L DR010002  
 L DR010003  
 L DR010004  
 L DR010005  
 G DR010006  
 G DR010007  
 G DR010008  
 G DR010009  
 L DR020001  
 L DR020002  
 L DR020003  
 L DR020004  
 L DR020005  
 G DR020006  
 G DR020007  
 G DR020008  
 G DR020009  
 G BAL1  
 G BAL2  
 N OBJ

COLUMNS

Q01001	OBJ	1.0000	<b>BAL1</b>	<b>1.000</b>
Q01001	DIF01001	0.81642E+01	DIF01002	0.13411E+02
Q01001	DIF01003	0.17481E+02	DIF01004	0.15720E+02
Q01001	DIF02001	0.77105E+01	DIF02002	0.81007E+01
Q01001	DIF02003	0.79189E+01	DIF02004	0.62541E+01
Q01001	DR010001	0.17992E+03	DR010002	0.15956E+03
Q01001	DR010003	0.99542E+01	DR010004	0.15561E+03
Q01001	DR010005	0.43191E+03	DR010006	0.66832E+01
Q01001	DR010007	0.14001E+02	DR010008	0.26553E+02
Q01001	DR010009	0.40146E+02		
Q01001	DR020001	0.28949E+02	DR020002	0.29659E+02
Q01001	DR020003	0.13823E+02	DR020004	0.28879E+02
Q01001	DR020005	0.28078E+02	DR020006	0.11768E+02
Q01001	DR020007	0.11951E+02	DR020008	0.14197E+02

Q01001	DR020009	0.15493E+02		
Q02001	OBJ	1.0000	<b>BAL2</b>	<b>1.000</b>
Q02001	DIF02001	0.81642E+01	DIF02002	0.13411E+02
Q02001	DIF02003	0.17481E+02	DIF02004	0.15720E+02
Q02001	DR020001	0.17992E+03	DR020002	0.15956E+03
Q02001	DR020003	0.99542E+01	DR020004	0.15561E+03
Q02001	DR020005	0.43191E+03	DR020006	0.66832E+01
Q02001	DR020007	0.14001E+02	DR020008	0.26553E+02
Q02001	DR020009	0.40146E+02		
Q01002	OBJ	1.0000	<b>BAL1</b>	<b>1.000</b>
Q01002	DIF01001	0.19372E+02	DIF01002	0.86257E+01
Q01002	DIF01003	0.45041E+01	DIF01004	0.26437E+01
Q01002	DIF02001	0.14814E+02	DIF02002	0.85608E+01
Q01002	DIF02003	0.55619E+01	DIF02004	0.36689E+01
Q01002	DR010001	0.67215E+01	DR010002	0.60359E+01
Q01002	DR010003	0.62028E+02	DR010004	0.59800E+01
Q01002	DR010005	0.66834E+01	DR010006	0.38717E+03
Q01002	DR010007	0.27418E+02	DR010008	0.13228E+02
Q01002	DR010009	0.76126E+01		
Q01002	DR020001	0.11981E+02	DR020002	0.11428E+02
Q01002	DR020003	0.37489E+02	DR020004	0.11225E+02
Q01002	DR020005	0.11769E+02	DR020006	0.39594E+02
Q01002	DR020007	0.20561E+02	DR020008	0.13456E+02
Q01002	DR020009	0.98090E+01		
Q02002	OBJ	1.0000	<b>BAL2</b>	<b>1.000</b>
Q02002	DIF02001	0.19372E+02	DIF02002	0.86257E+01
Q02002	DIF02003	0.45041E+01	DIF02004	0.26437E+01
Q02002	DR020001	0.67215E+01	DR020002	0.60359E+01
Q02002	DR020003	0.62028E+02	DR020004	0.59800E+01
Q02002	DR020005	0.66834E+01	DR020006	0.38717E+03
Q02002	DR020007	0.27418E+02	DR020008	0.13228E+02
Q02002	DR020009	0.76126E+01		
Q01003	OBJ	-1.0000	<b>BAL1</b>	<b>-1.000</b>
Q01003	DIF01001	-0.31994E+02	DIF01002	-0.17166E+02
Q01003	DIF01003	-0.95931E+01	DIF01004	-0.57806E+01
Q01003	DIF02001	-0.91502E+01	DIF02002	-0.63330E+01
Q01003	DIF02003	-0.47126E+01	DIF02004	-0.33140E+01
Q01003	DR010001	-0.14011E+02	DR010002	-0.12973E+02
Q01003	DR010003	-0.28951E+02	DR010004	-0.12909E+02
Q01003	DR010005	-0.14001E+02	DR010006	-0.27417E+02
Q01003	DR010007	-0.21074E+03	DR010008	-0.28579E+02
Q01003	DR010009	-0.16479E+02		
Q01003	DR020001	-0.12223E+02	DR020002	-0.11970E+02
Q01003	DR020003	-0.20667E+02	DR020004	-0.11720E+02
Q01003	DR020005	-0.11950E+02	DR020006	-0.20561E+02
Q01003	DR020007	-0.13104E+02	DR020008	-0.10295E+02
Q01003	DR020009	-0.85876E+01		
Q02003	OBJ	-1.0000	<b>BAL2</b>	<b>-1.000</b>
Q02003	DIF02001	-0.31994E+02	DIF02002	-0.17166E+02
Q02003	DIF02003	-0.95931E+01	DIF02004	-0.57806E+01
Q02003	DR020001	-0.14011E+02	DR020002	-0.12973E+02
Q02003	DR020003	-0.28951E+02	DR020004	-0.12909E+02
Q02003	DR020005	-0.14001E+02	DR020006	-0.27417E+02
Q02003	DR020007	-0.21074E+03	DR020008	-0.28579E+02

Q02003	DR020009	-0.16479E+02		
Q01004	OBJ	-1.0000	<b>BAL1</b>	<b>-1.000</b>
Q01004	DIF01001	-0.17407E+02	DIF01002	-0.28650E+02
Q01004	DIF01003	-0.18668E+02	DIF01004	-0.11718E+02
Q01004	DIF02001	-0.69626E+01	DIF02002	-0.57777E+01
Q01004	DIF02003	-0.48619E+01	DIF02004	-0.36042E+01
Q01004	DR010001	-0.26331E+02	DR010002	-0.25115E+02
Q01004	DR010003	-0.15836E+02	DR010004	-0.25183E+02
Q01004	DR010005	-0.26553E+02	DR010006	-0.13228E+02
Q01004	DR010007	-0.28579E+02	DR010008	-0.20992E+03
Q01004	DR010009	-0.35396E+02		
Q01004	DR020001	-0.14571E+02	DR020002	-0.14561E+02
Q01004	DR020003	-0.14342E+02	DR020004	-0.14227E+02
Q01004	DR020005	-0.14201E+02	DR020006	-0.13455E+02
Q01004	DR020007	-0.10295E+02	DR020008	-0.96834E+01
Q01004	DR020009	-0.91080E+01		
Q02004	OBJ	-1.0000	<b>BAL2</b>	<b>-1.000</b>
Q02004	DIF02001	-0.17407E+02	DIF02002	-0.28650E+02
Q02004	DIF02003	-0.18668E+02	DIF02004	-0.11718E+02
Q02004	DR020001	-0.26331E+02	DR020002	-0.25115E+02
Q02004	DR020003	-0.15836E+02	DR020004	-0.25183E+02
Q02004	DR020005	-0.26553E+02	DR020006	-0.13228E+02
Q02004	DR020007	-0.28579E+02	DR020008	-0.20992E+03
Q02004	DR020009	-0.35396E+02		
Q01005	OBJ	-1.0000	<b>BAL1</b>	<b>-1.000</b>
Q01005	DIF01001	-0.10410E+02	DIF01002	-0.19316E+02
Q01005	DIF01003	-0.28980E+02	DIF01004	-0.20445E+02
Q01005	DIF02001	-0.56896E+01	DIF02002	-0.53342E+01
Q01005	DIF02003	-0.48657E+01	DIF02004	-0.37299E+01
Q01005	DR010001	-0.39102E+02	DR010002	-0.39148E+02
Q01005	DR010003	-0.96869E+01	DR010004	-0.39893E+02
Q01005	DR010005	-0.40147E+02	DR010006	-0.76122E+01
Q01005	DR010007	-0.16480E+02	DR010008	-0.35396E+02
Q01005	DR010009	-0.21464E+03		
Q01005	DR020001	-0.15928E+02	DR020002	-0.16135E+02
Q01005	DR020003	-0.10893E+02	DR020004	-0.15749E+02
Q01005	DR020005	-0.15498E+02	DR020006	-0.98091E+01
Q01005	DR020007	-0.85883E+01	DR020008	-0.91081E+01
Q01005	DR020009	-0.92744E+01		
Q02005	OBJ	-1.0000	<b>BAL2</b>	<b>-1.000</b>
Q02005	DIF02001	-0.10410E+02	DIF02002	-0.19316E+02
Q02005	DIF02003	-0.28980E+02	DIF02004	-0.20445E+02
Q02005	DR020001	-0.39102E+02	DR020002	-0.39148E+02
Q02005	DR020003	-0.96869E+01	DR020004	-0.39893E+02
Q02005	DR020005	-0.40147E+02	DR020006	-0.76122E+01
Q02005	DR020007	-0.16480E+02	DR020008	-0.35396E+02
Q02005	DR020009	-0.21464E+03		
Q01006	OBJ	-1.0000	<b>BAL1</b>	<b>-1.000</b>
Q01006	DIF01001	-0.77557E+01	DIF01002	-0.14700E+02
Q01006	DIF01003	-0.24083E+02	DIF01004	-0.26166E+02
Q01006	DIF02001	-0.50783E+01	DIF02002	-0.50368E+01
Q01006	DIF02003	-0.47606E+01	DIF02004	-0.37032E+01
Q01006	DR010001	-0.45348E+02	DR010002	-0.47645E+02
Q01006	DR010003	-0.73425E+01	DR010004	-0.49326E+02

Q01006	DR010005	-0.47098E+02	DR010006	-0.55942E+01
Q01006	DR010007	-0.12294E+02	DR010008	-0.25909E+02
Q01006	DR010009	-0.51208E+02		
Q01006	DR020001	-0.16210E+02	DR020002	-0.16521E+02
Q01006	DR020003	-0.93659E+01	DR020004	-0.16119E+02
Q01006	DR020005	-0.15761E+02	DR020006	-0.82578E+01
Q01006	DR020007	-0.77416E+01	DR020008	-0.86745E+01
Q01006	DR020009	-0.91486E+01		
Q02006	OBJ	-1.0000	BAL2	-1.000
Q02006	DIF02001	-0.77557E+01	DIF02002	-0.14700E+02
Q02006	DIF02003	-0.24083E+02	DIF02004	-0.26166E+02
Q02006	DR020001	-0.45348E+02	DR020002	-0.47645E+02
Q02006	DR020003	-0.73425E+01	DR020004	-0.49326E+02
Q02006	DR020005	-0.47098E+02	DR020006	-0.55942E+01
Q02006	DR020007	-0.12294E+02	DR020008	-0.25909E+02
Q02006	DR020009	-0.51208E+02		

RHS

RHS	DIF01001	0.22226E+02	DIF01002	0.18153E+02
RHS	DIF01003	0.15311E+02	DIF01004	0.11451E+02
RHS	DIF02001	0.33775E+02	DIF02002	0.26247E+02
RHS	DIF02003	0.21515E+02	DIF02004	0.15893E+02
RHS	DR010001	0.15655E+03	DR010002	0.15645E+03
RHS	DR010003	0.15970E+03	DR010004	0.15584E+03
RHS	DR010005	0.18588E+03	DR010006	-0.73322E+01
RHS	DR010007	-0.18664E+02	DR010008	-0.21783E+02
RHS	DR010009	-0.23916E+02		
RHS	DR020001	0.17372E+03	DR020002	0.17345E+03
RHS	DR020003	0.18275E+03	DR020004	0.17247E+03
RHS	DR020005	0.20264E+03	DR020006	0.19255E+02
RHS	DR020007	-0.21743E+01	DR020008	-0.85498E+01
RHS	DR020009	-0.12483E+02		
RHS	BAL1	0.0000	BAL2	0.0000

ENDATA

Optimal Solution: output from MINOS, using modified MPS file as input

MINOS --- VERSION 4.9 MAR 1983  
 - - - - -

SPECS FILE

-----

BEGIN SPECS FOR AWRA PROBLEM

MAXIMIZE  
 OBJECTIVE OBJ  
 RHS RHS  
 NONLINEAR VARIABLES 0  
 SUPERBASICS LIMIT 1  
 DERIVATIVE LEVEL 3  
 VERIFY LEVEL 1  
 MULTIPLE PRICE 1  
 ROWS 50  
 COLUMNS 100  
 ELEMENTS 5000  
 SCALE PRINT YES  
 FUNCTION PRECISION 1.0E-12  
 MPS FILE 9  
 OLD BASIS FILE 0  
 INSERT FILE 0  
 NEW BASIS FILE 55  
 PUNCH FILE 56  
 BACKUP FILE 57  
 SAVE FREQUENCY 10  
 SOLUTION YES  
 MAJOR ITERATIONS 10  
 ITERATIONS 101

END

1

PARAMETERS

-----

MPS INPUT DATA.

ROW LIMIT.....	50	LIST LIMIT.....	0	LOWER BOUND DEFAULT....	0.00E-01
COLUMN LIMIT.....	100	ERROR MESSAGE LIMIT....	10	UPPER BOUND DEFAULT....	1.00E+20
ELEMENTS LIMIT (COEFFS)	5000	PHANTOM ELEMENTS.....	0	AIJ TOLERANCE.....	1.00E-10

FILES.

MPS FILE (INPUT FILE)..	9	OLD BASIS FILE (MAP)...	0	(CARD READER).....	5
SOLUTION FILE.....	0	NEW BASIS FILE (MAP)...	55	(PRINTER).....	6
INSERT FILE.....	0	BACKUP BASIS FILE.....	57	(SCRATCH FILE).....	8
PUNCH FILE.....	56	LOAD FILE.....	0	DUMP FILE.....	0

FREQUENCIES.

LOG ITERATIONS.....	1	CHECK ROW ERROR.....	30	CYCLE LIMIT.....	1
SAVE NEW BASIS MAP....	10	FACTORIZE (INVERT)....	50	CYCLE TOLERANCE.....	0.00E-01

LP PARAMETERS.

ITERATIONS LIMIT.....	101	FEASIBILITY TOLERANCE..	1.00E-06	PARTIAL PRICE FACTOR...	1
CRASH OPTION.....	1	OPTIMALITY TOLERANCE...	1.00E-06	MULTIPLE PRICE.....	1
WEIGHT ON OBJECTIVE....	0.00E-01	PIVOT TOLERANCE.....	3.67E-11	SCALE TOLERANCE.....	0.90

NONLINEAR PROBLEMS.

NONLINEAR CONSTRAINTS..	0	HESSIAN DIMENSION.....	0	FUNCTION PRECISION.....	1.00E-12
NONLINEAR JACOBIAN VARS	0	SUPERBASICS LIMIT.....	1	DIFFERENCE INTERVAL....	1.00E-06
NONLINEAR OBJECTIV VARS	0	TRUNCATED CG METHOD....	1	CENTRAL DIFFCE INTERVAL	1.00E-04
PROBLEM NUMBER.....	0	LINESEARCH TOLERANCE...	0.10000	DERIVATIVE LEVEL.....	3
UNBOUNDED OBJECTV VALUE	1.00E+20	SUBSPACE TOLERANCE.....	0.20000	VERIFY LEVEL.....	1
UNBOUNDED STEP SIZE....	1.00E+10			EMERGENCY VERIFY LEVEL..	1

AUGMENTED LAGRANGIAN.

JACOBIAN.....	SPARSE	MAJOR ITERATIONS LIMIT.	10	RADIUS OF CONVERGENCE..	1.00E-02
LAGRANGIAN.....	YES	MINOR ITERATIONS LIMIT.	40	ROW TOLERANCE.....	1.00E-06
PENALTY PARAMETER.....	0.00E-01	COMPLETION.....	FULL	PRINT LEVEL..(JFLXI)...	1
DAMPING PARAMETER.....	2.00E+00				

MISCELLANEOUS.

LU FACTOR TOLERANCE....	0.100000	WORKSPACE (USER).....	0	DEBUG LEVEL.....	0
LU UPDATE TOLERANCE....	0.100000	WORKSPACE (TOTAL).....	200000	LINESEARCH DEBUG AFTER.	999999

REASONABLE WORKSPACE LIMITS ARE 0 ... 7917 ... 200000 WORDS  
 ACTUAL WORKSPACE LIMITS ARE 0 ... 200000 ... 200000 WORDS

1

MPS FILE

-----

1	NAME	SAMPLE P
2	ROWS	
32	COLUMNS	
171	RHS	
187	ENDATA	

NAMES SELECTED

-----

OBJECTIVE	OBJ	(MAX)	1
RHS	RHS		26
RANGES			0
BOUNDS			0

MATRIX STATISTICS

-----

	TOTAL	NORMAL	FREE	FIXED	BOUNDED
ROWS	29	2	1	0	26
COLUMNS	12	12	0	0	0

NO. OF MATRIX ELEMENTS	258	DENSITY	74.138
NO. OF REJECTED COEFFS	0	AIJTOL	1.00000E-10
BIGGEST AND SMALLEST COEFFS	4.31910E+02	1.00000E+00	(EXCLUDING OBJ AND RHS)

LENGTH OF ROW-NAME HASH TABLE 101  
 COLLISIONS DURING TABLE LOOKUP 125

NONZEROS ALLOWED FOR IN LU FACTORS 132700

1  
 ITERATIONS

-----  
 1

SCALING  
 -----

	MIN ELEM	MAX ELEM	MAX COL RATIO
AFTER 0	1.00E+00	4.32E+02	431.91
AFTER 1	1.22E-01	8.18E+00	66.91
AFTER 2	1.28E-01	7.82E+00	61.22

ROW SCALES R(I) (SCALED AIJ) = (ORIGINAL AIJ) \* R(I) / C(J)

-----

1	0.06204	2	0.06237	3	0.07594	4	0.09511	5	0.07806
6	0.08538	7	0.07594	8	0.09511	9	0.03008	10	0.03371
11	0.04207	12	0.03429	13	0.01947	14	0.02055	15	0.01846
16	0.01861	17	0.02409	18	0.03008	19	0.03371	20	0.04570
21	0.03429	22	0.01947	23	0.02055	24	0.02477	25	0.02414
26	0.02409	27	0.81297	28	0.85375	29	1.00000		

COLUMN SCALES C(J)

-----

1	1.07463	2	1.07463	3	1.01703	4	1.01703	5	0.89464
6	1.19301	7	0.92330	8	1.17375	9	0.89943	10	0.89943
11	0.53492	12	0.53492						

CRASH OPTION 1

FREE ROWS 1 FREE COLS 0 PASS2 (E ROWS) 0 PASS3 2 REMAINDER 26

FACTORIZE	1	DEMAND	0	ITERATION	0	INFEAS	1	OBJECTV	0.000000000E-01
SLACKS	27	LINEAR	2	NONLINEAR	0	ELEMS	70	DENSITY	8.32
LROW	70	LCOL	70	LENL	0	LENU	70	INCRSE	0.00
COMPRSSNS	0	MERIT	0.0	LMAX	0.0	UMAX	7.8E+00	GROWTH	1.0
ITN	0	-- INFEASIBLE.		NUM =	1	SUM =	2.889086878E-01		

ITN	PH	PP	NOPT	DJ,RG	+SBS	-SBS	-BS	STEP	PIVOT	L	U	NCP	NINF	SINF,OBJECTIVE
1	1	1	4	-7.7E+00	4	4	2	0.0E-01	1.1E+00	0	70	0	1	2.88908688E-01
2	1	1	6	-1.5E+01	12	12	35	2.0E-02	1.5E+01	0	70	0	1	2.88908688E-01

ITN 2 -- FEASIBLE SOLUTION. OBJECTIVE = 4.303674377E-01

3	2	1	2	1.2E+00	40	40	12	3.1E-02	-6.4E-01	1	83	0	0	4.66674543E-01
4	2	1	3	-9.1E-01	2	2	34	4.7E-01	7.8E+00	1	70	0	0	8.99770302E-01
5	2	1	2	-8.4E-01	3	3	4	2.9E-01	1.0E-01	3	83	0	0	1.14072090E+00
6	2	1	1	1.2E+00	35	35	13	5.6E-01	-1.5E+00	6	95	0	0	1.80320632E+00
7	2	1	2	-9.7E-01	4	4	17	6.7E-01	1.5E+00	7	95	0	0	2.45069218E+00
8	2	1	1	-5.5E-01	6	6	36	3.7E-01	-3.4E+00	9	107	0	0	2.65296004E+00

BIGGEST DJ = -5.675E-02 (VARIABLE 25) NORM RG = 0.000E-01 NORM PI = 1.000E+00

1

EXIT -- OPTIMAL SOLUTION FOUND.

NO. OF ITERATIONS 8 OBJECTIVE VALUE 2.6529600365290E+00

NORM OF X 1.135E+01 NORM OF PI 1.000E+00

BASIS MAP SAVED ON FILE 55 ITN = 8

BASIS PUNCHED ON FILE 56

1

PROBLEM NAME SAMPLE P OBJECTIVE VALUE 2.6529600365E+00

STATUS OPTIMAL SOLN ITERATION 8 SUPERBASICS 0

OBJECTIVE OBJ (MAX)

RHS RHS

RANGES

BOUNDS

SECTION 1 - ROWS

NUMBER	...ROW..	STATE	...ACTIVITY...	SLACK ACTIVITY	..LOWER LIMIT.	..UPPER LIMIT.	..DUAL ACTIVITY	..I
13	DIF01001	UL	22.22600	0.00000	NONE	22.22600	-0.01098	1
14	DIF01002	BS	13.95642	4.19658	NONE	18.15300	0.00000	2
15	DIF01003	BS	11.63903	3.67197	NONE	15.31100	0.00000	3
16	DIF01004	BS	9.09877	2.35223	NONE	11.45100	0.00000	4
17	DIF02001	UL	33.77500	0.00000	NONE	33.77500	-0.05676	5
18	DIF02002	BS	21.97972	4.26728	NONE	26.24700	0.00000	6
19	DIF02003	BS	18.14874	3.36626	NONE	21.51500	0.00000	7
20	DIF02004	BS	13.89158	2.00142	NONE	15.89300	0.00000	8
21	HD010001	BS	81.25627	75.29373	NONE	156.55000	0.00000	9
22	HD010002	BS	72.13254	84.31746	NONE	156.45000	0.00000	10
23	HD010003	BS	64.44569	95.25431	NONE	159.70000	0.00000	11
24	HD010004	BS	70.43819	85.40181	NONE	155.84000	0.00000	12
25	HD010005	UL	185.88000	0.00000	NONE	185.88000	-0.00110	13
26	HD010006	BS	379.23743	-386.56963	-7.33220	NONE	0.00000	14
27	HD010007	BS	32.47382	-51.13782	-18.66400	NONE	0.00000	15
28	HD010008	BS	23.88915	-45.67215	-21.78300	NONE	0.00000	16
29	HD010009	BS	24.07354	-47.98954	-23.91600	NONE	0.00000	17
30	HD020001	BS	100.56284	73.15716	NONE	173.72000	0.00000	18
31	HD020002	BS	91.53432	81.91568	NONE	173.45000	0.00000	19
32	HD020003	BS	114.61925	68.13075	NONE	182.75000	0.00000	20
33	HD020004	BS	89.35787	83.11213	NONE	172.47000	0.00000	21
34	HD020005	UL	202.64000	0.00000	NONE	202.64000	-0.00137	22

35	HD020006	BS	489.62079	-470.36579	19.25500	NONE	0.00000	23
36	HD020007	LL	-2.17430	0.00000	-2.17430	NONE	0.00396	24
37	HD020008	BS	36.51745	-45.06725	-8.54980	NONE	0.00000	25
38	HD020009	BS	36.18865	-48.67165	-12.48300	NONE	0.00000	26
39	BAL1	BS	1.38768	-1.38768	0.00000	NONE	0.00000	27
40	BAL2	BS	1.26528	-1.26528	0.00000	NONE	0.00000	28
41	OBJ	BS	2.65296	-2.65296	NONE	NONE	1.00000	29

1

SECTION 2 - COLUMNS

NUMBER	.COLUMN.	STATE	...ACTIVITY...	.OBJ GRADIENT.	..LOWER LIMIT.	..UPPER LIMIT.	REDUCED GRADNT	M+J
1	Q01001	BS	0.41534	1.00000	0.00000	NONE	0.00000	30
2	Q02001	BS	0.40750	1.00000	0.00000	NONE	0.00000	31
3	Q01002	BS	0.97234	1.00000	0.00000	NONE	0.00000	32
4	Q02002	BS	1.16626	1.00000	0.00000	NONE	0.00000	33
5	Q01003	LL	0.00000	-1.00000	0.00000	NONE	-0.15368	34
6	Q02003	BS	0.30847	-1.00000	0.00000	NONE	0.00000	35
7	Q01004	LL	0.00000	-1.00000	0.00000	NONE	-0.40999	36
8	Q02004	LL	0.00000	-1.00000	0.00000	NONE	-0.08884	37
9	Q01005	LL	0.00000	-1.00000	0.00000	NONE	-0.53557	38
10	Q02005	LL	0.00000	-1.00000	0.00000	NONE	-0.41940	39
11	Q01006	LL	0.00000	-1.00000	0.00000	NONE	-0.58801	40
12	Q02006	LL	0.00000	-1.00000	0.00000	NONE	-0.54392	41

ENDRUN

## APPENDIX V -- AQMAN PROGRAM LISTING

Modifications to subroutines that were originally part of the Trescott code include conversion to FORTRAN-77 and the specification of all variables as double precision. All other changes are denoted within the code with a "\$" in column 73.

### \*\*NOTE:

Before executing AQMAN, make sure that the management problem does not require more CPU storage than is currently allocated by the specification statements at the start of each added AQMAN subroutine. It may be necessary to increase the size of arrays in the following COMMON blocks: RESP, WELLS, DIFFS, DEF, LOCATS, STRESS, PARAMS, TYF GRINFO, QUAD1. The user may also need to increase the size of the arrays HD and Q.

C		AQM	20	
C	*****	AQM	30	
C	A Q M A N	*	AQM	40
C	COMPUTER CODE FOR AQUIFER MANAGEMENT PROBLEMS	*	AQM	50
C		*	AQM	60
C	BY S.M.GORELICK AND L.J.LEFKOFF	*	AQM	70
C	U.S. GEOLOGICAL SURVEY	*	AQM	80
C	OCTOBER, 1986	*	AQM	90
C	*****	AQM	100	
C		AQM	110	
C	C---Check Dimensions!!!! Current limits are:	AQM	120	
C	C---- NWLS = no. of wells = 200,	AQM	130	
C	C---- NCNTR = no. of control nodes = 500,	AQM	140	
C	C---- NNPER = no. of pumping periods = 50,	AQM	150	
C	C---- NGRAD = no. of control pairs = 400,	AQM	160	
C	C---- NNPER*NWLS = 2000	AQM	170	
C	C---- NNPER*NCNTR = 2500	AQM	180	
C	C---- NNPER*NGRAD = 1000	AQM	190	
C	C---List of dimensioned variables with their minimum size:	AQM	200	
C	C  HD(NNPER*NCNTR) = solved heads	AQM	210	
C	C  Q(NNPER*NWLS) = stresses	AQM	220	
C	C  HDUS(NNPER*NCNTR) = unstressed heads	AQM	230	
C	C  CONHD(NNPER*NCNTR) = user's limits on head	AQM	240	
C	C  DRDRES(NNPER*NCNTR) = drawdown responses	AQM	250	
C	C  MNGDRD(NNPER*NCNTR) = manageable drawdown	AQM	260	
C	C  UNITQ(NWLS) = unit stresses	AQM	270	
C	C  FIXQ(NWLS,NNPER) = fixed stress at non-decision wells	AQM	280	
C	C  KEYGRD(NGRAD) = key for gradient/velocity only	AQM	290	
C	C  GRADE(NNPER*NGRAD) = manageable difference-in-drawdown	AQM	300	
C	C  RDIF(NNPER*NGRAD) = difference-in-drawdown response	AQM	310	
C	C  KDEFHD(NCNTR) = key for head definition	AQM	320	
C	C  KDEFGR(NGRAD) = key for gradient or velocity definition	AQM	330	
C	C  ILOCW(NWLS) = I-location of wells	AQM	340	
C	C  JLOCW(NWLS) = J-location of wells	AQM	350	
C	C  ILOCC(NCNTR) = I-location of control points	AQM	360	
C	C  JLOCC(NCNTR) = J-location of control points	AQM	370	
C	C  KEYQ(NWLS) = key for non-decision wells	AQM	380	
C	C  KEYWL(NCNTR) = key for well at control location	AQM	390	
C	C  XRAD(NWLS) = well radius	AQM	400	
C	C  QWELL(NNPER*NWLS) = stress at wells	AQM	410	
C	C  XHEAD(NNPER*NCNTR) = solved heads	AQM	420	
C	C  TIMINC(NNPER) = length of initial times steps	AQM	430	
C	C  CONTYP(NNPER*NCNTR) = type of constraint on head	AQM	440	
C	C  GRATYP(NNPER*NGRAD) = type of constraint on gradient or velocity	AQM	450	
C	C  SURF(NWLS) = land surface elevation at wells	AQM	460	
C	C  COSTC(NWLS,NNPER) = unit pumping cost	AQM	470	
C	C--The remaining variables appear only in Subroutine GRADS:	AQM	480	
C	C  GFACT(NNPER*NGRAD) = conversion factor for gradient or velocity	AQM	490	
C	C  GCON(NNPER*NGRAD) = user's constaint on gradient or velocity	AQM	500	
C	C  ILOCG1(NGRAD) = I-location of first half of control pair	AQM	510	
C	C  JLOCG1(NGRAD) = J-location of first half of control pair	AQM	520	
C	C  ILOCG2(NGRAD) = I-location of second half of control pair	AQM	530	
C	C  JLOCG2(NGRAD) = J-location of second half of control pair	AQM	540	

C	KEEP1(NNPER*NGRAD) = vector pointer within DRDRES	AQM 550
C	KEEP2(NNPER*NGRAD) = vector pointer within DRDRES	AQM 560
C		AQM 570
C	--Main program to generate LINEAR responses to unit pumping or	AQM 580
C	----injection stresses.	AQM 590
	IMPLICIT REAL *8 (A-H,O-Z)	AQM 600
	REAL *8 MNGDRD	AQM 610
	INTEGER *4 CASE,TYPE,NNAME	AQM 620
	CHARACTER *1 CONTYP,GRATYP	AQM 630
	DIMENSION HD(2500),TYPE(4)	AQM 640
	COMMON /RESP/ HDUS(2500),CONHD(2500),DRDRES(2500),MNGDRD(2500)	AQM 650
	COMMON /WELLS/ UNITQ(200),FIXQ(200,50)	AQM 660
	COMMON /DIFFS/ NGRAD,KEYGRD(400),GRADE(1000),RDIF(1000)	AQM 670
	COMMON /DEF/ KDEFHD(500),KDEFGR(400)	AQM 680
	COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),	AQM 690
	& KEYQ(200),KEYWL(500),XRAD(200)	AQM 700
	COMMON /STRESS/ QWELL(2000),XHEAD(2500)	AQM 710
	COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,	AQM 720
	& TIMINC(50)	AQM 730
	COMMON /TYP/ CONTYP(2500),GRATYP(1000)	AQM 740
	COMMON /ALPHAS/ NNAME(16),CASE	AQM 750
	DATA TYPE/'LINE','NONL','LINE','QUAD'/	AQM 760
C	--Call PRE to compute transient, unmanaged (unstressed) heads:	AQM 770
	CALL PRE(1,Q,HD)	AQM 780
C	--Store unstressed (includes boundary conditions and fixed wells)	AQM 790
C	---head vector:	AQM 800
	NPER=NNPER	AQM 810
	WRITE(17,3)	AQM 820
	3 FORMAT(/19X,'CONTROL LOCATIONS AND UNSTRESSED HEADS'/6X,'Period',	AQM 830
	& 3x,'Location # I-Loc. J-Loc. Unmanaged Head KEYWL')	AQM 840
	DO 100 N=1,NNPER	AQM 850
	DO 100 I=1,NCNTR	AQM 860
	K=(N-1)*NCNTR+I	AQM 870
	HDUS(K)=HD(K)	AQM 880
	WRITE(17,5)K,N,I,ILOCC(I),JLOCC(I),HDUS(K),KEYWL(I)	AQM 890
	5 FORMAT(I5,I5,5X,I5,5X,I5,5X,I5,G20.9,I5)	AQM 900
	100 CONTINUE	AQM 910
C	--If the management problem contains a quadratic objective function,	AQM 920
C	---call QUAD to compute the cost coefficients for linear part of	AQM 930
C	---objective:	AQM 940
	IF(CASE.EQ.TYPE(4)) CALL QUAD	AQM 950
C	--Read user's desired limit on head and type of constraint at	AQM 960
C	---each control location for all pumping periods:	AQM 970
	WRITE(17,15)	AQM 980
	15 FORMAT(/10X,'USER IMPOSED LIMITS ON HEAD AT CONTROL LOCATIONS'/,	AQM 990
	&3X,'Period',4X,'Loc. # I-Location J-Location ',4x,'Limit',	AQM1000
	&6X,'Type KEYGRD KDEFHD')	AQM1010
	DO 200 N=1,NPER	AQM1020
	DO 210 I=1,NCNTR	AQM1030
	K=(N-1)*NCNTR+I	AQM1040
	READ(14,20)CONHD(K),CONTYP(K)	AQM1050
20	FORMAT(G10.0,4X,A1)	AQM1060
	IF(KDEFHD(I).EQ.0)WRITE(17,25)N,I,ILOCC(I),JLOCC(I),CONHD(K),	AQM1070
	& CONTYP(K),KEYGRD(I),KDEFHD(I)	AQM1080

```

        IF(KDEFHD(I).NE.0)WRITE(17,26)N,I,ILOCC(I),JLOCC(I),CONHD(K), AQM1090
    &   KEYGRD(I),KDEFHD(I) AQM1100
    25   FORMAT(3X,I3,7X,I4,5X,I5,5X,I5,5X,G15.3,4X,A1,4X,I2,6X,I2) AQM1110
    26   FORMAT(3X,I3,7X,I4,5X,I5,5X,I5,5X,G15.3,4X,'E',4X,I2,6X,I2) AQM1120
    210  CONTINUE AQM1130
    200  CONTINUE AQM1140
C--Write well information: AQM1150
    WRITE(17,30) AQM1160
    30   FORMAT(/18X,'WELL LOCATIONS AND TYPE'/2X,'Period   Loc. #',4x, AQM1170
    &   'I-Loc.   J-Loc.   KEYQ   Fixed or Unit Rate') AQM1180
    DO 220 N=1,NNPER AQM1190
    DO 220 I=1,NWLS AQM1200
        IF(KEYQ(I).EQ.1)WRITE(17,35)N,I,ILOCW(I),JLOCW(I),KEYQ(I), AQM1210
    &   FIXQ(I,N) AQM1220
        IF(KEYQ(I).NE.1)WRITE(17,35)N,I,ILOCW(I),JLOCW(I),KEYQ(I), AQM1230
    &   UNITQ(I) AQM1240
    35   FORMAT(5(I5,5x),G10.4) AQM1250
    220  CONTINUE AQM1260
C--Compute the available manageable drawdown at each control location AQM1270
C---for all periods by subtracting the desired limits on heads AQM1280
C---from the un-stressed heads. AQM1290
        LENGTH=NPEN*NCNTR AQM1300
    DO 250 K=1,LENGTH AQM1310
        MNGDRD(K)=HDUS(K)-CONHD(K) AQM1320
    250  CONTINUE AQM1330
C--If gradient controls are included, Call GRADS to adjust right- AQM1340
C---hand-sides of gradient constraints by unstressed heads: AQM1350
        IF(NGRAD.NE.0) CALL GRADS(1) AQM1360
C--Call PRE to get the unit response for each managed well. Then AQM1370
C---subtract this from the unstressed heads to obtain the drawdown AQM1380
C---response vector, which is passed to MPSFMT: AQM1390
        KCALL=1 AQM1400
        KMPS=0 AQM1410
        DO 300 IWLS=1,NWLS AQM1420
            KCALL=KCALL+1 AQM1430
C--If the well is an unmanaged (fixed) well, do not call PRE, do AQM1440
C---not store drawdown responses in the DRDRES vector, and do not AQM1450
C---call MPSFMT: AQM1460
            IF(KEYQ(IWLS).EQ.1)GO TO 320 AQM1470
            CALL PRE(KCALL,Q,HD) AQM1480
            DO 310 K=1,LENGTH AQM1490
                DRDRES(K)=HDUS(K)-HD(K) AQM1500
    310  CONTINUE AQM1510
            IF (NGRAD.NE.0) CALL GRADS(2) AQM1520
            KMPS=KMPS+1 AQM1530
            CALL MPSFMT(KMPS,IWLS,1) AQM1540
C--After PRE and MPSFMT have been called for the last well, call MPSFMT AQM1550
C----again to construct Right-Hand Side (RHS) of constraints: AQM1560
    320  IF(IWLS.EQ.NWLS)CALL MPSFMT(KMPS,IWLS,2) AQM1570
    300  CONTINUE AQM1580
C AQM1590
        STOP AQM1600
        END AQM1610
C-----

```

C--AQMAN's Main enters here. (For non-linear problem, optimization	PRE 10
C---code enters here; this in future versions of AQMAN).	PRE 20
C	PRE 30
C--- *** Check Dimensions!! Current limits are listed at start of	PRE 40
C----- main program.	PRE 50
C	PRE 60
SUBROUTINE PRE(KCALL,Q,HD)	PRE 70
IMPLICIT REAL *8 (A-H,O-Z)	PRE 80
INTEGER *4 CASE,TYPE,NNAME	PRE 90
CHARACTER *1 CONTYP,GRATYP	PRE 100
DIMENSION HD(2500),Q(2000),TYPE(4)	PRE 110
COMMON /WELLS/ UNITQ(200),FIXQ(200,50)	PRE 120
COMMON /DIFFS/ NGRAD,KEYGRD(400),GRADE(1000),RDIF(1000)	PRE 130
COMMON /DEF/ KDEFHD(500),KDEFGR(400)	PRE 140
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),	PRE 150
& KEYQ(200),KEYWL(500),XRAD(200)	PRE 160
COMMON /STRESS/ QWELL(2000),XHEAD(2500)	PRE 170
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,	PRE 180
& TIMINC(50)	PRE 190
COMMON /TYP/ CONTYP(2500),GRATYP(1000)	PRE 200
COMMON /ALPHAS/ NNAME(16),CASE	PRE 210
DATA TYPE/'LINE','NONL','LINE','QUAD'/	PRE 220
C--Read data from Unit 14 if this is first call of PRE.	PRE 230
IF(KCALL.NE.1)GO TO 200	PRE 240
READ(14,5)CASE,NNAME	PRE 250
5 FORMAT(A4,2X,16A4)	PRE 260
100 CONTINUE	PRE 270
C--Check that CASE has been correctly entered:	PRE 280
IF(CASE.EQ.TYPE(3).OR.CASE.EQ.TYPE(4))GO TO 101	PRE 290
WRITE(16,12)	PRE 300
12 FORMAT(/2X,'PROGRAM TERMINATED BY SUBROUTINE PRE--CASE INCORRECTLY	PRE 310
1 ENTERED'/)	PRE 320
STOP	PRE 330
101 CONTINUE	PRE 340
C--Read pumping period data:	PRE 350
READ(14,15)NWLS,NCNTR,NNPER,CDELTA,NGRAD	PRE 360
15 FORMAT(3I10,F10.0,I10)	PRE 370
READ(14,20)TIMPER	PRE 380
READ(14,20)(TIMINC(N),N=1,NNPER)	PRE 390
20 FORMAT(8G10.0)	PRE 400
C--Read data on wells.	PRE 410
IKEYQ=0	PRE 420
DO 150 I=1,NWLS	PRE 430
C---Read the number of fixed (unmanaged) wells.	PRE 440
120 IF(I.EQ.1)READ(14,30)NKEYQ	PRE 450
30 FORMAT(I10,F10.0)	PRE 460
C---For each well, read location, radius, KEYQ and UNITQ.	PRE 470
C----If KEYQ(I) equals 0 or 2, I is a managed well.	PRE 480
C----If KEYQ(I) equals 1, I is an unmanaged (fixed) well.	PRE 490
C----UNITQ(I) is the unit stress applied to (managed) well I.	PRE 500
C----A positive value for UNITQ indicates recharge; negative UINTQ	PRE 510
C----indicates a pumping well.	PRE 520
C-****WARNING**** Use care if UNITQ varies with I: Objective function	PRE 530
C---coefficients of MPS file will be scaled to compensate for variable	PRE 540

```

C---stresses. Remember this when interpreting optimization results. PRE 550
    READ(14,25)ILOCW(I),JLOCW(I),XRAD(I),KEYQ(I),UNITQ(I) PRE 560
25  FORMAT(2I10,F10.0,I10,F10.0) PRE 570
    IF(KEYQ(I).EQ.0 .OR. KEYQ(I).EQ.2)GO TO 150 PRE 580
    IKEYQ=IKEYQ+1 PRE 590
    DO 130 N=1,NNPER PRE 600
130  READ(14,35)FIXQ(I,N) PRE 610
    35  FORMAT(G10.0) PRE 620
150  CONTINUE PRE 630
C--Check for non-uniform unit stresses PRE 640
    ISW=0 PRE 650
    DO 160 I=1,NWLS PRE 660
    IF(KEYQ(I).EQ.1)GO TO 160 PRE 670
    ISW=ISW+1 PRE 680
    USW2=UNITQ(I) PRE 690
    IF(ISW.EQ.1)GO TO 155 PRE 700
    IF(USW2.NE.USW1)WRITE(16,32) PRE 710
32  FORMAT(//2X,'*****WARNING*** THE UNITQ VECTOR AS READ FROM UNIT PRE 720
114 IS NOT UNIFORM, '/' SO DIFFERENT UNIT STRESSES WILL BE APPLIED PRE 730
2  AT SOME WELLS. '/1X,'THE OBJECTIVE FUNCTION COEFFICIENTS IN THE MPPRE 740
3S FILE WILL BE SCALED ACCORDINGLY.') PRE 750
155  USW1=UNITQ(I) PRE 760
160  CONTINUE PRE 770
C--Check data on unmanaged wells: PRE 780
    IF(IKEYQ.EQ.NKEYQ)go to 170 PRE 790
    WRITE(16,40)IKEYQ,NKEYQ PRE 800
40  FORMAT(/2X,'PROGRAM TERMINATED BY SUBROUTINE PRE--'/2X,'THE NUMBERPRE 810
1  OF UNIT KEYQ's','I3,' ,DOES NOT EQUAL NKEYQ','I3/) PRE 820
    STOP PRE 830
170  CONTINUE PRE 840
C--Read data on control locations. PRE 850
    DO 180 I=1,NCNTR PRE 860
    READ(14,45)ILOCC(I),JLOCC(I),KEYWL(I),KEYGRD(I),KDEFHD(I) PRE 870
45  FORMAT(5I10) PRE 880
180  CONTINUE PRE 890
200  CONTINUE PRE 900
C--Compute QWELL (pumpage and injection rates) vector: PRE 910
    IUNIT=KCALL-1 PRE 920
    IF(KCALL.NE.1.AND.KEYQ(IUNIT).EQ.1)WRITE(16,50)IUNIT PRE 930
50  FORMAT(/2X,'WARNING--PRE HAS BEEN CALLED BY AQMAN FOR A NON-DECISPRE 940
1  ION WELL, WELL NUMBER',I4/) PRE 950
205  DO 210 N=1,NNPER PRE 960
    DO 210 I=1,NWLS PRE 970
    IN=(N-1)*NWLS+I PRE 980
    QWELL(IN)=0.0 PRE 990
    IF(KEYQ(I).EQ.1)QWELL(IN)=FIXQ(I,N) PRE1000
C--No unit stresses applied on unstressed or steay-state runs or in PRE1010
C---non-first periods. PRE1020
    IF(KCALL.LE.1 .OR. N.NE.1)GO TO 210 PRE1030
C--Enter unit stress into pumpage/injection vector. PRE1040
    IF(I.EQ.IUNIT)QWELL(IUNIT)=UNITQ(I) PRE1050
210  CONTINUE PRE1060
240  CONTINUE PRE1070
C--Initialize KPER: PRE1080

```

KPER=1	PRE1090
C--Call the TRESMOTT:	PRE1100
CALL TRES(KCALL)	PRE1110
C--After TRESMOTT simulates all pumping/management periods, convert	PRE1120
C--XHEAD vector from "AQMAN1" Common to HD vector, which is passed	PRE1130
C--back to AQMAN's Main:	PRE1140
KTOT=NCNTR*NNPER	PRE1150
DO 300 K=1,KTOT	PRE1160
300 HD(K)=XHEAD(K)	PRE1170
RETURN	PRE1180
END	PRE1190
C-----	
C--Check input data from unit 14 to be sure that control nodes	CHK 10
C---indicated to also be well nodes (by KEYWL not equal 0) are	CHK 20
C---indeed well nodes, having a non-zero well radius (for computation	CHK 30
C---of in-well head).	CHK 40
C--Also check for non-linearities introduced by problem specification.	CHK 50
SUBROUTINE CHKDAT(NW,WATER,CONVRT,EVAP,LEAK)	CHK 60
IMPLICIT REAL *8 (A-H,O-Z)	CHK 70
INTEGER *4 CHK,WATER,CONVRT,EVAP,LEAK,CASE,TYPE,NNAME	CHK 80
DIMENSION TYPE(4)	CHK 90
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),	CHK 100
& KEYQ(200),KEYWL(500),XRAD(200)	CHK 110
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,	CHK 120
& TIMINC(50)	CHK 130
COMMON /SARRAY/ VF4(11),CHK(15)	CHK 150
COMMON /ALPHAS/ NNAME(16),CASE	CHK 160
DATA TYPE/'LINE','NONL','LINE','QUAD'/	CHK 170
KSUM=0	CHK 180
DO 110 KC=1,NCNTR	CHK 190
IF(KEYWL(KC).EQ.0)GO TO 110	CHK 200
KSUM=KSUM+1	CHK 210
IC=ILOCC(KC)	CHK 220
JC=JLOCC(KC)	CHK 230
DO 100 KW=1,NWLS	CHK 240
KWM=KW	CHK 250
IF(ILOCW(KW).NE.IC)GO TO 100	CHK 260
IF(JLOCW(KW).NE.JC)GO TO 100	CHK 270
KWM=KW-1	CHK 280
IF(XRAD(KW).GT.0)GO TO 110	CHK 290
WRITE(16,2)KW	CHK 300
STOP	CHK 310
100 CONTINUE	CHK 320
IF(KWM.EQ.NWLS)WRITE(16,4)KC	CHK 330
STOP	CHK 340
110 CONTINUE	CHK 350
IF(KSUM.EQ.NW)GO TO 120	CHK 360
WRITE(16,6)KSUM,NW	CHK 370
STOP	CHK 380
120 CONTINUE	CHK 390
IF(WATER.EQ.CHK(2) .OR. CONVRT.EQ.CHK(7))WRITE(16,12)	CHK 410
IF(CONVRT.EQ.CHK(7))WRITE(16,12)	CHK 420
IF(EVAP.EQ.CHK(6))WRITE(16,14)	CHK 430
IF(LEAK.EQ.CHK(9))WRITE(16,16)	CHK 440

RETURN	CHK 450
2 FORMAT(/2X,'PROGRAM TERMINATED BY SUBROUTINE CHKDAT:'/2X,' WELL ',	CHK 460
1I3,' IS SPECIFIED BY KEYWL TO BE A CONTROL LOCATION,'/3X,	CHK 470
2' BUT HAS A NON-POSITIVE WELL RADIUS'/)	CHK 480
4 FORMAT(/2X,'PROGRAM TERMINATED BY SUBROUTINE CHKDAT:'/2X,'CONTROL	CHK 490
1LOCATION',I3,' IS SPECIFIED BY KEYWL TO REQUIRE IN-WELL HEAD,'/	CHK 500
23X,' BUT NO WELL EXISTS THERE'/)	CHK 510
6 FORMAT(/2X,'PROGRAM TERMINATED BY SUBROUTINE CHKDAT:'/2X,'THE NUMBCHK	CHK 520
1ER OF NON-ZERO KEYWLS',I3,' DOES NOT EQUAL NW',I3/)	CHK 530
12 FORMAT(/2X,'*****WARNING*** A NON-LINEARITY HAS BEEN INTRODUCED BCHK	CHK 540
1Y THE SPECIFICATION'/' OF UNCONFINED CONDITIONS <from unit 15, lCHK	CHK 550
2ine 3>.'/' ADDITION OF RESPONSE MATRICES BY A LINEAR PROGRAM MAY	CHK 560
3GIVE ERRONEOUS RESULTS'/)	CHK 570
14 FORMAT(/2X,'*****WARNING*** A NON-LINEARITY HAS BEEN INTRODUCED BCHK	CHK 580
1Y THE SPECIFICATION'/' OF EVAPORTRANSPIRATION <from unit 15, linCHK	CHK 590
2e 3>.'/2x,'ADDITION OF RESPONSE MATRICES BY A LINEAR PROGRAM MAY	CHK 600
3IVE ERRONEOUS RESULTS'/)	CHK 610
16 FORMAT(/2X,'*****WARNING*** A NON-LINEARITY HAS BEEN INTRODUCED BCHK	CHK 620
1Y THE SPECIFICATION'/' OF LEAKAGE CONDITIONS <from unit 15, lineCHK	CHK 630
2 3>.'/2x,'ADDITION OF RESPONSE MATRICES BY A LINEAR PROGRAM MAY	CHK 640
3VE ERRONEOUS RESULTS'/)	CHK 650
END	CHK 660
C-----	
C--Subroutine for control of head differences, gradients, or	GRA 20
C---velocities.	GRA 30
SUBROUTINE GRADS(NENT)	GRA 40
IMPLICIT REAL *8 (A-H,O-Z)	GRA 50
REAL *8 MNGDRD	GRA 60
CHARACTER *1 CONTYP,GRATYP	GRA 70
COMMON /GRINFO/ KEEPCL(1000),KEEPC2(1000),ILOCG1(400),JLOGG1(400),	GRA 80
&ILOCG2(400),JLOGG2(400),GFACT(1000),GCON(1000)	GRA 90
COMMON /RESP/ HDUS(2500),CONHD(2500),DRDRES(2500),MNGDRD(2500)	GRA 100
COMMON /DIFFS/ NGRAD,KEYGRD(400),GRADE(1000),RDIF(1000)	GRA 110
COMMON /DEF/ KDEFHD(500),KDEFGR(400)	GRA 120
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),	GRA 130
& KEYQ(200),KEYWL(500),XRAD(200)	GRA 140
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,	GRA 150
& TIMING(50)	GRA 160
COMMON /TYP/ CONTYP(2500),GRATYP(1000)	GRA 170
IF (NENT.EQ.2) GO TO 300	GRA 180
C--Read and Write the I and J location of the two nodes of each	GRA 190
C---head-difference control pair.	GRA 200
WRITE(17,10)	GRA 210
10 FORMAT(/13X,'CONTROL PAIR LOCATIONS AND DEFINITIONS'/2X,	GRA 220
& 'Pair # 1st I-Loc. 1st J-Loc. 2nd I-Loc. 2nd J-Loc.	GRA 230
& 'KDEFGR')	GRA 240
DO 100 NG=1,NGRAD	GRA 250
READ(13,20)ILOCG1(NG),JLOGG1(NG),ILOCG2(NG),JLOGG2(NG),KDEFGR(NG)	GRA 260
20 FORMAT(5I10)	GRA 270
100 WRITE(17,25)NG,ILOGG1(NG),JLOGG1(NG),ILOCG2(NG),JLOGG2(NG),	GRA 280
& KDEFGR(NG)	GRA 290
25 FORMAT(3X,I3,7X,I3,8X,I3,11X,I3,9X,I3,9X,I2)	GRA 300
WRITE(17,30)	GRA 310
	GRA 320

```

30 FORMAT(/1X,'USER IMPOSED LIMITS ON HEAD DIFFERENCE AT CONTROL ' GRA 330
& 'PAIRS'/2X,'Period Pair # Conversion Factor Difference 'GRA 340
& 'Limit Type') GRA 350
DO 120 N=1,NNPER GRA 360
DO 120 NG=1,NGRAD GRA 370
IG=NG+(N-1)*NGRAD GRA 380
C--Read the factor to convert a gradient or velocity to a head GRA 390
C---difference, and read the value and direction of the desired limit GRA 400
C---on head difference, gradient, or velocity for all periods: GRA 410
READ(13,35)GFACT(IG),GCON(IG),GRATYP(IG) GRA 420
35 FORMAT(2G15.6,4X,A1) GRA 430
IF(KDEFGR(NG).EQ.0)WRITE(17,37)N,NG,GFACT(IG),GCON(IG),GRATYP(IG) GRA 440
IF(KDEFGR(NG).NE.0)WRITE(17,38)N,NG,GFACT(IG),GCON(IG) GRA 450
37 FORMAT(2X,I3,7X,I3,8X,G15.6,4X,G15.6,6X,A1) GRA 460
38 FORMAT(2X,I3,7X,I3,8X,G15.6,4X,G15.6,6X,'E') GRA 470
120 CONTINUE GRA 480
C--Use the GFACT, GCON and HDUS vectors to compute the head difference GRA 490
C---to be used as the RHS of the constraints in the MPS file and GRA 500
C---optimization model. GRA 510
DO 280 N=1,NNPER GRA 520
DO 270 NGD=1,NGRAD GRA 530
NG=NGD+(N-1)*NGRAD GRA 540
IC=1 GRA 550
210 IF(ILOGG1(NGD).EQ.ILOCC(IC))GO TO 230 GRA 560
220 IC=IC+1 GRA 570
IF(IC.LE.NCNTR) GO TO 210 GRA 580
WRITE(16,40)NGD GRA 590
40 FORMAT(/2X,'EXECUTION TERMINATED BY GRADS--',2X,'LOCATION OF FGRA 600
1IRST NODE IN CONTROL PAIR',I4,' IS NOT ALSO A PRIMARY CONTROL LOCAGRA 610
2TION'/) GRA 620
STOP GRA 630
230 IC1=IC GRA 640
IF(JLOGG1(NGD).NE.JLOCC(IC1))GO TO 220 GRA 650
KEEPC1(NG)=(N-1)*NCNTR+IC1 GRA 660
IC=1 GRA 670
240 IF(ILOGG2(NGD).EQ.ILOCC(IC))GO TO 260 GRA 680
250 IC=IC+1 GRA 690
IF(IC.LE.NCNTR) GO TO 240 GRA 700
WRITE(16,45)NGD GRA 710
45 FORMAT(/2X,'EXECUTION TERMINATED BY GRADS--',2X,'LOCATION OF SGRA 720
1ECOND NODE IN CONTROL PAIR',I4,' IS NOT ALSO A PRIMARY CONTROL LOCGRA 730
2ATION'/) GRA 740
STOP GRA 750
260 IC2=IC GRA 760
IF(JLOGG2(NGD).NE.JLOCC(IC2))GO TO 250 GRA 770
KEEPC2(NG)=(N-1)*NCNTR+IC2 GRA 780
C--Head difference between locations 1 & 2 is defined as GRA 790
C---head(1)-head(2): GRA 800
KCON1=(N-1)*NCNTR+IC1 GRA 810
KCON2=(N-1)*NCNTR+IC2 GRA 820
C--GRADE is vector of size = NPER*NGRAD. GRA 830
C--If constraint is a definition use unmanaged gradients only -- This GRA 840
C---used at lines MPS3060 to MPS3240 GRA 850
GRADE(NG)=HDUS(KCON1)-HDUS(KCON2)-(GFACT(NG)*GCON(NG)) GRA 860

```

```

          IF(KDEFGR(NG).EQ.1)GRADE(NG)=HDUS(KCON1)-HDUS(KCON2)      GRA 870
270  CONTINUE                                                         GRA 880
280  CONTINUE                                                         GRA 890
      RETURN                                                         GRA 900
300  CONTINUE                                                         GRA 910
      DO 320 N=1,NNPER                                               GRA 920
          DO 310 NGD=1,NGRAD                                         GRA 930
              NG=NGD+(N-1)*NGRAD                                     GRA 940
              KDRD1=KEEPC1(NG)                                       GRA 950
              KDRD2=KEEPC2(NG)                                       GRA 960
C--Difference in drawdown response to pumping between locations 1 & 2  GRA 970
C----is defined as DRDRES(1)-DRDRES(2):                             GRA 980
          RDIF(NG)=DRDRES(KDRD1)-DRDRES(KDRD2)                       GRA 990
310  CONTINUE                                                         GRA1000
320  CONTINUE                                                         GRA1010
      RETURN                                                         GRA1020
      END                                                             GRA1030

C-----
C---This subroutine takes drawdown response coefficients and converts  MPS 10
C-----them to MPS format. Response functions are repeated and staggered MPS 20
C-----as necessary to simulate multiple pumping periods. It is assumed MPS 30
C-----that the response functions are contained in a vector, ordered  MPS 40
C-----by pumping well, then observation time (pumping period), then  MPS 50
C-----control location.                                           MPS 60
C-----NWLS=no. of pumping wells;                                   MPS 70
C-----NCNTR=no. of control locations/observation wells;          MPS 80
C-----NPER=no. of pumping periods;                                MPS 90
C-----DRDRES=vector of responses                                  MPS 100
C-----MNGDRD=vector of constraints on drawdown                    MPS 110
      SUBROUTINE MPSFMT(KMPS,IWLS,NENT)                                MPS 120
      IMPLICIT REAL *8 (A-H,O-Z)                                     MPS 130
      REAL *8 MNGDRD                                               MPS 140
      INTEGER *4 IROW,IROW1,IROW2,NNAME,CASE,TYPE                  MPS 150
      CHARACTER *1 CONTYP,GRATYP                                   MPS 160
      DIMENSION TYPE(4)                                           MPS 170
      COMMON /RESP/ HDUS(2500),CONHD(2500),DRDRES(2500),MNGDRD(2500) MPS 180
      COMMON /WELLS/ UNITQ(200),FIXQ(200,50)                       MPS 190
      COMMON /DIFFS/ NGRAD,KEYGRD(400),GRADE(1000),RDIF(1000)    MPS 200
      COMMON /DEF/ KDEFHD(500),KDEFGR(400)                         MPS 210
      COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),
& KEYQ(200),KEYWL(500),XRAD(200)                                  MPS 230
      COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,
& TIMINC(50)                                                      MPS 250
      COMMON /QUAD1/ SURF(200),COSTC(200,50)                       MPS 260
      COMMON /TYP/ CONTYP(2500),GRATYP(1000)                      MPS 270
      COMMON /ALPHAS/ NNAME(16),CASE                               MPS 280
      DATA TYPE/'LINE','NONL','LINE','QUAD'/                      MPS 290
      NPER=NNPER                                                    MPS 300
C--If this is final call of MPSFMT, skip to RHS section:         MPS 310
      IF(NENT.EQ.2)GO TO 400                                       MPS 320
C--If this is not first call of MPSFMT, skip to COLUMN section:  MPS 330
      IF(KMPS.NE.1)GO TO 150                                       MPS 340
C--Check for too many digits in number of observation sites and  MPS 350
C---periods:                                                       MPS 360

```

```

        IF(NCNTR.LE.9999)GO TO 5                                MPS 370
        WRITE(16,1705)                                         MPS 380
1705  FORMAT(/2X,'NUMBER OF OBSERVATION WELLS EXCEEDS 9999--PROGRAM TERMMP
1       INATED BY SUBROUTINE MPSFMT'/)                          MPS 390
        STOP                                                    MPS 410
        5 CONTINUE                                             MPS 420
        IF(NPER.LE.99)GO TO 10                                  MPS 430
        WRITE(16,1710)                                         MPS 440
1710  FORMAT(/2X,'NUMBER OF PUMPING PERIODS EXCEEDS 99--PROGRAM TERMINATMPS 450
1       LED BY SUBROUTINE MPSFMT'/)                             MPS 460
        STOP                                                    MPS 470
        10 CONTINUE                                           MPS 480
C---Check for too many digits in number of pumping/injection sites: MPS 490
        IF(NWLS.LE.999)GO TO 15                                MPS 500
        WRITE(16,1715)                                         MPS 510
1715  FORMAT(/2X,'NUMBER OF PUMPING WELLS EXCEEDS 999--PROGRAM TERMINATEMPS 520
1       D BY SUBROUTINE MPSFMT'/)                              MPS 530
        STOP                                                    MPS 540
        15 CONTINUE                                           MPS 550
C---Write problem name:                                       MPS 560
        WRITE(18,1720)NNAME                                    MPS 570
1720  FORMAT('NAME',10X,16A4)                                  MPS 580
C---Write row section:                                       MPS 590
        WRITE(18,1725)                                         MPS 600
1725  FORMAT('ROWS')                                          MPS 610
        IF(NGRAD.EQ.0)GO TO 122                                MPS 620
C---Write row names for gradient pairs:                        MPS 630
        DO 120 KT=1,NPER                                       MPS 640
        DO 120 KG=1,NGRAD                                       MPS 650
            IG=KG+(KT-1)*NGRAD                                  MPS 660
            IROW=1000*KT+KG                                     MPS 670
            IF(KDEFGR(KG).EQ.1)GO TO 105                       MPS 680
            IF(KDEFGR(KG).GT.1 .OR. KDEFGR(KG).LT.0)GO TO 118 MPS 690
            IF(GRATYP(IG).NE.'L')GO TO 100                    MPS 700
            IF(KT.LE.9)WRITE(18,1731)IROW                      MPS 710
            IF(KT.GE.10)WRITE(18,1732)IROW                    MPS 720
1731  FORMAT(' G ', 'DIF0',I4)                                MPS 730
1732  FORMAT(' G ', 'DIF',I5)                                  MPS 740
            GO TO 120                                           MPS 750
        100 IF(GRATYP(IG).NE.'E')GO TO 110                    MPS 760
        105 IF(KT.LE.9)WRITE(18,1733)IROW                      MPS 770
            IF(KT.GE.10)WRITE(18,1734)IROW                    MPS 780
1733  FORMAT(' E ', 'DIF0',I4)                                MPS 790
1734  FORMAT(' E ', 'DIF',I5)                                  MPS 800
            GO TO 120                                           MPS 810
        110 IF(GRATYP(IG).NE.'G')GO TO 115                    MPS 820
            IF(KT.LE.9)WRITE(18,1735)IROW                      MPS 830
            IF(KT.GE.10)WRITE(18,1736)IROW                    MPS 840
1735  FORMAT(' L ', 'DIF0',I4)                                MPS 850
1736  FORMAT(' L ', 'DIF',I5)                                  MPS 860
            GO TO 120                                           MPS 870
        115 WRITE(16,1737)KG,KT                                MPS 880
1737  FORMAT(2X,'PROGRAM EXECUTION TERMINATED --'/4X,'CONSTRAINT TYPE MPS 890
        &AT CONTROL PAIR',I4,' DURING PERIOD',I3,' IS NEITHER L,E, NOR G') MPS 900

```

STOP	MPS 910
118 WRITE(16,1740)KW,KT	MPS 920
1740 FORMAT(2X,'PROGRAM EXECUTION TERMINATED --'/4X,'KDEFGR AT '	MPS 930
& 'CONTROL PAIR',I4,' DURING PERIOD',I3,' IS IMPROPERLY DEFINED')	MPS 940
STOP	MPS 950
120 CONTINUE	MPS 960
122 CONTINUE	MPS 970
C---Write row names for individual control locations. Direction of	MPS 980
C----inequalities is reversed since constraints are expressed	MPS 990
C----in terms of drawdown.	MPS1000
DO 140 KT=1,NPER	MPS1010
DO 140 KW=1,NCNTR	MPS1020
IF(NGRAD.EQ.0)GO TO 125	MPS1030
IF(KEYGRD(KW).EQ.1)GO TO 140	MPS1040
125 CONTINUE	MPS1050
IT=KW+(KT-1)*NCNTR	MPS1060
IROW=10000*KT+KW	MPS1070
IF(KDEFHD(KW).EQ.1)GO TO 130	MPS1080
IF(KDEFHD(KW).LT.0 .OR. KDEFHD(KW).GT.1)GO TO 138	MPS1090
IF(CONTYP(IT).NE.'L')GO TO 128	MPS1100
IF(KT.LE.9)WRITE(18,1741)IROW	MPS1110
IF(KT.GE.10)WRITE(18,1742)IROW	MPS1120
1741 FORMAT(' G ', 'DR0', I5)	MPS1130
1742 FORMAT(' G ', 'DR', I6)	MPS1140
GO TO 140	MPS1150
128 IF(CONTYP(IT).NE.'E')GO TO 132	MPS1160
130 IF(KT.LE.9)WRITE(18,1743)IROW	MPS1170
IF(KT.GE.10)WRITE(18,1744)IROW	MPS1180
1743 FORMAT(' E ', 'DR0', I5)	MPS1190
1744 FORMAT(' E ', 'DR', I6)	MPS1200
GO TO 140	MPS1210
132 IF(CONTYP(IT).NE.'G')GO TO 135	MPS1220
IF(KT.LE.9)WRITE(18,1745)IROW	MPS1230
IF(KT.GE.10)WRITE(18,1746)IROW	MPS1240
1745 FORMAT(' L ', 'DR0', I5)	MPS1250
1746 FORMAT(' L ', 'DR', I6)	MPS1260
GO TO 140	MPS1270
135 WRITE(16,1747)KW,KT	MPS1280
1747 FORMAT(2X,'PROGRAM EXECUTION TERMINATED --'/4X,'CONSTRAINT TYPE	MPS1290
&AT CONTROL LOCATION',I4,' DURING PERIOD',I3,' IS NEITHER L,E, NOR	MPS1300
&G')	MPS1310
STOP	MPS1320
138 WRITE(16,1749)KW,KT	MPS1330
1749 FORMAT(2X,'PROGRAM EXECUTION TERMINATED --'/4X,'KDEFHD AT '	MPS1340
& 'CONTROL LOCATION',I4,' DURING PERIOD',I3,' IS IMPROPERLY DEFIN	MPS1350
&ED')	MPS1360
STOP	MPS1370
140 CONTINUE	MPS1380
C---End row section with objective row:	MPS1390
WRITE(18,1750)	MPS1400
1750 FORMAT(' N ', 'OBJ')	MPS1410
C---Start column section:	MPS1420
WRITE(18,1755)	MPS1430
1755 FORMAT('COLUMNS')	MPS1440

150 CONTINUE	MPS1450
C---Write all responses (by location and by time) from pumping well 1	MPS1460
C-----for all time periods, and then responses from next pumping well	MPS1470
C-----for all time periods, etc.	MPS1480
C---Row DR010006 is drawdown (response) during pumping period 1 at	MPS1490
C-----control location 6; Row DIF03012 is difference-in-drawdown	MPS1500
C-----response during period 3 at gradient pair 12. Column Q02003 is	MPS1510
C-----pumping period 2, pumping well 3.	MPS1520
DO 350 IPER=1,NPER	MPS1530
KILOPR=IPER*1000	MPS1540
NUMWEL=KMPS+KILOPR	MPS1550
C---Write scaled objective coefficient into column section for linear	MPS1560
C----objective function:	MPS1570
IF(CASE.EQ.TYPE(4)) GO TO 160	MPS1580
COEFF=-UNITQ(IWLS)	MPS1590
IF(IPER.LE.9)WRITE(18,1760)NUMWEL,COEFF	MPS1600
IF(IPER.GE.10)WRITE(18,1765)NUMWEL,COEFF	MPS1610
1760    FORMAT(4X,'Q0',I4,4X,'OBJ',7X,G12.5)	MPS1620
1765    FORMAT(4X,'Q',I5,4X,'OBJ',7X,G12.5)	MPS1630
IF(NGRAD.EQ.0)GO TO 300	MPS1640
GO TO 190	MPS1650
C---Write objective into column section for linear part of quadratic	MPS1660
C----objective function:	MPS1670
160    SCOST=COSTC(KMPS,IPER)*(-UNITQ(KMPS))	MPS1680
IF(IPER.LE.9)WRITE(18,1767)NUMWEL,SCOST	MPS1690
IF(IPER.GE.10)WRITE(18,1768)NUMWEL,SCOST	MPS1700
1767    FORMAT(4X,'Q0',I4,4X,'OBJ',7X,G12.5)	MPS1710
1768    FORMAT(4X,'Q',I5,4X,'OBJ',7X,G12.5)	MPS1720
IF(NGRAD.EQ.0)GO TO 300	MPS1730
C---Write column section for gradient control pairs:	MPS1740
190    DO 230 KT=IPER,NPER	MPS1750
DO 230 KG=1,NGRAD	MPS1760
IF(MOD(KG,2).EQ.1)GO TO 210	MPS1770
IROW2=1000*KT+KG	MPS1780
KRES2=KG+(KT-1)*NGRAD-(IPER-1)*NGRAD	MPS1790
IF(IPER.GE.10)GO TO 205	MPS1800
IF(KT.LE.9)WRITE(18,1770)NUMWEL,IROW1,RDIF(KRES1),IROW2,	MPS1810
&    RDIF(KRES2)	MPS1820
IF(KT.GE.10)WRITE(18,1775)NUMWEL,IROW1,RDIF(KRES1),IROW2,	MPS1830
&    RDIF(KRES2)	MPS1840
1770    FORMAT(4X,'Q0',I4,4X,'DIF0',I4,2X,E12.5,3X,'DIF0',I4,2X,E12.5)	MPS1850
1775    FORMAT(4X,'Q0',I4,4X,'DIF',I5,2X,E12.5,3X,'DIF',I5,2X,E12.5)	MPS1860
GO TO 230	MPS1870
205    IF(KT.LE.9)WRITE(18,1780)NUMWEL,IROW1,RDIF(KRES1),IROW2,	MPS1880
&    RDIF(KRES2)	MPS1890
IF(KT.GE.10)WRITE(18,1785)NUMWEL,IROW1,RDIF(KRES1),IROW2,	MPS1900
&    RDIF(KRES2)	MPS1910
1780    FORMAT(4X,'Q',I5,4X,'DIF0',I4,2X,E12.5,3X,'DIF0',I4,2X,E12.5)	MPS1920
1785    FORMAT(4X,'Q',I5,4X,'DIF',I5,2X,E12.5,3X,'DIF',I5,2X,E12.5)	MPS1930
GO TO 230	MPS1940
210    IROW1=1000*KT+KG	MPS1950
KRES1=KG+(KT-1)*NGRAD-(IPER-1)*NGRAD	MPS1960
IF(KG.NE.NGRAD)GO TO 230	MPS1970
C---Write single last value if it exists:	MPS1980

	IF(IPER.GT.9)GO TO 220	MPS1990
	IF(KT.LE.9)WRITE(18,1790)NUMWEL,IROW1,RDIF(KRES1)	MPS2000
	IF(KT.GE.10)WRITE(18,1795)NUMWEL,IROW1,RDIF(KRES1)	MPS2010
1790	FORMAT(4X,'Q0',I4,4X,'DIFO',I4,2X,E12.5)	MPS2020
1795	FORMAT(4X,'Q0',I4,4X,'DIF',I5,2X,E12.5)	MPS2030
	GO TO 230	MPS2040
220	IF(KT.LE.9)WRITE(18,1805)NUMWEL,IROW1,RDIF(KRES1)	MPS2050
	IF(KT.GE.10)WRITE(18,1810)NUMWEL,IROW1,RDIF(KRES1)	MPS2060
1805	FORMAT(4X,'Q',I5,4X,'DIFO',I4,2X,E12.5)	MPS2070
1810	FORMAT(4X,'Q',I5,4X,'DIF',I5,2X,E12.5)	MPS2080
230	CONTINUE	MPS2090
300	CONTINUE	MPS2100
C---	Write column section for individual control locations.	MPS2110
	DO 340 KT=IPER,NPER	MPS2120
	ISNGL=0	MPS2130
	KW=0	MPS2140
	DO 330 KKW=1,NCNTR	MPS2150
305	KW=KW+1	MPS2160
	IF(KW.GT.NCNTR .AND. ISNGL.EQ.0)GO TO 340	MPS2170
	IF(KW.GT.NCNTR .AND. ISNGL.EQ.1)GO TO 322	MPS2180
	IF(KEYGRD(KW).EQ.1)GO TO 305	MPS2190
	IF(MOD(KKW,2).EQ.1)GO TO 320	MPS2200
	ISNGL=0	MPS2210
	IROW2=10000*KT+KW	MPS2220
	KRES2=KW+(KT-1)*NCNTR-(IPER-1)*NCNTR	MPS2230
	IF(IPER.GE.10)GO TO 315	MPS2240
	IF(KT.LE.9)WRITE(18,1815)NUMWEL,IROW1,DRDRES(KRES1),IROW2,	MPS2250
&	DRDRES(KRES2)	MPS2260
	IF(KT.GE.10)WRITE(18,1820)NUMWEL,IROW1,DRDRES(KRES1),IROW2,	MPS2270
&	DRDRES(KRES2)	MPS2280
1815	FORMAT(4X,'Q0',I4,4X,'DR0',I5,2X,E12.5,3X,'DR0',I5,2X,E12.5)	MPS2290
1820	FORMAT(4X,'Q0',I4,4X,'DR',I6,2X,E12.5,3X,'DR',I6,2X,E12.5)	MPS2300
	GO TO 330	MPS2310
315	IF(KT.LE.9)WRITE(18,1825)NUMWEL,IROW1,DRDRES(KRES1),IROW2,	MPS2320
&	DRDRES(KRES2)	MPS2330
	IF(KT.GE.10)WRITE(18,1830)NUMWEL,IROW1,DRDRES(KRES1),IROW2,	MPS2340
&	DRDRES(KRES2)	MPS2350
1825	FORMAT(4X,'Q',I5,4X,'DR0',I5,2X,E12.5,3X,'DR0',I5,2X,E12.5)	MPS2360
1830	FORMAT(4X,'Q',I5,4X,'DR',I6,2X,E12.5,3X,'DR',I6,2X,E12.5)	MPS2370
	GO TO 330	MPS2380
320	IROW1=10000*KT+KW	MPS2390
	KRES1=KW+(KT-1)*NCNTR-(IPER-1)*NCNTR	MPS2400
	ISNGL=1	MPS2410
	IF(KW.NE.NCNTR)GO TO 330	MPS2420
C---	Write single last value if it exists:	MPS2430
322	IF(IPER.GT.9)GO TO 325	MPS2440
	IF(KT.LE.9)WRITE(18,1835)NUMWEL,IROW1,DRDRES(KRES1)	MPS2450
	IF(KT.GE.10)WRITE(18,1840)NUMWEL,IROW1,DRDRES(KRES1)	MPS2460
1835	FORMAT(4X,'Q0',I4,4X,'DR0',I5,2X,E12.5)	MPS2470
1840	FORMAT(4X,'Q0',I4,4X,'DR',I6,2X,E12.5)	MPS2480
	GO TO 340	MPS2490
325	IF(KT.LE.9)WRITE(18,1845)NUMWEL,IROW1,DRDRES(KRES1)	MPS2500
	IF(KT.GE.10)WRITE(18,1850)NUMWEL,IROW1,DRDRES(KRES1)	MPS2510
1845	FORMAT(4X,'Q',I5,4X,'DR0',I5,2X,E12.5)	MPS2520

1850	FORMAT(4X, 'Q', I5, 4X, 'DR', I6, 2X, E12.5)	MPS2530
	GO TO 340	MPS2540
330	CONTINUE	MPS2550
340	CONTINUE	MPS2560
C---	If objective function is quadratic, write responses at control	MPS2570
C----	locations that are also managed wells to unit 19.	MPS2580
	IF(CASE.NE.TYPE(4) .OR. IPER.GT.1) GO TO 350	MPS2590
	DO 345 KTQ=1, NPER	MPS2600
	DO 345 KC=1, NCNTR	MPS2610
	IF(KEYWL(KC).NE.1)GO TO 345	MPS2620
	KRES=KC+(KTQ-1)*NCNTR	MPS2630
	WRITE(19, 1852)KMPS, KC, KTQ, DRDRES(KRES)	MPS2640
1852	FORMAT(6X, I4, 2I5, F15.7)	MPS2650
345	CONTINUE	MPS2660
350	CONTINUE	MPS2670
C---	Return to MAIN program to obtain unit response for next well.	MPS2680
	RETURN	MPS2690
C---	If constraints are definitions (KDEFHD =1 and/or KDEFGR=1) add	MPS2700
C---	Identity matrix to define H as Drawdown + Unstressed heads,	MPS2710
C---	and/or defines G as Diff. in Drawdown + Unstressed Diff. in Head	MPS2720
C---	Entry point is line 400 if all response info. (rest of COLUMN	MPS2730
C---	section has been written.	MPS2740
	400 CONTINUE	MPS2750
C---	Write columns section DEFINING gradient variables	MPS2760
	ONE=1.ODO	MPS2770
	IF(NGRAD.EQ.0)GO TO 540	MPS2780
	DO 530 KT=1, NPER	MPS2790
	DO 520 IG=1, NGRAD	MPS2800
	IF(KDEFGR(IG).NE.1) GO TO 520	MPS2810
	IROW1=1000*KT+IG	MPS2820
C---	Write single value	MPS2830
510	IF(KT.LE.9)WRITE(18, 1423)IROW1, IROW1, ONE	MPS2840
	IF(KT.GE.10)WRITE(18, 1424)IROW1, IROW1, ONE	MPS2850
1423	FORMAT(4X, 'G0', I4, 4X, 'DIF0', I4, 2X, E12.5)	MPS2860
1424	FORMAT(4X, 'G', I5, 4X, 'DIF', I5, 2X, E12.5)	MPS2870
520	CONTINUE	MPS2880
530	CONTINUE	MPS2890
C---	Write DEFS for for individual control locations.	MPS2900
540	DO 580 KT=1, NPER	MPS2910
	DO 570 KKW=1, NCNTR	MPS2920
	IF(KDEFHD(KKW).NE.1)GO TO 570	MPS2930
560	IROW1=10000*KT+KKW	MPS2940
C---	Write single HEAD DEF	MPS2950
565	IF(KT.LE.9)WRITE(18, 1435)IROW1, IROW1, ONE	MPS2960
	IF(KT.GE.10)WRITE(18, 1440)IROW1, IROW1, ONE	MPS2970
1435	FORMAT(4X, 'H0', I5, 3X, 'DR0', I5, 2X, E12.5)	MPS2980
1440	FORMAT(4X, 'H', I6, 3X, 'DR', I6, 2X, E12.5)	MPS2990
570	CONTINUE	MPS3000
580	CONTINUE	MPS3010
C---	Write Right-Hand-Side section:	MPS3020
600	WRITE(18, 1855)	MPS3030
1855	FORMAT('RHS')	MPS3040
C--	RHS for gradient pairs.	MPS3050
C--	For gradient definitions (KDEFGR=1), GRADE is defined as unstressed	MPS3060

C---	gradient without any user-defined constraint. See line GRA 700	MPS3070
	IF(NGRAD.EQ.0)GO TO 640	MPS3080
	DO 630 KT=1,NPER	MPS3090
	DO 620 KG=1,NGRAD	MPS3100
	IF(MOD(KG,2).EQ.1)GO TO 610	MPS3110
	IROW2=1000*KT+KG	MPS3120
	KCON2=KG+(KT-1)*NGRAD	MPS3130
	IF(KT.LE.9)WRITE(18,1860)IROW1,GRADE(KCON1),IROW2,GRADE(KCON2)	MPS3140
	IF(KT.GE.10)WRITE(18,1865)IROW1,GRADE(KCON1),IROW2,GRADE(KCON2)	MPS3150
1860	FORMAT(4X,'RHS',7X,'DIF0',I4,2X,E12.5,3X,'DIF0',I4,2X,E12.5)	MPS3160
1865	FORMAT(4X,'RHS',7X,'DIF',I5,2X,E12.5,3X,'DIF',I5,2X,E12.5)	MPS3170
	GO TO 620	MPS3180
610	IROW1=1000*KT+KG	MPS3190
	KCON1=KG+(KT-1)*NGRAD	MPS3200
	IF(KG.NE.NGRAD)GO TO 620	MPS3210
	IF(KT.LE.9)WRITE(18,1870)IROW1,GRADE(KCON1)	MPS3220
	IF(KT.GE.10)WRITE(18,1875)IROW1,GRADE(KCON1)	MPS3230
1870	FORMAT(4X,'RHS',7X,'DIF0',I4,2X,E12.5)	MPS3240
1875	FORMAT(4X,'RHS',7X,'DIF',I5,2X,E12.5)	MPS3250
	620 CONTINUE	MPS3260
	630 CONTINUE	MPS3270
	640 CONTINUE	MPS3280
C---	Write RHS for individual control locations.	MPS3290
	DO 680 KT=1,NPER	MPS3300
	ISNGL=0	MPS3310
	KW=0	MPS3320
	DO 670 KKW=1,NCNTR	MPS3330
650	KW=KW+1	MPS3340
	IF(KW.GT.NCNTR .AND. ISNGL.EQ.0)GO TO 680	MPS3350
	IF(KW.GT.NCNTR .AND. ISNGL.EQ.1)GO TO 665	MPS3360
	IF(KEYGRD(KW).EQ.1)GO TO 650	MPS3370
	IF(MOD(KKW,2).EQ.1)GO TO 660	MPS3380
	ISNGL=0	MPS3390
	IROW2=10000*KT+KW	MPS3400
	KCON2=KW+(KT-1)*NCNTR	MPS3410
	IF(KDEFHD(KW).EQ.1)X2=HDUS(KCON2)	MPS3420
	IF(KDEFHD(KW).NE.1)X2=MNGDRD(KCON2)	MPS3430
	IF(KT.LE.9)WRITE(18,1880)IROW1,X1,IROW2,X2	MPS3440
	IF(KT.GE.10)WRITE(18,1885)IROW1,X1,IROW2,X2	MPS3450
1880	FORMAT(4X,'RHS',7X,'DRO',I5,2X,E12.5,3X,'DRO',I5,2X,E12.5)	MPS3460
1885	FORMAT(4X,'RHS',7X,'DR',I6,2X,E12.5,3X,'DR',I6,2X,E12.5)	MPS3470
	GO TO 670	MPS3480
660	IROW1=10000*KT+KW	MPS3490
	KCON1=KW+(KT-1)*NCNTR	MPS3500
	ISNGL=1	MPS3510
	IF(KDEFHD(KW).EQ.1)X1=HDUS(KCON1)	MPS3520
	IF(KDEFHD(KW).NE.1)X1=MNGDRD(KCON1)	MPS3530
	IF(KW.NE.NCNTR)GO TO 670	MPS3540
665	IF(KT.LE.9)WRITE(18,1890)IROW1,X1	MPS3550
	IF(KT.GE.10)WRITE(18,1895)IROW1,X1	MPS3560
1890	FORMAT(4X,'RHS',7X,'DRO',I5,2X,E12.5)	MPS3570
1895	FORMAT(4X,'RHS',7X,'DR',I6,2X,E12.5)	MPS3580
	GO TO 680	MPS3590
670	CONTINUE	MPS3600

680 CONTINUE	MPS3610
C---Write end of data	MPS3620
WRITE(18,1905)	MPS3630
1905 FORMAT('ENDATA')	MPS3640
RETURN	MPS3650
END	MPS3660
-----	
C--Subroutine to compute coefficients for linear part of quadratic	QUA 10
C----objective function.	QUA 20
SUBROUTINE QUAD	QUA 30
IMPLICIT REAL*8 (A-H,O-Z)	QUA 40
REAL *8 MNGDRD	QUA 50
CHARACTER *1 CONTYP,GRATYP	QUA 60
COMMON /RESP/ HDUS(2500),CONHD(2500),DRDRES(2500),MNGDRD(2500)	QUA 80
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),	QUA 90
& KEYQ(200),KEYWL(500),XRAD(200)	QUA 100
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELTA,TIMPER,	QUA 110
& TIMINC(50)	QUA 120
COMMON /QUAD1/ SURF(200),COSTC(200,50)	QUA 130
COMMON /TYP/ CONTYP(2500),GRATYP(1000)	QUA 140
C--Check data to see that quadratic managed wells are listed as first	QUA 150
C----managed wells.	QUA 160
IORD=0	QUA 170
DO 85 I=1,NWLS	QUA 180
IF(KEYQ(I).EQ.2)IORD=2	QUA 190
IF(KEYQ(I).NE.0)GO TO 85	QUA 200
IF(IORD.EQ.0)GO TO 85	QUA 210
WRITE(16,84)I	QUA 220
84    FORMAT(6X,'PROGRAM TERMINATED BY SUBROUTINE QUAD--'/2X,	QUA 230
1'WELL NUMBER ',I3,' SHOWS THAT ALL QUADRATIC DECISION WELLS ARE'/	QUA 240
22X,' NOT LISTED BEFORE ALL NON-QUADRATIC DECISION WELLS')	QUA 250
STOP	QUA 260
85    CONTINUE	QUA 270
C--Compute number of quadratic managed wells and check to see that	QUA 280
C----these are listed as first control locations.	QUA 290
KWLS=0	QUA 300
IORD=0	QUA 310
DO 100 I=1,NCNTR	QUA 320
IF(I.NE.1)GO TO 90	QUA 330
IF(KEYWL(1).EQ.1)IORD=1	QUA 340
90    IF(KEYWL(I).NE.1)GO TO 95	QUA 350
KWLS=KWLS+1	QUA 360
IF(IORD.EQ.1)GO TO 100	QUA 370
WRITE(16,91)I	QUA 380
91    FORMAT(2X,'PROGRAM TERMINATED BY SUBROUTINE QUAD--'/3X,'CONTROL	QUA 390
1'LOCATION',I4,' SHOWS THAT ALL QUADRATIC DECISION WELLS ARE NOT '	QUA 400
2/3X,'LISTED SEQUENTIALLY AS THE FIRST CONTROL LOCATIONS')	QUA 410
STOP	QUA 420
95    IORD=2	QUA 430
100 CONTINUE	QUA 440
C--Read annual discount rate, constant pumping cost, and key to	QUA 450
C----indicate whether costs are constant (0) or variable (1):	QUA 460
READ(13,10)ANNDIS,COSTF,KEYCOS	QUA 470
10    FORMAT(G10.3,G10.0,I10)	QUA 480

IF(KEYCOS.EQ.0) GO TO 110	QUA 490
C--Read variable pumping costs into cost vector:	QUA 500
DO 105 N=1,NNPER	QUA 510
READ(13,15)(COSTC(I,N),I=1,KWLS)	QUA 520
15    FORMAT(8G10.0)	QUA 530
105 CONTINUE	QUA 540
GO TO 130	QUA 550
C--Put constant pumping costs into costs vector:	QUA 560
110 DO 120 N=1,NNPER	QUA 570
DO 120 I=1,KWLS	QUA 580
COSTC(I,N)=COSTF	QUA 590
120 CONTINUE	QUA 600
C--Discount pumping costs according to management period lengths by	QUA 610
C---months:	QUA 620
130 DISMON=ANNDIS/12.0	QUA 630
NDAYS=0	QUA 640
DO 140 N=1,NNPER	QUA 650
NDAYS=NDAYS+TIMPER	QUA 660
NMONTH=NDAYS/30	QUA 670
DISFAC=1./((1.+DISMON)**NMONTH)	QUA 680
DO 140 I=1,KWLS	QUA 690
COSTC(I,N)=DISFAC*COSTC(I,N)	QUA 700
140 CONTINUE	QUA 710
C--Read elevation of land surface at all quadratic decision wells:	QUA 720
READ(13,20)(SURF(I),I=1,KWLS)	QUA 730
20    FORMAT(8G10.0)	QUA 740
C--Compute pumping lifts under unmanaged conditions:	QUA 750
DO 170 N=1,NNPER	QUA 760
KK=0	QUA 770
LBEG=(N-1)*NCNTR+1	QUA 780
LEND=N*NCNTR	QUA 790
DO 170 IW=1,NWLS	QUA 800
KC=0	QUA 810
IF(KEYQ(IW).EQ.0)GO TO 145	QUA 820
KK=KK+1	QUA 830
GO TO 170	QUA 840
145    DO 150 L=LBEG,LEND	QUA 850
KC=KC+1	QUA 860
IF(ILOCW(IW).EQ.ILOCC(KC).AND.JLOCW(IW).EQ.JLOCC(KC))GO TO 160	QUA 870
IF(L.LT.LEND) GO TO 150	QUA 880
WRITE(16,50)IW	QUA 890
50    FORMAT(/2X,'TERMINATION BY SUBROUTINE QUAD ---',/, ' THE LOCATIO	QUA 900
1N OF WELL',I4,' DOES NOT CORRESPOND TO A CONTROL LOCATION'/)	QUA 910
STOP	QUA 920
150 CONTINUE	QUA 930
C--The difference between land surface and unmanaged head at each	QUA 940
C---well location gives the unmanaged lift. The product of this	QUA 950
C---lift and discounted cost per unit lift per unit pumpage gives	QUA 960
C---the cost coefficient for the linear part of the quadratic	QUA 970
C---objective function:	QUA 980
160 KIW=IW-KK	QUA 990
COSTC(KIW,N)=COSTC(KIW,N)*(SURF(KIW)-HDUS(L))	QUA1000
170 CONTINUE	QUA1010
RETURN	QUA1020

END	QUA1030
-----	
C--SUBROUTINE READ1(NENT,KP,KPML,NWEL,TMAX,NUMT,DELT,CDLT,I,J,II, &RADIUS,XWELL)	REA 10
IMPLICIT REAL *8 (A-H,O-Z)	REA 20
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500), & KEYQ(200),KEYWL(500),XRAD(200)	REA 30
COMMON /STRESS/ QWELL(2000),XHEAD(2500)	REA 40
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELT,TIMPER, & TIMINC(50)	REA 50
GO TO (100,200) NENT	REA 60
C--Retrieve pumping period info from "AQMAN" Common:	REA 70
100 KP=KPER	REA 80
KPML=KPER-1	REA 90
NWEL=NWLS	REA 100
TMAX=TIMPER	REA 110
DELT=TIMINC(KPER)	REA 120
CDLT=CDELT	REA 130
C--Set limit on time step number very high, so that TIMPER (length of C----period in days) will be used by TRES.	REA 140
NUMT=32000	REA 150
RETURN	REA 160
200 CONTINUE	REA 170
C--Retrieve well locations, radii, and pumpages from "AQMAN" Common:	REA 180
I=ILOCW(II)	REA 190
J=JLOCW(II)	REA 200
RADIUS=XRAD(II)	REA 210
LPER=(KPER-1)*NWLS	REA 220
KWEL=LPER+II	REA 230
XWELL=QWELL(KWEL)	REA 240
RETURN	REA 250
END	REA 260
-----	
C--SUBROUTINE WRITE1(NENT,IZ,JZ,KW,HW,PHI)	WRI 10
IMPLICIT REAL *8 (A-H,O-Z)	WRI 20
DIMENSION PHI(IZ,JZ)	WRI 30
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500), & KEYQ(200),KEYWL(500),XRAD(200)	WRI 40
COMMON /STRESS/ QWELL(2000),XHEAD(2500)	WRI 50
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELT,TIMPER, & TIMINC(50)	WRI 60
GO TO (101,102) NENT	WRI 70
C--Convert PHI matrix computed by TRESMOTT (at end of pumping period C----or if steady-state is reached) to XHEAD vector to store in C----"AQMAN1" COMMON:	WRI 80
101 KCNTR=NCNTR*(KPER-2)	WRI 90
LBEG=KCNTR+1	WRI 100
LEND=NCNTR*(KPER-1)	WRI 110
LL=0	WRI 120
DO 100 L=LBEG,LEND	WRI 130
LL=LL+1	WRI 140
DO 110 I=1,IZ	WRI 150
IF(I.NE.ILOCC(LL))GO TO 110	WRI 160
II=I	WRI 170
	WRI 180
	WRI 190
	WRI 200
	WRI 210

110	CONTINUE	WRI 220
	DO 120 J=1,JZ	WRI 230
	IF(J.NE.JLOCC(LL))GO TO 120	WRI 240
	JJ=J	WRI 250
120	CONTINUE	WRI 260
	XHEAD(L)=PHI(II,JJ)	WRI 270
100	CONTINUE	WRI 280
	RETURN	WRI 290
102	CONTINUE	WRI 300
C--	If KEYWL is not zero, write head at well radius into XHEAD vector:	WRI 310
	KKW=KW	WRI 320
	LBEG=NCNTR*(KPER-2)+1	WRI 330
	LEND=NCNTR*(KPER-1)	WRI 340
	LL=0	WRI 350
	DO 10 L=LBEG,LEND	WRI 360
	LL=LL+1	WRI 370
	IF(KEYWL(LL).EQ.0)GO TO 10	WRI 380
	KKW=KKW-1	WRI 390
	IF(KKW.NE.0)GO TO 10	WRI 400
	XHEAD(L)=HW	WRI 410
	RETURN	WRI 420
10	CONTINUE	WRI 430
	RETURN	WRI 440
	END	WRI 450

C-----

	SUBROUTINE TRES(KCALL)	
C	FINITE-DIFFERENCE MODEL	MAN 20
C	FOR	MAN 30
C	SIMULATION OF GROUND-WATER FLOW	MAN 40
C	IN TWO DIMENSIONS	MAN 50
C		MAN 60
C	BY P. C. TRECOTT, G. F. PINDER AND S. P. LARSON	MAN 70
C	U. S. GEOLOGICAL SURVEY	MAN 80
C	SEPTEMBER, 1975	MAN 90
C	*****	MAN 100
C	MAIN PROGRAM TO DIMENSION DIGITAL MODEL AND CONTROL SEQUENCE	MAN 110
C	OF COMPUTATIONS	MAN 120
C	-----	MAN 130

C---All lines inserted due to adaptation for optimization linkage are \$1-10  
C---marked in columns 73-80 with a \$. If \$\$ appears, the line is from \$1-20  
C---the original TRECOTT code, but has been altered. Lines containing \$1-30  
C---WRITES which are commented out are not marked. The first digit \$1-40  
C---after \$ or \$\$ denotes the TRECOTT subroutine: 1=Main,2=DATAI,etc. \$1-50  
C---The remaining digits run sequentially within a subroutine. \$1-60  
C---If no line number appears, the line was inserted or altered by the \$1-61  
C---the New Mexico district when converting the original TRECOTT code \$1-62  
C---into FORTRAN-77. \$1-63  
C SPECIFICATIONS: MAN 140  
IMPLICIT REAL \*8 (A-H,O-Z) \$1-70  
REAL \*8 KEEP,M \$\$1-71  
REAL \*4 HEADNG(32)  
INTEGER \*4 DIML,DIMW,CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,  
1CONTR,LEAK,RECH,SIP,ADI  
INTEGER \*4 IH,IZ,JZ,NW,ITMAX,L,ISUM,ISIZ,IP,JP,IR,JR,IC,JC,



10		MAN 590
	WRITE (P,350)	MAN 600
	STOP	MAN 610
20	READ (R,320) DIML,DIMW,NW,ITMAX	MAN 620
C	WRITE (P,340) DIML,DIMW,NW,ITMAX	MAN 630
C	--Check input data for consistency and linearity	\$1-131
	CALL CHKDAT(NW,WATER,CONVRT,EVAP,LEAK)	\$1-132
C		MAN 640
C	---COMPUTE DIMENSIONS FOR ARRAYS---	MAN 650
	IZ=DIML	MAN 660
	JZ=DIMW	MAN 670
	IH=MAX0(1,NW)	MAN 680
	IMAX=MAX0(DIML,DIMW)	MAN 690
	ISIZ=DIML*DIMW	MAN 700
	ISUM=2*ISIZ+1	MAN 710
	IMX1=ITMAX+1	MAN 720
	L(1)=1	MAN 730
	DO 30 I=2,4	MAN 740
	L(I)=ISUM	MAN 750
30	ISUM=ISUM+2*IMAX	MAN 760
	DO 40 I=5,16	MAN 770
	L(I)=ISUM	MAN 780
40	ISUM=ISUM+ISIZ	MAN 790
	IF (WATER.NE.CHK(2)) GO TO 60	MAN 800
	DO 50 I=17,19	MAN 810
	L(I)=ISUM	MAN 820
50	ISUM=ISUM+ISIZ	MAN 830
	IP=DIML	MAN 840
	JP=DIMW	MAN 850
	GO TO 80	MAN 860
60	DO 70 I=17,19	MAN 870
	L(I)=ISUM	MAN 880
70	ISUM=ISUM+1	MAN 890
	IP=1	MAN 900
	JP=1	MAN 910
80	IF (LEAK.NE.CHK(9)) GO TO 100	MAN 920
	DO 90 I=20,22	MAN 930
	L(I)=ISUM	MAN 940
90	ISUM=ISUM+ISIZ	MAN 950
	IR=DIML	MAN 960
	JR=DIMW	MAN 970
	GO TO 120	MAN 980
100	DO 110 I=20,22	MAN 990
	L(I)=ISUM	MAN1000
110	ISUM=ISUM+1	MAN1010
	IR=1	MAN1020
	JR=1	MAN1030
120	IF (CONVRT.NE.CHK(7)) GO TO 130	MAN1040
	L(23)=ISUM	MAN1050
	ISUM=ISUM+ISIZ	MAN1060
	IC=DIML	MAN1070
	JC=DIMW	MAN1080
	GO TO 140	MAN1090
130	L(23)=ISUM	MAN1100

	ISUM=ISUM+1	MAN1110
	IC=1	MAN1120
	JC=1	MAN1130
140	IF (EVAP.NE.CHK(6)) GO TO 150	MAN1140
	L(24)=ISUM	MAN1150
	ISUM=ISUM+ISIZ	MAN1160
	IL=DIWL	MAN1170
	JL=DIW	MAN1180
	GO TO 160	MAN1190
150	L(24)=ISUM	MAN1200
	ISUM=ISUM+1	MAN1210
	IL=1	MAN1220
	JL=1	MAN1230
160	IF (NUMS.NE.CHK(11)) GO TO 180	MAN1240
	DO 170 I=25,28	MAN1250
	L(I)=ISUM	MAN1260
170	ISUM=ISUM+ISIZ	MAN1270
	IS=DIWL	MAN1280
	JS=DIW	MAN1290
	GO TO 200	MAN1300
180	DO 190 I=25,28	MAN1310
	L(I)=ISUM	MAN1320
190	ISUM=ISUM+1	MAN1330
	IS=1	MAN1340
	JS=1	MAN1350
200	DO 210 I=29,31	MAN1360
	L(I)=ISUM	MAN1370
210	ISUM=ISUM+DIW	MAN1380
	DO 220 I=32,33	MAN1390
	L(I)=ISUM	MAN1400
220	ISUM=ISUM+DIWL	MAN1410
	L(34)=ISUM	MAN1420
	ISUM=ISUM+IH	MAN1430
	L(35)=ISUM	MAN1440
	ISUM=ISUM+2*IH	MAN1450
	IF (MOD(ISUM,2).EQ.0) ISUM=ISUM+1	MAN1460
230	L(36)=ISUM	MAN1480
	ISUM=ISUM+2*IMAX	MAN1490
	L(37)=ISUM	MAN1500
	ISUM=ISUM+IMX1	MAN1510
C	WRITE (P,330) ISUM	MAN1520
C		MAN1530
C	---PASS INTIIAL ADDRESSES OF ARRAYS TO SUBROUTINES---	MAN1540
	CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19)),Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(L(34)),Y(L(35)),Y(L(13)),10)	MAN1550
	CALL STEP(Y(L(1)),Y(L(5)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(14)),Y(L(17)),Y(L(18)),Y(L(23)),Y(L(29)),Y(L(30)),Y(L(32)),Y(L(34)),Y(L(35)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(12)),Y(L(13)),Y(L(15)),Y(L(19)),Y(L(21)),Y(L(22)),Y(L(24)),10)	MAN1560
	IF (NUMS.EQ.CHK(11)) CALL SOLVE1(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(L(32)),Y(L(33)),Y(L(34)),Y(L(35)),Y(L(36)),Y(L(37)),Y(L(38)),Y(L(39)),Y(L(40)),Y(L(41)),Y(L(42)),Y(L(43)),Y(L(44)),Y(L(45)),Y(L(46)),Y(L(47)),Y(L(48)),Y(L(49)),Y(L(50)),Y(L(51)),Y(L(52)),Y(L(53)),Y(L(54)),Y(L(55)),Y(L(56)),Y(L(57)),Y(L(58)),Y(L(59)),Y(L(60)),Y(L(61)),Y(L(62)),Y(L(63)),Y(L(64)),Y(L(65)),Y(L(66)),Y(L(67)),Y(L(68)),Y(L(69)),Y(L(70)),Y(L(71)),Y(L(72)),Y(L(73)),Y(L(74)),Y(L(75)),Y(L(76)),Y(L(77)),Y(L(78)),Y(L(79)),Y(L(80)),Y(L(81)),Y(L(82)),Y(L(83)),Y(L(84)),Y(L(85)),Y(L(86)),Y(L(87)),Y(L(88)),Y(L(89)),Y(L(90)),Y(L(91)),Y(L(92)),Y(L(93)),Y(L(94)),Y(L(95)),Y(L(96)),Y(L(97)),Y(L(98)),Y(L(99)),Y(L(100)))	MAN1570
		MAN1580
		MAN1590
		MAN1600
		MAN1602
		MAN1604
		MAN1620
		MAN1630
		MAN1640

```

3L(32)),Y(L(33)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(19)),Y(L(2MAN1650
43)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),Y(L(30)),MAN1652
5Y(L(34)),Y(L(35)),10)MAN1654
IF (NUMS.EQ.CHK(12)) CALL SOLVE2(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),YMAN1670
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))MAN1680
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(MAN1690
3L(32)),Y(L(33)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(19)),Y(L(2MAN1700
43)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),Y(L(30)),MAN1702
5Y(L(34)),Y(L(35)),10)MAN1704
IF (NUMS.EQ.CHK(13)) CALL SOLVE3(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),YMAN1720
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))MAN1730
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(MAN1740
3L(32)),Y(L(33)),Y(L(36)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(1MAN1750
49)),Y(L(23)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),MAN1752
5Y(L(30)),Y(L(34)),Y(L(35)),10)MAN1754
CALL COEF(Y(L(1)),Y(L(5)),Y(L(6)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10))MAN1770
1,Y(L(11)),Y(L(12)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(MAN1780
2L(19)),Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(3MAN1790
32)),Y(L(30)),Y(L(34)),Y(L(35)),10)MAN1800
CALL CHECKI(Y(L(1)),Y(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(10)),Y(L(1MAN1810
11)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(17)),Y(L(18)),Y(L(19))MAN1820
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),10MAN1830
3)
CALL PRNTAI(Y(L(1)),Y(L(8)),Y(L(9)),Y(L(12)),Y(L(14)),Y(L(29)),Y(LMAN1840
1(32)),1,10)MAN1850
C .....MAN1860
C .....MAN1870
C ---START COMPUTATIONS---MAN1880
C *****MAN1890
C ---READ AND WRITE DATA FOR GROUPS II AND III---MAN1900
900 CONTINUE $1-140
C--If not first call of TRES, enter DATAI only to set PHI=SURI: $1-150
CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(13)),1)
C--If not first call of TRES, do not read data: $1-160
IF(KCALL.NE.1)GO TO 910 $1-170
DO 1 I=1,9
IFMT(I)=IFMT3(I)
1 IN(I)=NAME(I)
IRN=2
CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(12)),2)
IF (WATER.EQ.CHK(2)) GO TO 240 MAN1930
DO 2 I=1,9
IFMT(I)=IFMT3(I)
2 IN(I)=NAME(9+I)
IRN=3
CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(

```

```

3L(34)),Y(L(35)),Y(L(9)),2)
GO TO 250
240 DO 3 I=1,9
    IFMT(I)=IFMT1(I)
3    IN(I)=NAME(18+I)
    INR=4
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(17)),2)
    DO 4 I=1,9
    IFMT(I)=IFMT2(I)
4    IN(I)=NAME(27+I)
    INR=5
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(18)),2)
    DO 5 I=1,9
    IFMT(I)=IFMT3(I)
5    IN(I)=NAME(36+I)
    INR=6
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(19)),2)
250 IF(CONVRT.EQ.CHK(7)) THEN
    DO 6 I=1,9
    IFMT(I)=IFMT2(I)
6    IN(I)=NAME(45+I)
    INR=7
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(23)),2)
    ENDIF
    IF (LEAK.NE.CHK(9)) GO TO 260
    DO 7 I=1,9
    IFMT(I)=IFMT1(I)
7    IN(I)=NAME(54+I)
    INR=8
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(20)),2)
    DO 8 I=1,9
    IFMT(I)=IFMT2(I)
8    IN(I)=NAME(63+I)
    INR=9
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(21)),2)
    DO 9 I=1,9

```

```

IFMT(I)-IFMT2(I)
9  IN(I)-NAME(72+I)
   INR=10
   CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(22)),2)
260 IF (EVAP.EQ.CHK(6)) THEN
    DO 11 I=1,9
    IFMT(I)-IFMT2(I)
11  IN(I)-NAME(81+I)
    INR=11
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(24)),2)
    ENDIF
    IF(RECH.EQ.CHK(10)) THEN
    DO 12 I=1,9
    IFMT(I)-IFMT1(I)
12  IN(I)-NAME(90+I)
    INR=12
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(13)),2)
    ENDIF
    CALL DATAI(Y(L(1)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10)),Y(L(11)),Y(L(1
12)),Y(L(13)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(L(19))
2,Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(32)),Y(
3L(34)),Y(L(35)),Y(L(13)),3)
C
C      ---INITIALIZE TRANSMISSIVITY VALUES IN WATER TABLE PROBLEM---      MAN2070
C--If not first call of TRES, enter COEF to recompute                        MAN2080
C-----transmissivities, based on heads (PHI) for unconfined aquifer:      $1-180
910 CONTINUE                                                                    $1-190
    KT=0                                                                           $1-200
    IF (WATER.EQ.CHK(2)) THEN                                                    MAN2090
    CALL COEF(Y(L(1)),Y(L(5)),Y(L(6)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(10))
1,Y(L(11)),Y(L(12)),Y(L(14)),Y(L(15)),Y(L(16)),Y(L(17)),Y(L(18)),Y(
2L(19)),Y(L(20)),Y(L(21)),Y(L(22)),Y(L(23)),Y(L(24)),Y(L(29)),Y(L(3
32)),Y(L(30)),Y(L(34)),Y(L(35)),2)
    ENDIF
C
C--If not first call of TRES, begin new pumping period.                       MAN2110
IF(KCALL.NE.1) GO TO 270                                                         $1-210
C      ---COMPUTE ITERATION PARAMETERS---                                       $1-220
IF(NUMS.EQ.CHK(11)) THEN                                                       MAN2120
CALL SOLVE1(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(
3L(32)),Y(L(33)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(19)),Y(L(2
43)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),Y(L(30)),
5Y(L(34)),Y(L(35)),1)

```



```

      ENDIF
C
C      ---ENTER APPROPRIATE SOLUTION ROUTINE AND COMPUTE SOLUTION---
C      IF (NUMS.EQ.CHK(11)) THEN
C      CALL SOLVE1(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(
3L(32)),Y(L(33)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(19)),Y(L(2
43)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),Y(L(30)),
5Y(L(34)),Y(L(35)),2)
C      ENDIF
C      IF(NUMS.EQ.CHK(12)) THEN
C      CALL SOLVE2(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(
3L(32)),Y(L(33)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(19)),Y(L(2
43)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),Y(L(30)),
5Y(L(34)),Y(L(35)),2)
C      ENDIF
C      IF (NUMS.EQ.CHK(13)) THEN
C      CALL SOLVE3(Y(L(1)),Y(L(2)),Y(L(3)),Y(L(4)),Y
1(L(5)),Y(L(6)),Y(L(7)),Y(L(9)),Y(L(12)),Y(L(13)),Y(L(14)),Y(L(15))
2,Y(L(16)),Y(L(25)),Y(L(26)),Y(L(27)),Y(L(28)),Y(L(29)),Y(L(31)),Y(
3L(32)),Y(L(33)),Y(L(36)),Y(L(37)),Y(L(10)),Y(L(11)),Y(L(24)),Y(L(1
49)),Y(L(23)),Y(L(20)),Y(L(22)),Y(L(21)),Y(L(8)),Y(L(17)),Y(L(18)),
5Y(L(30)),Y(L(34)),Y(L(35)),2)
C      ENDIF
C
C      ---CHECK FOR STEADY STATE AND PRINT OUTPUT AT DESIGNATED
C      TIME STEPS---
C      CALL STEP(Y(L(1)),Y(L(5)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(14)),Y(L(17)
1),Y(L(18)),Y(L(23)),Y(L(29)),Y(L(30)),Y(L(32)),Y(L(34)),Y(L(35)),Y
2(L(37)),Y(L(10)),Y(L(11)),Y(L(12)),Y(L(13)),Y(L(15)),Y(L(19)),Y(L(
320)),Y(L(21)),Y(L(22)),Y(L(24)),2)
C
C      ---LAST TIME STEP IN PUMPING PERIOD ?---
C      IF (IFINAL.NE.1) GO TO 280
C
C      ---CHECK FOR NEW PUMPING PERIOD---
C      IF (KP.LT.NPER) GO TO 270
C
C      ---DISK OUTPUT IF DESIRED---
C      IF (IDK2.NE.CHK(15)) GO TO 290
C      CALL STEP(Y(L(1)),Y(L(5)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(14)),Y(L(17)
1),Y(L(18)),Y(L(23)),Y(L(29)),Y(L(30)),Y(L(32)),Y(L(34)),Y(L(35)),Y
2(L(37)),Y(L(10)),Y(L(11)),Y(L(12)),Y(L(13)),Y(L(15)),Y(L(19)),Y(L(
320)),Y(L(21)),Y(L(22)),Y(L(24)),5)
C
C      ---PUNCHED OUTPUT IF DESIRED---
290 IF (PNCH.NE.CHK(1)) GO TO 300
C      CALL STEP(Y(L(1)),Y(L(5)),Y(L(7)),Y(L(8)),Y(L(9)),Y(L(14)),Y(L(17)
1),Y(L(18)),Y(L(23)),Y(L(29)),Y(L(30)),Y(L(32)),Y(L(34)),Y(L(35)),Y
2(L(37)),Y(L(10)),Y(L(11)),Y(L(12)),Y(L(13)),Y(L(15)),Y(L(19)),Y(L(
320)),Y(L(21)),Y(L(22)),Y(L(24)),6)

```

```

C
C--Return to PRE, rather than stopping:
300 RETURN
C ---CHECK FOR NEW PROBLEM---
C 300 READ (R,320,END=310) NEXT
C IF (NEXT.EQ.0) GO TO 10
C 310 STOP
C .....
C ---FORMATS---
C -----
C
C 320 FORMAT (4I10)
C 330 FORMAT ('0',54X,'WORDS OF Y VECTOR USED =',I7)
C 340 FORMAT ('0',62X,'NUMBER OF ROWS =',I5/60X,'NUMBER OF COLUMNS =',I5
1/9X,'NUMBER OF WELLS FOR WHICH DRAWDOWN IS COMPUTED AT A SPECIFIED
2 RADIUS =',I5,/39X,'MAXIMUM PERMITTED NUMBER OF ITERATIONS =',I5)
C 350 FORMAT ('-',36X,'NO EQUATION SOLVING SCHEME SPECIFIED, EXECUTION T
1ERMINATED'/37X,58('*'))
C 360 FORMAT ('1',60X,'U. S. G. S.'//55X,'FINITE-DIFFERENCE MODEL'/65X,'
1FOR'/51X,'SIMULATION OF GROUND-WATER FLOW'//60X,'JANUARY, 1975'//1
233('*')/'0',32A4//133('*'))
C 370 FORMAT (20A4)
C 380 FORMAT (16(A4,1X))
C 390 FORMAT ('-SIMULATION OPTIONS: ',13(A4,4X))
END
SUBROUTINE DATAI(PHI,STRT,SURI,T,TR,TC,S,QRE,WELL,TL,SL,PERM,BOTTODAT
1M,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,WR,NWR,A,NENT)
C -----DAT 30
C READ AND WRITE INPUT DATA DAT 40
C -----DAT 50
C DAT 60
C SPECIFICATIONS: DAT 70
IMPLICIT REAL *8 (A-H,O-Z) $2-10
REAL *8 M,MESUR $$2-11
INTEGER R,P,PU,DIML,DIMW
INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD
1,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C DAT 120
DIMENSION PHI(IZ,JZ),STRT(IZ,JZ),SURI(IZ,JZ),T(IZ,JZ),TR(IZ,JZ),
1),TC(IZ,JZ),S(IZ,JZ),QRE(IZ,JZ),WELL(IZ,JZ),TL(IZ,JZ),SL(IZ,
2JZ),PERM(IP,JP),BOTTOM(IP,JP),SY(IP,JP),RATE(IR,JR),RIVER(IR,
3JR),M(IR,JR),TOP(IC,JC),GRND(IL,JL),DELX(JZ),DELY(IZ),WR(IH)
4,NWR(IH,2),A(IZ,JZ),IN(9),IFMT(9)
C DAT 170
C DAT 180
COMMON /SARRAY/ VF4(11),CHK(15)
COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT
COMMON /PRI/ NA(4),N1,N2,N3
C DAT 190
C DAT 250

```

```

COMMON /PRR/ PRNT(122),DIGIT(122),XN(100),BLANK(60),SYM(17),
1YN(13),VF1(6),VF2(6),VF3(7),YLABEL(6),TITLE(5),XLABEL(3),XN1,
2MESUR,XSCALE,YSCALE,DINCH,FACT1,FACT2
COMMON /ARSize/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
COMMON /Names/IFMT,IN,IRN
COMMON /LOCATS/ ILOCW(200),JLOCW(200),ILOCC(500),JLOCC(500),          $2-20
& KEYQ(200),KEYWL(500),XRAD(200)                                     $2-30
COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELT,TIMPER,          $2-40
& TIMING(50)                                                         $2-50
GO TO(1,2,3,4) NENT
RETURN                                                                DAT 300
C .....
C *****
C ENTRY DATAIN(PHI,STRT,SURI,T,TR,TC,QRE,WELL,TL,SL
C 1,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,WR,NWR)
C *****
1 CONTINUE
IF(KCALLP.NE.1)GO TO 970                                             $2-60
C                                                                DAT 350
C ---READ AND WRITE SCALAR PARAMETERS---                             DAT 360
READ (R,500) CONTR,XSCALE,YSCALE,DINCH,FACT1,FACT2,MESUR          DAT 370
C IF (CONTR.EQ.CHK(3)) WRITE (P,610) XSCALE,YSCALE,MESUR,MESUR,DINCHDAT 380
C 1,FACT1,FACT2                                                    DAT 390
READ (R,490) NPER,KTH,ERR,EROR,SS,QET,ETDIST,LENGTH              DAT 400
C--Overwrite the value of NNPER from AQMAN common onto NPER:      $2-61
NPER=NNPER                                                         $2-62
READ(R,485) HMAX,FACTX,FACTY
IF (ETDIST.LE.0.) ETDIST=1.                                        DAT 420
C WRITE (P,520) NPER,KTH,ERR,EROR,SS,QET,ETDIST,FACTX,FACTY      DAT 430
C                                                                DAT 440
C ---READ CUMULATIVE MASS BALANCE PARAMETERS---                     DAT 450
READ (R,600) SUM,SUMP,PUMPT,CFLUXT                                DAT 460
READ (R,600) QRET,CHST,CHDT,FLUXT
READ (R,605) STORT,ETFLXT,FLXNT
IF (IDK1.EQ.CHK(14)) GO TO 20                                     DAT 480
IF (SUM.EQ.0.0) GO TO 40
C WRITE (P,480) SUM                                                DAT 500
C ..... DAT 510
C                                                                DAT 520
C ---HEAD DATA TO CONTINUE PREVIOUS COMPUTATIONS READ HERE---    DAT 530
C -----FROM CARDS:                                             DAT 540
DO 10 I=1,DIML                                                    DAT 550
READ (R,540) (PHI(I,J),J=1,DIMW)                                DAT 560
C 10 WRITE (P,530) I,(PHI(I,J),J=1,DIMW)                          DAT 570
10 CONTINUE
GO TO 40                                                           DAT 580
C -----READ AND WRITE DATA FROM UNIT 6 ON DISK RATHER THAN CARDS: DAT 590
20 READ (6) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETFLDAT 600
1XT,FLXNT                                                         DAT 610
C WRITE (P,480) SUM                                                DAT 620
DO 30 I=1,DIML                                                    DAT 630
C 30 WRITE (P,530) I,(PHI(I,J),J=1,DIMW)                          DAT 640
30 CONTINUE
REWIND 6                                                           DAT 650

```

C	..... STRT (STARTING HEAD) .....	DAT 660
40	READ (R,495) FACT,IVAR,IPRN,IRECS,IRECD	DAT 670
	IF (IRECS.EQ.1) READ (5,REC-1) STRT	DAT 680
C	IF ((IVAR.EQ.1.OR.IRECS.EQ.1).AND.IPRN.NE.1) WRITE (P,470)	DAT 690
	DO 80 I=1,DIML	DAT 700
	IF (IVAR.EQ.1) READ (R,540) (STRT(I,J),J-1,DIMW)	DAT 710
	DO 70 J=1,DIMW	DAT 720
	IF (IRECS.EQ.1) GO TO 60	DAT 730
	IF (IVAR.NE.1) GO TO 50	DAT 740
	STRT(I,J)=STRT(I,J)*FACT	DAT 750
	GO TO 60	DAT 760
50	STRT(I,J)=FACT	DAT 770
60	SURI(I,J)=STRT(I,J)	DAT 780
	T(I,J)=0.	DAT 785
	TL(I,J)=0.	DAT 790
	SL(I,J)=0.	DAT 800
	TR(I,J)=0.	DAT 810
	TC(I,J)=0.	DAT 820
	WELL(I,J)=0.0	DAT 830
	QRE(I,J)=0.	DAT 840
70	IF (SUM.EQ.0.0.AND.IDK1.NE.CHK(14)) PHI(I,J)=STRT(I,J)	DAT 850
	IF (IVAR.EQ.0.AND.IRECS.EQ.0.OR.IPRN.EQ.1) GO TO 80	DAT 860
C	WRITE (P,530) I,(STRT(I,J),J-1,DIMW)	DAT 870
80	CONTINUE	DAT 880
C	IF (IVAR.NE.1.AND.IRECS.NE.1) WRITE (P,420) FACT	DAT 890
C	IF (IRECD.EQ.1) WRITE (5,REC-1) STRT	DAT 900
	IF(KCALLP.EQ.1)RETURN	\$2-100
970	DO 990 I=1,DIML	\$2-110
	DO 990 J=1,DIMW	\$2-120
990	PHI(I,J)=SURI(I,J)	\$2-200
	RETURN	DAT 910
C		DAT 920
C	---READ REMAINING ARRAYS FROM CARDS OR DISK (AS SPECIFIED IN THE	DAT 930
C	OPTIONS) AND WRITE THEM ON DISK IF SPECIFIED IN THE OPTIONS---	DAT 940
C	*****	DAT 950
C	ENTRY ARRAY(A,IFMT,IN,IRN)	
C	*****	DAT 970
2	CONTINUE	
	READ (R,495) FACT,IVAR,IPRN,IRECS,IRECD	DAT 980
	IK=4*IRECS+2*IVAR+IPRN+1	DAT 990
	GO TO (90,90,110,110,140,140), IK	DAT1000
90	DO 100 I=1,DIML	DAT1010
	DO 100 J=1,DIMW	
100	A(I,J)=FACT	DAT1030
C	WRITE (P,430) IN,FACT	DAT1040
	GO TO 160	DAT1050
C 110	IF (IK.EQ.3) WRITE (P,440) IN	DAT1060
110	CONTINUE	
	DO 130 I=1,DIML	DAT1070
	READ (R,510) (A(I,J),J-1,DIMW)	DAT1080
	DO 120 J=1,DIMW	DAT1090
120	A(I,J)=A(I,J)*FACT	DAT1100
C 130	IF (IK.EQ.3) WRITE (P,IFMT) I,(A(I,J),J-1,DIMW)	DAT1110
130	CONTINUE	

	GO TO 160	DAT1120
140	READ (5,REC=IRN) A	DAT1130
	IF (IK.EQ.6) GO TO 160	DAT1140
C	WRITE (P,440) IN	DAT1150
	DO 150 I=1,DIML	DAT1160
C 150	WRITE (P,IFMT) I,(A(I,J),J=1,DIMW)	DAT1170
	150 CONTINUE	
C 160	IF (IRECD.EQ.1) WRITE (5,REC=IRN) A	DAT1180
160	CONTINUE	
	RETURN	DAT1190
C		DAT1200
C	---INSERT ZERO VALUES IN THE T OR PERM MATRIX AROUND THE	DAT1210
C	BORDER OF THE MODEL---	DAT1220
C	*****	DAT1230
C	ENTRY MDAT(T,TL,PERM,RATE,M,DELX,DELY)	
C	*****	DAT1250
3	CONTINUE	
	DO 180 I=1,DIML	DAT1260
	DO 180 J=1,DIMW	DAT1270
	IF (WATER.EQ.CHK(2)) GO TO 170	DAT1280
	IF (I.EQ.1.OR.I.EQ.DIML.OR.J.EQ.1.OR.J.EQ.DIMW) T(I,J)=0.	DAT1290
	GO TO 180	DAT1300
170	IF (I.EQ.1.OR.I.EQ.DIML.OR.J.EQ.1.OR.J.EQ.DIMW) PERM(I,J)=0.	DAT1310
180	CONTINUE	DAT1320
C	..... DELX,DELY .....	DAT1330
	READ (R,495) FACT,IVAR,IPRN,IRECS,IRECD	DAT1340
	IF (IRECS.EQ.1) GO TO 210	DAT1350
	IF (IVAR.EQ.1) READ (R,498) DELX	DAT1360
	DO 200 J=1,DIMW	DAT1370
	IF (IVAR.NE.1) GO TO 190	DAT1380
	DELX(J)=DELX(J)*FACT	DAT1390
	GO TO 200	DAT1400
190	DELX(J)=FACT	DAT1410
200	CONTINUE	DAT1420
	GO TO 220	DAT1430
210	READ (5,REC=13) DELX	DAT1440
C 220	IF (IRECD.EQ.1) WRITE (5,REC=13) DELX	DAT1450
220	CONTINUE	
C	IF (IVAR.EQ.1.OR.IRECS.EQ.1.AND.IPRN.NE.1) WRITE (P,550) DELX	DAT1460
C	IF (IVAR.NE.1.AND.IRECS.NE.1) WRITE (P,450) FACT	DAT1470
	READ (R,495) FACT,IVAR,IPRN,IRECS,IRECD	DAT1480
	IF (IRECS.EQ.1) GO TO 250	DAT1490
	IF (IVAR.EQ.1) READ (R,498) DELY	DAT1500
	DO 240 I=1,DIML	DAT1510
	IF (IVAR.NE.1) GO TO 230	DAT1520
	DELY(I)=DELY(I)*FACT	DAT1530
	GO TO 240	DAT1540
230	DELY(I)=FACT	DAT1550
240	CONTINUE	DAT1560
	GO TO 260	DAT1570
250	READ (5,REC=14) DELY	DAT1580
C 260	IF (IRECD.EQ.1) WRITE (5,REC=14) DELY	DAT1590
260	CONTINUE	
C	IF (IVAR.EQ.1.OR.IRECS.EQ.1.AND.IPRN.NE.1) WRITE (P,560) DELY	DAT1600

C	IF (IVAR.NE.1.AND.IRECS.NE.1) WRITE (P,460) FACT	DAT1610
C		DAT1620
C	---INITIALIZE VARIABLES---	DAT1630
	JNO1=DIMW-1	DAT1640
	INO1=DIML-1	DAT1650
	IF (LEAK.NE.CHK(9).OR.SS.NE.0.) GO TO 280	DAT1660
	DO 270 I=2,INO1	DAT1670
	DO 270 J=2,JNO1	DAT1680
	IF (M(I,J).EQ.0.) GO TO 270	DAT1690
	TL(I,J)=RATE(I,J)/M(I,J)	DAT1700
270	CONTINUE	DAT1710
280	ETQB=0.0	DAT1720
	ETQD=0.0	DAT1730
	SUBS=0.0	DAT1740
	U=1.0	DAT1750
	TT=0.0	DAT1760
	IM=MINO(6*DIMW+4,124)	DAT1770
	IM=(132-IM)/2	DAT1780
	VF4(3)=DIGIT(IM)	DAT1790
	VF4(8)=DIGIT(IM+5)	DAT1800
	WIDTH=0.	DAT1810
	DO 290 J=2,JNO1	DAT1820
290	WIDTH=WIDTH+DELX(J)	DAT1830
	YDIM=0.	DAT1840
	DO 300 I=2,INO1	DAT1850
300	YDIM=YDIM+DELY(I)	DAT1860
	RETURN	DAT1870
C	.....	DAT1880
C		DAT1890
C	---READ TIME PARAMETERS AND PUMPING DATA FOR A NEW PUMPING PERIOD---	DAT1900
C	*****	DAT1910
C	ENTRY NEWPER(PHI,STRT,WELL,SL,RATE,RIVER,M,DELX,DELY,WR,NWR)	
C	*****	DAT1930
4	CONTINUE	
C		DAT1940
	IF(KPER.GT.1)GO TO 905	\$2-210
C--Re-initialize cumulative time and mass balance parameters:		\$2-220
	SUM=0.0	\$2-230
	SUMP=0.0	\$2-240
	PUMPT=0.0	\$2-250
	CFLUXT=0.0	\$2-260
	QRET=0.0	\$2-270
	CHST=0.0	\$2-280
	CHDT=0.0	\$2-290
	FLUXT=0.0	\$2-300
	STORT=0.0	\$2-310
	ETFLXT=0.0	\$2-320
	FLXNT=0.0	\$2-330
	ETQB=0.0	\$2-340
	ETQD=0.0	\$2-350
	SUBS=0.0	\$2-360
	U=1.0	\$2-370
	TT=0.0	\$2-380
905	CONTINUE	\$2-390

C--Comment out the TRESMOTT read statement for pumping period info:	\$2-391
C READ (R,505) KP,KPM1,NWEL,TMAX,NUMT,CDLT,DELT	\$\$2-392
C--Get pumping period data from "AQMAN" COMMON:	\$2-480
910 CALL READ1(1,KP,KPM1,NWEL,TMAX,NUMT,DELT,CDLT,M1,M2,M3,M4,M5)	\$2-490
C	DAT1960
C ---COMPUTE ACTUAL DELT AND NUMT---	DAT1970
DT=DELT/24.	DAT1980
TM=0.0	DAT1990
DO 310 I=1,NUMT	DAT2000
DT=CDLT*DT	DAT2010
TM=TM+DT	DAT2020
IF (TM.GE.TMAX) GO TO 320	DAT2030
310 CONTINUE	DAT2040
GO TO 330	DAT2050
320 DELT=TMAX/TM*DELT	DAT2060
NUMT=I	DAT2070
C 330 WRITE (P,570) KP,TMAX,NUMT,DELT,CDLT	DAT2080
330 CONTINUE	
DELT=DELT*3600.	DAT2090
TMAX=TMAX*86400.	DAT2100
C	DAT2110
C ---INITIALIZE SUMP, STRT, SL, WELL AND WR---	DAT2120
C WRITE (P,580) NWEL	DAT2130
IF (KP.GT.KPM1) SUMP=0.	DAT2140
DO 350 I=1,DIML	DAT2150
DO 350 J=1,DIMW	DAT2160
IF (KP.EQ.KPM1) GO TO 340	DAT2170
STRT(I,J)=PHI(I,J)	DAT2180
340 IF (LEAK.NE.CHK(9)) GO TO 350	DAT2190
IF (M(I,J).EQ.0.) GO TO 350	DAT2200
SL(I,J)=RATE(I,J)/M(I,J)*(RIVER(I,J)-STRT(I,J))	DAT2210
350 WELL(I,J)=0.	DAT2220
C--If start of a new call of TRES, set starting heads to original	\$2-550
C---initial heads:	\$2-560
IF(KPER.NE.1)GO TO 930	\$2-570
DO 920 I=1,DIML	\$2-580
DO 920 J=1,DIMW	\$2-590
STRT(I,J)=SURI(I,J)	\$2-600
920 CONTINUE	\$2-610
930 CONTINUE	\$2-620
IF (NW.EQ.0) GO TO 370	DAT2230
DO 360 I=1,NW	DAT2240
360 WR(I)=0.	DAT2250
370 CONTINUE	
IF (NWEL.EQ.0) GO TO 410	DAT2260
C	DAT2270
C ---READ AND WRITE WELL PUMPING RATES AND WELL RADII---	DAT2280
KW=0	DAT2290
DO 400 II=1,NWEL	DAT2300
C--Comment out the TRESMOTT read statement for well data:	\$2-670
C READ (R,490) I,J,WELL(I,J),RADIUS	\$\$2-680
C--Retrieve well locations, radii, and pumpages, from "AQMAN" COMMON:	\$2-690
940 CALL READ1(2,M1,M2,M3,M4,M5,M6,M7,I,J,II,RADIUS,XWELL)	\$2-700
WELL(I,J)=XWELL	\$2-710

IF (RADIUS.EQ.0.) GO TO 380	DAT2320
KW=KW+1	DAT2330
IF (KW.GT.NW) GO TO 380	DAT2340
NWR(KW,1)=I	DAT2350
NWR(KW,2)=J	DAT2360
WR(KW)=RADIUS	DAT2370
C WRITE (P,590) I,J,WELL(I,J),WR(KW)	DAT2380
GO TO 390	DAT2390
C 380 WRITE (P,590) I,J,WELL(I,J)	DAT2400
380 CONTINUE	
390 WELL(I,J)=WELL(I,J)/(DELX(J)*DELY(I))	DAT2410
400 CONTINUE	DAT2420
C--Increase pumping period counter:	\$2-720
410 KPER=KPER+1	\$2-730
RETURN	DAT2430
C .....	DAT2440
C	DAT2450
C FORMATS:	DAT2460
C	DAT2470
C -----	DAT2480
C	DAT2490
C	DAT2500
420 FORMAT ('0',63X,'STARTING HEAD =',G15.7)	DAT2510
430 FORMAT ('0',41X,9A4,'-',G15.7)	DAT2520
440 FORMAT ('1',49X,9A4,/,65X,'MATRIX',/,50X,36('-'))	DAT2530
450 FORMAT ('0',72X,'DELX =',G15.7)	DAT2540
460 FORMAT ('0',72X,'DELY =',G15.7)	DAT2550
470 FORMAT ('1',60X,'STARTING HEAD MATRIX'/61X,20('-'))	DAT2560
480 FORMAT ('1',40X,' CONTINUATION - HEAD AFTER ',G20.7,' SEC PUMPING	DAT2570
1'/42X,58('-'))	DAT2580
485 FORMAT (3G10.0)	
490 FORMAT (2I10,5G10.0,I10,3G10.0)	
495 FORMAT (G10.0,4I10)	
498 FORMAT (8G10.0)	
500 FORMAT (A4,6X,5G10.0,A6)	DAT2600
505 FORMAT (3I10,G10.0,I10,2G10.0)	
510 FORMAT (20F4.0)	DAT2610
520 FORMAT ('0',51X,'NUMBER OF PUMPING PERIODS =',I5/49X,'TIME STEPS B	DAT2620
1ETWEEN PRINTOUTS =',I5//51X,'ERROR CRITERION FOR CLOSURE =',G15.7/DAT2630	
241X,' STEADY STATE ERROR CRITERION =',G15.7//44X,'SPECIFIC	DAT2640
3 STORAGE OF CONFINING BED =',G15.7/54X,'EVAPOTRANSPIRATION RATE ='	DAT2650
4,G15.7/56X,'EFFECTIVE DEPTH OF ET =',G15.7//22X,'MULTIPLICATION FADAT2660	
5CTOR FOR TRANSMISSIVITY IN X DIRECTION =',G15.7/63X,'IN Y DIRECTIODAT2670	
6N =',G15.7)	DAT2680
530 FORMAT ('0',I2,2X,20F6.1/(5X,20F6.1))	DAT2690
540 FORMAT (8F10.4)	DAT2700
550 FORMAT (1H1,46X,40HGRID SPACING IN PROTOTYPE IN X DIRECTION/47X,40	DAT2710
1('-')//('0',12F10.0))	DAT2720
560 FORMAT (1H-,46X,40HGRID SPACING IN PROTOTYPE IN Y DIRECTION/47X,40	DAT2730
1('-')//('0',12F10.0))	DAT2740
570 FORMAT ('-',50X,'PUMPING PERIOD NO.',I4,':',F10.2,' DAYS'/51X,38('	DAT2750
1-')//53X,'NUMBER OF TIME STEPS=',I6//59X,'DELT IN HOURS =',F10.3//	DAT2760
253X,'MULTIPLIER FOR DELT =',F10.3)	DAT2770
580 FORMAT ('-',63X,I4,' WELLS'/65X,9('-')//50X,'I',9X,'J PUMPING R	DAT2780

```

LATE WELL RADIUS'/)
590 FORMAT (41X,2I10,2F13.4)
600 FORMAT (4G20.10)
605 FORMAT (3G20.10)
610 FORMAT ('0',30X,'ON ALPHAMERIC MAP:'/'40X,'MULTIPLICATION FACTOR FODAT2820
1R X DIMENSION =' ,G15.7/40X,'MULTIPLICATION FACTOR FOR Y DIMENSION DAT2830
2=' ,G15.7/55X,'MAP SCALE IN UNITS OF ' ,A11/50X,'NUMBER OF ' ,A8,' PDAT2840
3ER INCH =' ,G15.7/43X,'MULTIPLICATION FACTOR FOR DRAWDOWN =' ,G15.7/DAT2850
447X,'MULTIPLICATION FACTOR FOR HEAD =' ,G15.7)
END
SUBROUTINE STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,DDNSTP 10
1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,NENT)
C -----STP 30
C INITIALIZE DATA FOR TIME STEP, CHECK FOR STEADY STATE, STP 40
C PRINT AND PUNCH RESULTS STP 50
C -----STP 60
C STP 70
C SPECIFICATIONS: STP 80
C IMPLICIT REAL *8 (A-H,O-Z) $3-10
C REAL *8 MESUR,KEEP,M $$$-20
C REAL *4 MINS,CASE,TYPE,NNAME $$$-30
C INTEGER R,P,PU,DIML,DIMW,YYY
C INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM
C 1,HEAD,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C STP 130
C DIMENSION PHI(IZ,JZ), KEEP(IZ,JZ), STRT(IZ,JZ), SURI(IZ,JZ), T(IZ,STP 140
1JZ), BOTTOM(IP,JP), WELL(IZ,JZ), PERM(IP,JP), TOP(IC,JC), DELX(JZ)STP 150
2,DDN(JZ), DELY(IZ), WR(IH), NWR(IH,2), ITTO(200), TEST3(IMX1),
3TR(IZ,JZ),TC(IZ,JZ),S(IZ,JZ),QRE(IZ,JZ),TL(IZ,JZ),SY(IP,JP),
4RATE(IR,JR),RIVER(IR,JR),M(IR,JR),GRND(IL,JL)
C DIMENSION TYPE(4) $3-40
C STP 170
C COMMON /SARRAY/ VF4(11),CHK(15) STP 180
C COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
C COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
C COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT STP 240
C COMMON /ARSIZE/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
C COMMON /PRI/ NA(4),N1,N2,N3
C COMMON /PRR/ PRNT(122),DIGIT(122),XN(100),BLANK(60),SYM(17),
1YN(13),VF1(6),VF2(6),VF3(7),YLABEL(6),TITLE(5),XLABEL(3),XN1,
2MESUR,XSCALE,YSCALE,DINCH,FACT1,FACT2
C STP 290
C COMMON /ALPHAS/ NNAME(16),CASE $3-50
C COMMON /PARAMS/ KCALLP,NWLS,NCNTR,NNPER,KPER,CDELT,TIMPER, $3-51
& TIMINC(50) $3-52
C DATA TYPE/'LINE','NONL','LINE','QUAD'/ $3-53
C DATA PIE/3.141593/,YYY/:00000000/
C GO TO (1,2,3,4,5,6) NENT
C RETURN STP 310
C .....STP 320
C .....STP 330

```

C	---	START A NEW TIME STEP---	STP 340
C	*****		STP 350
C	ENTRY	NEWSTP(PHI,KEEP)	
C	*****		STP 370
1	CONTINUE		
	KT	=KT+1	STP 380
	KOUNT	=0	STP 390
	DO 10 I	=1, DIML	STP 400
	DO 10 J	=1, DIMW	STP 410
10	KEEP(I, J)	=PHI(I, J)	STP 420
	DELT	=CDLT*DELT	STP 430
	SUM	=SUM+DELT	STP 440
	SUMP	=SUMP+DELT	STP 450
	DAYS	SP=SUM/86400.	STP 460
	YRSP	=DAYS/365.	STP 470
	HRS	=SUM/3600.	STP 480
	MINS	=HRS*60.	STP 490
	DAYS	=HRS/24.	STP 500
	YRS	=DAYS/365.	STP 510
	RETURN		STP 520
C	.....		STP 530
C			STP 540
C	---	CHECK FOR STEADY STATE---	STP 550
C	*****		STP 560
C	ENTRY	STEADY(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,	
C	1DDN,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,		
C	2M,GRND)		
C	*****		STP 580
2	CONTINUE		
	TEST2	=0.	STP 590
	DO 20 I	=2, INO1	STP 600
	DO 20 J	=2, JNO1	STP 610
	DTT	=DABS(DBLE(KEEP(I, J) - PHI(I, J)))	
20	TEST2	=DMAX1(TEST2,DTT)	
	IF (TEST2	.GE.EROR) GO TO 30	STP 630
C	WRITE (P,330)	KT	STP 640
	IFINAL	=1	STP 650
	GO TO	40	STP 660
30	IF (KT	.EQ.NUMT) IFINAL=1	STP 670
C			STP 680
C	---	ENTRY FOR TERMINATING COMPUTATIONS IF MAXIMUM ITERATIONS	STP 690
C	EXCEEDED---		STP 700
C	*****		STP 710
C	ENTRY	TERM1(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,	
C	1DDN,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND)		
C	*****		STP 730
3	CONTINUE		
40	IF (KT	.GT.200) WRITE (P,400)	STP 740
	ITTO(KT)	=KOUNT	STP 750
	IF (KOUNT	.LE.ITMAX) GO TO 80	STP 760
	IERR	=2	STP 770
	KOUNT	=KOUNT-1	STP 780
	ITTO(KT)	=KOUNT	STP 790
	IF (KT	.EQ.1) GO TO 60	STP 800

```

C                                                    STP 810
C   ---WRITE ON DISK OR PUNCH CARDS AS SPECIFIED IN THE OPTIONS--- STP 820
C   XXX=SUM-DELT                                                    STP 830
C   IF (IDK2.EQ.CHK(15)) WRITE (6) ((KEEP(I,J),YYY,I-1,DIML),J-1,DIMW)STP 840
C   1,XXX,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETFLXT,FLXNT STP 850
C   IF (PNCH.NE.CHK(1)) GO TO 80                                    STP 860
C   WRITE (PU,360) XXX,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETSTP 870
C   1FLXT,FLXNT                                                    STP 880
C   DO 50 I=1,DIML                                                STP 890
C   50 WRITE (PU,350) (KEEP(I,J),J-1,DIMW)                        STP 900
C   50 CONTINUE
C   GO TO 80                                                        STP 910
C   60 IF (IDK2.EQ.CHK(15)) WRITE (6) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHSTSTP 920
C   1,CHDT,FLUXT,STORT,ETFLXT,FLXNT                               STP 930
C   60 CONTINUE
C   IF (PNCH.NE.CHK(1)) GO TO 80                                    STP 940
C   WRITE (PU,360) SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETSTP 950
C   1FLXT,FLXNT                                                    STP 960
C   DO 70 I=1,DIML                                                STP 970
C   70 WRITE (PU,350) (PHI(I,J),J-1,DIMW)                          STP 980
C   70 CONTINUE
C                                                                 STP 990
C   80 IF (CHCK.EQ.CHK(5)) THEN
C       CALL CHECKI(PHI,KEEP,PHE,STRT,T,TR,TC,S,QRE,WELL,TL,PERM,BOTTOM
C       1,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,1)
C       ENDIF
C       IF (IERR.EQ.2) GO TO 90                                    STP1010
C                                                                 STP1020
C   ---PRINT OUTPUT AT DESIGNATED TIME STEPS---                    STP1030
C--Only "print" results (ie, Call WRITE1, etc) at end of a pumping $3-201
C---period. The TRESCOTT variable KTH is thus ignored.             $3-202
C   IF (IFINAL.NE.1) RETURN                                       $$-203
C   90 WRITE (P,340) KT,DELT,SUM,MIN,S,HRS,DAYS,YRS,DAYSP,YRSP    STP1050
C   90 CONTINUE
C   IF (CHCK.EQ.CHK(5)) THEN
C       CALL CHECKI(PHI,KEEP,PHE,STRT,T,TR,TC,S,QRE,WELL,TL,PERM,BOTTOM
C       1,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,2)
C       ENDIF
C   IF (TT.NE.0.) WRITE (P,320) TMIN,TT                            STP1070
C   KOUNT=KOUNT+1                                                  STP1080
C   WRITE(P,300) (TEST3(J),J=1,KOUNT)
C   WRITE (P,290) TEST2                                            STP1100
C   I3=1                                                            STP1110
C   I5=0                                                            STP1120
C   100 I5=I5+40                                                    STP1130
C   I4=MIN0(KT,I5)                                                STP1140
C   WRITE (P,390) (I,I=I3,I4)                                       STP1150
C   WRITE (P,380)                                                    STP1160
C   WRITE (P,370) (ITTO(I),I=I3,I4)                                  STP1170
C   WRITE (P,380)                                                    STP1180
C   IF (KT.LE.I5) GO TO 110                                         STP1190
C   I3=I3+40                                                        STP1200
C   GO TO 100                                                       STP1210
C                                                                 STP1220

```

C	---	PRINT ALPHAMERIC MAPS---	STP1230
110	IF (CONTR.NE.CHK(3))	GO TO 120	STP1240
	IF(FACT1.NE.0.)	THEN	
	CALL PRNTAI(PHI,SURI,T,S,WELL,DELX,DELY,1,2)		
	ENDIF		
	IF (FACT2.NE.0.)	THEN	
	CALL PRNTAI(PHI,SURI,T,S,WELL,DELX,DELY,2,2)		
	ENDIF		
120	CONTINUE		\$3-209
C			STP1280
C--	Convert head matrix PHI to vector XHEAD and store in "AQMAN" COMMON:		\$3-210
	CALL WRITEL(1,IZ,JZ,KW,HW,PHI)		\$3-240
C	---	PRINT HEAD MATRIX---	STP1290
C	WRITE (P,310)		STP1300
	DO 130 I=1,DIML		STP1310
C 130	WRITE (P,VF4) I,(PHI(I,J),J=1,DIMW)		STP1320
130	CONTINUE		
140	IF (NUM.NE.CHK(4))	GO TO 170	STP1330
C			STP1340
C	---	PRINT DRAWDOWN---	STP1350
C	WRITE (P,280)		STP1360
C	*****		STP1370
C	ENTRY DRDN(PHI,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,		
C	1DDN,DELY,WR,NWR)		
C	*****		STP1390
4	CONTINUE		
	DO 160 I=1,DIML		STP1400
	DO 150 J=1,DIMW		STP1410
150	DDN(J)=SURI(I,J)-PHI(I,J)		STP1420
C 160	WRITE (P,VF4) I,(DDN(J),J=1,DIMW)		STP1430
160	CONTINUE		
170	IF (NW.EQ.0.OR.IERR.EQ.1)	GO TO 230	STP1440
C	.....		STP1450
C			STP1460
C	---	COMPUTE APPROXIMATE HEAD FOR PUMPING WELLS---	STP1470
C	WRITE (P,260)		STP1480
	DO 220 KW=1,NW		STP1490
	IF (WR(KW).EQ.0.)	GO TO 220	STP1500
	I=NWR(KW,1)		STP1510
	J=NWR(KW,2)		STP1520
C			STP1530
C	COMPUTE EFFECTIVE RADIUS OF WELL IN MODEL---		STP1540
	RE=(DELX(J)+DELY(I))/9.62		STP1550
	IF (WATER.NE.CHK(2))	GO TO 180	STP1560
	IF (CONVRT.NE.CHK(7))	GO TO 190	STP1570
	IF (PHI(I,J).LT.TOP(I,J))	GO TO 190	STP1580
C			STP1590
C	---	COMPUTATION FOR WELL IN ARTESIAN AQUIFER---	STP1600
180	HW=PHI(I,J)+WELL(I,J)*DLOG(RE/WR(KW))/(2.*PIE*T(I,J))*DELX(J)*DELY		\$3-330
1(I)			STP1620
	GO TO 210		STP1630
C			STP1640
C	---	COMPUTATION FOR WELL IN WATER TABLE AQUIFER	STP1650
190	HED=PHI(I,J)-BOTTOM(I,J)		STP1660

```

ARG=HED*HED+WELL(I,J)*DLOG(RE/WR(KW))/(PIE*PERM(I,J))*DELX(J)*DELY$$3-340
1(I) STP1680
IF (ARG.GT.0.) GO TO 200 STP1690
ARGDRY=-WELL(I,J)*DLOG(RE/WR(KW))/(PIE*PERM(I,J))*DELX(J)*DELY(I) $3-350
HW=PHI(I,J)-DSQRT(ARGDRY)+BOTTOM(I,J) $3-360
WRITE (P,270) I,J STP1700
WRITE (P,273)I,J,HW $3-370
C GO TO 220 STP1710
GO TO 210 $3-380
200 HW=DSQRT(ARG)+BOTTOM(I,J) $$3-390
C STP1730
C ---COMPUTE DRAWDOWN AT THE WELL AND PRINT RESULTS--- STP1740
210 DRAW=SURI(I,J)-HW STP1750
C WRITE (P,250) I,J,WR(KW),HW,DRAW STP1760
C--Enter in-well heads into XHEAD: $3-400
CALL WRITE1(2,IZ,JZ,KW,HW,PHI) $3-450
220 CONTINUE STP1770
230 IF (IERR.NE.2) RETURN STP1780
STOP STP1790
C STP1800
C ---DISK OUTPUT--- STP1810
C ***** STP1820
C ENTRY DISK(PHI)
C ***** STP1840
5 CONTINUE
C WRITE (6) PHI,SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETFSTP1850
C 1LXT,FLXNT STP1860
RETURN STP1870
C ..... STP1880
C STP1890
C ---PUNCHED OUTPUT--- STP1900
C ***** STP1910
C ENTRY PUNCH(PHI)
C ***** STP1930
6 CONTINUE
C WRITE (PU,360) SUM,SUMP,PUMPT,CFLUXT,QRET,CHST,CHDT,FLUXT,STORT,ETSTP1940
C 1FLXT,FLXNT STP1950
DO 240 I=1,DIML STP1960
C 240 WRITE (PU,350) (PHI(I,J),J=1,DIMW) STP1970
240 CONTINUE
RETURN STP1980
C STP1990
C ..... STP2000
C STP2010
C FORMATS: STP2020
C STP2030
C STP2040
C ----- STP2050
C STP2060
C STP2070
250 FORMAT (' ',43X,2I5,3F11.2) STP2080
260 FORMAT ('-',50X,'HEAD AND DRAWDOWN IN PUMPING WELLS'/51X,34('-')//STP2090
148X,'I J WELL RADIUS HEAD DRAWDOWN'//) STP2100
270 FORMAT (' ',43X,2I5,' WELL IS DRY') STP2110

```

```

273 FORMAT (' ',10X,'IN-WELL HEAD AT NODE ',2I5,' IS ',F12.4)           $3-460
280 FORMAT (1H1,60X,'DRAWDOWN'/61X,8('-'))                             STP2120
290 FORMAT ('OMAXIMUM CHANGE IN HEAD FOR THIS TIME STEP =',F10.3/' ',5STP2130
13('-'))                                                                STP2140
300 FORMAT('OMAXIMUM HEAD CHANGE FOR EACH ITERATION',
1/' ',39('-'))/('0',10F12.4))
310 FORMAT ('1',60X,'HEAD MATRIX'/61X,11('-'))                         STP2170
320 FORMAT ('ODIMENSIONLESS TIME FOR THIS STEP RANGES FROM',G15.7,' TSTP2180
10',G15.7)                                                                STP2190
330 FORMAT ('-*****STEADY STATE AT TIME STEP',I4,'*****')         STP2200
340 FORMAT (1H1,44X,57('-')/45X,[' ',14X,'TIME STEP NUMBER =',I9,14X,[' STP2210
1'/45X,57('-')//50X,29HSIZE OF TIME STEP IN SECONDS=,F14.2//55X,'TOSTP2220
2TAL SIMULATION TIME IN SECONDS=,F14.2/80X,8HMINUTES=,F14.2/82X,6HSTP2230
3HOURS=,F14.2/83X,5HDAYS=,F14.2/82X,'YEARS= ',F14.2//45X,'DURATION STP2240
4OF CURRENT PUMPING PERIOD IN DAYS= ',F14.2/82X,'YEARS= ',F14.2//) STP2250
350 FORMAT (8F10.4)                                                    STP2260
360 FORMAT (4G20.10)                                                    STP2270
370 FORMAT ('OITERATIONS:',40I4)                                        STP2280
380 FORMAT (' ',10('-'))                                                STP2290
390 FORMAT ('OTIME STEP :',40I4)                                        STP2300
400 FORMAT ('0',10('*'),'THE NUMBER OF TIME STEPS EXCEEDS THE DIMENSIOSTP2310
1N OF THE VECTOR ITTO AND MAY CAUSE UNEXPECTED RESULTS IN ADDITIONASTP2320
2L'/ 'OCOMPUTATION. AVOID PROBLEMS BY INCREASING THE DIMENSION OF TSTP2330
3HE VECTOR ITTO IN STEP',10('*'))                                        STP2340
END                                                                        STP2350-
SUBROUTINE SOLVE1(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL, DSIP 10
1EL, ETA, V, XI, DELX, BET, DELY, ALF, TEST3, TR, TC, GRND, SY, TOP, RATE, M,
2RIVER, SURI, PERM, BOTTOM, DDN, WR, NWR, NENT)
C -----SIP 40
C SOLUTION BY THE STRONGLY IMPLICIT PROCEDURE SIP 50
C -----SIP 60
C SIP 70
C SPECIFICATIONS: SIP 80
C IMPLICIT REAL *8 (A-H,O-Z) $4-10
C REAL *8 KEEP,M $4-11
C INTEGER R,P,PU,DIML,DIMW,IORDER(21)
C INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD
C 1,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C SIP 140
C DIMENSION PHI(1),BE(1),G(1),TEMP(1),KEEP(1),PHE(1),STRT(1)
C 1,T(1),S(1),QRE(1),WELL(1),TL(1),SL(1),DEL(1),ETA(1),V(1)
C 2,XI(1),DELX(1),BET(1),DELY(1),ALF(1),TEST3(1),TR(1),TC(1)
C 3,GRND(1),SY(1),TOP(1),RATE(1),M(1),RIVER(1),SURI(1),
C 4PERM(1),BOTTOM(1),DDN(1),WR(1),NWR(1)
C DIMENSION RHOP(20) $4-20
C SIP 190
C COMMON /SARRAY/ VF4(11),CHK(15) SIP 200
C COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
C 1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
C 2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
C COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
C 1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
C COMMON /ARSIZE/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
C GO TO (1,2) NENT

```

```

RETURN SIP 260
C .....SIP 270
C SIP 280
C ---COMPUTE AND PRINT ITERATION PARAMETERS--- SIP 290
C ***** SIP 300
C ENTRY ITER1(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BET, DELY, ALF, TEST3, TR, TC, GRND, SY, TOP, RATE, M,
C 2RIVER)
C ***** SIP 320
1 CONTINUE
C ---INITIALIZE ORDER OF ITERATION PARAMETERS (OR REPLACE WITH A SIP 330
C READ STATEMENT)--- SIP 340
DATA IORDER/1,2,3,4,5,1,2,3,4,5,11*1/
I2=INO1-1 SIP 360
J2=JNO1-1 SIP 370
L2=LENGTH/2 SIP 380
PL2=L2-1. SIP 390
W=0. SIP 400
PI=0. SIP 410
C SIP 420
C ---COMPUTE AVERAGE MAXIMUM PARAMETER FOR PROBLEM--- SIP 430
DO 10 I=2,INO1 SIP 440
DO 10 J=2,JNO1 SIP 450
N=I+DIML*(J-1) SIP 460
IF (T(N).EQ.0.) GO TO 10 SIP 470
PI=PI+1. SIP 480
DX=DELX(J)/WIDTH SIP 490
DY=DELY(I)/YDIM SIP 500
W=W+1. -DMIN1(2.*DX*DX/(1.+FACTY*DX*DX/(FACTX*DY*DY)), 2.*DY*DY/(1.+$$$4-30
1FACTX*DY*DY/(FACTY*DX*DX))) SIP 520
10 CONTINUE SIP 530
W=W/PI SIP 540
C SIP 550
C ---COMPUTE PARAMETERS IN GEOMETRIC SEQUENCE--- SIP 560
PJ=-1. SIP 570
DO 20 I=1,L2 SIP 580
PJ=PJ+1. SIP 590
20 TEMP(I)=1.-(1.-W)**(PJ/PL2) SIP 600
C SIP 610
C ---ORDER SEQUENCE OF PARAMETERS--- SIP 620
DO 30 J=1,LENGTH SIP 630
30 RHOP(J)=TEMP(IORDER(J)) SIP 640
C WRITE (P,370) HMAX SIP 650
C WRITE (P,380) LENGTH, (RHOP(J), J=1, LENGTH) SIP 660
RETURN SIP 670
C * * * * *
C ---INITIALIZE DATA FOR A NEW ITERATION----
C
40 KOUNT=KOUNT+1 SIP 710
IF (KOUNT.LE.ITMAX) GO TO 50 SIP 720
WRITE (P,360) SIP 730
CALL STEP(PHI, KEEP, STRT, SUR1, T, WELL, PERM, BOTTOM, TOP, DELX, DDN
1, DELY, WR, NWR, TEST3, TR, TC, S, QRE, TL, SY, RATE, RIVER, M, GRND, 3)
50 IF (MOD(KOUNT, LENGTH)) 60, 60, 70 SIP 750

```

```

C ***** SIP 760
C ENTRY NEWITA(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BET, DELY, ALF, TEST3, TR, TC, GRND, SY, TOP, RATE, M,
C 2RIVER, SUR, PERM, BOTTOM, DDN, WR, NWR)
C ***** SIP 780
2 CONTINUE
C ..... SIP 680
C ..... SIP 690
C ---INITIALIZE DATA FOR A NEW ITERATION--- SIP 700
60 NTH=0 SIP 790
70 NTH=NTH+1 SIP 800
W-RHOP(NTH) SIP 810
TEST3(KOUNT+1)=0. SIP 820
TEST=0. SIP 830
N=DIML*DIMW SIP 840
DO 80 I=1, N SIP 850
PHE(I)=PHI(I) SIP 860
DEL(I)=0. SIP 870
ETA(I)=0. SIP 880
V(I)=0. SIP 890
80 XI(I)=0. SIP 900
BIGI=0.0 SIP 910
C ..... SIP 920
C ---COMPUTE TRANSMISSIVITY AND T COEFFICIENTS IN WATER TABLE SIP 930
C OR WATER TABLE-ARTESIAN SIMUATION--- SIP 940
C IF (WATER.NE.CHK(2)) GO TO 90 SIP 950
CALL COEF(PHI, KEEP, PHE, STRT, SUR, T, TR, TC, S, WELL, TL, SL, PERM, BOTTOM
1, SY, RATE, RIVER, M, TOP, GRND, DELX, DELY, DDN, WR, NWR, 2)
C ..... SIP 970
C ---CHOOSE SIP NORMAL OR REVERSE ALGORITHM--- SIP 980
90 IF (MOD(KOUNT,2)) 100,230,100 SIP 990
C ..... SIP1000
C ---ORDER EQUATIONS WITH ROW 1 FIRST - 3X3 EXAMPLE: SIP1010
C 1 2 3 SIP1020
C 4 5 6 SIP1030
C 7 8 9 SIP1040
C ..... SIP1050
100 DO 210 I=2, INO1 SIP1060
DO 210 J=2, JNO1 SIP1070
N=I+DIML*(J-1) SIP1080
NL=N-DIML SIP1090
NR=N+DIML SIP1100
NA=N-1 SIP1110
NB=N+1 SIP1120
C ..... SIP1130
C ---SKIP COMPUTATIONS IF NODE IS OUTSIDE AQUIFER BOUNDARY--- SIP1140
C IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 210 SIP1150
C ..... SIP1160
C ---COMPUTE COEFFICIENTS--- SIP1170
D=TR(NL)/DELX(J) SIP1180
F=TR(N)/DELX(J) SIP1190
B=TC(NA)/DELY(I) SIP1200
H=TC(N)/DELY(I) SIP1210
IF (EVAP.NE.CHK(6)) GO TO 120 SIP1220

```

C		SIP1230
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	SIP1240
	ETQB=0.	SIP1250
	ETQD=0.0	SIP1260
	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 120	SIP1270
	IF (PHE(N).GT.GRND(N)) GO TO 110	SIP1280
	ETQB=QET/ETDIST	SIP1290
	ETQD=ETQB*(ETDIST-GRND(N))	SIP1300
	GO TO 120	SIP1310
110	ETQD=QET	SIP1320
C		SIP1330
C	---COMPUTE STORAGE TERM---	SIP1340
120	IF (CONVRT.EQ.CHK(7)) GO TO 130	SIP1350
	RHO=S(N)/DELT	SIP1360
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	SIP1370
	GO TO 200	SIP1380
C		SIP1390
C	---COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	SIP1400
130	SUBS=0.0	SIP1410
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 170	SIP1420
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 160	SIP1430
	IF (KEEP(N)-PHE(N)) 140,150,150	SIP1440
140	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	SIP1450
	GO TO 170	SIP1460
150	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	SIP1470
160	RHO=SY(N)/DELT	SIP1480
	GO TO 180	SIP1490
170	RHO=S(N)/DELT	SIP1500
180	IF (LEAK.NE.CHK(9)) GO TO 200	SIP1510
C		SIP1520
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	SIP1530
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 200	SIP1540
	HED1=DMAX1(STRT(N),TOP(N))	\$\$\$4-40
	U=1.	SIP1560
	HED2=0.	SIP1570
	IF (PHE(N).GE.TOP(N)) GO TO 190	SIP1580
	HED2=TOP(N)	SIP1590
	U=0.	SIP1600
190	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	SIP1610
200	CONTINUE	SIP1620
C		SIP1630
C	---SIP 'NORMAL' ALGORITHM---	SIP1640
C	---FORWARD SUBSTITUTE, COMPUTING INTERMEDIATE VECTOR V---	SIP1650
	E=B-D-F-H-RHO-TL(N)*U-ETQB	SIP1660
	CH=DEL(NA)*B/(1.+W*DEL(NA))	SIP1670
	GH=ETA(NL)*D/(1.+W*ETA(NL))	SIP1680
	BH=B-W*CH	SIP1690
	DH=D-W*GH	SIP1700
	EH=E+W*CH+W*GH	SIP1710
	FH=F-W*CH	SIP1720
	HH=H-W*GH	SIP1730
	ALFA=BH	SIP1740
	BETA=DH	SIP1750
	GAMA=EH-ALFA*ETA(NA)-BETA*DEL(NL)	SIP1760

	DEL(N)=FH/GAMA	SIP1770
	ETA(N)=HH/GAMA	SIP1780
	RES=-D*PHI(NL)-F*PHI(NR)-H*PHI(NB)-B*PHI(NA)-E*PHI(N)-RHO*KEEP(N)-	SIP1790
	1SL(N)-QRE(N)-WELL(N)+ETQD-SUBS-TL(N)*STRT(N)	SIP1800
	V(N)=(HMAX*RES-ALFA*V(NA)-BETA*V(NL))/GAMA	SIP1810
210	CONTINUE	SIP1820
C		SIP1830
C	---BACK SUBSTITUTE FOR VECTOR XI---	SIP1840
	DO 220 I=1,I2	SIP1850
	I3=DIPL-I	SIP1860
	DO 220 J=1,J2	SIP1870
	J3=DIMW-J	SIP1880
	N=I3+DIPL*(J3-1)	SIP1890
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 220	SIP1900
	XI(N)=V(N)-DEL(N)*XI(N+DIPL)-ETA(N)*XI(N+1)	SIP1910
C		SIP1920
C	---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERION---	SIP1930
	TCHK=DABS(XI(N))	\$\$\$4-50
	IF(TCHK.GT.BIGI) BIGI=TCHK	
	PHI(N)=PHI(N)+XI(N)	
220	CONTINUE	SIP1970
	IF (BIGI.GT.ERR) TEST=1.	SIP1980
	TEST3(KOUNT+1)=BIGI	SIP1990
	IF (TEST.EQ.1.) GO TO 40	SIP2000
	RETURN	SIP2010
C		SIP2020
C	.....	SIP2030
C	---ORDER EQUATIONS WITH THE LAST ROW FIRST - 3X3 EXAMPLE:	SIP2040
C	7 8 9	SIP2050
C	4 5 6	SIP2060
C	1 2 3	SIP2070
C	.....	SIP2080
230	DO 340 II=1,I2	SIP2090
	I=DIPL-II	SIP2100
	DO 340 J=2,JN01	SIP2110
	N=I+DIPL*(J-1)	SIP2120
	NL=N-DIPL	SIP2130
	NR=N+DIPL	SIP2140
	NA=N-1	SIP2150
	NB=N+1	SIP2160
C		SIP2170
C	---SKIP COMPUTATIONS IF NODE IS OUTSIDE AQUIFER BOUNDARY---	SIP2180
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 340	SIP2190
C		SIP2200
C	---COMPUTE COEFFICIENTS---	SIP2210
	D=TR(NL)/DELX(J)	SIP2220
	F=TR(N)/DELX(J)	SIP2230
	B=TC(NA)/DELY(I)	SIP2240
	H=TC(N)/DELY(I)	SIP2250
	IF (EVAP.NE.CHK(6)) GO TO 250	SIP2260
C		SIP2270
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	SIP2280
	ETQB=0.	SIP2290
	ETQD=0.0	SIP2300

	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 250	SIP2310
	IF (PHE(N).GT.GRND(N)) GO TO 240	SIP2320
	ETQB=QET/ETDIST	SIP2330
	ETQD=ETQB*(ETDIST-GRND(N))	SIP2340
	GO TO 250	SIP2350
240	ETQD=QET	SIP2360
C		SIP2370
C	---COMPUTE STORAGE TERM---	SIP2380
250	IF (CONVRT.EQ.CHK(7)) GO TO 260	SIP2390
	RHO=S(N)/DELT	SIP2400
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	SIP2410
	GO TO 330	SIP2420
C		SIP2430
C	---COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	SIP2440
260	SUBS=0.0	SIP2450
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 300	SIP2460
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 290	SIP2470
	IF (KEEP(N)-PHE(N)) 270,280,280	SIP2480
270	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	SIP2490
	GO TO 300	SIP2500
280	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	SIP2510
290	RHO=SY(N)/DELT	SIP2520
	GO TO 310	SIP2530
300	RHO=S(N)/DELT	SIP2540
310	IF (LEAK.NE.CHK(9)) GO TO 330	SIP2550
C		SIP2560
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	SIP2570
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 330	SIP2580
	HED1=DMAX1(STRT(N),TOP(N))	\$\$\$4-60
	U=1.	SIP2600
	HED2=0.	SIP2610
	IF (PHE(N).GE.TOP(N)) GO TO 320	SIP2620
	HED2=TOP(N)	SIP2630
	U=0.	SIP2640
320	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	SIP2650
330	CONTINUE	SIP2660
C		SIP2670
C	---SIP 'REVERSE' ALGORITHM---	SIP2680
C	---FORWARD SUBSTITUTE, COMPUTING INTERMEDIATE VECTOR V---	SIP2690
	E=B-D-F-H-RHO-TL(N)*U-ETQB	SIP2700
	CH=DEL(NB)*H/(1.+W*DEL(NB))	SIP2710
	GH=ETA(NL)*D/(1.+W*ETA(NL))	SIP2720
	BH=H-W*CH	SIP2730
	DH=D-W*GH	SIP2740
	EH=E+W*CH+W*GH	SIP2750
	FH=F-W*CH	SIP2760
	HH=B-W*GH	SIP2770
	ALFA=BH	SIP2780
	BETA=DH	SIP2790
	GAMA=EH-ALFA*ETA(NB)-BETA*DEL(NL)	SIP2800
	DEL(N)=FH/GAMA	SIP2810
	ETA(N)=HH/GAMA	SIP2820
	RES=D*PHI(NL)-F*PHI(NR)-H*PHI(NB)-B*PHI(NA)-E*PHI(N)-RHO*KEEP(N)-	SIP2830
	1SL(N)-QRE(N)-WELL(N)+ETQD-SUBS-TL(N)*STRT(N)	SIP2840

	V(N)=(HMAX*RES-ALFA*V(NB)-BETA*V(NL))/GAMA	SIP2850
340	CONTINUE	SIP2860
C		SIP2870
C	---BACK SUBSTITUTE FOR VECTOR XI---	SIP2880
	DO 350 I3=2,INO1	SIP2890
	DO 350 J=1,J2	SIP2900
	J3=DIMW-J	SIP2910
	N=I3+DIML*(J3-1)	SIP2920
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 350	SIP2930
	XI(N)=V(N)-DEL(N)*XI(N+DIML)-ETA(N)*XI(N-1)	SIP2940
C		SIP2950
C	---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERION---	SIP2960
	TCHK=DABS(XI(N))	\$\$4-70
	IF(TCHK.GT.BIGI) BIGI=TCHK	
	PHI(N)=PHI(N)+XI(N)	
350	CONTINUE	SIP3000
	IF (BIGI.GT.ERR) TEST=1.	SIP3010
	TEST3(KOUNT+1)=BIGI	SIP3020
	IF (TEST.EQ.1.) GO TO 40	SIP3030
	RETURN	SIP3040
C		SIP3050
C	.....	SIP3060
C		SIP3070
C	---FORMATS---	SIP3080
C		SIP3090
C	-----	SIP3100
C		SIP3110
C		SIP3120
360	FORMAT ('OEXCEEDED PERMITTED NUMBER OF ITERATIONS'/' ',39('*'))	SIP3130
370	FORMAT ('-',44X,'SOLUTION BY THE STRONGLY IMPLICIT PROCEDURE'/45X,143('_ '),//,61X,'BETA=',F5.2)	SIP3140
380	FORMAT (1H0,I5,22H ITERATION PARAMETERS: ,6D15.7/(/28X,6D15.7/))	SIP3160
	END	SIP3170-
	SUBROUTINE SOLVE2(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL, DSOR	10
	1EL, ETA, V, XI, DELX, BETA, DELY, ALFA, TEST3, TR, TC, GRND, SY, TOP, RATE, M, RIVSOR	20
	2ER, SURI, PERM, BOTTOM, DDN, WR, NWR, NENT)	
C	-----	SOR 40
C	SOLUTION BY LINE SUCCESSIVE OVERRELAXATION	SOR 50
C	-----	SOR 60
C		SOR 70
C	SPECIFICATIONS:	SOR 80
	IMPLICIT REAL *8 (A-H,O-Z)	\$\$5-10
	REAL *8 IMK,KEEP,M	\$\$5-20
	INTEGER R, P, PU, DIML, DIMW	
	INTEGER CHK, WATER, CONVRT, EVAP, CHCK, PNCH, NUM, HEAD	
	1, CONTR, LEAK, RECH, SIP, ADI, NUMS, IDK1, IDK2	
C		SOR 140
	DIMENSION PHI(1), BE(1), G(1), TEMP(1), KEEP(1), PHE(1), STRT(1)	
	1, T(1), S(1), QRE(1), WELL(1), TL(1), SL(1), DEL(1), ETA(1),	
	2V(1), XI(1), DELX(1), BETA(1), DELY(1), ALFA(1), TEST3(1),	
	3TR(1), TC(1), GRND(1), SY(1), TOP(1), RATE(1), M(1), RIVER(1)	
	DIMENSION RHOP(20)	\$\$5-30
C		SOR 190
	COMMON /SARRAY/ VF4(11),CHK(15)	SOR 200

```

COMMON /SPARAMI/ WATER, CONVRT, EVAP, CHCK, PNCH, NUM, HEAD, CONTR, LEAK,
1RECH, SIP, NUMS, LSOR, ADI, IERR, KOUNT, IFINAL, NUMT, KT, KP, NPER, KTH,
2ITMAX, LENGTH, NWEL, NW, DIML, DIMW, I, J, IDK1, IDK2, JNO1, INO1, R, P, PU
COMMON /SPARAMR/ U, SS, TT, TMIN, ETDIST, QET, ERR, TMAX, CDLT, HMAX, YDIM,
1WIDTH, DELT, SUM, SUMP, SUBS, STORE, TEST, ETQB, ETQD, FACTX, FACTY, EROR
COMMON /ARSIZE/ IZ, JZ, IP, JP, IR, JR, IC, JC, IL, JL, IS, JS, IH, IMAX, IMX1
GO TO (1,2) NENT
RETURN

```

```

C ..... SOR 270
C ..... SOR 280
C ---WRITE ACCELERATION PARAMETER--- SOR 290
C ***** SOR 300
C ENTRY ITER2(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BETA, DELY, ALFA, TEST3, TR, TC, GRND, SY, TOP, RATE, M,
C 2RIVER)
C ***** SOR 320
1 CONTINUE
C WRITE (P,490) SOR 330
C WRITE (P,500) HMAX, LENGTH SOR 340
C RETURN SOR 350
C ..... SOR 360
C ..... SOR 370
C ---INITIALIZE DATA FOR A NEW ITERATION--- SOR 380
10 KOUNT=KOUNT+1 SOR 390
IF (KOUNT.LE.ITMAX) GO TO 20 SOR 400
WRITE (P,510) SOR 410
CALL STEP(PHI, KEEP, STRT, SUR1, T, WELL, PERM, BOTTOM, TOP, DELX, DDN
1, DELY, WR, NWR, TEST3, TR, TC, S, QRE, TL, SY, RATE, RIVER, M, GRND, 3)
C ***** SOR 430
C ENTRY NEWITB(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BETA, DELY, ALFA, TEST3, TR, TC, GRND, SY, TOP, RATE, M,
C 2RIVER, SUR1, PERM, BOTTOM, DDN, WR, NWR)
C ***** SOR 450
2 CONTINUE
20 TEST3(KOUNT+1)=0. SOR 460
TEST=0. SOR 470
N=DIML*DIMW SOR 480
DO 30 I=1, N SOR 490
30 PHE(I)=PHI(I) SOR 500
BIGI=0.0 SOR 510
C ..... SOR 520
C ---COMPUTE TRANSMISSIVITY AND T COEFFICIENTS IN WATER TABLE SOR 530
C OR WATER TABLE-ARTESIAN SIMUATION--- SOR 540
C IF (WATER.NE.CHK(2)) GO TO 40 SOR 550
CALL COEF(PHI, KEEP, PHE, STRT, SUR1, T, TR, TC, S, WELL, TL, SL, PERM, BOTTOM
1, SY, RATE, RIVER, M, TOP, GRND, DELX, DELY, DDN, WR, NWR, 2)
C ..... SOR 570
C ..... SOR 580
C ---SOLUTION BY LSOR--- SOR 590
C ..... SOR 600
40 NO3=DIMW-2 SOR 610
TEMP(DIMW)=0.0 SOR 620
DO 170 I=2, INO1 SOR 630
DO 150 J=2, JNO1 SOR 640

```

	N=I+DIML*(J-1)	SOR 650
	NA=N-1	SOR 660
	NB=N+1	SOR 670
	NL=N-DIML	SOR 680
	NR=N+DIML	SOR 690
	BE(J)=0.0	SOR 700
	G(J)=0.0	SOR 710
C		SOR 720
C	---SKIP COMPUTATIONS IF NODE IS OUTSIDE AQUIFER BOUNDARY---	SOR 730
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 150	SOR 740
C		SOR 750
C	---COMPUTE COEFFICIENTS---	SOR 760
	D=TR(N-DIML)/DELX(J)	SOR 770
	F=TR(N)/DELX(J)	SOR 780
	B=TC(N-1)/DELY(I)	SOR 790
	H=TC(N)/DELY(I)	SOR 800
	IF (EVAP.NE.CHK(6)) GO TO 60	SOR 810
C		SOR 820
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	SOR 830
	ETQB=0.	SOR 840
	ETQD=0.0	SOR 850
	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 60	SOR 860
	IF (PHE(N).GT.GRND(N)) GO TO 50	SOR 870
	ETQB=QET/ETDIST	SOR 880
	ETQD=ETQB*(ETDIST-GRND(N))	SOR 890
	GO TO 60	SOR 900
50	ETQD=QET	SOR 910
C		SOR 920
C	---COMPUTE STORAGE TERM---	SOR 930
60	IF (CONVRT.EQ.CHK(7)) GO TO 70	SOR 940
	RHO=S(N)/DELT	SOR 950
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	SOR 960
	GO TO 140	SOR 970
C		SOR 980
C	---COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	SOR 990
70	SUBS=0.0	SOR1000
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 110	SOR1010
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 100	SOR1020
	IF (KEEP(N)-PHE(N)) 80,90,90	SOR1030
80	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	SOR1040
	GO TO 110	SOR1050
90	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	SOR1060
100	RHO=SY(N)/DELT	SOR1070
	GO TO 120	SOR1080
110	RHO=S(N)/DELT	SOR1090
120	IF (LEAK.NE.CHK(9)) GO TO 140	SOR1100
C		SOR1110
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	SOR1120
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 140	SOR1130
	HED1=DMAX1(STRT(N),TOP(N))	\$\$5-40
	U=1.	SOR1150
	HED2=0.	SOR1160
	IF (PHE(N).GE.TOP(N)) GO TO 130	SOR1170
	HED2=TOP(N)	SOR1180

	U=0.	SOR1190
130	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	SOR1200
140	CONTINUE	SOR1210
C		SOR1220
C	---FORWARD SUBSTITUTE, COMPUTING INTERMEDIATE VECTOR G---	SOR1230
	E=-D-F-B-H-RHO-TL(N)*U-ETQB	SOR1240
	W=E-D*BE(J-1)	SOR1250
	BE(J)=F/W	SOR1260
	Q=-B*PHI(NA)-H*PHI(NB)-RHO*KEEP(N)-SL(N)-QRE(N)-WELL(N)+ETQD-SUBS-	SOR1270
	1TL(N)*STRT(N)-D*PHI(NL)-F*PHI(NR)-E*PHI(N)	SOR1280
	G(J)=(Q-D*G(J-1))/W	SOR1290
150	CONTINUE	SOR1300
C		SOR1310
C	---BACK SUBSTITUTE FOR TEMP---	SOR1320
	DO 160 KNO4=1,NO3	SOR1330
	NO4=DIMW-KNO4	SOR1340
	TEMP(NO4)=G(NO4)-BE(NO4)*TEMP(NO4+1)	SOR1350
160	CONTINUE	SOR1360
C		SOR1370
C	---EXTRAPOLATED VALUE OF PHI---	SOR1380
	DO 170 J=2,JNO1	SOR1390
	N=I+DIML*(J-1)	SOR1400
	PHI(N)=PHI(N)+HMAX*TEMP(J)	SOR1410
C		SOR1420
C	---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERION---	SOR1430
	TCHK=DABS(TEMP(J))	SOR1440
	IF(TCHK.GT.BIGI) BIGI=TCHK	
170	CONTINUE	SOR1460
	IF (BIGI.GT.ERR) TEST=1.	SOR1470
	TEST3(KOUNT+1)=BIGI	SOR1480
	IF (KOUNT.EQ.0) GO TO 10	SOR1490
	IF (TEST.EQ.0.) RETURN	SOR1500
C		SOR1510
C	---TEST FOR TWO DIMENSIONAL CORRECTION---	SOR1520
	IF (MOD(KOUNT,LENGTH).NE.0) GO TO 10	SOR1530
	GO TO 200	SOR1540
180	DO 190 I=2,INO1	SOR1550
	DO 190 J=2,JNO1	SOR1560
	N=I+DIML*(J-1)	SOR1570
	IF (T(N).EQ.0.) GO TO 190	SOR1580
	PHI(N)=PHI(N)+ALFA(I)+BETA(J)	SOR1590
190	CONTINUE	SOR1600
	GO TO 10	SOR1610
C	.....	SOR1620
C		SOR1630
C	---TWO DIMENSIONAL CORRECTION TO LSOR---	SOR1640
C	-----	SOR1650
C		SOR1660
C	---COMPUTE ALFA CORRECTION FOR ROWS---	SOR1670
200	DO 210 I=1,DIML	SOR1680
	ALFA(I)=0.	SOR1690
	BE(I)=0.0	SOR1700
210	G(I)=0.0	SOR1710
	DO 330 I=2,INO1	SOR1720

	A=0.	SOR1730
	B2=0.	SOR1740
	C=0.	SOR1750
	Q=0.	SOR1760
C		SOR1770
C	---SUMMATION OF COEFFICIENTS FOR EACH ROW---	SOR1780
	DO 320 J=2,JN01	SOR1790
	N=I+DIML*(J-1)	SOR1800
	NA=N-1	SOR1810
	NB=N+1	SOR1820
	NL=N-DIML	SOR1830
	NR=N+DIML	SOR1840
	IF (S(N).LT.0.) GO TO 330	SOR1850
	IF (T(N).EQ.0.) GO TO 320	SOR1860
C		SOR1870
C	---COMPUTE COEFFICIENTS---	SOR1880
	D=TR(N-DIML)/DELX(J)	SOR1890
	F=TR(N)/DELX(J)	SOR1900
	B=TC(N-1)/DELY(I)	SOR1910
	H=TC(N)/DELY(I)	SOR1920
	IF (EVAP.NE.CHK(6)) GO TO 230	SOR1930
C		SOR1940
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	SOR1950
	ETQB=0.	SOR1960
	ETQD=0.0	SOR1970
	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 230	SOR1980
	IF (PHE(N).GT.GRND(N)) GO TO 220	SOR1990
	ETQB=QET/ETDIST	SOR2000
	ETQD=ETQB*(ETDIST-GRND(N))	SOR2010
	GO TO 230	SOR2020
	220 ETQD=QET	SOR2030
C		SOR2040
C	---COMPUTE STORAGE TERM---	SOR2050
	230 IF (CONVRT.EQ.CHK(7)) GO TO 240	SOR2060
	RHO=S(N)/DELT	SOR2070
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	SOR2080
	GO TO 310	SOR2090
	240 SUBS=0.0	SOR2100
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 280	SOR2110
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 270	SOR2120
	IF (KEEP(N)-PHE(N)) 250,260,260	SOR2130
	250 SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	SOR2140
	GO TO 280	SOR2150
	260 SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	SOR2160
	270 RHO=SY(N)/DELT	SOR2170
	GO TO 290	SOR2180
	280 RHO=S(N)/DELT	SOR2190
	290 IF (LEAK.NE.CHK(9)) GO TO 310	SOR2200
C		SOR2210
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	SOR2220
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 310	SOR2230
	HED1=DMAX1(STRT(N),TOP(N))	\$\$5-50
	U=1.	SOR2250
	HED2=0.	SOR2260

	IF (PHE(N).GE.TOP(N)) GO TO 300	SOR2270
	HED2=TOP(N)	SOR2280
	U=0.	SOR2290
300	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	SOR2300
310	CONTINUE	SOR2310
C		SOR2320
	A=A-B	SOR2330
	B1=B+H+RHO+TL(N)*U+ETQB	SOR2340
	B2=B2+B1	SOR2350
	C=C-H	SOR2360
	Q=Q+(D*PHI(NL)+F*PHI(NR)+B*PHI(NA)+H*PHI(NB)+RHO*KEEP(N)+SL(N)+QRESOR2370	
	1(N)+WELL(N)-ETQD+SUBS+TL(N)*STRT(N)-(D+F+B1)*PHI(N)	SOR2380
320	CONTINUE	SOR2390
C		SOR2400
C	---COMPUTATION OF INTERMEDIATE VECTOR G---	SOR2410
	W=B2-A*BE(I-1)	SOR2420
	BE(I)=C/W	SOR2430
	G(I)=(Q-A*G(I-1))/W	SOR2440
330	CONTINUE	SOR2450
C		SOR2460
C	---BACK SUBSTITUTE FOR ALFA---	SOR2470
	NO3=DIML-2	SOR2480
	DO 340 KNO4=1,NO3	SOR2490
	NO4=DIML-KNO4	SOR2500
340	ALFA(NO4)=G(NO4)-BE(NO4)*ALFA(NO4+1)	SOR2510
C	*****	SOR2520
C		SOR2530
C	---COMPUTE BETA CORRECTION FOR COLUMNS---	SOR2540
	DO 350 J=1,DIMW	SOR2550
	BETA(J)=0.	SOR2560
	BE(J)=0.0	SOR2570
350	G(J)=0.0	SOR2580
	DO 470 J=2,JNO1	SOR2590
	A=0.	SOR2600
	B2=0.	SOR2610
	C=0.	SOR2620
	Q=0.	SOR2630
C		SOR2640
C	---SUMMATION OF COEFFICIENTS FOR EACH COLUMN---	SOR2650
	DO 460 I=2,INO1	SOR2660
	N=I+DIML*(J-1)	SOR2670
	NA=N-1	SOR2680
	NB=N+1	SOR2690
	NL=N-DIML	SOR2700
	NR=N+DIML	SOR2710
	IF (S(N).LT.0.) GO TO 470	SOR2720
	IF (T(N).EQ.0.) GO TO 460	SOR2730
	D=TR(N-DIML)/DELX(J)	SOR2740
	F=TR(N)/DELX(J)	SOR2750
	B=TC(N-1)/DELY(I)	SOR2760
	H=TC(N)/DELY(I)	SOR2770
	IF (EVAP.NE.CHK(6)) GO TO 370	SOR2780
C		SOR2790
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	SOR2800

	ETQB=0.	SOR2810
	ETQD=0.0	SOR2820
	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 370	SOR2830
	IF (PHE(N).GT.GRND(N)) GO TO 360	SOR2840
	ETQB=QET/ETDIST	SOR2850
	ETQD=ETQB*(ETDIST-GRND(N))	SOR2860
	GO TO 370	SOR2870
360	ETQD=QET	SOR2880
C		SOR2890
C	---COMPUTE STORAGE TERM---	SOR2900
370	IF (CONVRT.EQ.CHK(7)) GO TO 380	SOR2910
	RHO=S(N)/DELT	SOR2920
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	SOR2930
	GO TO 450	SOR2940
C		SOR2950
C	---COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	SOR2960
380	SUBS=0.0	SOR2970
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 420	SOR2980
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 410	SOR2990
	IF (KEEP(N)-PHE(N)) 390,400,400	SOR3000
390	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	SOR3010
	GO TO 420	SOR3020
400	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	SOR3030
410	RHO=SY(N)/DELT	SOR3040
	GO TO 430	SOR3050
420	RHO=S(N)/DELT	SOR3060
430	IF (LEAK.NE.CHK(9)) GO TO 450	SOR3070
C		SOR3080
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	SOR3090
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 450	SOR3100
	HED1=DMAX1(STRT(N),TOP(N))	\$\$\$-60
	U=1.	SOR3120
	HED2=0.	SOR3130
	IF (PHE(N).GE.TOP(N)) GO TO 440	SOR3140
	HED2=TOP(N)	SOR3150
	U=0.	SOR3160
440	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	SOR3170
450	CONTINUE	SOR3180
C		SOR3190
	A=A-D	SOR3200
	B1=D+F+RHO+TL(N)*U+ETQB	SOR3210
	B2=B2+B1	SOR3220
	C=C-F	SOR3230
	Q=Q+(D*PHI(NL)+F*PHI(NR)+B*PHI(NA)+H*PHI(NB)+RHO*KEEP(N)+SL(N)+QRESOR3240	
	1(N)+WELL(N)-ETQD+SUBS+TL(N)*STRT(N)-(B+H+B1)*PHI(N))	SOR3250
460	CONTINUE	SOR3260
C		SOR3270
C	---COMPUTATION OF INTERMEDIATE VECTOR G---	SOR3280
	W=B2-A*BE(J-1)	SOR3290
	BE(J)=C/W	SOR3300
	G(J)=(Q-A*G(J-1))/W	SOR3310
470	CONTINUE	SOR3320
C		SOR3330
C	---BACK SUBSTITUTE FOR BETA---	SOR3340

```

NO3=DIMW-2
DO 480 KNO4=1,NO3
NO4=DIMW-KNO4
480 BETA(NO4)=G(NO4)-BE(NO4)*BETA(NO4+1)
GO TO 180
C .....
C .....
C ---FORMATS---
C .....
C .....
C .....
C .....
C .....
490 FORMAT ('-',45X,'SOLUTION BY LINE SUCCESSIVE OVERRELAXATION'/46X,4SOR3470
12(' '))
500 FORMAT ('-',26X,'ACCELERATION PARAMETER =',F6.3,' TWO DIMENSIONALSOR3490
1 CORRECTION EVERY',I5,' ITERATIONS')
510 FORMAT ('OEXCEEDED PERMITTED NUMBER OF ITERATIONS'/' ',39('*')) SOR3510
END SOR3520-
SUBROUTINE SOLVE3(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL, DADI 10
1EL, ETA, V, XI, DELX, BETA, DELY, ALFA, XII, TEST3, TR, TC, GRND, SY, TOP, RATE, MADI 20
2, RIVER, SURI, PERM, BOTTOM, DDN, WR, NWR, NENT)
C .....
C SOLUTION BY THE ALTERNATING DIRECTION IMPLICIT METHOD
C .....
C .....
C SPECIFICATIONS:
IMPLICIT REAL *8 (A-H,O-Z) $6-10
REAL *8 IMK,KEEP,M $6-20
INTEGER R,P,PU,DIML,DIMW
INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD
1,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C .....
C DIMENSION PHI(1),BE(1),G(1),TEMP(1),KEEP(1),PHE(1),STRT(1)
1,T(1),S(1),QRE(1),WELL(1),TL(1),SL(1),DEL(1),ETA(1),V(1)
2,XI(1),DELX(1),BETA(1),DELY(1),ALFA(1),XII(1),TEST3(1),
3TR(1),TC(1),GRND(1),SY(1),TOP(1),RATE(1),M(1),RIVER(1)
DIMENSION RHOP(20)
C .....
C COMMON /SARRAY/ VF4(11),CHK(15)
COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
COMMON /ARSIZE/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
GO TO (1,2) NENT
RETURN
C .....
C .....
C ---COMPUTE AND PRINT ITERATION PARAMETERS---
C *****
C ENTRY ITER3(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BETA, DELY, ALFA, XII, TEST3, TR, TC, GRND, SY, TOP,
C 2RATE, M, RIVER)

```

```

C *****
1 CONTINUE ADI 320
HMIN=2. ADI 330
IN4=DIMW-2 ADI 340
IN5=DI ML-2 ADI 350
XVAL=3.1415**2/(2.*IN4*IN4) ADI 360
YVAL=3.1415**2/(2.*IN5*IN5) ADI 370
DO 10 I=2,INO1 ADI 380
DO 10 J=2,JNO1 ADI 390
N=I+DI ML*(J-1) ADI 400
IF (T(N).EQ.0.) GO TO 10 ADI 410
XPART=XVAL*(1/(1+DELX(J)**2*FACTY/DELY(I)**2*FACTX)) ADI 420
YPART=YVAL*(1/(1+DELY(I)**2*FACTX/DELX(J)**2*FACTY)) ADI 430
HMIN=DMIN1(HMIN,XPART,YPART) $$$6-40
10 CONTINUE ADI 450
ALPHA=DEXP(DLOG(HMAX/HMIN)/(LENGTH-1)) $$$6-50
RHOP(1)=HMIN ADI 470
DO 20 NTIME=2,LENGTH ADI 480
20 RHOP(NTIME)=RHOP(NTIME-1)*ALPHA ADI 490
C WRITE (P,400)
C WRITE (P,410) LENGTH, (RHOP(J),J=1,LENGTH)
RETURN ADI 520
C ..... ADI 530
C ADI 540
C ---INITIALIZE DATA FOR A NEW ITERATION--- ADI 550
30 KOUNT=KOUNT+1 ADI 560
IF (KOUNT.LE.ITMAX) GO TO 40 ADI 570
WRITE (P,390) ADI 580
CALL STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM, TOP,DELX,DDN
1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,3)
40 IF (MOD(KOUNT,LENGTH)) 50,50,60 ADI 600
C ***** ADI 610
C ENTRY NEWITC(PHI, BE, G, TEMP, KEEP, PHE, STRT, T, S, QRE, WELL, TL, SL,
C 1DEL, ETA, V, XI, DELX, BETA, DELY, ALFA, XII, TEST3, TR, TC, GRND, SY, TOP,
C 2RATE, M, RIVER, SURJ, PERM, BOTTOM, DDN, WR, NWR)
C ***** ADI 630
2 CONTINUE
50 NTH=0 ADI 640
60 NTH=NTH+1 ADI 650
PARAM=RHOP(NTH) ADI 660
TEST3(KOUNT+1)=0. ADI 670
TEST=0. ADI 680
N=DI ML*DI MW ADI 690
DO 70 I=1,N ADI 700
70 PHE(I)=PHI(I) ADI 710
BIGI=0.0 ADI 720
C ADI 730
C ---COMPUTE TRANSMISSIVITY AND T COEFFICIENTS IN WATER TABLE ADI 740
C OR WATER TABLE-ARTESIAN SIMUATION--- ADI 750
IF (WATER.NE.CHK(2)) GO TO 80 ADI 760
CALL COEF(PHI,KEEP,PHE,STRT,SURI,T,TR,TC,S,WELL,TL,SL,PERM,BOTTOM
1,SY,RATE,RIVER,M, TOP,GRND,DELX,DELY,DDN,WR,NWR,2)
C ..... ADI 780
C ADI 790

```

C	---SOLUTION BY ADI---	ADI 800
C	-----	ADI 810
C	---COMPUTE IMPLICITLY ALONG ROWS---	ADI 820
80	NO3=DIMW-2	ADI 830
	DO 90 J=1,DIMW	ADI 840
	N=1+DIML*(J-1)	ADI 850
90	TEMP(J)=PHI(N)	ADI 860
	DO 230 I=2,DIML	ADI 870
	DO 200 J=2,JNO1	ADI 880
	N=I+DIML*(J-1)	ADI 890
	NA=N-1	ADI 900
	NB=N+1	ADI 910
	NL=N-DIML	ADI 920
	NR=N+DIML	ADI 930
	BE(J)=0.0	ADI 940
	G(J)=0.0	ADI 950
C		ADI 960
C	---SKIP COMPUTATIONS IF NODE IS OUTSIDE AQUIFER BOUNDARY---	ADI 970
	IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 200	ADI 980
C		ADI 990
C	---COMPUTE COEFFICIENTS---	ADI1000
	D=TR(N-DIML)/DELX(J)	ADI1010
	F=TR(N)/DELX(J)	ADI1020
	B=TC(N-1)/DELY(I)	ADI1030
	H=TC(N)/DELY(I)	ADI1040
	IF (EVAP.NE.CHK(6)) GO TO 110	ADI1050
C		ADI1060
C	---COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	ADI1070
	ETQB=0.	ADI1080
	ETQD=0.0	ADI1090
	IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 110	ADI1100
	IF(PHE(N).GT.GRND(N))GO TO 100	
	ETQB=QET/ETDIST	ADI1120
	ETQD=ETQB*(ETDIST-GRND(N))	ADI1130
	GO TO 110	ADI1140
100	ETQD=QET	ADI1150
C		ADI1160
C	---COMPUTE STORAGE TERM---	ADI1170
110	IF (CONVRT.EQ.CHK(7)) GO TO 120	ADI1180
	RHO=S(N)/DELT	ADI1190
	IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	ADI1200
	GO TO 190	ADI1210
C		ADI1220
C	---COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	ADI1230
120	SUBS=0.0	ADI1240
	IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 160	ADI1250
	IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 150	ADI1260
	IF (KEEP(N)-PHE(N)) 130,140,140	ADI1270
130	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	ADI1280
	GO TO 160	ADI1290
140	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	ADI1300
150	RHO=SY(N)/DELT	ADI1310
	GO TO 170	ADI1320
160	RHO=S(N)/DELT	ADI1330

170	IF (LEAK.NE.CHK(9)) GO TO 190	ADI1340
C		ADI1350
C	---COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	ADI1360
	IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 190	ADI1370
	HED1=DMAX1(STRT(N),TOP(N))	\$\$\$6-60
	U=1.	ADI1390
	HED2=0.	ADI1400
	IF (PHE(N).GE.TOP(N)) GO TO 180	ADI1410
	HED2=TOP(N)	ADI1420
	U=0.	ADI1430
180	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	ADI1440
190	CONTINUE	ADI1450
C		ADI1460
C	---CALCULATE VALUES FOR PARAMETERS USED IN THOMAS ALGORITHM	ADI1470
C	AND FORWARD SUBSTITUTE TO COMPUTE INTERMEDIATE VECTOR G---	ADI1480
	IMK=(B+D+F+H)*PARAM	ADI1490
	E=-D-F-RHO-IMK-TL(N)*U-ETQB	ADI1500
	W=E-D*BE(J-1)	ADI1510
	BE(J)=F/W	ADI1520
	Q=-B*PHI(NA)+(B+H-IMK-E)*PHI(N)-H*PHI(NB)-RHO*KEEP(N)-SL(N)-QRE(N)	ADI1530
	1-WELL(N)+ETQD-SUBS-TL(N)*STRT(N)-D*PHI(NL)-F*PHI(NR)	ADI1540
	G(J)=(Q-D*G(J-1))/W	ADI1550
200	CONTINUE	ADI1560
C		ADI1570
C	---BACK SUBSTITUTE FOR HEAD VALUES AND PLACE THEM IN TEMP---	ADI1580
	XII(DIMW)=0.DO	ADI1590
	DO 220 KNO4=1,NO3	ADI1600
	NO4=DIMW-KNO4	ADI1610
	N=I+DIML*(NO4-1)	ADI1620
C		ADI1630
C	---FIRST PLACE TEMP VALUES IN PHI(N-1)---	ADI1640
	PHI(N-1)=TEMP(NO4)	ADI1650
	IF (T(N).NE.0..AND.S(N).GE.0.) GO TO 210	ADI1660
	XII(NO4)=0.DO	ADI1670
	GO TO 220	ADI1680
210	XII(NO4)=G(NO4)-BE(NO4)*XII(NO4+1)	ADI1690
220	TEMP(NO4)=PHI(N)+XII(NO4)	ADI1700
230	CONTINUE	ADI1710
C	.....	ADI1720
C		ADI1730
C	---COMPUTE IMPLICITLY ALONG COLUMNS---	ADI1740
	NO3=DIML-2	ADI1750
	DO 240 I=1,DIML	ADI1760
240	TEMP(I)=PHI(I)	ADI1770
	DO 380 J=2,DIMW	ADI1780
	DO 350 I=2,IN01	ADI1790
	N=I+DIML*(J-1)	ADI1800
	NA=N-1	ADI1810
	NB=N+1	ADI1820
	NL=N-DIML	ADI1830
	NR=N+DIML	ADI1840
	BE(I)=0.0	ADI1850
	G(I)=0.0	ADI1860
C		ADI1870

C	---	SKIP COMPUTATIONS IF NODE IS OUTSIDE AQUIFER BOUNDARY---	ADI1880
		IF (T(N).EQ.0..OR.S(N).LT.0.) GO TO 350	ADI1890
C			ADI1900
C	---	COMPUTE COEFFICIENTS---	ADI1910
		D=TR(N-DIML)/DELX(J)	ADI1920
		F=TR(N)/DELX(J)	ADI1930
		B=TC(N-1)/DELY(I)	ADI1940
		H=TC(N)/DELY(I)	ADI1950
		IF (EVAP.NE.CHK(6)) GO TO 260	ADI1960
C			ADI1970
C	---	COMPUTE EXPLICIT AND IMPLICIT PARTS OF ET RATE---	ADI1980
		ETQB=0.	ADI1990
		ETQD=0.0	ADI2000
		IF (PHE(N).LE.GRND(N)-ETDIST) GO TO 260	ADI2010
		IF (PHE(N).GT.GRND(N)) GO TO 250	ADI2020
		ETQB=QET/ETDIST	ADI2030
		ETQD=ETQB*(ETDIST-GRND(N))	ADI2040
		GO TO 260	ADI2050
	250	ETQD=QET	ADI2060
C			ADI2070
C	---	COMPUTE STORAGE TERM---	ADI2080
	260	IF (CONVRT.EQ.CHK(7)) GO TO 270	ADI2090
		RHO=S(N)/DELT	ADI2100
		IF (WATER.EQ.CHK(2)) RHO=SY(N)/DELT	ADI2110
		GO TO 340	ADI2120
C			ADI2130
C	---	COMPUTE STORAGE COEFFICIENT FOR CONVERSION PROBLEM---	ADI2140
	270	SUBS=0.0	ADI2150
		IF (KEEP(N).GE.TOP(N).AND.PHE(N).GE.TOP(N)) GO TO 310	ADI2160
		IF (KEEP(N).LT.TOP(N).AND.PHE(N).LT.TOP(N)) GO TO 300	ADI2170
		IF (KEEP(N)-PHE(N)) 280,290,290	ADI2180
	280	SUBS=(SY(N)-S(N))/DELT*(KEEP(N)-TOP(N))	ADI2190
		GO TO 310	ADI2200
	290	SUBS=(S(N)-SY(N))/DELT*(KEEP(N)-TOP(N))	ADI2210
	300	RHO=SY(N)/DELT	ADI2220
		GO TO 320	ADI2230
	310	RHO=S(N)/DELT	ADI2240
	320	IF (LEAK.NE.CHK(9)) GO TO 340	ADI2250
C			ADI2260
C	---	COMPUTE NET LEAKAGE TERM FOR CONVERSION SIMULATION---	ADI2270
		IF (RATE(N).EQ.0..OR.M(N).EQ.0.) GO TO 340	ADI2280
		HED1=DMAX1(STRT(N),TOP(N))	\$\$6-70
		U=1.	ADI2300
		HED2=0.	ADI2310
		IF (PHE(N).GE.TOP(N)) GO TO 330	ADI2320
		HED2=TOP(N)	ADI2330
		U=0.	ADI2340
	330	SL(N)=RATE(N)/M(N)*(RIVER(N)-HED1)+TL(N)*(HED1-HED2-STRT(N))	ADI2350
	340	CONTINUE	ADI2360
C			ADI2370
C	---	CALCULATE VALUES FOR PARAMETERS USED IN THOMAS ALGORITHM	ADI2380
C		AND FORWARD SUBSTITUTE TO COMPUTE INTERMEDIATE VECTOR G---	ADI2390
		IMK=(B+D+F+H)*PARAM	ADI2400
		E=-B-H-RHO-IMK-TL(N)*U-ETQB	ADI2410

```

W=E-B*BE(I-1) ADI2420
BE(I)=H/W ADI2430
Q=-D*PHI(NL)+(D+F-IMK-E)*PHI(N)-F*PHI(NR)-RHO*KEEP(N)-SL(N)-QRE(N) ADI2440
1-WELL(N)+ETQD-SUBS-TL(N)*STRT(N)-B*PHI(NA)-H*PHI(NB) ADI2450
G(I)=(Q-B*G(I-1))/W ADI2460
350 CONTINUE ADI2470
C ADI2480
C ---BACK SUBSTITUTE FOR HEAD VALUES AND PLACE THEM IN TEMP--- ADI2490
XII(DIML)=0.DO ADI2500
DO 370 KNO4=1,NO3 ADI2510
NO4=DIML-KNO4 ADI2520
N=NO4+DIML*(J-1) ADI2530
C ADI2540
C ---FIRST PLACE TEMP VALUES IN PHI(N-DIML)---- ADI2550
PHI(N-DIML)=TEMP(NO4) ADI2560
IF (T(N).NE.0..AND.S(N).GE.0.) GO TO 360 ADI2570
XII(NO4)=0.DO ADI2580
TEMP(NO4)=PHI(N) ADI2590
GO TO 370 ADI2600
360 XII(NO4)=G(NO4)-BE(NO4)*XII(NO4+1) ADI2610
TEMP(NO4)=PHI(N)+XII(NO4) ADI2620
C ADI2630
C ---COMPARE MAGNITUDE OF CHANGE WITH CLOSURE CRITERION--- ADI2640
TCHK=DABS(TEMP(NO4)-PHE(N)) $$$6-80
IF(TCHK.GT.BIGI) BIGI=TCHK
370 CONTINUE ADI2670
380 CONTINUE ADI2680
IF (BIGI.GT.ERR) TEST=1. ADI2690
TEST3(KOUNT+1)=BIGI ADI2700
IF (TEST.EQ.1.) GO TO 30 ADI2710
RETURN ADI2720
C ADI2730
C ADI2740
C ---FORMATS--- ADI2750
C ADI2760
C ----- ADI2770
C ADI2780
C ADI2790
390 FORMAT ('OEXCEEDED PERMITTED NUMBER OF ITERATIONS'/' ',39('*')) ADI2800
400 FORMAT ('-',38X,'SOLUTION BY THE ALTERNATING DIRECTION IMPLICIT PRADI2810
1OCEDURE'/39X,56('*'))
410 FORMAT (///1H0,I5,22H ITERATION PARAMETERS:,6D12.3//28X,10D12.3) ADI2830
END ADI2840-
SUBROUTINE COEF(PHI,KEEP,PHE,STRT,SURI,T,TR,TC,S,WELL,TL,SL,PERM,BCOF 10
1OTTOM,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,DDN,WR,NWR,NENT)
C -----COF 30
C COMPUTE COEFFICIENTS COF 40
C -----COF 50
C COF 60
C SPECIFICATIONS: COF 70
IMPLICIT REAL *8 (A-H,O-Z) $7-10
REAL *8 KEEP,M $7-11
INTEGER R,P,PU,DIML,DIMW
INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD

```

```

1, CONTR, LEAK, RECH, SIP, ADI, NUMS, IDK1, IDK2
C
C          DIMENSION PHI(1), KEEP(1), PHE(1), STRT(1), SURI(1), T(1), TR(1)
1, TC(1), S(1), WELL(1), TL(1), SL(1), PERM(1), BOTTOM(1), SY(1),
2RATE(1), RIVER(1), M(1), TOP(1), GRND(1), DELX(1), DELY(1),
3DDN(1), WR(1), NWR(1)
C
C          COMMON /SARRAY/ VF4(11), CHK(15)
C          COMMON /SPARAMI/ WATER, CONVRT, EVAP, CHCK, PNCH, NUM, HEAD, CONTR, LEAK,
1RECH, SIP, NUMS, LSOR, ADI, IERR, KOUNT, IFINAL, NUMT, KT, KP, NPER, KTH,
2ITMAX, LENGTH, NWEL, NW, DIML, DIMW, I, J, IDK1, IDK2, JNO1, INO1, R, P, PU
C          COMMON /SPARAMR/ U, SS, TT, TMIN, ETDIST, QET, ERR, TMAX, CDLT, HMAX, YDIM,
1WIDTH, DELT, SUM, SUMP, SUBS, STORE, TEST, ETQB, ETQD, FACTX, FACTY, EROR
C          COMMON /ARSIZE/ IZ, JZ, IP, JP, IR, JR, IC, JC, IL, JL, IS, JS, IH, IMAX, IMX1
C
C          GO TO (1,2,3) NENT
DATA PIE/3.141593/
RETURN
C
C          .....
C          ---COMPUTE COEFFICIENTS FOR TRANSIENT PART OF LEAKAGE TERM---
C          *****
C          ENTRY CLAY(T, S, TL, RATE, M)
C          *****
1          CONTINUE
          TMIN=1.E30
          TT=0.0
          PRATE=0.
          DO 50 I=1, DIML
          DO 50 J=1, DIMW
          N=I+DIML*(J-1)
C
C          ---SKIP COMPUTATIONS IF T, RATE OR M = 0, OR IF CONSTANT
C          HEAD BOUNDARY---
1          IF (RATE(N).LE.0..OR.T(N).EQ.0..OR.M(N).EQ.0..OR.S(N).LT.0.) GO TO
1          50
C
C          ---IF VALUE FOR TL(N ) WILL EQUAL VALUE FOR PREVIOUS NODE,
C          SKIP PART OF COMPUTATIONS---
C          IF (RATE(N)*M(N).EQ.PRATE) GO TO 40
C          DIMT=RATE(N)*SUMP/(M(N)*M(N)*SS*3)
C          IF (DIMT.GT.TT) TT=DIMT
C          IF (DIMT.LT.TMIN) TMIN=DIMT
C          PPT=PIE*PIE*DIMT
C
C          ---RECOMPUTE PPT IF DIMT WITHIN RANGE FOR SHORT TIME COMPUTATION---
C          IF (DIMT.LT.1.0E-03) PPT=1.0/DIMT
C          CC=(2.3-PPT)/(2.*PPT)
C
C          ---COMPUTE SUM OF EXPONENTIALS---
C          SUMN=0.0
C          DO 20 K=1,200
C          POWER=K*K*PPT
C          IF (POWER.LE.150.) GO TO 10

```

	POWER=150	COF 600
10	PEX=DEXP(-POWER)	\$\$7-20
	SUMN=SUMN+PEX	COF 620
	IF (PEX.GT.0.00009) GO TO 20	COF 630
	IF (K.GT.CC) GO TO 30	COF 640
20	CONTINUE	COF 650
C		COF 660
C	---COMPUTE DENOMINATER DEPENDING ON VALUE OF DIMT---	COF 670
30	DENOM=1.0	COF 680
	IF (DIMT.LT.1.0E-03) DENOM=DSQRT(PIE*DIMT)	\$\$7-30
C		COF 700
C	---HEAD VALUES ARE NOT INCLUDED IN COMPUTATION OF Q FACTOR SINCE	COF 710
C	LEAKAGE IS CONSIDERED IMPLICITLY---	COF 720
40	Q1=RATE(N)/(M(N)*DENOM)	COF 730
	TL(N)=Q1+2.*Q1*SUMN	COF 740
	PRATE=RATE(N)*M(N)	COF 750
50	CONTINUE	COF 760
	TMIN=TMIN*3.0	COF 770
	TT=TT*3.0	COF 780
	RETURN	COF 790
C	.....	COF 800
C		COF 810
C	---COMPUTE TRANSMISSIVITY IN WT OR WT-ARTESIAN CONVERSION PROBLEM---	COF 820
C	*****	COF 830
C	ENTRY TRANS(PHI,KEEP,SURI,T,TR,TC,WELL,PERM,BOTTOM,TOP,DDN,	
C	1WR,NWR,DELX,DELY)	
C	*****	COF 850
2	CONTINUE	
	DO 60 I=1,DIML	COF 860
	DO 60 J=1,DIMW	COF 870
	N=I+DIML*(J-1)	COF 880
	IF (PERM(N).EQ.0.) GO TO 60	COF 890
	HED=PHI(N)	COF 900
	IF (CONVRT.EQ.CHK(7)) HED=DMIN1(PHI(N),TOP(N))	\$\$7-40
	T(N)=PERM(N)*(HED-BOTTOM(N))	COF 920
	IF (T(N).GT.0.) GO TO 60	COF 930
	IF (WELL(N).LT.0.) GO TO 70	COF 940
C		COF 950
C	---THE FOLLOWING STATEMENTS APPLY WHEN NODES (EXCEPT WELL NODES)	COF 960
C	GO DRY---	COF 970
	PERM(N)=0.	COF 980
	T(N)=0.0	COF 990
	TR(N-DIML)=0.	COF1000
	TR(N)=0.	COF1010
	TC(N-1)=0.	COF1020
	TC(N)=0.	COF1030
	PHI(N)=SURI(N)	COF1040
C	WRITE (P,150) I,J	COF1050
60	CONTINUE	COF1060
	IF (KT.EQ.0) RETURN	COF1070
	GO TO 90	COF1080
C		COF1090
C	---START PROGRAM TERMINATION WHEN A WELL GOES DRY---	COF1100
70	WRITE (P,120) I,J	COF1110

C	WRITE (P,130)	COF1120
	IERR=1	COF1130
	CALL STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,DDN	
	1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,4)	
	DO 80 I=2,INO1	COF1150
	DO 80 J=2,JNO1	COF1160
	N=I+DIML*(J-1)	COF1170
80	PHI(N)=KEEP(N)	COF1180
	SUM=SUM-DELT	COF1190
	SUMP=SUMP-DELT	COF1200
	KT=KT-1	COF1210
	IF (KT.EQ.0) STOP	COF1220
	IF (IDK2.EQ.CHK(15)) THEN	
	CALL STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,DDN	
	1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,5)	
	ENDIF	
	IF (PNCH.EQ.CHK(1)) THEN	
	CALL STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,DDN	
	1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,6)	
	ENDIF	
	IF (MOD(KT,KTH).EQ.0) STOP	COF1250
C	WRITE (P,140) KT,SUM	COF1260
	CALL STEP(PHI,KEEP,STRT,SURI,T,WELL,PERM,BOTTOM,TOP,DELX,DDN	
	1,DELY,WR,NWR,TEST3,TR,TC,S,QRE,TL,SY,RATE,RIVER,M,GRND,4)	
	IF(CHCK.EQ.CHK(5)) THEN	
	CALL CHECKI(PHI,KEEP,PHE,STRT,T,TR,TC,S,QRE,WELL,TL,PERM,BOTTOM	
	1,SY,RATE,RIVER,M,GRND,DELX,DELY,2)	
	ENDIF	
	STOP	COF1290
C		COF1300
C	---COMPUTE T COEFFICIENTS---	COF1310
C	*****	COF1320
C	ENTRY TCOF(T,TR,DELX,DELY)	COF1330
3	CONTINUE	
C	*****	COF1340
90	DO 110 I=1,INO1	COF1350
	DO 110 J=1,JNO1	COF1360
	N=I+DIML*(J-1)	COF1370
	NR=N+DIML	COF1380
	NB=N+1	COF1390
	IF (T(N).EQ.0.) GO TO 110	COF1400
	IF (T(NR).EQ.0.) GO TO 100	COF1410
	TR(N)=(2.*T(NR)*T(N))/(T(N)*DELX(J+1)+T(NR)*DELX(J))*FACTX	COF1420
100	IF (T(NB).EQ.0.) GO TO 110	COF1430
	TC(N)=(2.*T(NB)*T(N))/(T(N)*DELY(I+1)+T(NB)*DELY(I))*FACTY	COF1440
110	CONTINUE	COF1450
	RETURN	COF1460
C		COF1470
C	---FORMATS---	COF1480
C		COF1490
C	-----	COF1500
C		COF1510
C		COF1520
120	FORMAT ('-*****WELL',I3,',',I3,' GOES DRY*****')	COF1530

```

130 FORMAT ('1',50X,'DRAWDOWN WHEN WELL WENT DRY')          COF1540
140 FORMAT ('1',32X,'DRAWDOWN FOR TIME STEP',I3,'; SIMULATION TIME =',COF1550
11PE15.7,' SECONDS')          COF1560
150 FORMAT ('-',20('*'),' NODE ',I4,',',I4,' GOES DRY ',20('*')) COF1570
END          COF1580-
SUBROUTINE CHECKI(PHI,KEEP,PHE,STRT,T,TR,TC,S,QRE,WELL,TL,PERM,BOTCHK 10
1TOM,SY,RATE,RIVER,M,TOP,GRND,DELX,DELY,NENT)          CHK 20
-----CHK 30
C COMPUTE A MASS BALANCE          CHK 40
C -----CHK 50
C          CHK 60
C SPECIFICATIONS:          CHK 70
IMPLICIT REAL *8 (A-H,O-Z)          $8-10
REAL *8 KEEP,M          $$8-11
INTEGER R,P,PU,DIML,DIMW
INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD
1,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C          CHK 120
DIMENSION PHI(IZ,JZ),KEEP(IZ,JZ),PHE(IZ,JZ),STRT(IZ,JZ),T(IZ,JCHK 130
IZ),TR(IZ,JZ),TC(IZ,JZ),S(IZ,JZ),QRE(IZ,JZ),WELL(IZ,JZ),TL(IZCHK 140
2,JZ),PERM(IZ,JZ),BOTTOM(IP,JP),SY(IP,JP),RATE(IR,JR),RIVER(IRCHK 150
3,JR),M(IR,JR),TOP(IC,JC),GRND(IL,JL),DELX(JZ),DELY(IZ)
COMMON /BAL/ QE(100,100),QL(100,100),QCH(150),LROW(150),LCOL(150)
C          CHK 170
COMMON /SARRAY/ VF4(11),CHK(15)          CHK 180
COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
COMMON /CK/ ETFLXT,STORT,QRET,CHST,CHDT,FLUXT,PUMPT,CFLUXT,FLXNT  CHK 240
COMMON /ARSize/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
GO TO (1,2) NENT
RETURN          CHK 260
C          CHK 270
C *****          CHK 280
C ENTRY CHECK(PHI,KEEP,STRT,T,WELL,TOP,DELX,DELY,TR,TC,S,
C 2QRE,TL,SY,RATE,RIVER,M,GRND)
1 CONTINUE
C *****          CHK 300
C --- INITIALIZE VARIABLES ---          CHK 310
PUMP=0.          CHK 320
STOR=0.          CHK 330
FLUXS=0.0          CHK 340
CHD1=0.0          CHK 350
CHD2=0.0          CHK 360
QREFLX=0.          CHK 370
CFLUX=0.          CHK 380
FLUX=0.          CHK 390
ETFLUX=0.          CHK 400
FLXN=0.0          CHK 410
DO 5 ICH=1,100
QCH(ICH)=0.
LROW(ICH)=0.

```

```

    LCOL(ICH)=0.
5  CONTINUE
    ICH=0
C  .....CHK 420
C  .....CHK 430
C  ---COMPUTE RATES, STORAGE AND PUMPAGE FOR THIS STEP---      CHK 440
    QL(1,1)=0.
    QE(1,1)=0.
    DO 240 I=2,DIML                                             CHK 450
    DO 240 J=2,DIMW                                             CHK 460
    QL(I,J)=0.
    QE(I,J)=0.
    IF (T(I,J).EQ.0.) GO TO 240                                CHK 470
    AREA=DELX(J)*DELY(I)                                       CHK 480
    IF (S(I,J).GE.0.) GO TO 120                                CHK 490
C  .....CHK 500
C  ---COMPUTE FLOW RATES TO AND FROM CONSTANT HEAD BOUNDARIES---  CHK 510
    ICH=ICH+1
    LROW(ICH)=I
    LCOL(ICH)=J
    IF (S(I,J-1).LT.0..OR.T(I,J-1).EQ.0.) GO TO 30           CHK 520
    X=(STRT(I,J)-PHI(I,J-1))*TR(I,J-1)*DELY(I)               CHK 530
    QCH(ICH)=QCH(ICH)+X
    IF (X) 10,30,20                                           CHK 540
10  CHD1=CHD1+X                                               CHK 550
    GO TO 30                                                   CHK 560
20  CHD2=CHD2+X                                               CHK 570
30  IF (S(I,J+1).LT.0..OR.T(I,J+1).EQ.0.) GO TO 60           CHK 580
    X=(STRT(I,J)-PHI(I,J+1))*TR(I,J)*DELY(I)                 CHK 590
    QCH(ICH)=QCH(ICH)+X
    IF (X) 40,60,50                                           CHK 600
40  CHD1=CHD1+X                                               CHK 610
    GO TO 60                                                   CHK 620
50  CHD2=CHD2+X                                               CHK 630
60  IF (S(I-1,J).LT.0..OR.T(I-1,J).EQ.0.) GO TO 90           CHK 640
    X=(STRT(I,J)-PHI(I-1,J))*TC(I-1,J)*DELX(J)               CHK 650
    QCH(ICH)=QCH(ICH)+X
    IF (X) 70,90,80                                           CHK 660
70  CHD1=CHD1+X                                               CHK 670
    GO TO 90                                                   CHK 680
80  CHD2=CHD2+X                                               CHK 690
90  IF (S(I+1,J).LT.0..OR.T(I+1,J).EQ.0.) GO TO 240           CHK 700
    X=(STRT(I,J)-PHI(I+1,J))*TC(I,J)*DELX(J)                 CHK 710
    QCH(ICH)=QCH(ICH)+X
    IF (X) 100,240,110                                        CHK 720
100 CHD1=CHD1+X                                               CHK 730
    GO TO 240                                                 CHK 740
110 CHD2=CHD2+X                                               CHK 750
    GO TO 240                                                 CHK 760
C  .....CHK 770
C  ---RECHARGE AND WELLS---                                     CHK 780
120 QREFLX=QREFLX+QRE(I,J)*AREA                               CHK 790
    IF (WELL(I,J)) 130,150,140                                CHK 800
130 PUMP=PUMP+WELL(I,J)*AREA                                  CHK 810

```

	GO TO 150	CHK 820
	140 CFLUX=CFLUX+WELL(I,J)*AREA	CHK 830
	150 IF (EVAP.NE.CHK(6)) GO TO 190	CHK 840
C		CHK 850
C	---COMPUTE ET RATE---	CHK 860
	IF (PHI(I,J).GE.GRND(I,J)-ETDIST) GO TO 160	CHK 870
	ETQ=0.0	CHK 880
	GO TO 180	CHK 890
	160 IF (PHI(I,J).LE.GRND(I,J)) GO TO 170	CHK 900
	ETQ=QET	CHK 910
	GO TO 180	CHK 920
	170 ETQ=QET/ETDIST*(PHI(I,J)+ETDIST-GRND(I,J))	CHK 930
	180 ETFLUX=ETFLUX-ETQ*AREA	CHK 940
	QE(I,J)=ETQ*AREA	
C		CHK 950
C	---COMPUTE VOLUME FROM STORAGE---	CHK 960
	190 STORE=S(I,J)	CHK 970
	IF (WATER.EQ.CHK(2)) STORE=SY(I,J)	CHK 980
	IF (CONVRT.NE.CHK(7)) GO TO 230	CHK 990
	X=KEEP(I,J)-PHI(I,J)	CHK1000
	IF (X) 200,210,210	CHK1010
	200 HED1=PHI(I,J)	CHK1020
	HED2=KEEP(I,J)	CHK1030
	X=DABS(X)	\$\$8-20
	GO TO 220	CHK1050
	210 HED1=KEEP(I,J)	CHK1060
	HED2=PHI(I,J)	CHK1070
	220 STORE=S(I,J)	CHK1080
	IF (HED1-TOP(I,J).LE.0.) STORE=SY(I,J)	CHK1090
	IF ((HED1-TOP(I,J))*(HED2-TOP(I,J)).LT.0.0) STORE=(HED1-TOP(I,J))/	CHK1100
	1X*S(I,J)+(TOP(I,J)-HED2)/X*SY(I,J)	CHK1110
	230 STOR=STOR+STORE*(KEEP(I,J)-PHI(I,J))*AREA	CHK1120
C		CHK1130
C	---COMPUTE LEAKAGE RATE---	CHK1140
	IF (LEAK.NE.CHK(9)) GO TO 240	CHK1150
	IF (M(I,J).EQ.0.) GO TO 240	CHK1160
	HED1=STRT(I,J)	CHK1170
	IF (CONVRT.EQ.CHK(7)) HED1=DMAX1(STRT(I,J),TOP(I,J))	\$\$8-30
	HED2=PHI(I,J)	CHK1190
	IF (CONVRT.EQ.CHK(7)) HED2=DMAX1(PHI(I,J),TOP(I,J))	\$\$8-40
	XX=RATE(I,J)*(RIVER(I,J)-HED1)*AREA/M(I,J)	CHK1210
	YY=TL(I,J)*(HED1-HED2)*AREA	CHK1220
	FLUX=FLUX+XX	CHK1230
	XNET=XX+YY	CHK1240
	QL(I,J)=XNET	
	FLUXS=FLUXS+XNET	CHK1250
	IF (XNET.LT.0.) FLXN=FLXN-XNET	CHK1260
	240 CONTINUE	CHK1270
C		CHK1280
C		CHK1290
C	---COMPUTE CUMULATIVE VOLUMES, TOTALS, AND DIFFERENCES---	CHK1300
	STORT=STORT+STOR	CHK1310
	STOR=STOR/DELT	CHK1320
	ETFLXT=ETFLXT-ETFLUX*DELT	CHK1330

```

FLUXT=FLUXT+FLUXS*DELT                                CHK1340
FLXNT=FLXNT+FLXN*DELT                                CHK1350
FLXPT=FLUXT+FLXNT                                    CHK1360
QRET=QRET+QREFLX*DELT                                CHK1370
CHDT=CHDT-CHD1*DELT                                  CHK1380
CHST=CHST+CHD2*DELT                                  CHK1390
PUMPT=PUMPT-PUMP*DELT                                CHK1400
CFLUXT=CFLUXT+CFLUX*DELT                             CHK1410
TOTL1=STORT+QRET+CFLUXT+CHST+FLXPT                  CHK1420
TOTL2=CHDT+PUMPT+ETFLXT+FLXNT                       CHK1430
SUMR=QREFLX+CFLUX+CHD2+CHD1+PUMP+ETFLUX+FLUXS+STOR  CHK1440
DIFF=TOTL2-TOTL1                                     CHK1450
PERCNT=0.0                                            CHK1460
IF (TOTL2.EQ.0.) GO TO 250                            CHK1470
PERCNT=DIFF/TOTL2*100.                               CHK1480
250 RETURN                                            CHK1490
C .....CHK1500
C .....CHK1510
C ---PRINT RESULTS---                                CHK1520
C *****CHK1530
C ENTRY CWRITE                                       CHK1540
C *****CHK1550
2 CONTINUE
C .....CHK1560
C WRITE (P,260) STOR,QREFLX,STORT,CFLUX,QRET,PUMP,CFLUXT,ETFLUX,CHSTCHK1570
C 1,FLXPT,CHD2,TOTL1,CHD1,FLUX,FLUXS,ETFLXT,CHDT,SUMR,PUMPT,FLXNT,TOTCHK1580
C 2L2,DIFF,PERCNT                                    CHK1590
IF(LEAK.NE.CHK(9)) GO TO 277
C WRITE(P,281)
DO 275 I=1,DIML
C275 WRITE(P,280) I,(QL(I,J),J=1,DIMW)
275 CONTINUE
277 IF(EVAP.NE.CHK(6)) GO TO 282
C WRITE(P,279)
DO 276 I=1,DIML
C276 WRITE(P,280) I,(QE(I,J),J=1,DIMW)
276 CONTINUE
279 FORMAT('1',49X,' EVAPOTRANSPIRATION-FLUX MATRIX ',/,49X,32('-'))
280 FORMAT (1X,I4,10(1X,1PE11.4),/, (5X,10(1X,1PE11.4)))
281 FORMAT('1',49X,' LEAKAGE-FLUX MATRIX ',/,49X,21('-'))
C282 WRITE(P,270)(LROW(ICHX),LCOL(ICHX),QCH(ICHX),ICHX=1,ICH)
282 CONTINUE
RETURN
C .....CHK1600
C ---FORMATS---                                     CHK1610
C .....CHK1620
C .....CHK1630
C .....CHK1640
C .....CHK1650
C .....CHK1660
260 FORMAT ('0',10X,'CUMULATIVE MASS BALANCE:',16X,'L**3',23X,'RATES FCHK1670
1OR THIS TIME STEP:',16X,'L**3/T'/11X,24('-'),43X,25('-')//20X,'SOUCHK1680
2RCES:',69X,' STORAGE =',F20.4/20X,8('-'),68X,'RECHARGE =',F20.4/27XCHK1690
3,' STORAGE =',F20.2,35X,' CONSTANT FLUX =',F20.4/26X,'RECHARGE =',F2CHK1700
40.2,41X,' PUMPING =',F20.4/21X,' CONSTANT FLUX =',F20.2,30X,'EVAPOTRCHK1710

```

```

5ANSPARATION =',F20.4/21X,'CONSTANT HEAD =',F20.2,34X,'CONSTANT HEACHK1720
6D: '/27X,'LEAKAGE =',F20.2,46X,'IN =',F20.4/21X,'TOTAL SOURCES =',FCHK1730
720.2,45X,'OUT =',F20.4/96X,'LEAKAGE: '/20X,'DISCHARGES: ',45X,'FROM CHK1740
8PREVIOUS PUMPING PERIOD =',F20.4/20X,11('-'),68X,'TOTAL =',F20.4/1CHK1750
96X,'EVAPOTRANSPIRATION =',F20.2/21X,'CONSTANT HEAD =',F20.2,36X,'SCHK1760
$SUM OF RATES= ',F20.4/19X,'QUANTITY PUMPED =',F20.2/27X,'LEAKAGE =',CHK1770
$F20.2/19X,'TOTAL DISCHARGE =',F20.2//17X,'DISCHARGE-SOURCES =',F20CHK1780
$.2/15X,'PER CENT DIFFERENCE =',F20.2//)                                CHK1790
270 FORMAT(/4X,'CONSTANT HEAD DISCHARGE: '/
15X,'ROW      COL      DISCHARGE (CFS)'/
15X,'---      ---      -----'/
2(5X,I3,4X,I3,4X,E11.4))
      END                                                                CHK1800-
      SUBROUTINE PRNTAI(PHI,SURI,T,S,WELL,DELX,DELY,NG,NENT)
C -----PRN 20
C PRINT MAPS OF DRAWDOWN AND HYDRAULIC HEAD                                PRN 30
C -----PRN 40
C                                                                PRN 50
C SPECIFICATIONS:                                                        PRN 60
C IMPLICIT REAL *8 (A-H,O-Z)                                           $9-10
C REAL *8 MESUR,K                                                       $$9-20
C INTEGER R,P,PU,DIML,DIMW
C INTEGER  CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD
C 1,CONTR,LEAK,RECH,SIP,ADI,NUMS,IDK1,IDK2
C                                                                PRN 110
C DIMENSION PHI(IZ,JZ),SURI(IZ,JZ),S(IZ,JZ),WELL(IZ,JZ),DELX(JZ)PRN 120
C 1,DELY(IZ),T(IZ,JZ)                                                  PRN 130
C                                                                PRN 140
C                                                                PRN 150
COMMON /SARRAY/ VF4(11),CHK(15)
COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,
1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,
2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU
COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,
1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR
COMMON /PRI/ NA(4),N1,N2,N3
COMMON /PRR/ PRNT(122),DIGIT(122),XN(100),BLANK(60),SYM(17),
1YN(13),VF1(6),VF2(6),VF3(7),YLABEL(6),TITLE(5),XLABEL(3),XN1,
2MESUR,XSCALE,YSCALE,DINCH,FACT1,FACT2
COMMON /ARSIZE/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1
GO TO (1,2) NENT
RETURN                                                                PRN 250
C .....PRN 260
C .....PRN 270
C ---INITIALIZE VARIABLES FOR PLOT---                                PRN 280
C *****PRN 290
C ENTRY MAP(WELL,DELX,DELY)                                           PRN 300
C *****PRN 310
1 CONTINUE
10 XSF=DINCH*XSCALE                                                    PRN 320
   YSF=DINCH*YSCALE                                                    PRN 330
   NYD=YDIM/YSF                                                         PRN 340
   IF (NYD*YSF.LE.YDIM-DELY(INO1)/2.) NYD=NYD+1                      PRN 350
   IF (NYD.LE.12) GO TO 20                                              PRN 360
   DINCH=YDIM/(12.*YSCALE)                                              PRN 370

```

C	WRITE (P,310) DINCH	PRN 380
C	IF (YSCALE.LT.1.0) WRITE (P,320)	PRN 390
	GO TO 10	PRN 400
20	NXD=WIDTH/XSF	PRN 410
	IF (NXD*XSF.LE.WIDTH-DELX(JN01)/2.) NXD=NXD+1	PRN 420
	N4=NXD*N1+1	PRN 430
	N5=NXD+1	PRN 440
	N6=NYD+1	PRN 450
	N8=N2*NYD+1	PRN 460
	NA(1)=N4/2-1	PRN 470
	NA(2)=N4/2	PRN 480
	NA(3)=N4/2+3	PRN 490
	NC=(N3-N8-10)/2	PRN 500
	ND=NC+N8	PRN 510
	NE=MAX0(N5,N6)	PRN 520
	VF1(3)=DIGIT(ND)	PRN 530
	VF2(3)=DIGIT(ND)	PRN 540
	VF3(3)=DIGIT(NC)	PRN 550
	XLABEL(3)=MESUR	PRN 560
	YLABEL(6)=MESUR	PRN 570
	DO 40 I=1,NE	PRN 580
	NNX=N5-I	PRN 590
	NNY=I-1	PRN 600
	IF (NNY.GE.N6) GO TO 30	PRN 610
	YN(I)=YSF*NNY/YSCALE	PRN 620
30	IF (NNX.LT.0) GO TO 40	PRN 630
	XN(I)=XSF*NNX/YSCALE	PRN 640
40	CONTINUE	PRN 650
	RETURN	PRN 660
C	.....	PRN 670
C		PRN 680
C	*****	PRN 690
C	ENTRY PRNTA(PHI,SURI,T,S,WELL,DELX,DELY,NG)	
C	*****	PRN 710
2	CONTINUE	
C	---VARIABLES INITIALIZED EACH TIME A PLOT IS REQUESTED---	PRN 720
	DIST=WIDTH-DELX(JN01)/2.	PRN 730
	JJ=JN01	PRN 740
	LL=1	PRN 750
	Z=NXD*XSF	PRN 760
C	IF (NG.EQ.1) WRITE (P,280) (TITLE(I),I=1,2)	PRN 770
C	IF (NG.EQ.2) WRITE (P,280) (TITLE(I),I=3,5)	PRN 780
	DO 270 I=1,N4	PRN 790
C		PRN 800
C	---LOCATE X AXES---	PRN 810
	IF (I.EQ.1.OR.I.EQ.N4) GO TO 50	PRN 820
	PRNT(1)=SYM(12)	PRN 830
	PRNT(N8)=SYM(12)	PRN 840
	IF ((I-1)/N1*N1.NE.I-1) GO TO 70	PRN 850
	PRNT(1)=SYM(14)	PRN 860
	PRNT(N8)=SYM(14)	PRN 870
	GO TO 70	PRN 880
C		PRN 890
C	---LOCATE Y AXES---	PRN 900

50	DO 60 J=1,N8	PRN 910
	IF ((J-1)/N2*N2.EQ.J-1) PRNT(J)=SYM(14)	PRN 920
60	IF ((J-1)/N2*N2.NE.J-1) PRNT(J)=SYM(13)	PRN 930
C		PRN 940
C	---COMPUTE LOCATION OF NODES AND DETERMINE APPROPRIATE SYMBOL---	PRN 950
70	IF (DIST.LT.0..OR.DIST.LT.Z-XN1*XSF) GO TO 220	PRN 960
	YLEN=DELY(2)/2.	PRN 970
	DO 200 L=2,IN01	PRN 980
	J=YLEN*N2/YSF+1.5	PRN 990
	IF (T(L,JJ).EQ.0.) GO TO 140	PRN1000
	IF (S(L,JJ).LT.0.) GO TO 190	PRN1010
	INDX3=0	PRN1020
	GO TO (80,90), NG	PRN1030
80	K=(SURI(L,JJ)-PHI(L,JJ))*FACT1	PRN1040
C	-TO CYCLE SYMBOLS FOR DRAWDOWN, REMOVE C FROM COL. 1 OF NEXT CARD-	PRN1050
C	K=DMOD(K,10.)	\$\$\$9-20
	GO TO 100	PRN1070
90	K=PHI(L,JJ)*FACT2	PRN1080
100	IF (K) 110,140,120	PRN1090
110	IF (J-2.GT.0) PRNT(J-2)=SYM(13)	PRN1100
	N=-K	PRN1110
	IF (N.LT.100) GO TO 130	PRN1120
	GO TO 170	PRN1130
120	N=K	PRN1140
	IF (N.LT.100) GO TO 130	PRN1150
	IF (N.GT.999) GO TO 170	PRN1160
	INDX3=N/100	PRN1170
	IF (J-2.GT.0) PRNT(J-2)=SYM(INDX3)	PRN1180
	N=N-INDX3*100	PRN1190
130	INDX1=MOD(N,10)	PRN1200
	IF (INDX1.EQ.0) INDX1=10	PRN1210
C	-TO CYCLE SYMBOLS FOR DRAWDOWN, REMOVE C FROM COL. 1 OF NEXT CARD-	PRN1220
C	IF (NG.EQ.1) GO TO 150	PRN1230
	INDX2=N/10	PRN1240
	IF (INDX2.GT.0) GO TO 160	PRN1250
	INDX2=10	PRN1260
	IF (INDX3.EQ.0) INDX2=15	PRN1270
	GO TO 160	PRN1280
140	INDX1=15	PRN1290
150	INDX2=15	PRN1300
160	IF (J-1.GT.0) PRNT(J-1)=SYM(INDX2)	PRN1310
	PRNT(J)=SYM(INDX1)	PRN1320
	GO TO 200	PRN1330
170	DO 180 II=1,3	PRN1340
	JI=J-3+II	PRN1350
180	IF (JI.GT.0) PRNT(JI)=SYM(11)	PRN1360
190	IF (S(L,JJ).LT.0.) PRNT(J)=SYM(16)	PRN1370
200	YLEN=YLEN+(DELY(L)+DELY(L+1))/2.	PRN1380
210	DIST=DIST-(DELX(JJ)+DELX(JJ-1))/2.	PRN1390
	JJ=JJ-1	PRN1400
	IF (JJ.EQ.0) GO TO 220	PRN1410
	IF (DIST.GT.Z-XN1*XSF) GO TO 210	PRN1420
220	CONTINUE	PRN1430
C		PRN1440

C	---	PRINT AXES, LABELS, AND SYMBOLS---	PRN1450
	IF (I-NA(LL).EQ.0)	GO TO 240	PRN1460
	IF ((I-1)/N1*N1-(I-1))	250,230,250	PRN1470
C	230	WRITE (P,VF1) (BLANK(J),J=1,NC), (PRNT(J),J=1,N8), XN(1+(I-1)/6)	PRN1480
	230	CONTINUE	
		GO TO 260	PRN1490
C	240	WRITE (P,VF2) (BLANK(J),J=1,NC), (PRNT(J),J=1,N8), XLABEL(LL)	PRN1500
	240	CONTINUE	
		LL=LL+1	PRN1510
		GO TO 260	PRN1520
C	250	WRITE (P,VF2) (BLANK(J),J=1,NC), (PRNT(J),J=1,N8)	PRN1530
	250	CONTINUE	
C			PRN1540
C	---	COMPUTE NEW VALUE FOR Z AND INITIALIZE PRNT---	PRN1550
	260	Z=Z-2.*XN1*XSF	PRN1560
		DO 270 J=1,N8	PRN1570
	270	PRNT(J)=SYM(15)	PRN1580
C			PRN1590
C	---	NUMBER AND LABEL Y AXIS AND PRINT LEGEND---	PRN1600
C	WRITE (P,VF3) (BLANK(J),J=1,NC), (YN(I),I=1,N6)		PRN1610
C	WRITE (P,300) (YLABEL(I),I=1,6)		PRN1620
C	IF (NG.EQ.1)	WRITE (P,290) FACT1	PRN1630
C	IF (NG.EQ.2)	WRITE (P,290) FACT2	PRN1640
		RETURN	PRN1650
C			PRN1660
C	---	FORMATS---	PRN1670
C			PRN1680
C	-----		PRN1690
C			PRN1700
C			PRN1710
	280	FORMAT ('1',53X,4A8//)	PRN1720
	290	FORMAT ('OEXPLANATION'/' ',11('-')// ' R - CONSTANT HEAD BOUNDARY'/	PRN1730
		1' *** - VALUE EXCEEDED 3 FIGURES'/' MULTIPLICATION FACTOR -',F8.3)	PRN1740
	300	FORMAT ('0',39X,6A8)	PRN1750
	310	FORMAT ('0',25X,10('*'),' TO FIT MAP WITHIN 12 INCHES, DINCH REVIS	PRN1760
		LED TO',G15.7,1X,10('*'))	PRN1770
	320	FORMAT ('0',45X,'NOTE: GENERALLY SCALE SHOULD BE > OR = 1.0')	PRN1780
		END	PRN1790-
		BLOCK DATA	BLD 10
C	-----		BLD 20
		IMPLICIT REAL *8 (A-H,O-Z)	\$10-10
		REAL *8 MESUR	\$\$10-20
		INTEGER R,P,PU,DIML,DIMW	
		INTEGER CHK,WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK	
		1,RECH,SIP,ADI,NUMS,IDK1,IDK2	
C			BLD 60
		COMMON /DPARAM/ RHO,B,D,F,H	BLD 70
		COMMON /SARRAY/ VF4(11),CHK(15)	BLD 80
		COMMON /SPARAMI/ WATER,CONVRT,EVAP,CHCK,PNCH,NUM,HEAD,CONTR,LEAK,	
		1RECH,SIP,NUMS,LSOR,ADI,IERR,KOUNT,IFINAL,NUMT,KT,KP,NPER,KTH,	
		2ITMAX,LENGTH,NWEL,NW,DIML,DIMW,I,J,IDK1,IDK2,JNO1,INO1,R,P,PU	
		COMMON /SPARAMR/ U,SS,TT,TMIN,ETDIST,QET,ERR,TMAX,CDLT,HMAX,YDIM,	
		1WIDTH,DELT,SUM,SUMP,SUBS,STORE,TEST,ETQB,ETQD,FACTX,FACTY,EROR	
		COMMON /PRI/ NA(4),N1,N2,N3	

COMMON /PRR/ PRNT(122),DIGIT(122),XN(100),BLANK(60),SYM(17),  
LYN(13),VF1(6),VF2(6),VF3(7),YLABEL(6),TITLE(5),XLABEL(3),XN1,  
2MESUR,XSCALE,YSCALE,DINCH,FACT1,FACT2

COMMON /ARSize/ IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IH,IMAX,IMX1

C \*\*\*\*\*BLD 180  
C BLD 190

DATA IZ,JZ,IP,JP,IR,JR,IC,JC,IL,JL,IS,JS,IMAX/13\*20/,IH/1/

DATA CHK/'PUNC','WATE','CONT','NUME','CHEC','EVAP','CONV','HEAD','BLD 210  
1LEAK','RECH','SIP','LSOR','ADI','DK1','DK2','/R,P,PU/15,16,17/,  
2B,D,F,H/4\*0.DO/

DATA SYM/'1','2','3','4','5','6','7','8','9','0','\*','['','-','+', 'BLD 240  
1','R','W'/ BLD 250

DATA PRNT/122\*' '/,N1,N2,N3,XN1/6,10,133,.833333333D-1/,BLANK/60\*' BLD 260  
1' /,NA(4)/1000/ BLD 270

DATA XLABEL/' X DIS- ','TANCE IN',' MILES '/,YLABEL/'DISTANCE',  
1'FROM OR','IGIN IN','Y DIRECT','ION, IN','MILES '/,TITLE/  
2'PLOT OF','DRAWDOWN','PLOT OF','HYDRAULI','C HEAD '/

DATA DIGIT/'1','2','3','4','5','6','7','8','9','10','11','12','13' BLD 310

1,'14','15','16','17','18','19','20','21','22','23','24','25','26', BLD 320  
2'27','28','29','30','31','32','33','34','35','36','37','38','39', BLD 330

340','41','42','43','44','45','46','47','48','49','50','51','52','5 BLD 340  
43','54','55','56','57','58','59','60','61','62','63','64','65','66 BLD 350

5','67','68','69','70','71','72','73','74','75','76','77','78', '79 BLD 360  
6','80','81','82','83','84','85','86','87','88','89','90','91','92' BLD 370

7,'93','94','95','96','97','98','99','100','101','102','103', '104' BLD 380  
8,'105','106','107','108','109','110','111','112','113','114','115' BLD 390

9,'116','117','118','119','120','121','122'/ BLD 400

DATA VF1/'(1H ',' ',' ',' ','A1,F','10.2',')'/ BLD 410

DATA VF2/'(1H ',' ',' ',' ','A1,1','X,A8',')'/ BLD 420

DATA VF3/'(1H0',' ',' ',' ','A1,F','3.1','12F1','0.2')'/ BLD 430

DATA VF4/'(1H0',' ',' ',' ','X,12','2X','20F6','.1/(', ' ','X,2 BLD 440  
10','F6.1',')')'/ BLD 450

C \*\*\*\*\*BLD 460  
END BLD 470-